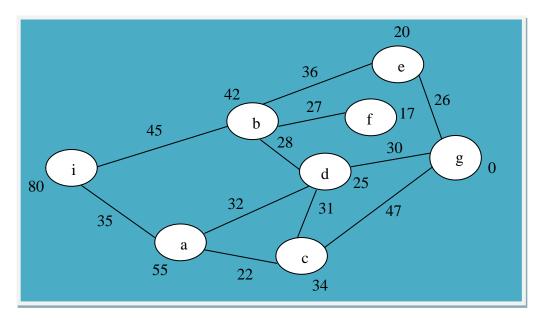
3.2. Greedy Best-First Search.

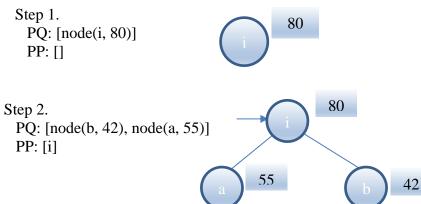
An example (problem instance):

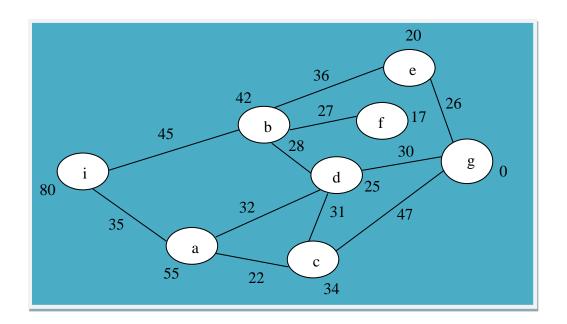


 $i-Initial\ state/node$ $g-Goal\ state/node$

h- Heuristic function (Straight-line distance up to g)

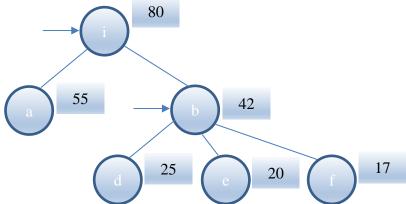
Execution of Greedy Best-First Search:

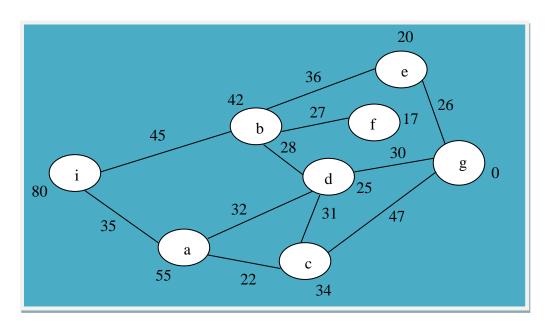




Step 3.

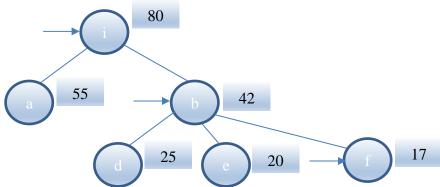
PQ: [node(f, 17), node(e, 20), node(d, 25), node(a, 55)] PP: [i, b]

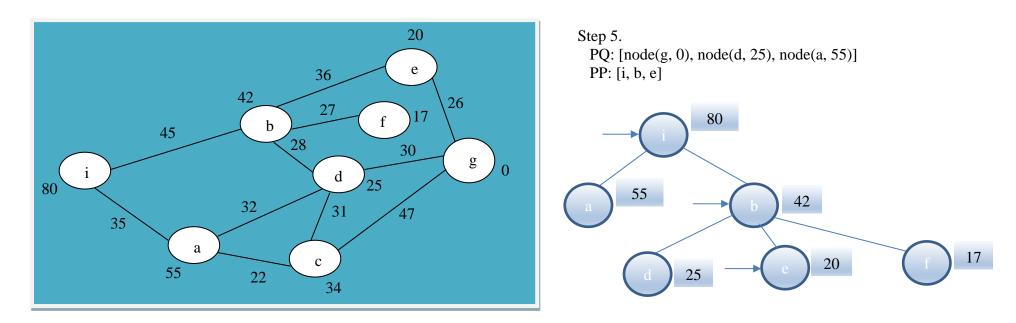






PQ: [node(e, 20), node(d, 25), node(a, 55)] PP: [i, b, f]





Next, from 'PQ: [node(g, 0), node(d, 25), node(a, 55)]' goal node g gets selected, so, terminate with Solution [i, b, e, g] that costs 107.