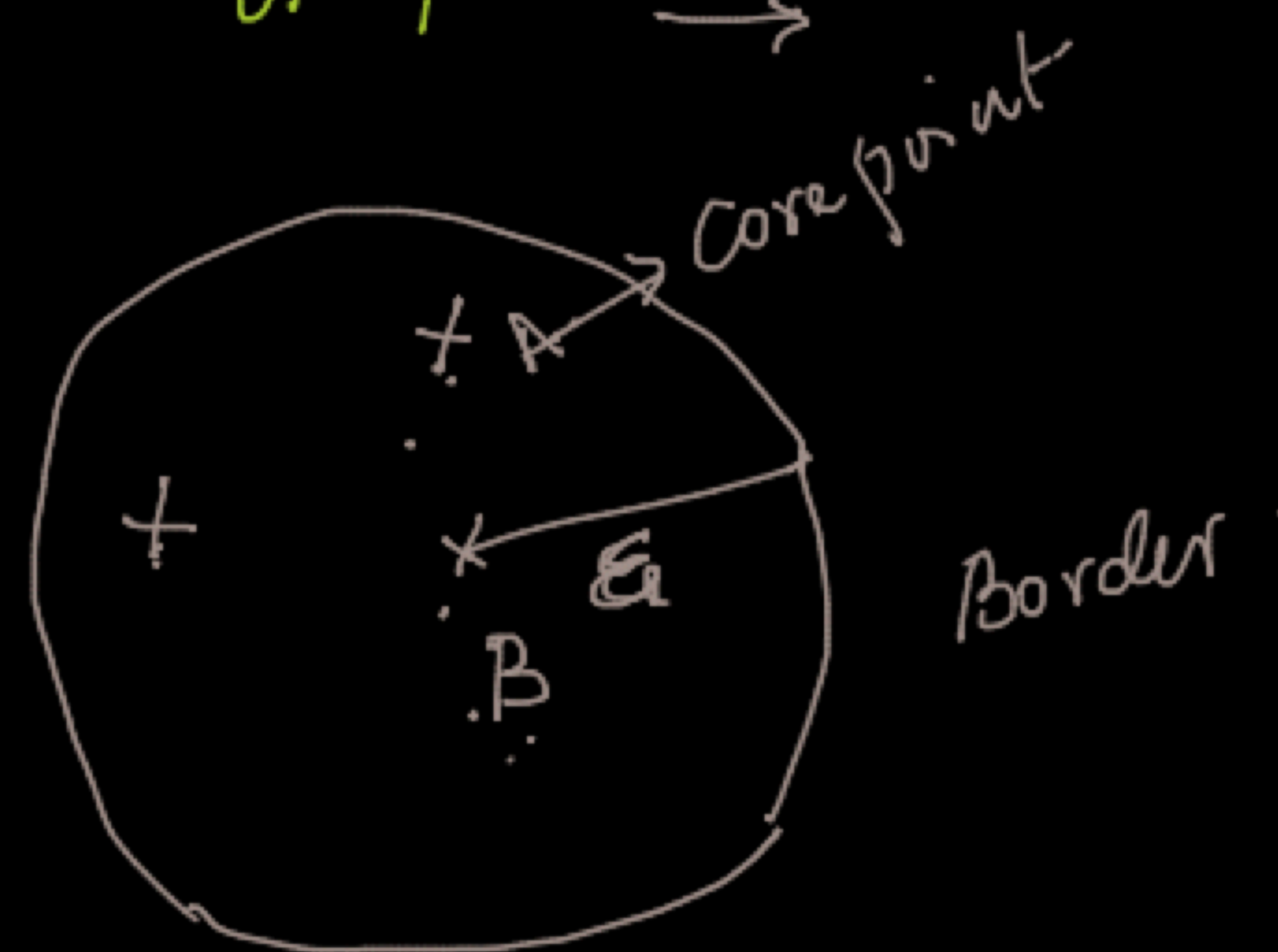


DBSCAN.

— Density Based Spatial Clustering of Applications with Noise

Minpoints ≥ 3 ✓
 Epsilon distance (ϵ) ✓

— Hyperparameters.



$< \text{Minpoints}$
 → No core points within ϵ radius

Noise point → $< \text{Minpoints}$

→ no core points with ϵ radius

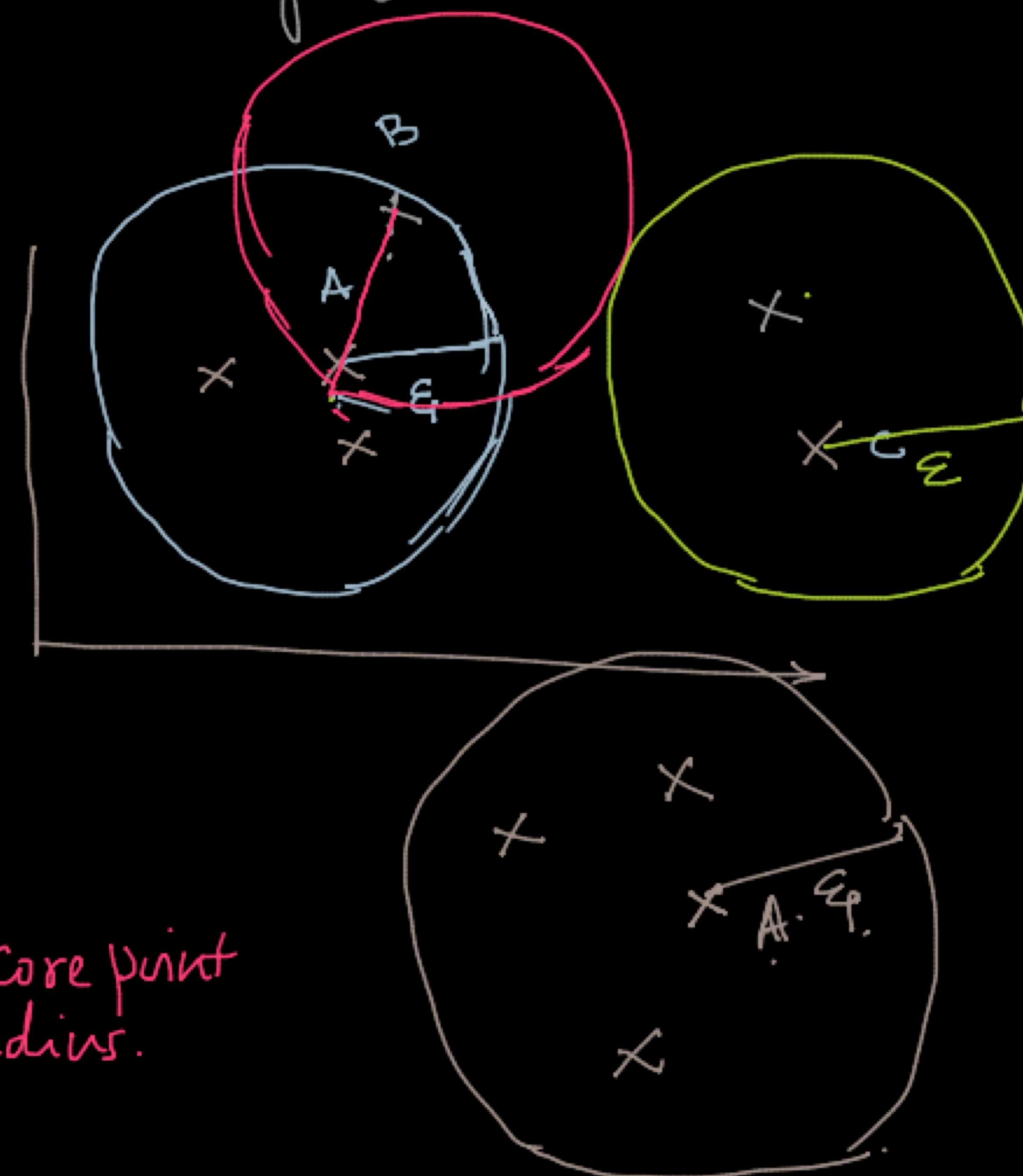
Core point
 Border Point
 Noise point

$\geq \text{Minpoints}$
 A → Core point

B → Border points

$< \text{Minpoints}$

— Includes a core point with ϵ -radius.



	x_1	x_2	x_3	
A	—	—	—	Core point ✓
B	—	—	—	Core point ✓
C	—	—	—	Border point ✓
D	—	—	—	Core point ✓
E	—	—	—	Noise point ✓ X
F	—	—	—	Border point ✓

Reachable



Min Points .

ϵ - distance .

Hyper param

Core point-

Border point

Noise point .

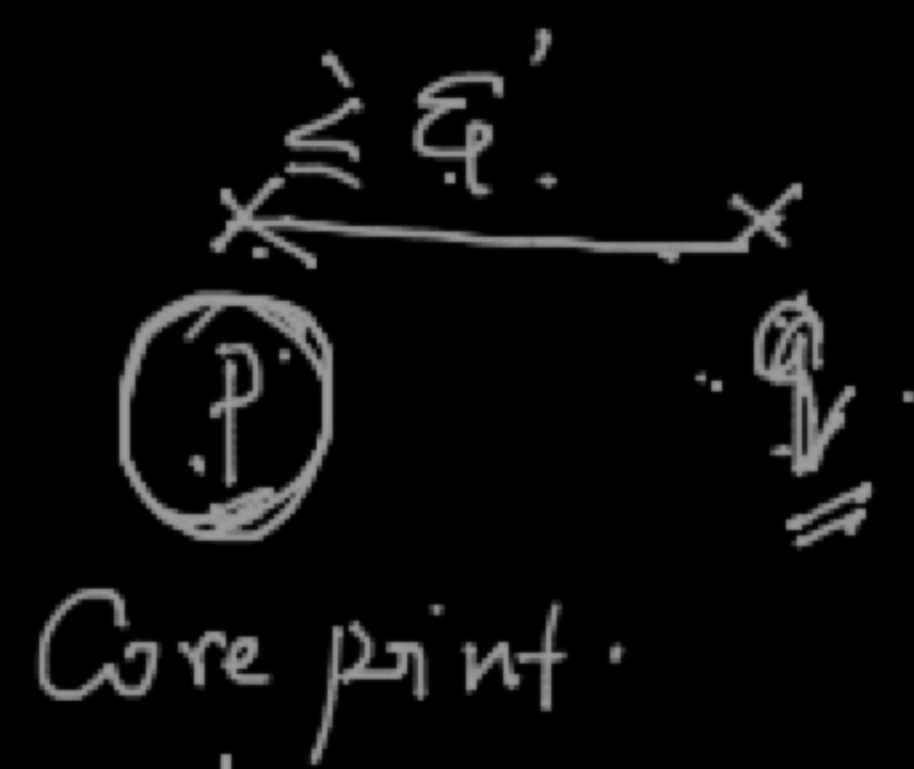
Directly Density Reachable points

Density Reachable . points.

Density Connected. points.

Reachability

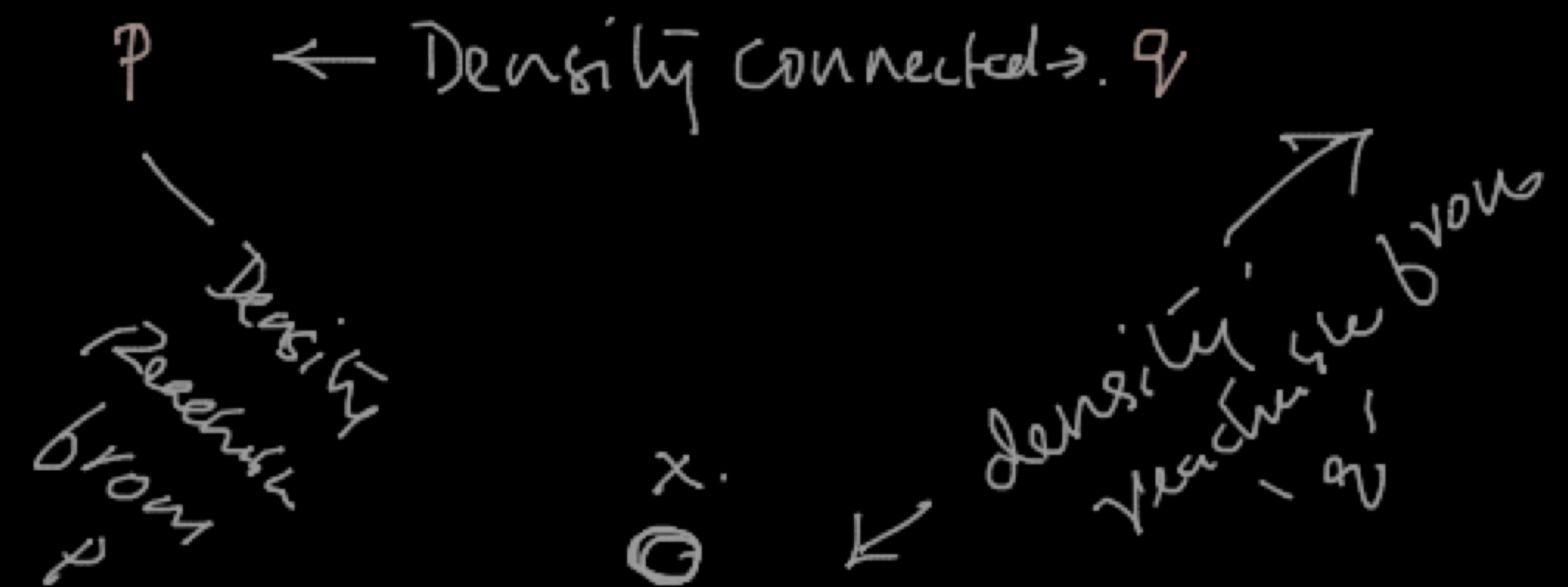
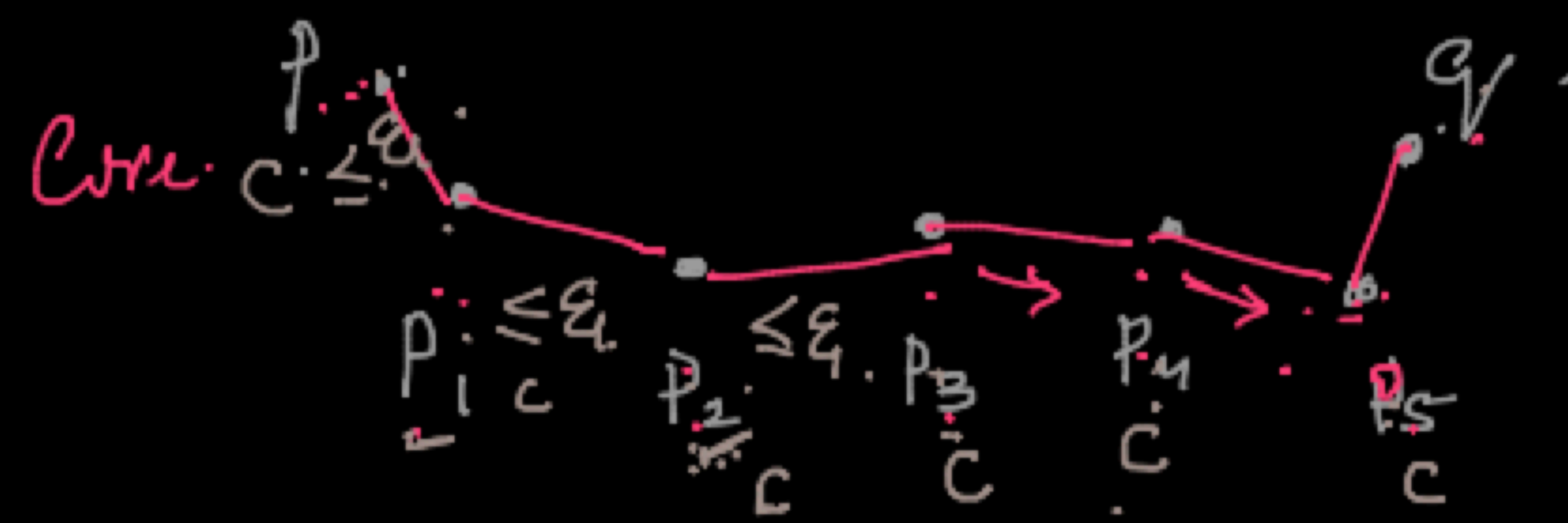
1. Directly density reachable



\rightarrow 'q' is directly density reachable from 'p'

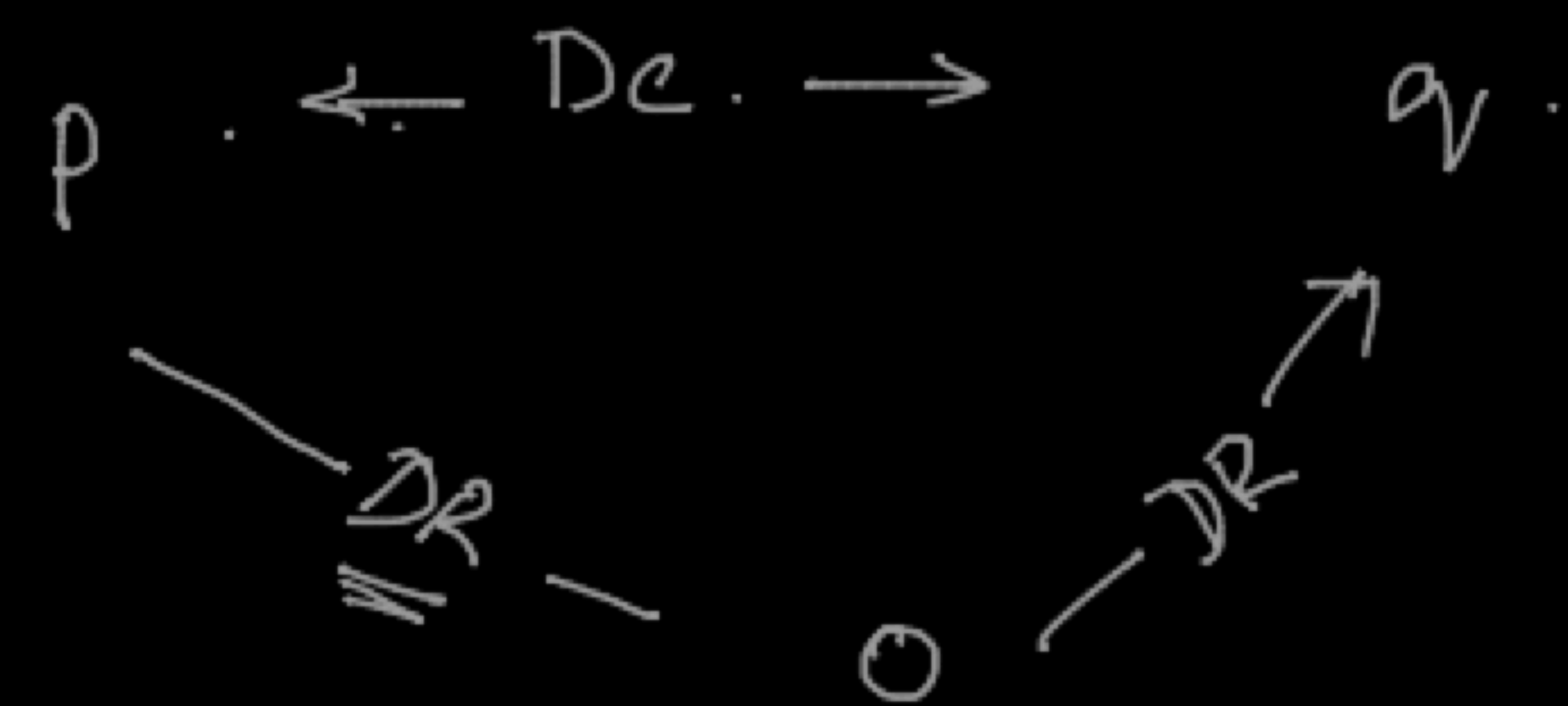
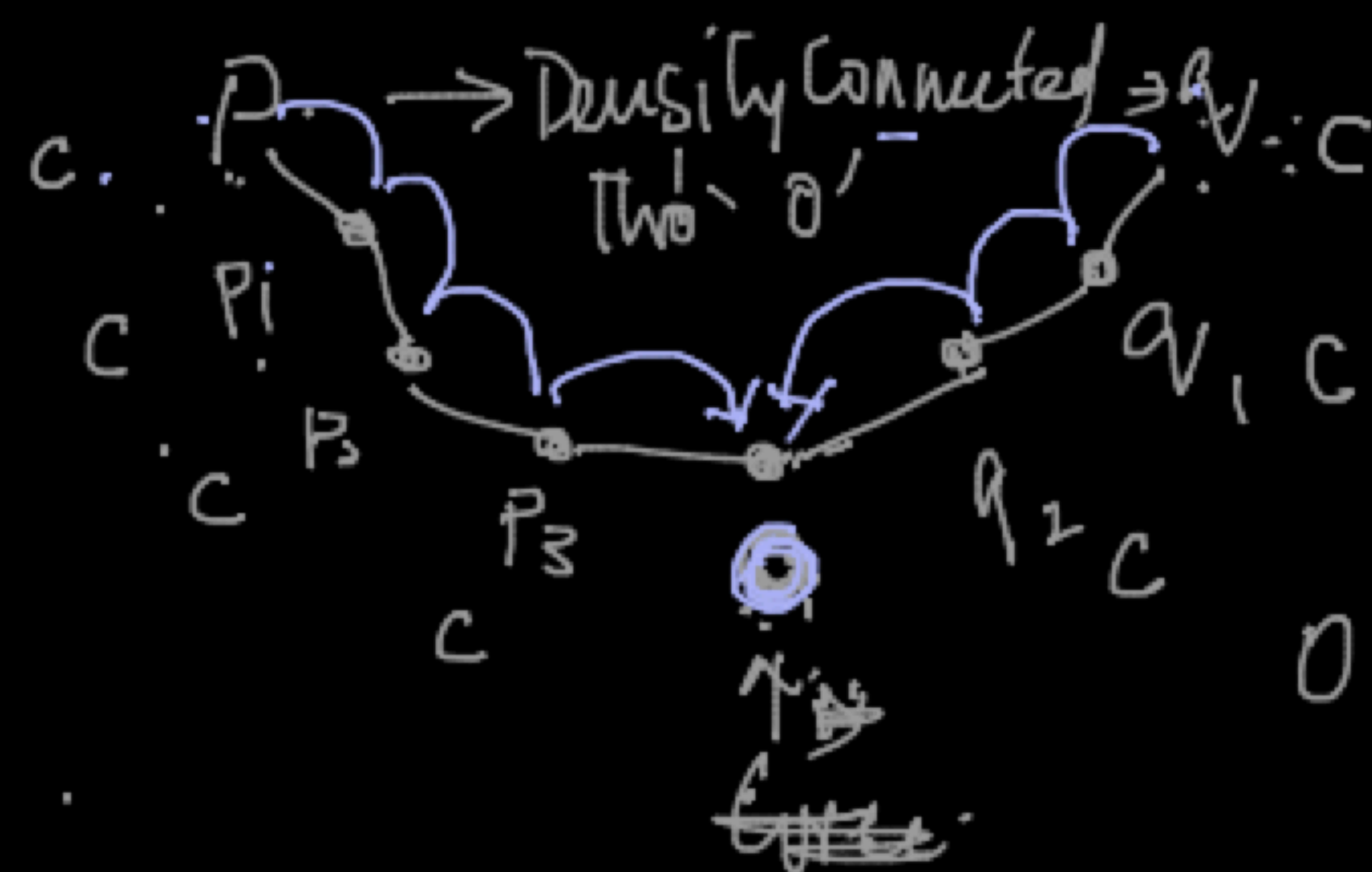
3. Density Connected Points.

2. Density Reachable ✓✓



ϵ

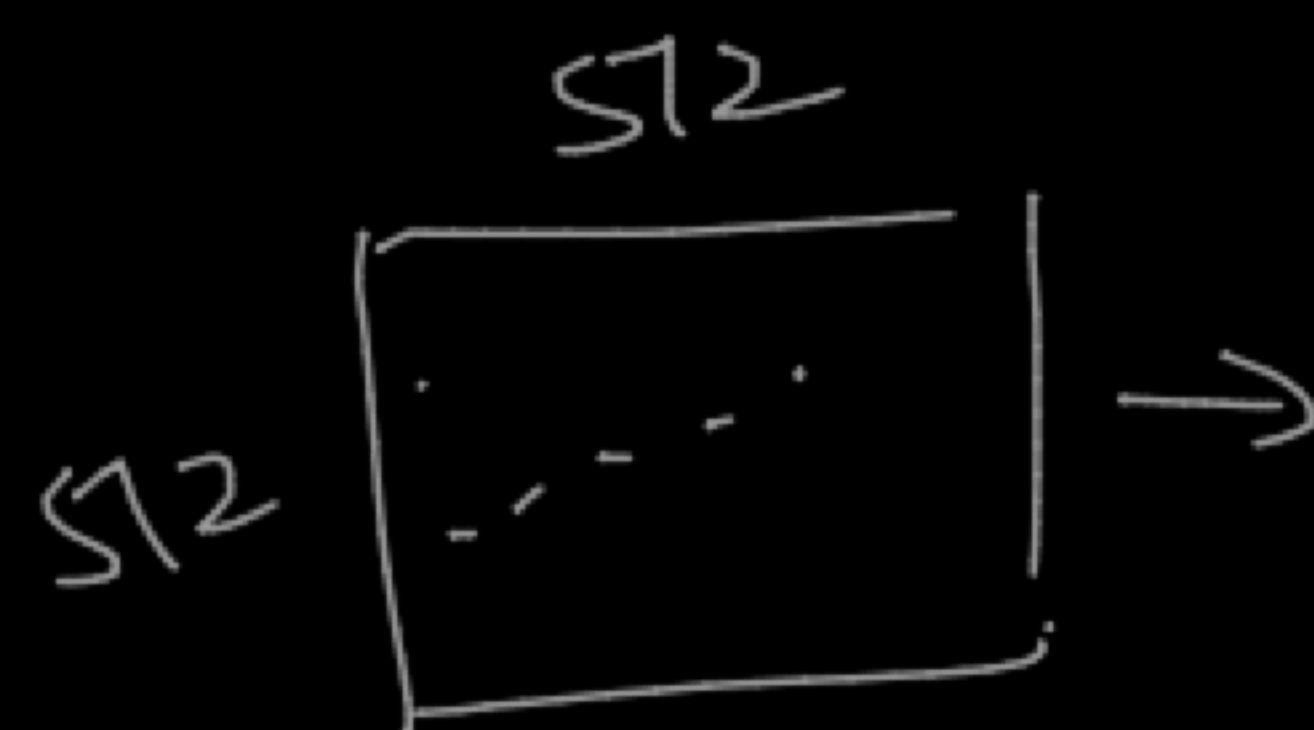
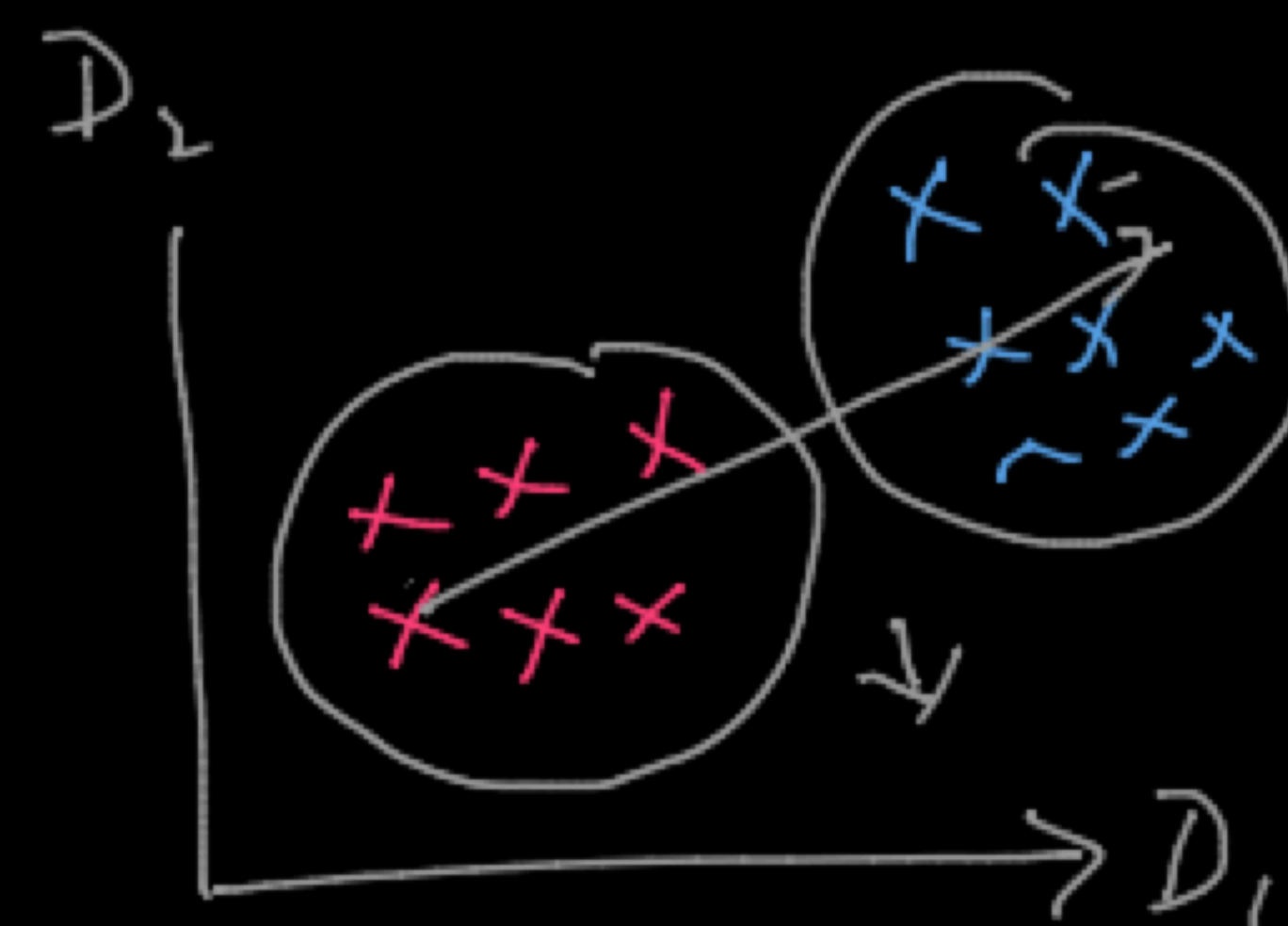
p, p1, p2, p3, p4, p5 \rightarrow Core points.



o is density reachable from p.
" " " q-

$$\begin{pmatrix} x_1 & x_2 & x_3 & \dots & \dots & \dots \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \end{pmatrix} \xrightarrow{\text{PCA}} \begin{pmatrix} x_{100} \\ y \\ M \\ B \end{pmatrix}$$

D_1	D_2	
-	-	M.
		B



Pixels.

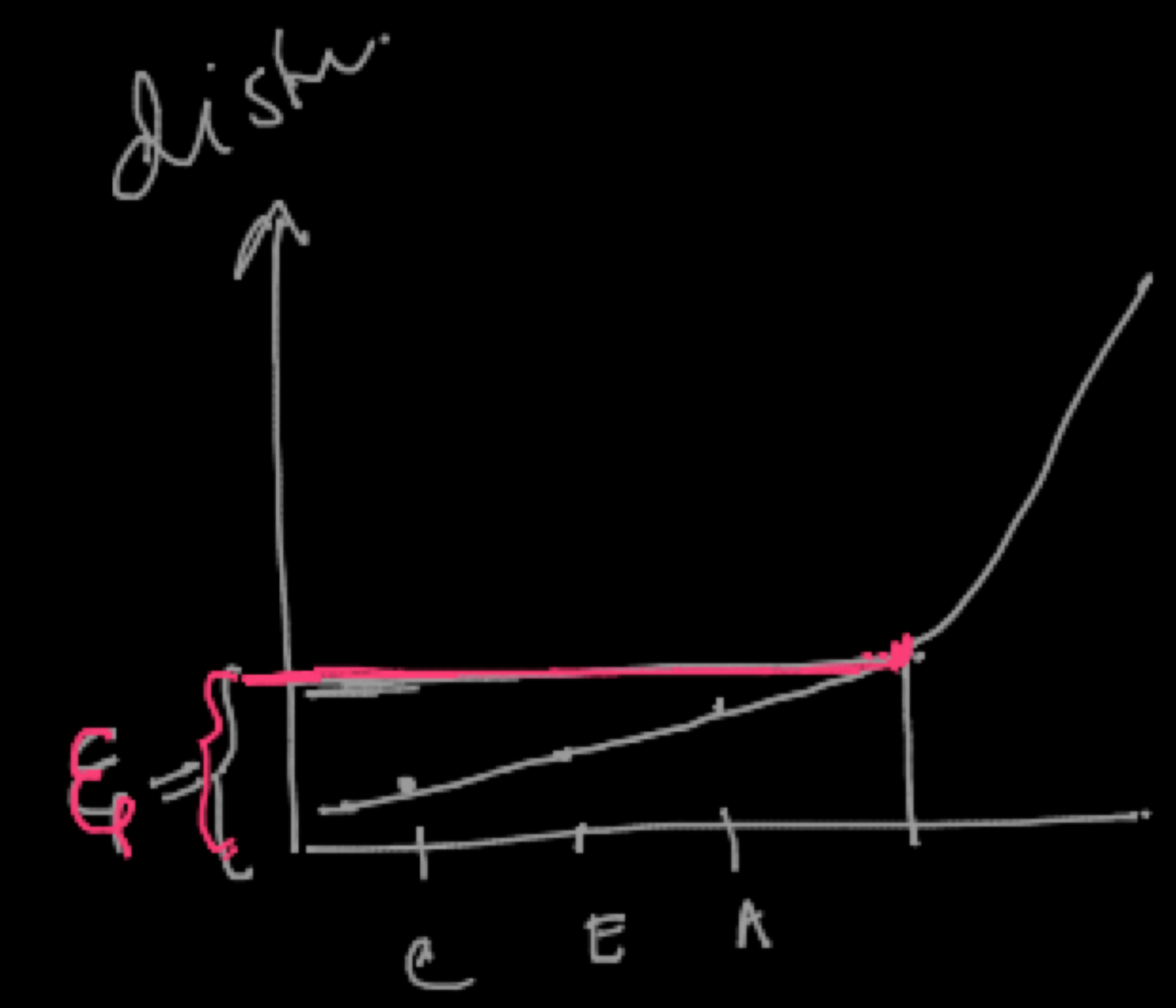
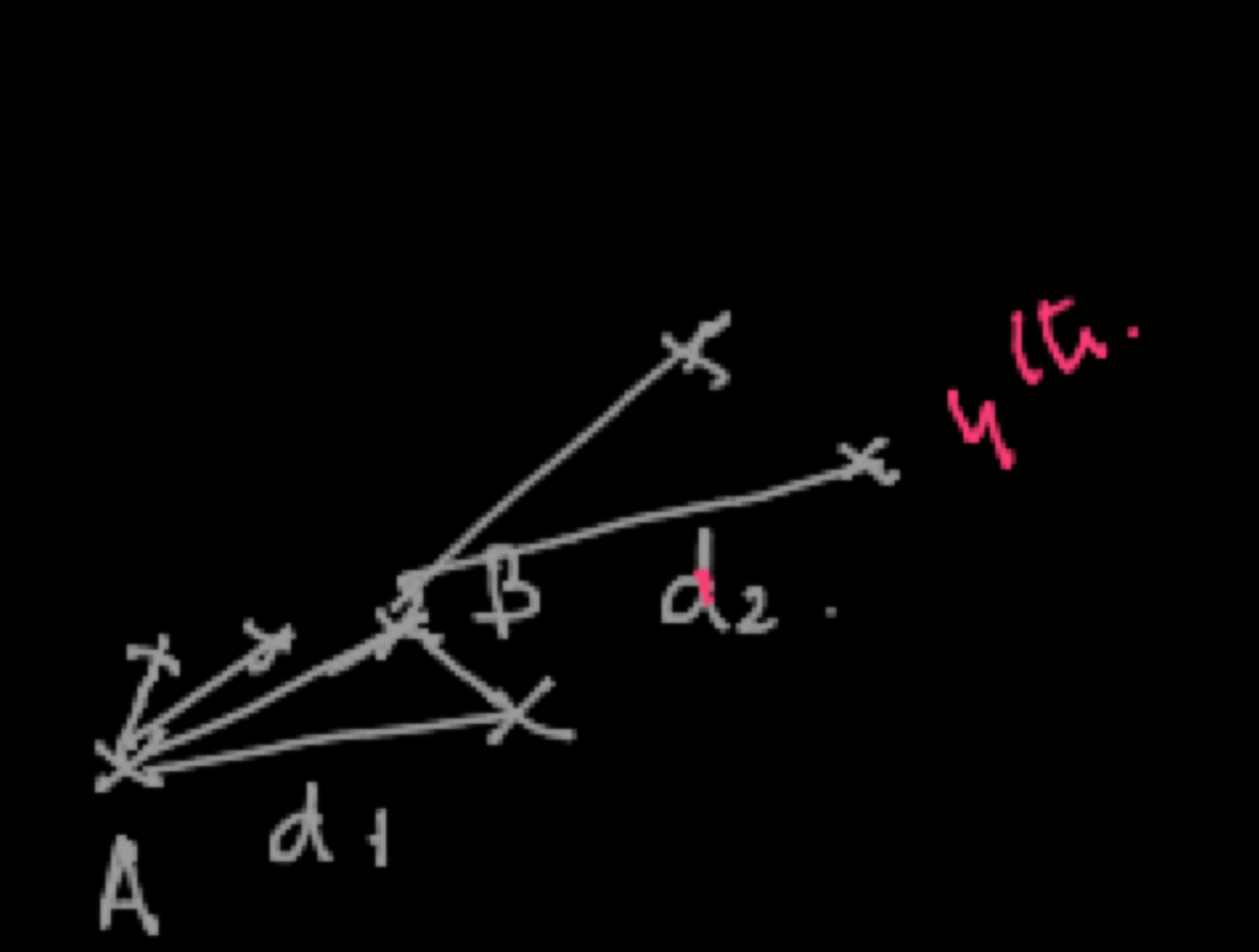
.	.	.	.



Minpoints $\overset{10}{\boxed{4}} \rightarrow \xi$.

Minpoints $\rightarrow \underline{2d}$ or $\underline{3d}$

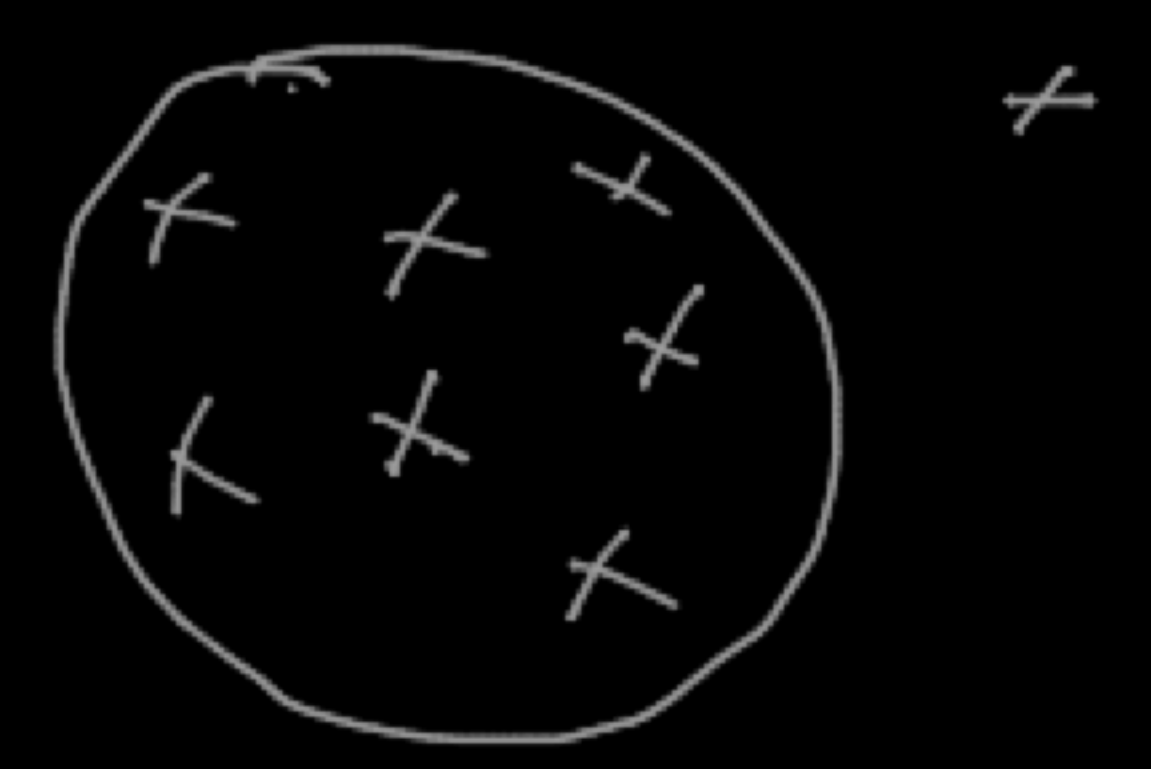
$x_1 \ x_2 \ x_3 \dots x_d \rightarrow$



A	d_1
B.	d_2
C	d_3
D.	d_4
E	d_5
F	d_6

ascending order

- C d_3
- E d_5
- A d_1
- B d_2
- D d_4
- F d_6



← Metrics →

$$\text{Dunn Index} = \frac{\text{Smallest distance between points not in a cluster.} \uparrow \checkmark}{\text{largest distance between points within a cluster.} \downarrow \checkmark}$$

⇒ As large as possible.

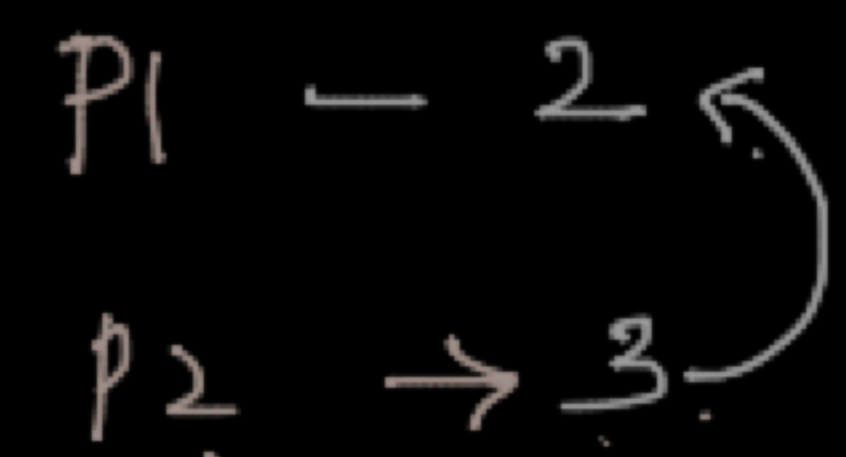
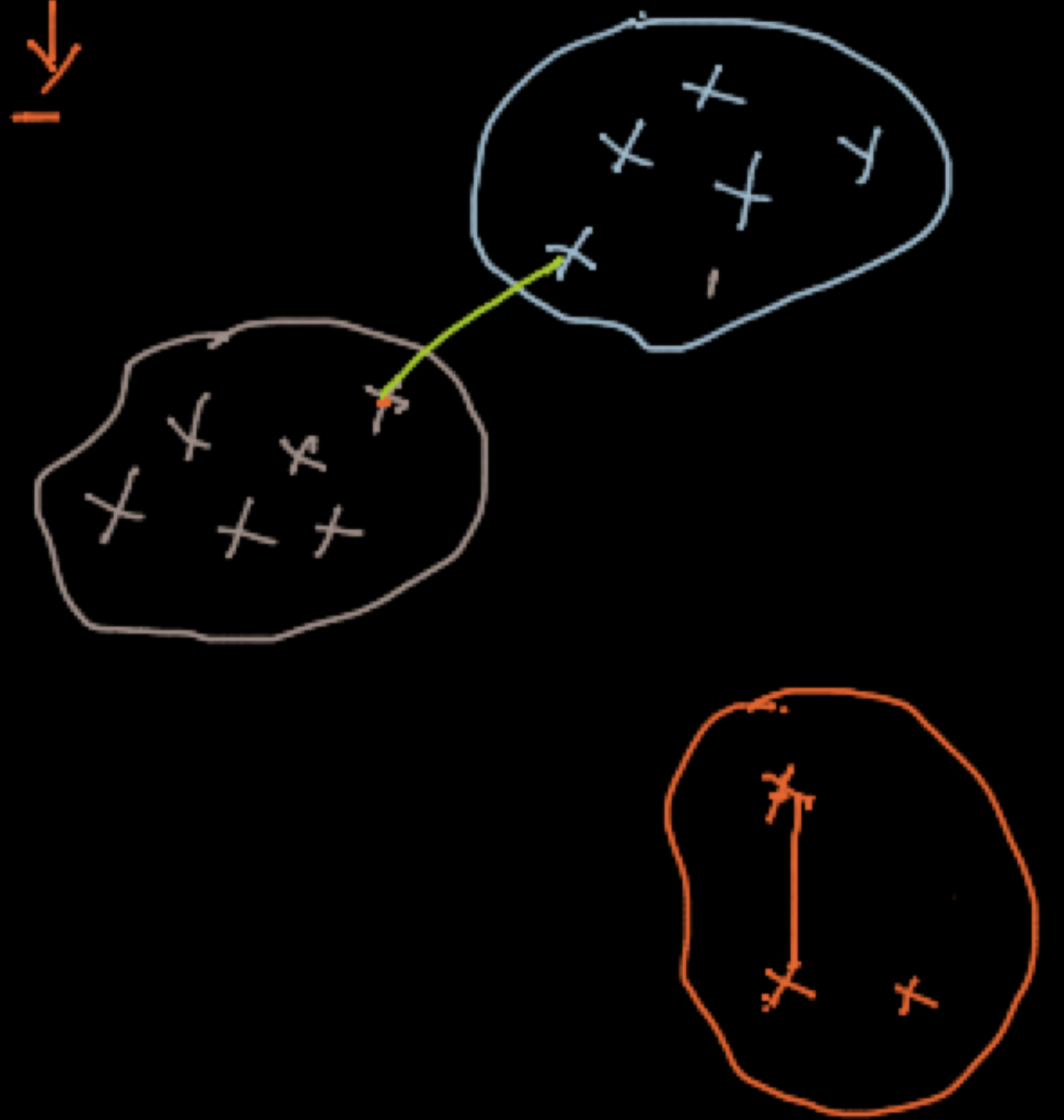
$$\text{Silhouette Score} = \frac{(b-a)}{\max(b,a)} \uparrow$$

≈ 1, 0

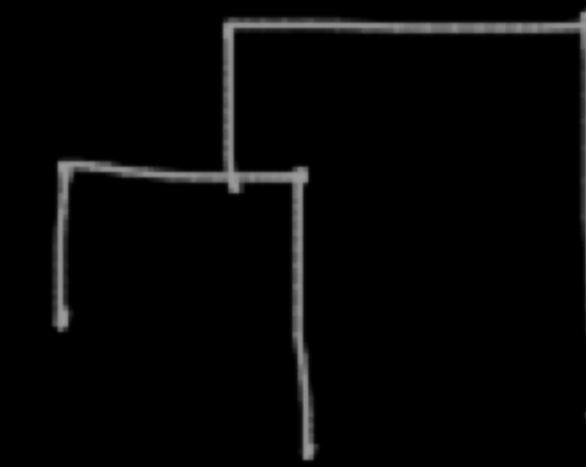
-ve values → wrong grouping of datapoints.

a - average intracluster distance. ✓ small
 b - average intercluster distance. - large

1. Small intracluster distance.
2. Inter Cluster distances



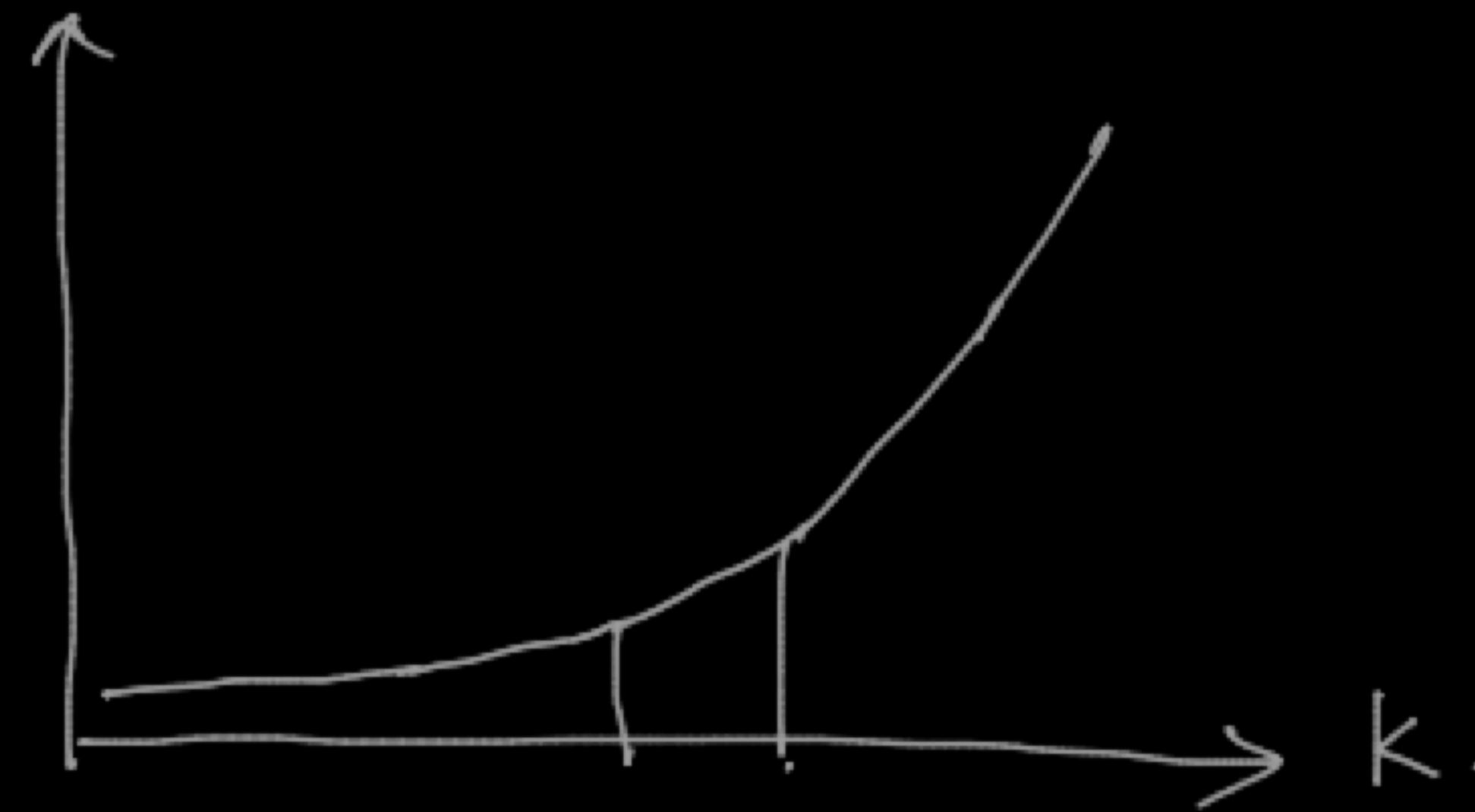
How many groups. $\left\{ \begin{array}{l} \textcircled{K} \rightarrow \text{K-means.} \\ \text{ } \rightarrow \text{How many groups.} \\ \text{ } \rightarrow \text{HAC.} \end{array} \right.$



DBSCAN \rightarrow



? $\text{DunInd.} \Rightarrow - \checkmark$
 , $\text{silh.} \Rightarrow - \checkmark$



$- \checkmark \quad - \checkmark \quad \equiv 2$
 $- \checkmark \quad - \checkmark \quad \}$

$K \rightarrow \text{No. of groups.}$
 $\left\{ \begin{array}{l} \text{K-Means} \\ \text{HAC.} \end{array} \right.$

DBSCAN \times
 $\times K.$
 $\rightarrow \text{Density}$