Algebraic Geometry — Exercises 24 April 2007

1. (3 points) Let $A \to B$ be a ring homomorphism, let $\Omega_{B/A}$ be the module of Kähler differentials of B over A, and let $d: B \to \Omega_{B/A}$ be the universal derivation. By definition, the canonical map

$$\operatorname{Hom}_B(\Omega_{B/A}, M) \longrightarrow \operatorname{Der}_A(B, M)$$

 $h \longmapsto h \circ d$

is an isomorphism for all B-modules M, where $\operatorname{Der}_A(B,M)$ is the B-module of A-derivations from B to M. Let $S \subseteq B$ be a multiplicative system; the composed map $A \to B \to S^{-1}B$ makes the localisation $S^{-1}B$ into an A-algebra.

(a) Show that for all $S^{-1}B$ -modules M and all B-modules N, there is a canonical isomorphism of $S^{-1}B$ -modules

$$\operatorname{Hom}_{S^{-1}B}(S^{-1}N, M) \xrightarrow{\sim} \operatorname{Hom}_B(N, M).$$

In particular, $\operatorname{Hom}_B(\Omega_{B/A}, M)$ and $\operatorname{Hom}_{S^{-1}B}(S^{-1}\Omega_{B/A}, M)$ are naturally isomorphic for all $S^{-1}B$ -modules M.

(b) Show that for all $S^{-1}B$ -modules M, there is a canonical isomorphism of $S^{-1}B$ -modules

$$\operatorname{Der}_A(S^{-1}B, M) \xrightarrow{\sim} \operatorname{Der}_A(B, M).$$

(c) Conclude that $\Omega_{S^{-1}B/A}$ is canonically isomorphic to $S^{-1}\Omega_{B/A}$.

For the following exercises, we consider an example treated in class. Let k be a field of characteristic different from 2, let d be a non-negative integer, and let

$$f = x^{2d+1} + f_{2d}x^{2d} + \dots + f_0 \in k[x]$$

be a polynomial which has no double roots over an algebraic closure of k. Since f is not a square, the element $y^2 - f$ is irreducible in k(x)[y] and the ring

$$K = k(x)[y]/(y^2 - f)$$

is a field. It was shown in class that there is a unique irreducible regular projective curve C over k which has K as its function field, and that C can be covered by the two affine open subsets

$$U = \text{Spec}(k[x, y]/(y^2 - f))$$
 and $V = \text{Spec}(k[u, v]/(v^2 - h)),$

where

$$h = f_0 u^{2d+2} + f_1 u^{2d+1} + \dots + f_{2d} u^2 + u.$$

The intersection of the two subsets is the affine scheme

$$\operatorname{Spec}(k[x, y, u, v]/(y^2 - f, ux - 1, x^{d+1}v - y))$$

seen as an open subset of both U and V via the morphisms induced by the obvious k-algebra homomorphisms. (In other words, the glueing data is given by the equations $u = x^{-1}$ and $v = x^{-d-1}y$.)

- **2.** (3 points) Let $P \in C(k)$ be the unique point of C where x has a pole (i.e. the point u = v = 0 in terms of the coordinates on V). Compute a basis for the k-vector space L(nP) for all $n \in \mathbf{Z}$. (Hint: Find an expression for $\operatorname{ord}_P(g_1(x) + yg_2(x))$ in terms of the polynomials g_1 and g_2 .)
- **3.** (3 points) Suppose $f_0 = 1$, and let Q be one of the two points where x has a zero. Compute a k-basis for L(nQ) for all $n \in \mathbb{Z}$. (Hint: First compute a k-basis for L(nQ + nR), where R is the other point where x has a zero. Then show that the completion

$$\widehat{\mathcal{O}}_{C,R} = \varprojlim_{n} \mathcal{O}_{C,R}/\mathfrak{m}_{R}^{n}$$

is isomorphic to the power series ring k[[x]]. Finally, consider the natural map

$$\phi: L(nQ + nR) \longrightarrow k((x)),$$

where the field of fractions of $\widehat{\mathcal{O}}_{C,R}$ has been identified with the field k((x)) of Laurent series. Show that

$$L(nQ) = \phi^{-1}(k[[x]])$$

and use this to determine a k-basis for L(nQ).)

4. (3 points) Let E be the irreducible regular projective curve over the field \mathbf{F}_3 which has as its function field

$$K = \mathbf{F}_3(x)[y]/(y^2 - x^3 + x - 1).$$

- (a) List the elements of $E(\mathbf{F}_3)$ (there are seven of them).
- (b) Let $P \in E(\mathbf{F}_3)$ be the unique point where x has a pole. For every point $Q \in E(\mathbf{F}_3)$, write

$$Q^* \mathcal{L}(4P) = \mathcal{L}(4P)_Q / \mathfrak{m}_Q \mathcal{L}(4P)_Q.$$

Make the canonical \mathbf{F}_3 -linear map

$$f: L(4P) \longrightarrow \bigoplus_{Q \in E(\mathbf{F}_3)} Q^* \mathcal{L}(4P)$$

explicit by giving a basis of both sides and the matrix of f with respect to these bases.

(Remark: In the language of coding theory, this map describes a linear error-correcting code over \mathbf{F}_3 of dimension 4, length 7, and distance 3, which can correct one error.)