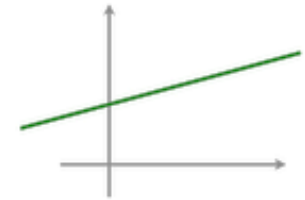


CSE4203: Computer Graphics

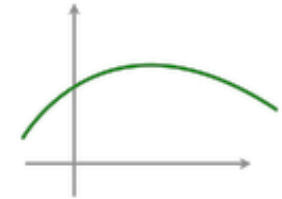
Bézier Curves

Polynomials

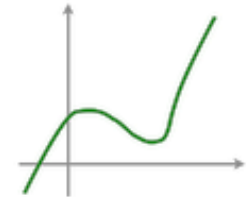
1st degree polynomial: $y = ax^0 + bx^1$



2nd degree polynomial: $y = ax^0 + bx^1 + cx^2$



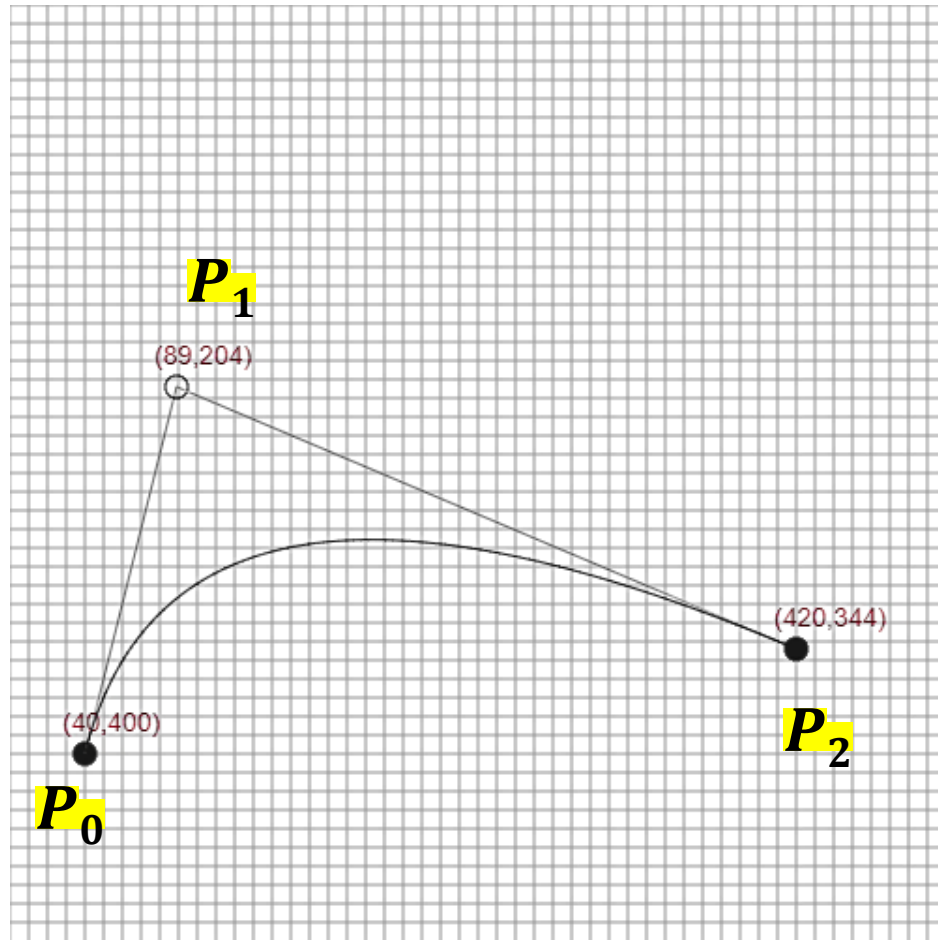
3rd degree polynomial: $y = ax^0 + bx^1 + cx^2 + dx^3$



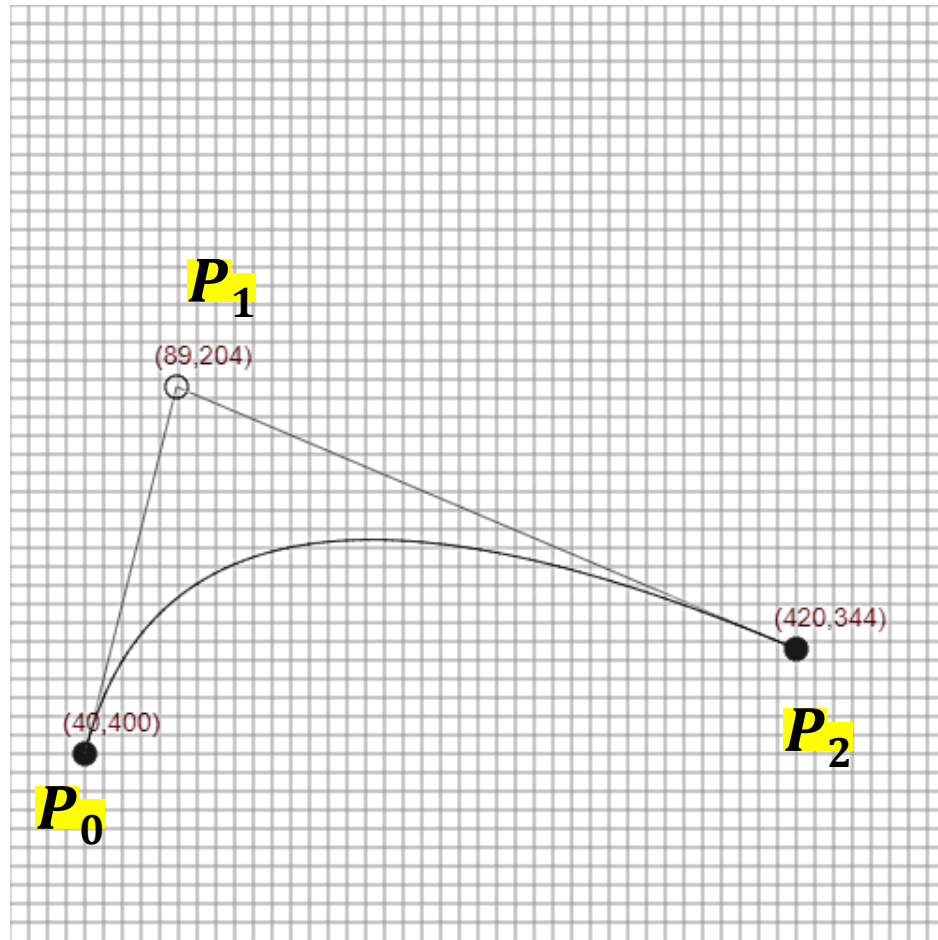
Bézier Curves

- First described in 1972 by Pierre Bézier

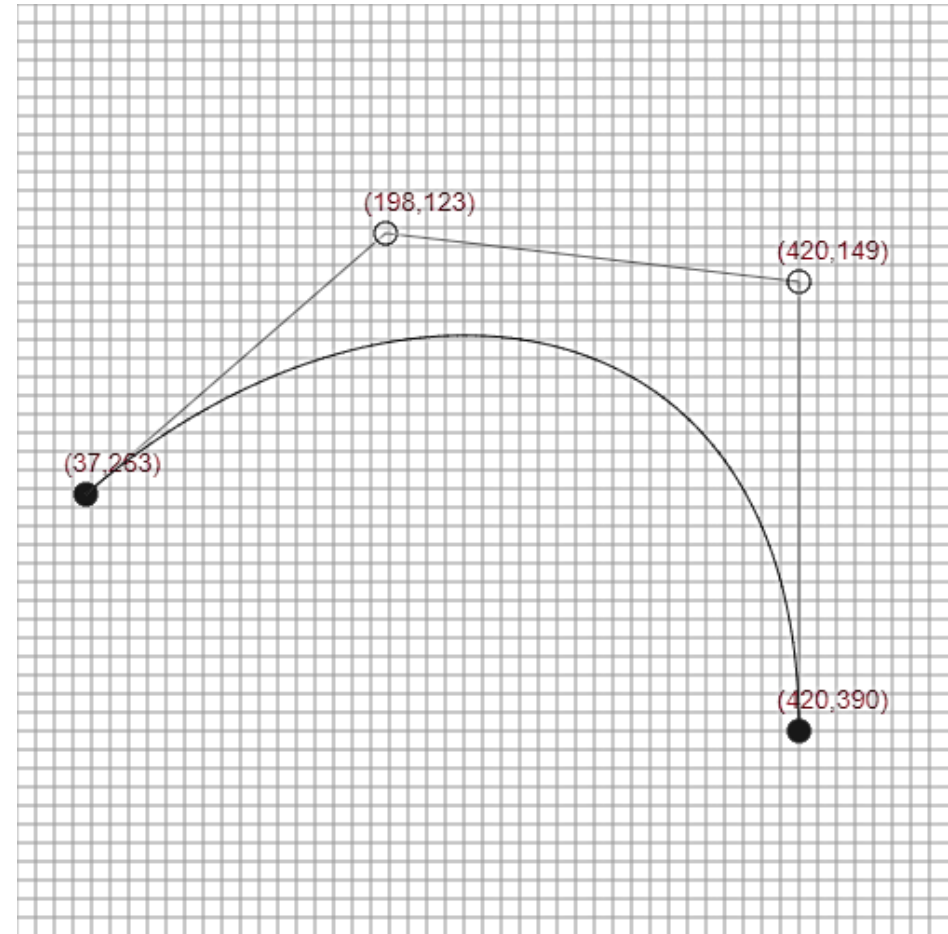
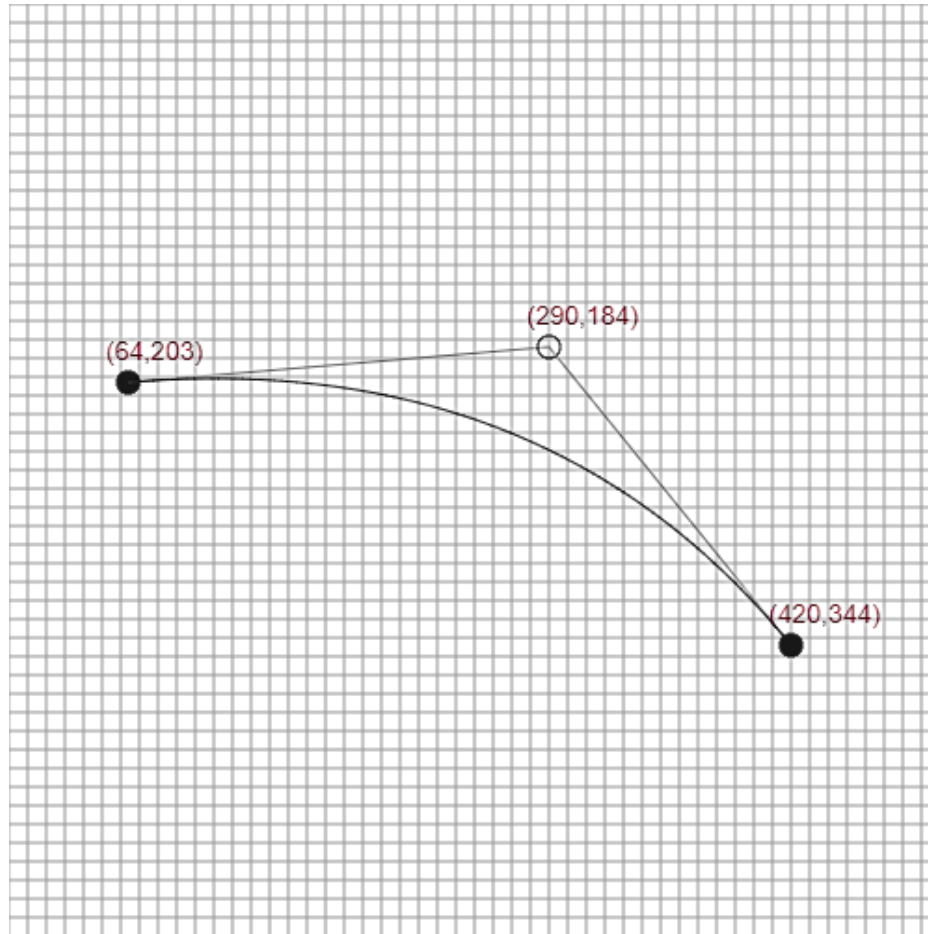
Control Points



Control Points



Control Points

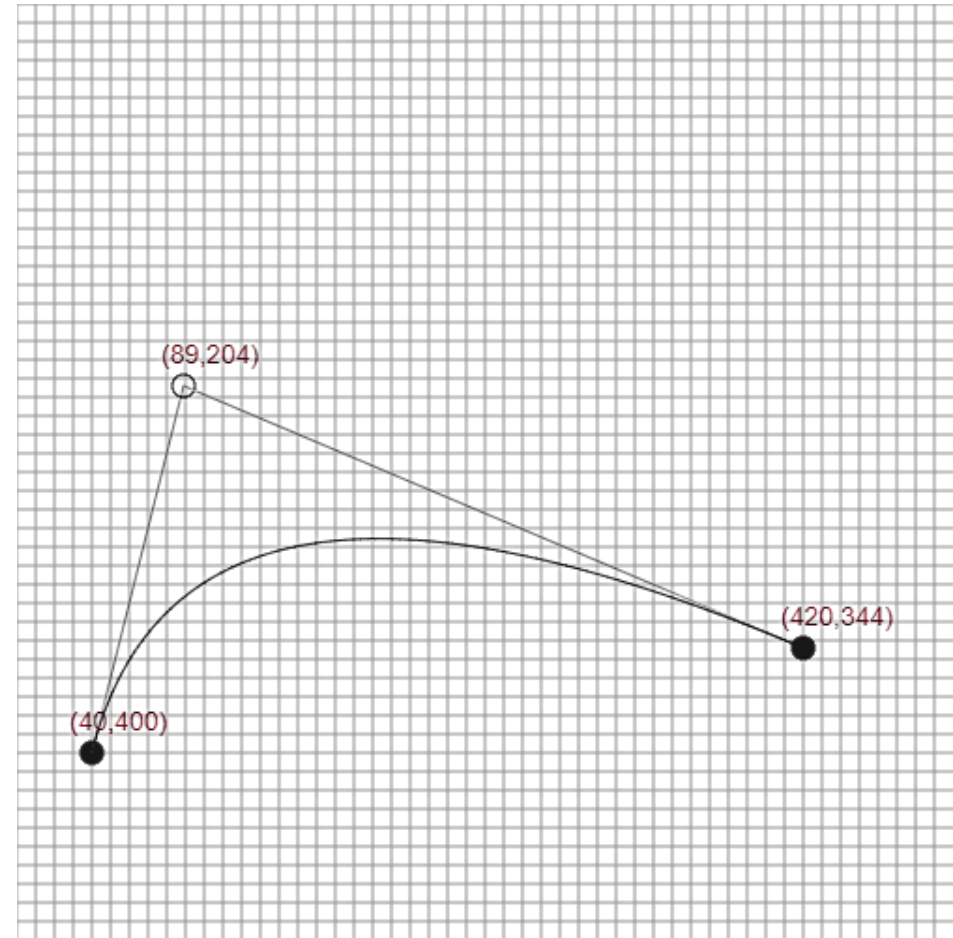


Inputs

- N number of control points
- Degree, $d = N - 1$

For example,

For 3 Control Points, $d = 2$



Inputs

- N number of control points
- Degree, $d = N - 1$

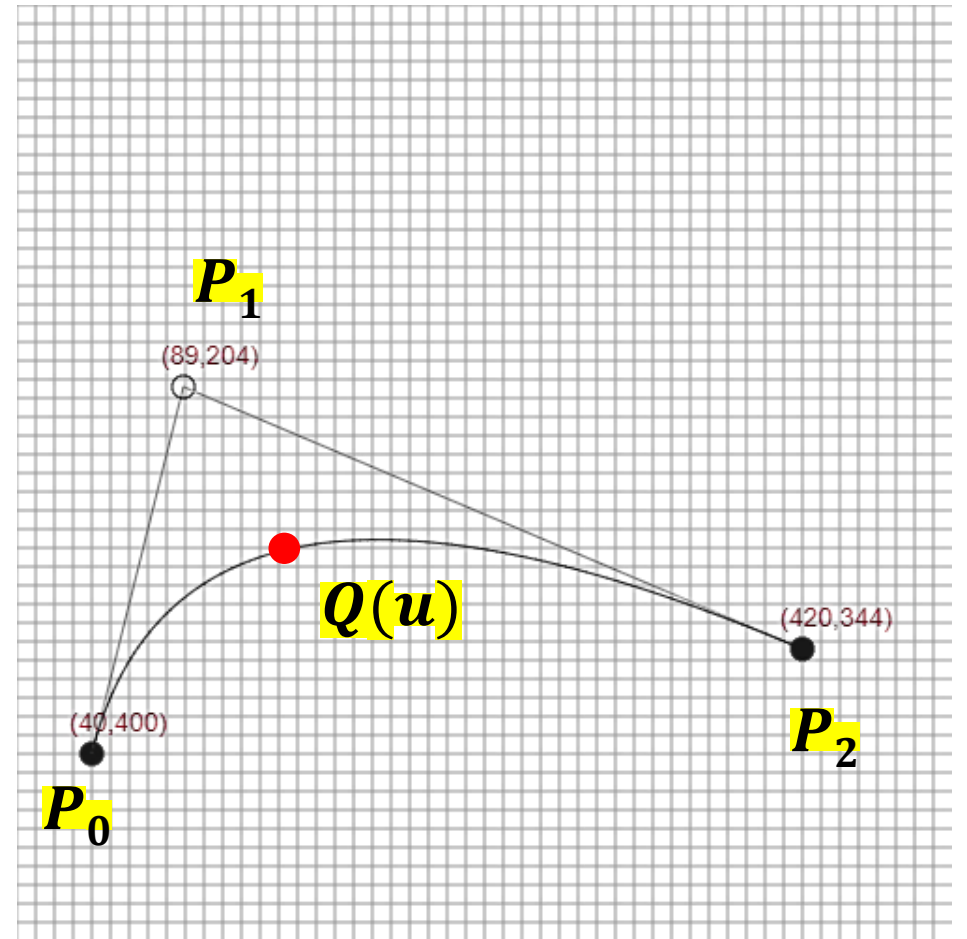
- N number of control points
- Degree, $d = N - 1$

What is the d here?

Bézier Curves

$$Q(u) = \sum_{i=0}^d B_{i,d}(u) P_i \quad 0 \leq u \leq 1$$

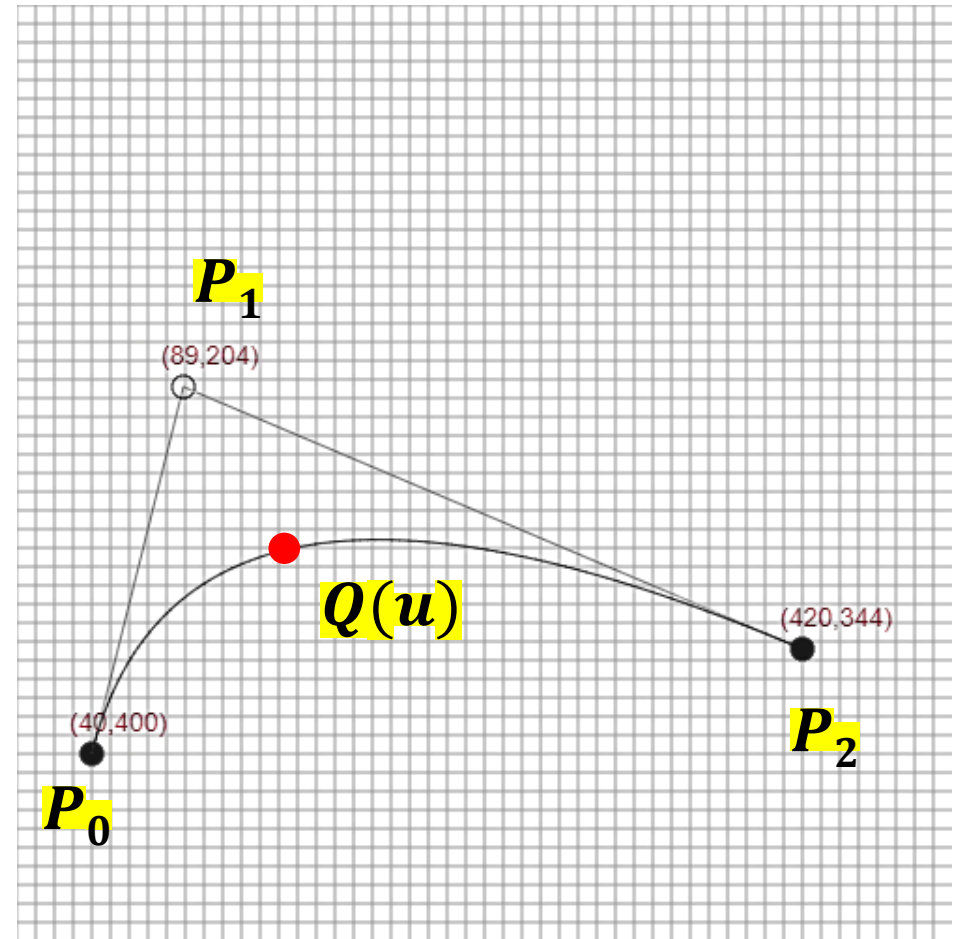
Example: $\sum_{i=0}^2 B_{i,2}(u) P_i = B_{0,2}(u) P_0 + B_{1,2}(u) P_1 + B_{2,2}(u) P_2$



Bézier Curves

$$Q(u) = \sum_{i=0}^d B_{i,d}(u) P_i \quad 0 \leq u \leq 1$$

$$B_{i,d}(u) = \binom{d}{i} u^i (1-u)^{d-i} \quad \binom{d}{i} = \frac{d!}{i!(d-i)!}$$

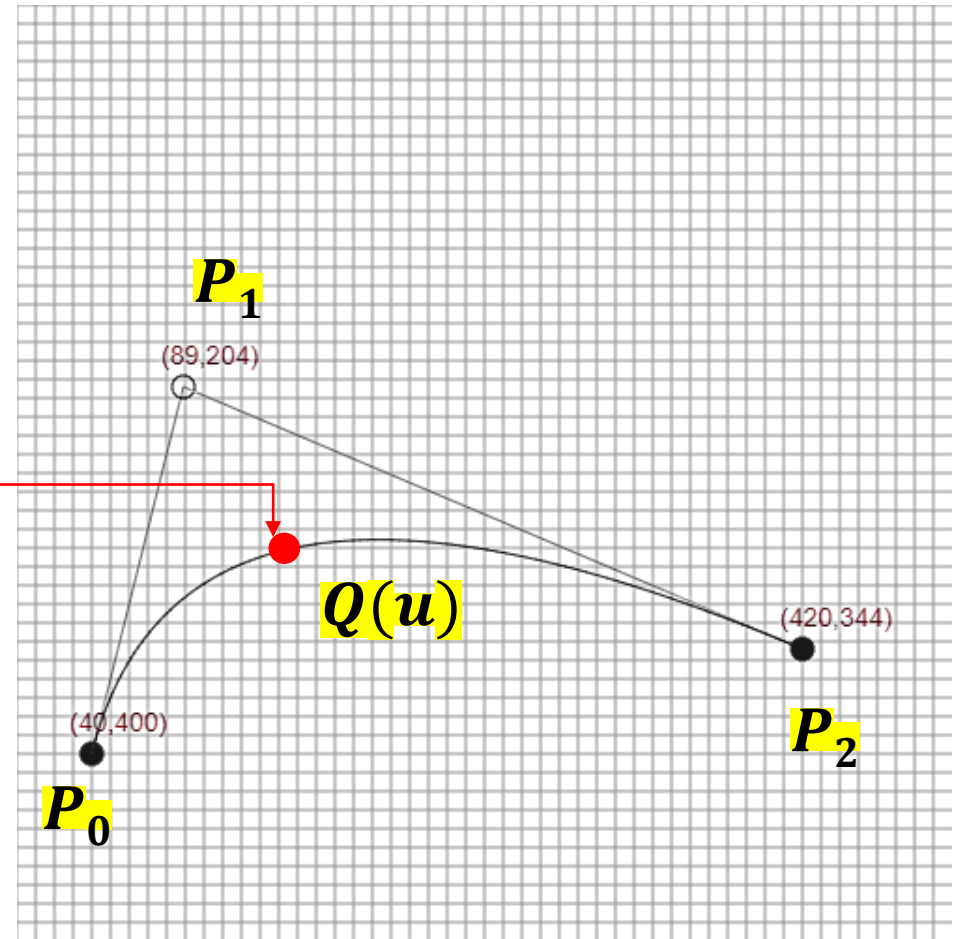


Bézier Curves

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$$B_{i,d}(u) = \binom{d}{i} u^i (1-u)^{d-i} \quad \binom{d}{i} = \frac{d!}{i!(d-i)!}$$

A point on the curve

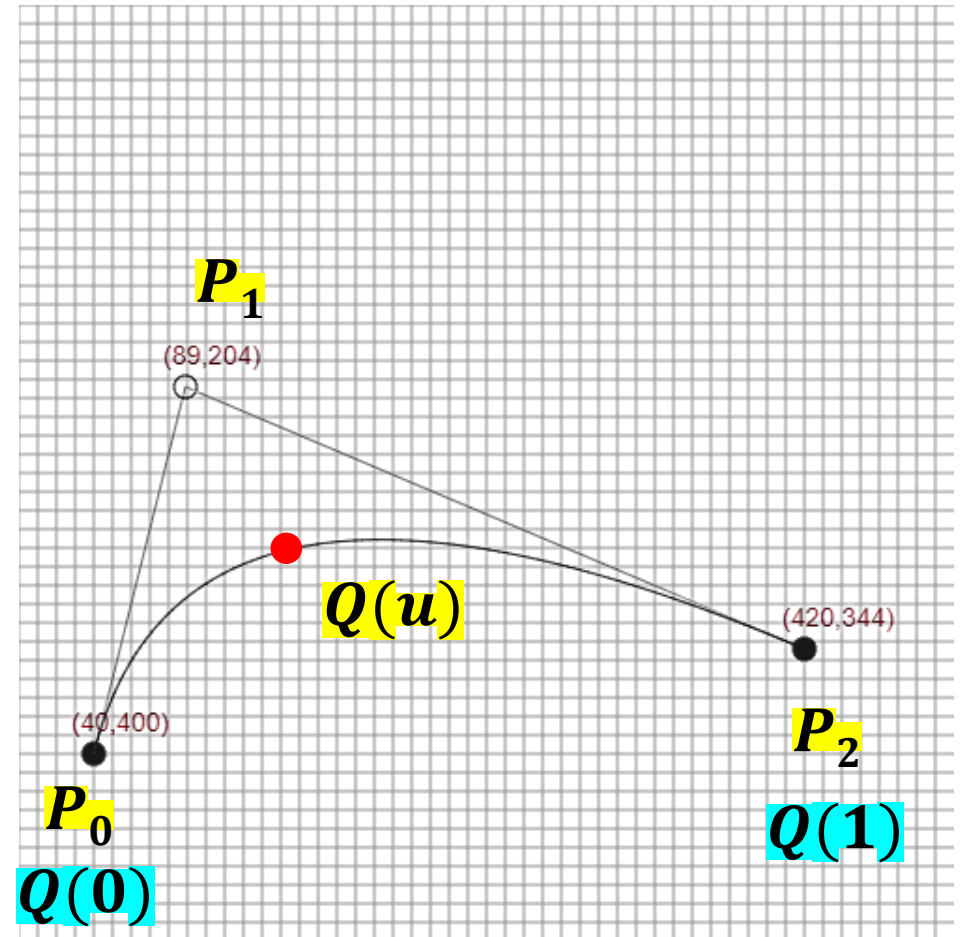


Bézier Curves

$$Q(u) = \sum_{i=0}^d B_{i,d}(u) P_i \quad 0 \leq u \leq 1$$

$$B_{i,d}(u) = \binom{d}{i} u^i (1-u)^{d-i} \quad \binom{d}{i} = \frac{d!}{i!(d-i)!}$$

Denoted with $Q_d(u)$



Bézier Curves

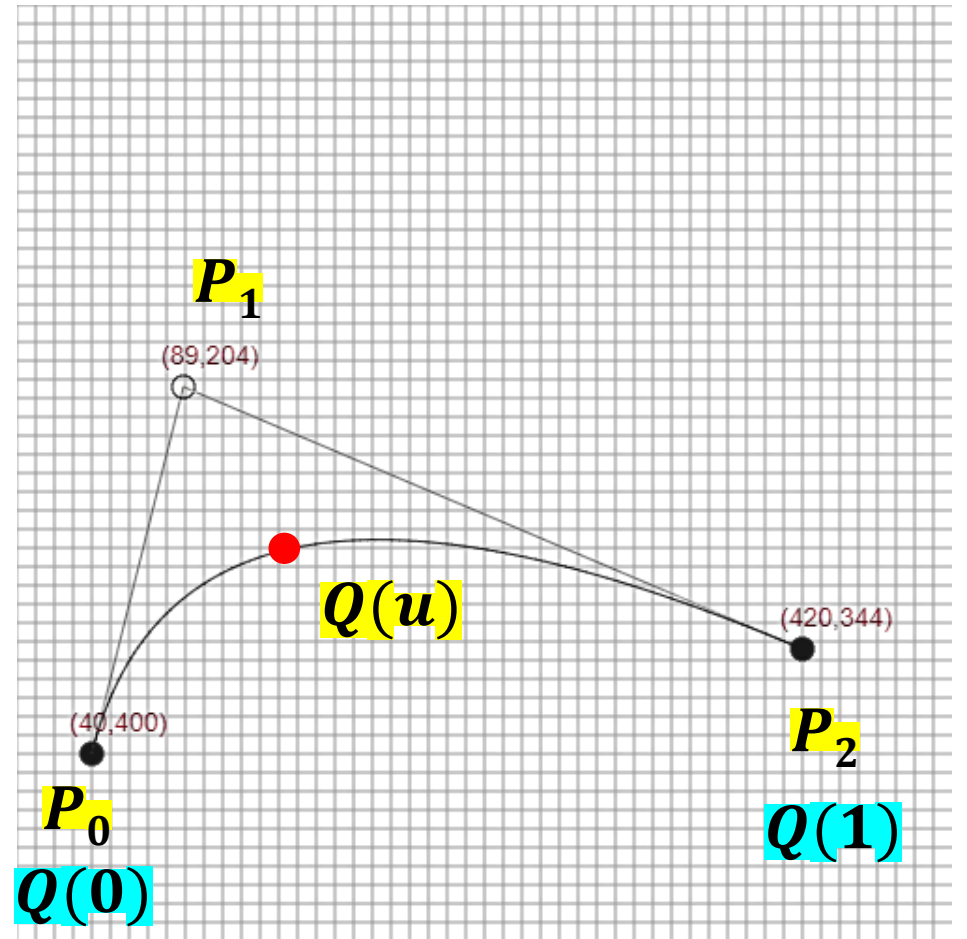
$$Q(u) = \sum_{i=0}^d B_{i,d}(u) P_i \quad 0 \leq u \leq 1$$

$$B_{i,d}(u) = \binom{d}{i} u^i (1-u)^{d-i} \quad \binom{d}{i} = \frac{d!}{i!(d-i)!}$$

Where is $Q_d(0.5)$ situated?

Where is $Q_d(0)$ situated?

Where is $Q_d(1)$ situated?

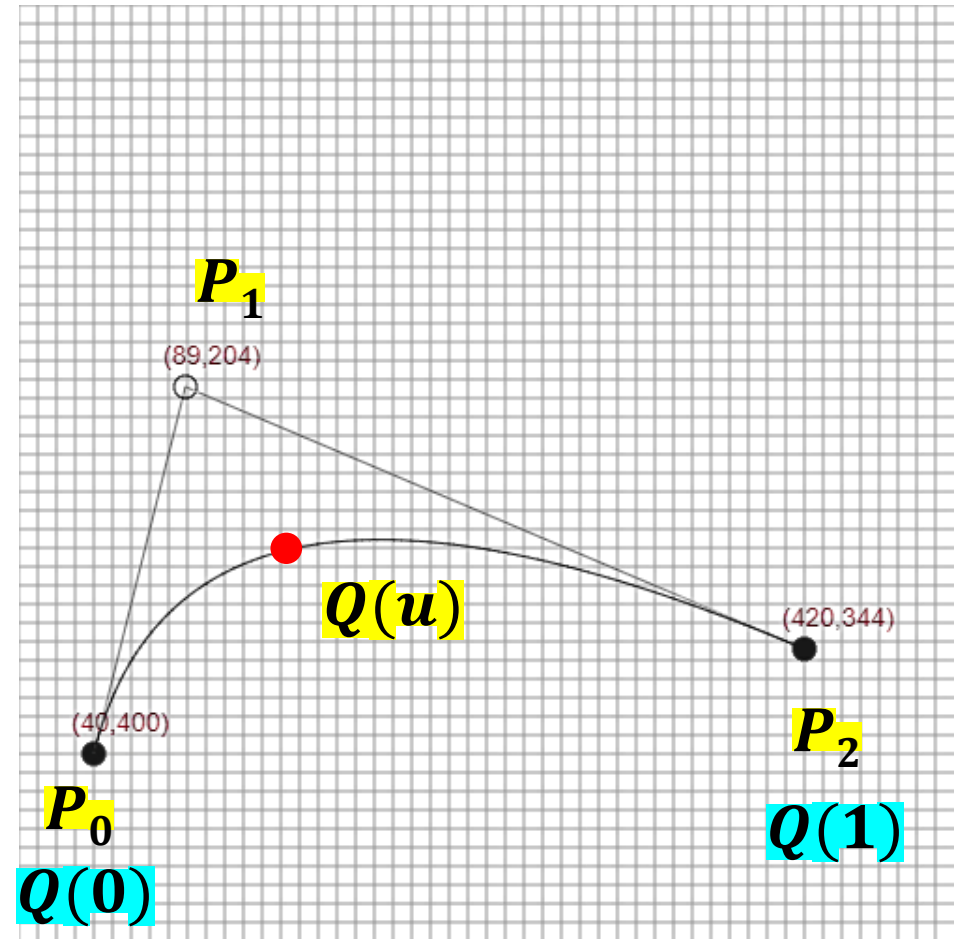


Bézier Curves

$$Q(u) = \sum_{i=0}^d B_{i,d}(u) P_i \quad 0 \leq u \leq 1$$

$$B_{i,d}(u) = \binom{d}{i} u^i (1-u)^{d-i} \quad \binom{d}{i} = \frac{d!}{i!(d-i)!}$$

Online simulator: <https://ytyt.github.io/siiiimple-bezier/>



Bézier Curves

$$Q(u) = \sum_{i=0}^d B_{i,d}(u) P_i \quad 0 \leq u \leq 1$$

$$B_{i,d}(u) = \binom{d}{i} u^i (1-u)^{d-i} \quad \binom{d}{i} = \frac{d!}{i!(d-i)!}$$

These polynomials are called "Bernstein polynomials" and denoted by $B_{i,d}(u)$

$$\begin{aligned} B_{0,2}(u) &= (1-u)^2 & B_{0,3}(u) &= (1-u)^3 \\ B_{1,2}(u) &= 2u(1-u) & B_{1,3}(u) &= 3u(1-u)^2 \\ B_{2,2}(u) &= u^2 & B_{2,3}(u) &= 3u^2(1-u) \\ & & B_{3,3}(u) &= u^3 \end{aligned}$$

$$Q_2(u) = P_0(1-u) + P_1[2u(1-u)] + P_2(u^2)$$

Example

Given control points $P_0 = (0, 0)$, $P_1 = (4, 2)$, $P_2 = (8, 0)$, find the Bézier curve values $Q_2(0)$, $Q_2(\frac{1}{2})$ and $Q_2(1)$.

Why subscript **2** for $Q_2(u)$?

Example

Given control points $P_0 = (0, 0)$, $P_1 = (4, 2)$, $P_2 = (8, 0)$, find the Bézier curve values $Q_2(0)$, $Q_2(\frac{1}{2})$ and $Q_2(1)$.

$$Q_2(u) = \sum_{i=0}^n B_{i,2}(u)P_i \quad 0 \leq u \leq 1$$

$$B_{i,d}(u) = \binom{d}{i} u^i (1-u)^{d-i} \quad \binom{d}{i} = \frac{d!}{i!(d-i)!}$$

$$Q_2(u) = B_{0,2}(u)P_0 + B_{1,2}(u)P_1 + B_{2,2}(u)P_2$$

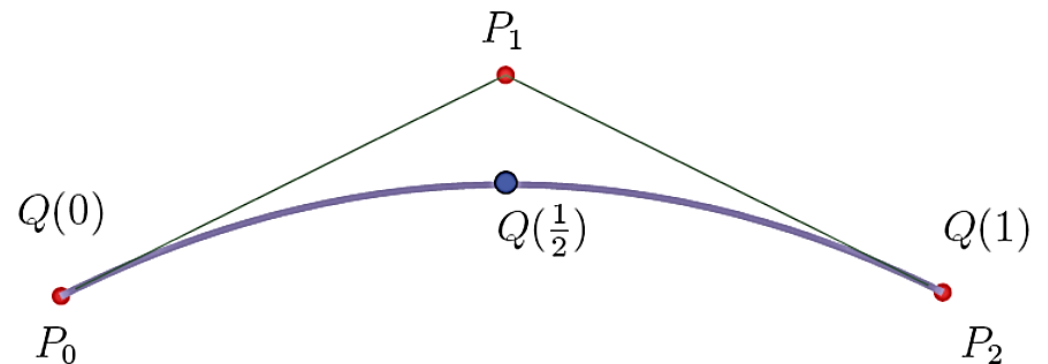
$$Q_2(u) = (1-u)^2 P_0 + 2(1-u)u P_1 + u^2 P_2$$

Example

Given control points $P_0 = (0, 0)$, $P_1 = (4, 2)$, $P_2 = (8, 0)$, find the Bézier curve values $Q_2(0)$, $Q_2(\frac{1}{2})$ and $Q_2(1)$.

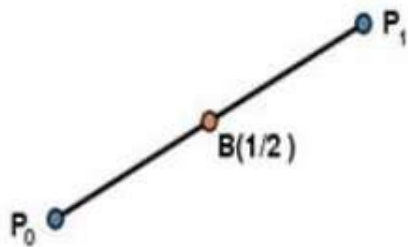
$$Q_2(u) = (1 - u)^2 P_0 + 2(1 - u)u P_1 + u^2 P_2$$

- $Q_2(0) = (1 - 0)^2 P_0 + 2(1 - 0)0 P_1 + 0^2 P_2 = P_0 = (0, 0)$
- $Q_2(\frac{1}{2}) = \dots \text{Do calculations} \dots = (4, 1)$
- $Q_2(1) = \dots \text{Do calculations} \dots = (8, 0)$

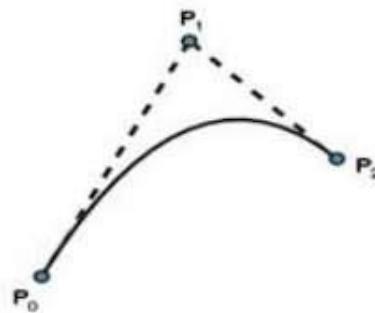


Properties of Bezier Curves

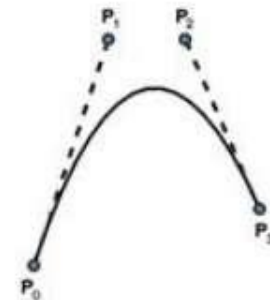
- They generally follow the shape of the control polygon, which consists of the segments joining the control points
- They always pass through the first and last control points
- They are contained in the convex hull of their defining control points
- The degree of the polynomial defining the curve segment (d) is one less than that the number of defining polygon point (n) i.e. $n = d+1$



Simple Bezier Curve



Quadratic Bezier Curve



Cubic Bezier Curve

Disadvantages

- A change to any of the control point alters the entire curve.
- Having a large number of control points requires high polynomials to be evaluated. This is expensive to compute.

