Introduction to Measure Theoretic Probability

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February 2, 2023

Chapter 1

Motivation & Preliminaries

Why study probability theory? If you're anything like me, you know the basics: dice rolls, taking expectations, and some basic distributions. But along the way, you had a few lingering questions: Why is the law of large numbers true? The central limit theorem? What the heck is a probability density, really? What does it even mean to condition on something with probability 0? There are also the existence of conditioning paradoxes. Perhaps you've heard about stochastic processes and the different limit theorems which show that random processes converge to an equilibrium. How the heck can you show that? We address these through a fundamental shift in perspective: remove the randomness from the study of probability. Rather than studying the "probability" of an event, study its size. The simple idea to use tools from measure theory has far reaching consequences. The added trouble may make you think — why are we doing this? But after a few headaches, the applications will be well worth it.

We will assume a very basic knowledge of real analysis.

1.1 Events, Sizes & The Universe

Let's begin our study of probability with a classic example: the roll of a fair die. We all know that each side of a die occurs with probability 1/6. But what do we even mean by this? Some people think of it from a frequentist perspective — if you roll the die 600 billion billion times, it will come up 2 about 100 billion billion times (assuming it doesn't break). In a way, this is silly and circular: we're defining probabilities by the Law of Large Numbers? What could we possibly extend this to densities? If we throw a dart 100 billion billion times, it will most likely hit a given spot 0 times.

The more prudent & careful approach is to think about the universe of possible events, and assign sizes to suitable subsets of those events. Formally, the universe is given by Ω . In the case of the dice roll, you could think of Ω as

describing every outcome in every instantiation of this dice roll in the multiverse. The amount of information captured by Ω could be aribtrary - it could contain the outcome of the dice roll, the weather, and what you get for Christmas. But for our game of Monopoly, we don't really care about everything. Hence we consider a family of subsets of interest \mathcal{F} . For example, \mathcal{F} might consist of the event a 1 is rolled, a 2 is rolled, and all combinations of these. Even if the set of possibilities where a 1 is rolled can be further split up by weather, we essentially turn a blind eye to these distinctions. In our case, \mathcal{F} is called a σ -algebra ("sigma algebra") and has the sensible closure properties.

Definition 1 (σ -algebra). A family of subsets \mathcal{F} of Ω is called a σ algebra if,

- $\varnothing \in \mathcal{F}, \Omega \in \mathcal{F}$
- Closure under complement: For all $A \in \mathcal{F}$, $A^c \in \mathcal{F}$ as well
- Closure under countable union: If $\{A_i\}_{i\in I}$ is a countable set such that $A_i \in \mathcal{F}$ for all $i \in I$, then $\bigcup_{i\in I} A_i \in \mathcal{F}$ as well

One can verify that these properties imply σ -algebras are also closed under countable union. These requirements are quite natural when considering the operations we normally do in probability.

Finally, we need a machine which computes sizes. This is done through a so-called measure μ . So in the dice roll, {roll a 6} $\in \mathcal{F}$, and μ ({roll a 6}) = 1/6. Formally, μ can be regarded as a set $\mu: \mathcal{F} \to \mathbb{R}^+$. Note that, in the probabilistic case, $\mu(\Omega) = 1$ (tee size of everything is 1), but this need not be true in general. In fact, we will consider a notable exception: the Lebesgue measure. The necessary properties of μ pair nicely with the definition of a σ -algebra. In short, we require nonnegative sizes, the size of nothing to be 0, and that the sizes of non-overlapping things adds.

Definition 2 (Measure). A (countably-additive) measure on \mathcal{F} is a function $\mu: \mathcal{F} \to \mathbb{R}$ such that,

- For all $A \in \mathcal{F}, \mu(A) \geqslant 0$
- $\mu(\emptyset) = \emptyset$
- If $\{A_i\}_i$ are countable in \mathcal{F} and pairwise disjoint, then $\mu(\cup_{i\in I}A_i)=\sum_{i\in I}\mu(A_i)$

In particular, if $\mu(\Omega) = 1$, μ is a probability measure. Hopefully, the first two conditions are clear and well-motivated. For the last one, we are simply requiring something like $\mu(\{\text{roll a }1 \cup \{\text{roll a }2\}\}) = \mu(\{\text{roll a }1\}) + \mu(\{\text{roll a }2\})$. There are a few special cases worth familiarizing ourselves with: probability measures \subseteq finite measures:

Definition 3 (Finite Measure). If $\mu(\Omega) < \infty$, then μ is finite.

Definition 4 (Probability Measure). If $\mu(\Omega) < \infty$, then μ is a probability measure.

Definition 5 (σ -finite). If $\Omega = \bigcup_{i \in I} A_i$, such that I is countable and each $A_i \in \mathcal{F}$ but $\mu(A_i) < \infty$, then μ is σ -finite

Definition 6 (Measure Space). A measure space is a triple $(\Omega, \mathcal{F}, \mu)$ where \mathcal{F} is a σ -algebra of subsets of Ω , and μ is a measure on \mathcal{F}

1.2 σ -algebras and Generating Sets

Suppose \mathcal{E} is a family of subsets of Ω (now, we make no assumptions on the nature of \mathcal{E}). We say the σ -algebra generated by \mathcal{E} , denoted $\sigma(\mathcal{E})$ is the smallest σ -algebra containing \mathcal{E} :

$$\sigma(\mathcal{E}) = \bigcap_{\sigma\text{-algebras } \mathcal{F}s.t.\mathcal{E} \subseteq \mathcal{F}} \mathcal{F}$$

In this sense, \mathcal{E} can be thought of as the atoms of Ω from which we build molecules in \mathcal{F} . As we will see, these atoms need not be unique. For example, if $\Omega = \{1, 2, 3, 4, 5, 6\}$, if $\mathcal{E} = \{\{1\}, \{2\}, \{3\}...\{6\}\}$, then $\sigma(\mathcal{E}) = \mathcal{P}(\Omega)$, the full power set. However, if $\mathcal{E} = \{\{1, 2, 3\}, \{4, 5, 6\}\}$, then the resulting structure has a "lower resolution:" $\sigma(\mathcal{E}) = \{\emptyset, \{1, 2, 3\}, \{4, 5, 6\}, \Omega\}$. Note that the following intuitive properties hold:

Lemma 1.2.1. Let $\mathcal{E} \subseteq \mathcal{P}(\Omega)$. Then,

- If \mathcal{E}_1 is a σ -algebra, then $\sigma(\mathcal{E}) = \mathcal{E}$
- If $\mathcal{E} \subseteq \mathcal{E}'$, then $\sigma(\mathcal{E}) \subseteq \sigma(\mathcal{E}')$

Proof. Clearly, as \mathcal{E} is a σ -algebra containing \mathcal{E} ,

$$\sigma(\mathcal{E}) = \mathcal{E} \cap \bigcap_{\sigma\text{-algebras } \mathcal{F}s.t.\mathcal{E} \subseteq \mathcal{F}} \mathcal{F} \subseteq \mathcal{E}$$

Also, $\sigma(\mathcal{E}) \supseteq \mathcal{E}$ by definition. We conclude $\sigma(\mathcal{E}) = \mathcal{E}$. For the latter claim, we prove $\sigma(\mathcal{E}) \subseteq \sigma(\mathcal{E}')$ by considering arbitrary elements of $\sigma(\mathcal{E})$. Suppose $A \in \sigma(\mathcal{E})$. By definition, for all \mathcal{F} containing \mathcal{E} , $A \in \mathcal{F}$. Note also that for all \mathcal{F}' containing \mathcal{E}' , \mathcal{F}' contains \mathcal{E} as well, so $A \in \mathcal{F}'$. As a consequence $A \in \sigma(\mathcal{E}')$. Since A was generic, $\sigma(\mathcal{E}) \subseteq \sigma(\mathcal{E}')$.

Theorem 1.2.2. Let Ω be countable with σ algebra \mathcal{F} . Then there exists a partition \mathcal{A} of Ω such that $\mathcal{F} = \left\{ \bigcup_i A_i : A_i \in \mathcal{A} \right\}$. In other words, \mathcal{F} works by simply combining atomic sets in \mathcal{A} .

Proof. We will form \mathcal{A} constructively. For $\omega \in \Omega$, let $A(\omega) = \arg\min_{F \in \mathcal{F}: \omega \in F} |F|$. Note that such a minimum must exist. And obviously, $A(\omega) \in \mathcal{F}$. Let us show that $\{A(\omega) : \omega \in \Omega\}$ are disjoint and their union is Ω . Suppose we have two sets $A(\omega_1), A(\omega_2)$. Suppose $A(\omega_1) \neq A(\omega_2)$, but $A(\omega_1) \cap A(\omega_2) \neq \emptyset$. Suppose without loss of generality that $A(\omega_1) \supset A(\omega_2)$. Then $\omega_1 \in A(\omega_1) \setminus A(\omega_2)$, where

 $|A(\omega_1)\backslash A(\omega_2)| < |A(\omega_1)|$. This is a contradiction, as $A(\omega_1)$ is supposed have minimal cardinality. Therefore, either $A(\omega_1) = A(\omega_2)$ or $A(\omega_1) \cap A(\omega_2) = \emptyset$. Furthermore, obviously $\cup_{\omega \in \Omega} A(\omega) = \Omega$, since for any $\omega \in \Omega$, $\omega \in A(\omega)$ at the very least.

We now show that \mathcal{F} consists of unions of the $A(\omega)$'s. Let $F \in \mathcal{F}$ be arbitrary. Note that $F = \bigcup_{\omega \in F} \omega \subseteq \bigcup_{\omega \in F} A(\omega)$. It remains to show that this inclusion is not strict. Suppose that there were a $\tilde{\omega} \in \bigcup_{\omega \in F} A(\omega) \backslash F$. Then there would be an $\omega \in F$ for which $\tilde{\omega} \in A(\omega) \backslash F$. Clearly, then $A(\tilde{\omega}) \cap A(\omega) \neq \emptyset$, so $A(\tilde{\omega}) = A(\omega)$. Yet $\tilde{\omega} \in A(\tilde{\omega}) \backslash F$, where $|A(\tilde{\omega}) \backslash F| < |A(\tilde{\omega})|$. This is, of course, a contradiction. Therefore, $F = \bigcup_{\omega \in F} \omega = \bigcup_{\omega \in F} A(\omega)$ as desired.

1.2.1 The Borel σ -algebra

It would be no overstatement to say the most often studied σ -algebra is the Borel σ -algebra. In this case, $\Omega = \mathbb{R}$, $\mathcal{E} =$ the open sets in \mathbb{R} , and $\mathcal{F} = \sigma(\mathcal{E})$. This is denoted $\mathcal{B}(\mathbb{R})$. More generally, the Borel σ -algebra of a metric space \mathcal{X} is denoted $\mathcal{B}(\mathcal{X})$. Recall from definition 1 that $\mathcal{B}(\mathbb{R})$ should be closed under compliment, and so $\mathcal{B}(\mathbb{R})$ contains the closed sets as well. Moving forward, the Borel σ -algebra will contain all the richness we will practically need.

1.2.2 Lebesgue-Stieltjes Measures

A generic class of measures is the set of Riemann-Stieltjes Measures. A distribution function (think CDF) is a map $F : \mathbb{R} \to \mathbb{R}$ such that,

- F(x) is nondecreasing with x
- F is right continuous $(\lim_{y\to x^+} F(y) = F(x))$

The corresponding Lebesgue-Stieltjes measure sets $\mu((a,b]) = F(b) - F(a)$. It can be shown that this is enough to specify the whole measure over $\mathcal{B}(\mathbb{R})$.

Example 1 (The Lebesgue Measure). The Lebesgue measure is the Lebesgue-Stieltjes Measure when F(x) = x, and so $\mu((a,b]) = b - a$.

Example 2 (The Normal Distribution). The normal distribution is induced by the Lebesgue-Stieltjes measure with $\mu((a,b]) = \int_a^b \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} dx$.

Example 3 (Probability Mass Functions from CDFs). More generally, when F is the CDF of a probability mass function, the corresponding Lebesgue-Stieltjes measure corresponds to that probability distribution.

1.3 All We Care About - Negligible Sets & Almost Everywhereness

To proceed with our study of measure theory, and thus probability theory, we will make use of the notion of something happening almost everywhere. We say an event $A \in \mathcal{F}$ occurs almost everywhere w.r.t a measure μ if $\mu(A^c) = 0$. Likewise, N is said to be a negligible set if $\mu(N) = 0$.

Proposition 1 (Properties of Negligible Sets). Suppose $(\Omega, \mathcal{F}, \mu)$ is a measure space.

- If A is negligible and $B \subseteq A$, then B is a negligible set
- If A_1, A_2 ... are negligible sets, then so is $\bigcup_{i=1}^{\infty} A_i$

Chapter 2

Extending Lebesgue-Stieltjes Measures & Carathedory's Theorem

Note that if you know you have a measure, you can do everything your heart desires! This chapter it not dedicated to the existence of measures so much as proving that we can construct measures with desireable properties.

2.1 The Problem

You are a contractor. Your client comes to you, embarassed, and says hey, I have my Lebesgue-Stieltjes measure μ . Could you help me define it uniquely over all of $\mathcal{B}(\mathbb{R})$? You say sure thing, let me just plug it into my measure extender machine. And out pops a new measure consistent, defined over new sets, and it is consistent with the old one. The main example to bear in mind is the Lebesgue measure.

Begin by saying that you have a measure μ_S (S for Start) defined on an semi-ring \mathcal{A} . While we have not yet defined semi-ring, think of it as an incredibly simple family of sets. For example, intervals of the form (a,b] comprise a semi-ring; we could specify a Lebesgue-Stieltjes function on this semi-ring. d-dimensional boxes like $\times_{i=1}^{d}(a_i,b_i]$ also comprise a semi-ring. The problem is basically this: your customer comes to you and says hey buddy, I already know what I want μ_S to be like on \mathcal{A} , can you help me out on $\sigma(\mathcal{A})$? You say, probably! More formally, we seek to prove a theorem roughly of the form:

Theorem 2.1.1. Under assumptions, given a baby measure μ_S defined on a semi-ring A, there exists a unique measure μ defined on $\sigma(A)$ which respects μ_S .

2.2 Semi-Rings & Rings

This will be boring, but necessary. We are going to define a series of related families of sets. Let Ω be the universe and \mathcal{A} be a family of subsets of Ω . The relationships to bear in mind are:

Semi-Ring
$$\implies$$
 Ring \implies Algebra $\implies \sigma$ – Algebra

Definition 7 (Semi-Ring). A family of sets A is said to be a semi-ring if, for all $A, B \in A$,

- $\emptyset \in \mathcal{A}$
- $A \cap B \in \mathcal{A}$
- $A \setminus B = \bigcup_{1 \leq j \leq n} C_j$, where $C_j \in A$ and the C_j 's are all pairwise disjoint.

Proposition 2. \mathcal{I} is a semi-ring.

The canonical example to bear in mind is the semi-ring of half-open intervals. Define \mathcal{I} to be all the sets of the form (a,b] with $a \leq b$ in \mathbb{R} . So $\mathcal{I} = \{(a,b] : a,b \in \mathbb{R}\}$.

Proof. Letting a = b, $(a, b] = \emptyset$. Properties (ii) and (iii) can be checked by simple casework on any two intervals A = (a, b], B = (c, d].

Note that semi-rings, in particular this semi-ring, is not closed under union. If we add this property, we obtain a ring.

Definition 8 (Ring). A family of sets A is said to be a ring if, for all $A, B \in A$,

- $\varnothing \in \mathcal{A}$
- A ∪ B
- $A \backslash B \in \mathcal{A}$

Just like how we defined the σ -algebra generated by a set, the ring generated by \mathcal{A} is the smallest ring containing \mathcal{A} .

Proposition 3. Let \mathcal{A} be a semi-ring. Let \mathcal{B} be the set of finite disjoint unions of elements of \mathcal{A} . Then $\mathcal{B} = ring(\mathcal{A})$

Proof. We begin by showing \mathcal{B} is a ring. Note that $\emptyset \in \mathcal{B}$ as $\emptyset \in \mathcal{A}$, so it can be considered as the union of one element of \mathcal{A} . Now, write $A = \bigcup_{i=1}^n A_i, B = \bigcup_{j=1}^m B_j$. We shall show that $A \cup B \in \mathcal{A}$. Indeed, $A \cup B = \bigcup_{i=1}^n A_i \cup \bigcup_{j=1}^m B_j$, which is also an element of \mathcal{A} by definition. Now, it remains to show that $A \setminus B \in \mathcal{A}$. To see this, note that,

$$A \backslash B = \bigcup_{i=1}^{n} A_i \backslash \bigcup_{j=1}^{m} B_j$$

This can be understood as those elements x which belong to at least one A_i , but not a single B_i . From this, it's clear that this can be understood as:

$$\bigcup_{i=1}^{n} \bigcap_{j=1}^{m} A_i \backslash B_j$$

Note also that by definition of a semi-ring, we can write $A_i \setminus B_j = \bigcup_{k=1}^{n_{i,j}} C_{i,j,k}$, where these are all disjoint. And thus, we have,

$$A \backslash B = \bigcup_{i=1}^{n} \bigcap_{j=1}^{m} \bigcup_{k=1}^{n_{i,j}} C_{i,j,k}$$

Now there's a bit of a subtle thing going on. As the $C_{i,j,k}$'s are pairwise disjoint for fixed k, if x is in $\bigcap_{j=1}^{m} \bigcup_{k=1}^{n_{i,j}} C_{i,j,k}$, it belongs to precisely one $C_{i,j,k}$ for each j. Let $C_{i,j} = \{C_{i,j,k} : 1 \leq k \leq n_{i,j}\}$. We may then write:

$$\bigcap_{j=1}^{m} \bigcup_{k=1}^{n_{i,j}} C_{i,j,k} = \bigcup_{\substack{C_1 \in C_{i,1} \dots C_{i,m} \in C_{i,m} \\ \in \mathcal{B}}} C_1 \cap C_2 \dots \cap C_m$$

Since \mathcal{A} is a semi-ring and thus is closed under intersection, each $C_1 \cap C_2 \dots \cap C_m$ is in \mathcal{A} , so the union of such intersections is in \mathcal{B} . Thus, $\bigcap_{j=1}^m \bigcup_{k=1}^{n_{i,j}} C_{i,j,k}$ is in \mathcal{A} for all i. And so, as we've already shown \mathcal{B} is closed under union, $A \setminus B \in \mathcal{B}$. This proves the desired property. And so \mathcal{B} is indeed a ring.

To see that $\mathcal{B} = \operatorname{ring}(\mathcal{A})$ is simple. As $\operatorname{ring}(\mathcal{A})$ is a ring, it must contain all unions of elements of \mathcal{A} , so $\mathcal{A} \subseteq \mathcal{B} \subseteq \operatorname{ring}(\mathcal{A})$. Taking the ring of all sides, and noting $\operatorname{ring}(\mathcal{B}) = \mathcal{B}$, as \mathcal{B} is a ring, $\operatorname{ring}(\mathcal{A}) \subseteq \mathcal{B} \subseteq \operatorname{ring}(\mathcal{A})$, so $\mathcal{B} = \operatorname{ring}(\mathcal{A})$.

2.3 Extending Lebesgue-Stieltjes Measures from Semi-Rings to Rings

We now show that we can extend measures from semi-rings to rings. First, we define a relaxed version of a measure that we care about.

Definition 9 (finitely additive measure). Suppose $\mu : \mathcal{A} \to \mathbb{R}$ is a function on subsets of Ω . We say μ is finitely additive if,

- $\mu(\emptyset) = 0$
- If $A \subseteq B, \mu(A) \leqslant \mu(B)$
- If $A, B \in \mathcal{A}$, $A \cap B = \emptyset$ and $A \cup B \in \mathcal{A}$, then $\mu(A \cup B) = \mu(A) + \mu(B)$

Theorem 2.3.1. Let μ_S be a countably additive measure defined on a semiring A. Let $\mathcal{B} = ring(A)$. Then there exists a unique finitely additive measure μ acting on \mathcal{B} which respects μ_S over A. Proof. We provide an explicit construction for μ , then verify that all is well. For an arbitrary element $B \in \mathcal{B}$, let $B = \bigcup_{i=1}^n A_i$ (we know from Proposition 3 that this is the form of such elements). And assume without loss of generality that the A_i 's are disjoint. Why can we do this? Note for $A, B \in \mathcal{A}$, we have $A \cup B = B \cup (A \backslash B) = B \cup \bigcup_{i=1}^m C_i$, where the C_i 's are pairwise disjoint. By induction, then, every finite union can be represented as a finite disjoint union. We do the perfectly natural thing: we want our measure to be finitely additive, so our hand is forced. We define,

$$\mu(B) = \sum_{i=1}^{n} \mu_S(A_i)$$

First, we must verify that this is consistent. Suppose $B = \bigcup_{j=1}^{m} B_i$. Then observe,

$$\sum_{i=1}^{n} \mu_{S}(A_{i}) = \sum_{i=1}^{n} \mu_{S}(A_{i} \cap B) = \sum_{i=1}^{n} \mu_{S}(A_{i} \cap \bigcup_{j=1}^{m} B_{j})$$
$$= \sum_{i=1}^{n} \sum_{j=1}^{m} \mu_{S}(A_{i} \cap B_{j}) = \sum_{i=1}^{m} \mu_{S}(B_{j})$$

Where we have employed the assumption that μ_S is finitely additive over \mathcal{A} and utilized the fact that semi-rings are closed under intersection (and so $\mu_S(A_i \cap B_j)$ is defined). From here, it is trivial to verify that μ is finitely additive. Indeed, we simply seek to show that if $A, B \in \mathcal{B}$ are disjoint, then $\mu(A \cup B) = \mu(A) \cup \mu(B)$. First, write $A = \bigcup_{i=1}^n A_i, B = \bigcup_{j=1}^m B_j$. Again, assume the A_i 's are pairwise disjoint, as are the B_j 's. But since $A \cap B = \emptyset$, the A_i 's are also disjoint with the B_j 's. So then,

$$\mu(A \cup B) = \mu\left(\bigcup_{i=1}^{n} A_i \cup \bigcup_{j=1}^{m} B_j\right) = \sum_{i=1}^{n} \mu(A_i) + \sum_{j=1}^{m} \mu(B_j) = \mu(A) + \mu(B)$$

Which proves the additivity property. By induction, one can easily establish that if $B_1, B_2...B_n \in \mathcal{B}$ are all pairwise disjoint, then $\mu(\cup_{i=1}^n B_i) = \sum_{i=1}^n \mu(B_i)$.

Uniqueness of μ is trivial. If there is a second μ' that respects μ_S , then countable additivity forces $\mu = \mu'$ over everything in \mathcal{B} .

At this point, we would like to show that μ is not only finitely additive, but countably additive over \mathcal{B} . The following proposition ensures that countable additivity of μ_S over \mathcal{A} is sufficient.

Theorem 2.3.2. Letting \mathcal{A} be a semi-ring and let \mathcal{J} be the ring generated by \mathcal{A} . Let μ_S , μ as described in the above theorem. Then if μ is countably additive over \mathcal{I} , then μ is countably additive over \mathcal{J} .

Proof. First, as $B \in \mathcal{B}$, we may write $B = \bigcup_{j=1}^m A_j$, where the A_j 's are pairwise disjoint. So let us first restrict our analysis to a particular A_j . Note that $B = \bigcup_{i=1}^{\infty} B_i$ as well. Note that, as the A_j 's are pairwise disjoint, as are the B_i 's, it must be the case that each A_j is a collection of the B_i 's. So let I_j be such that $A_j = \bigcup_{i \in I_j} B_i$. Note that, if we can prove that $\mu(A_j) = \sum_{i \in I_j} \mu(B_i)$ for each j, we will be done, since then finite additivity will imply,

$$\mu(B) = \sum_{j=1}^{m} \mu(A_j) = \sum_{j=1}^{m} \sum_{i \in I_j} \mu(B_i) = \sum_{i=1}^{\infty} \mu(B_i)$$

So it remains to prove $\mu(A_j) = \sum_{i \in I_j} \mu(B_i)$ for arbitrary A_j . Finally, observe that B_i can be written as $\bigcup_{k=1}^{n_i} C_{i,k}$. And so, $A_j = \bigcup_{i \in I_j} \bigcup_{k=1}^{n_i} C_{i,k}$. Then by countable additivity of μ_S on \mathcal{I} ,

$$\sum_{i \in I_j} \mu(B_i) = \sum_{i \in I_j} \sum_{k=1}^{n_i} \mu_S(C_{i,k}) = \mu(A_j)$$

Now, at this point, it will prove somewhat difficult to prove theorems in full generality. So let us abandon our hope of working with completely arbitrary semi-rings. From now on, we will let \mathcal{I} be the semi-ring of d-dimensional boxes $\{(a_1,b_1]\times(a_2,b_2]...\times(a_d,b_d]:a_1,b_1...a_d,b_d\in\mathbb{R}\}.$

Proposition 4. \mathcal{I} as described is a semi-ring

Proof. Exercise
$$\Box$$

It is worth asking: when is μ_S actually countably additive? Not any set function will do. For instance, if $\mu_S(a,b] = 2^{b-a}$, even though this satisfies the monotonicity property and $\mu_S(\varnothing) = 0$, additivity crumbles. Thus, we will restrict our study to d-dimensional Lebesgue-Stieltjes measures. That is, we assume the existence of d distribution functions $F_1...F_d$, and set,

$$\mu_S \left(\sum_{i=1}^d (a_i, b_i] \right) = \prod_{i=1}^d (F_i(b_i) - F_i(a_i))$$

Theorem 2.3.3. μ as described is countably additive over \mathcal{I} and thus its extension to \mathcal{J} is countably additive as well.

Proof. Assume $A = (a_1, b_1] \times ... \times (a_d, b_d] \in \mathcal{I}$. Also assume we have $A = \bigcup_{i=1}^{\infty} A_i$, where each $A_i = \times_{j=1}^{d} (a_{i,j}, b_{i,j}]$. We seek to show,

$$\mu_S(A) = \sum_{i=1}^n \mu_S(A_i)$$

We will argue this via induction on d.

Base Case: First, suppose d=1, so we consider a measure on the real line. First, observe μ_S is then finitely additive. If (a,b] and (c,d] are disjoint (assume a < c), then for $(a,b] \cup (c,d] \in \mathcal{I}$, we have b=c, so $\mu_S((a,b] \cup (c,d]) = \mu_S((a,d]) = F_1(d) - F_1(a)$. Likewise, $\mu_S((a,b]) + \mu_S((c,d]) = F_1(d) - F_1(c) + F_1(b) - F_1(a) = F_1(d) - F_1(a)$. We use this finite additivity over and over again. Note indeed, that

$$\sum_{i=1}^{n} \mu(A_i) = \mu\left(\bigcup_{i=1}^{n} A_i\right) \leqslant \mu\left(\bigcup_{i=1}^{\infty} A_i\right) = \mu(A)$$

Taking $n \to \infty$, we find $\sum_{i=1}^{\infty} \mu(A_i) \leqslant \mu(A)$. We now seek to show the reverse inequality. Fix any $\epsilon > 0$ and consider an augmentation of the A_i 's. Let $\delta > 0$ and $\delta_1, \delta_2, \ldots > 0$ be arbitrary for now. $A_i = (a_i, b_i]$, let $A_i' = (a_i, b_i + \delta_i]$. Also consider, where A = (a, b], consider the new interval $A' = [a + \delta, b]$. As $\{A_i'\}_i$ provides a covering of A, it provides a covering of A'. Thus, it is possible to extract a finite cover. So let $I \subseteq \mathbb{N}$ be such that $A' \subseteq \bigcup_{i \in I} A_i'$.

Proposition 5. If $A, B \in \mathcal{B}$, then $\mu(A \cup B) \leq \mu(A) + \mu(B)$

Proof. By additivity,

$$\mu(A \cup B) = \mu(A) + \mu(B \setminus A) \leq \mu(A) + \mu(B)$$

By induction, this holds for any finite number of sets as well. \Box

We can use this fact to upper bound $\mu(A')$ by a nondisjoint union:

$$\mu(A') \leqslant \mu\left(\bigcup_{i \in I} A'_{i}\right) \leqslant \sum_{i \in I} \mu(A'_{i})$$

$$= \sum_{i \in I} F(b_{i} + \delta_{i}) - F(a) = \sum_{i \in I} (F(b_{i} + \delta_{i}) - F(b_{i}) + F(b_{i}) - F(a))$$

$$\leqslant \sum_{i = 1}^{\infty} (F(b_{i}) - F(a_{i})) + (F(b_{i} + \delta_{i}) - F(b_{i}))$$

$$= \sum_{i = 1}^{\infty} \mu(A_{i}) + \sum_{i = 1}^{\infty} (F(b_{i} + \delta_{i}) - F(b_{i}))$$

Additionally,

$$\mu(A) = F(b) - F(a) = F(b) - F(a+\delta) + F(a+\delta) - F(a) = \mu(A') + F(a+\delta) - F(a)$$

By right continuity of F, we can let δ be such that $F(a + \delta) - F(a) < \epsilon/2$. We may also let each δ_i be such that $F(b + \delta_i) - F(b) < \epsilon/2^i$. So then,

$$\mu(A) < \mu(A') - \epsilon/2 \le \sum_{i=1}^{\infty} \mu(A_i) + \sum_{i=1}^{\infty} \epsilon/2^i - \epsilon/2$$

$$= \sum_{i=1}^{\infty} \mu(A_i) + \epsilon/2$$

At last, taking $\epsilon \to 0$, we find $\mu(A) \leq \sum_{i=1}^{\infty} \mu(A_i)$. This completes the proof of the base case.

Inductive Step: Now, we assume that this theorem is true in d-1 dimensions, and we seek to push it to d dimensions. So suppose that $A = \bigcup_{i=1}^{\infty} A_i$, where the A_i 's are disjoint. Now, without loss of generality, suppose that we take a common refinement of the A_i 's in the dth dimension. That is, let $H = \bigcup_{i=1}^{n} (a_{i,d} \cup b_{i,d})$ be the set of all numbers which are relevant to our partition along dimension d. Now put d in increasing order, such that: d is d in the d in the d in the d into a new collection d in d in

$$A = \cup_{k=1}^{\infty} \cup_{i \in I_k} A_i'$$

Define a new distribution function G where $G(c_k) = \sum_{1 \leq j \leq k} \mu(\cup_{i \in I_k} A_i')$. G thus corresonds to a 1-dimensional distribution function. So by the base case, we have,

$$\mu(A) = \sum_{k=1}^{\infty} \mu\bigg(\bigcup_{i \in I_k} A_i'\bigg)$$

Now, let μ_{d-1} be the measure induced by considering the first d-1 dimensions of the A_i 's. We have $\mu\left(\bigcup_{i\in I_k}A_i'\right)=(c_{k+1}-c_k)\mu_{d-1}\left(\bigcup_{i\in I_k}A_i'\right)$. So then, by induction,

$$\sum_{k=1}^{\infty} \mu\left(\bigcup_{i \in I_k} A_i'\right) = \sum_{k=1}^{\infty} (c_{k+1} - c_k) \mu_{d-1}\left(\bigcup_{i \in I_k} A_i'\right)$$
$$= \sum_{k=1}^{\infty} (c_{k+1} - c_k) \sum_{i \in I_k} \prod_{i=1}^{d-1} (a_i, b_i] = \sum_{k=1}^{\infty} \sum_{i \in I_k} \prod_{i=1}^{d} (a_i, b_i] = \sum_{i=1}^{\infty} \mu(A_i')$$

Note that the same decomposition into the dth and first d-1 dimensions yields:

$$\mu(A_i) = \sum_{i: A_i' \subseteq A_i} \mu(A_i')$$

Which collectively implies that $\mu(A) = \sum_{i=1}^{\infty} \mu(A_i)$. This completes the inductive step and thus the whole proof.

Corollary 2.3.3.1. If μ_S is a d-dimensional Lebesgue-Stieltjes measure on \mathcal{I} , then μ is countably additive on \mathcal{J}

2.3.1 Recap

Let's pause for a moment to focus on what we've actually done. We have shown that if we have a d-dimensional distribution function, we can extend it to a countably additive measure on a ring. We will find that rings are very nice. In particular, rings can approximate sets in the Borel σ algebra arbitrarily well. This is the fact we will use to define an outer measure.

2.4 Outer Measures

Thus far, we have worked our way "up" from our semi-ring and tried to build up something more sophisticated on rings, a more complicated family of sets. Now, we will develop a sort of master function, called a *outer measure*, which is indeed defined on all subsets of Ω and thus $\mathcal{B}(\mathbb{R}^d)$ as well. While outer measures do not behave well in general, we will show that it acts nicely on $\mathcal{B}(\mathbb{R}^d)$.

Recall we have a measure μ acting on the ring \mathcal{J} generated by the half-open intervals. We define the following outer measure on subsets of \mathbb{R}^d :

$$\mu^{\star}(A) = \inf\{\mu(J) : J \in \mathcal{J}, A \subseteq J\}$$

Intuitively, the idea is this: we wrap an element J of \mathcal{J} around A as tightly as possible, and then take sizes the way we know how. Then like shrink wrap, we make J as small as possible. First, let us establish a key fact.

Proposition 6. If
$$A \in \mathcal{J}$$
, then $\mu^{\star}(A) = \mu(A)$

Proof. Obviously, as A is a valid candidate from \mathcal{J} , $\mu^{\star}(A) \leq \mu(A)$. Now we show the reverse. Suppose by way of contradiction that $\mu^{\star}(A) < \mu(A)$. Then there would exist a $B \in \mathcal{J}$ with $A \subseteq B$ such that $\mu(B) < \mu(A)$. This is of course a contradiction of the monotonicity property.

Now, we define a very general family of sets: the Lebesgue measurable sets. This will turn out to be more general than we need.

Definition 10 (Lebesgue Measurable). Say a set $E \subseteq \mathbb{R}$ is Lebesgue-measurable if it satisfies the Caratheodory criterion: that for all $A \subseteq \mathbb{R}$, $\mu^*(A) = \mu^*(A \cap E) + \mu^*(A \cap E^c)$. Let the Lebesgue measurable sets be \mathcal{L} .

As a first observation, note that proposition 6 and Corollary 2.3.3.1 collectively imply that μ^* is countably additive on \mathcal{J} . Here are the remaining steps:

- 1. Prove that $\sigma(\mathcal{J}) = \mathcal{B}(\mathbb{R}^d)$
- 2. Observe $\mathcal{J} \subseteq \mathcal{L}$
- 3. Prove μ^{\star} is countably additive on \mathcal{L}

- 4. Prove \mathcal{L} is a σ -algebra
- 5. Deduce $\mathcal{B}(\mathbb{R}^d) = \sigma(\mathcal{J}) \subseteq \sigma(\mathcal{L}) = \mathcal{L}$

From this, it will follow that μ^* is a countably additive measure on $\mathcal{B}(\mathbb{R}^d)$, so we will be done.

2.4.1 Step 1

Theorem 2.4.1. $\sigma(\mathcal{J}) = \mathcal{B}(\mathbb{R}^d)$

Proof. Let us first prove $\mathcal{I} \subseteq \mathcal{B}(\mathbb{R})$ for d = 1. Indeed, note,

$$(a,b] = \bigcap_{n=1}^{\infty} (a,b+1/n)$$

And so each $(a, b] \in \mathcal{B}(\mathbb{R})$. Thus, $\mathcal{I} \subseteq \mathcal{B}(\mathbb{R})$. It remains to show the reverse inclusion.

Proposition 7. Every open set in \mathbb{R} can be written as the disjoint union of open intervals

Proof. Let O be open. Let $O_Q = O \cap \mathbb{Q}$. Observe that by definition of opennes, for each $q \in O_Q$, there exists a highest $\epsilon_q > 0$ such that $B_{\epsilon_q}(q) \subseteq O$. Now, let $C = \{B_{\epsilon_q}(q) : q \in O_Q\}$ and $S = \cup_{I \in C} I = O$. I claim O = S. To see this, observe for any $x \in O$ that there is an ϵ ball $B_{\epsilon}(x)$ contained in O. If we let q be a rational number s.t. $|x-q| < \epsilon/2$, by maximality of ϵ_q , we have $x \in B_{\epsilon_q}(q)$, so $x \in C$. Finally, let elements of D be obtained by connecting all intervals in C, so that D consists of disjoint open intervals and $\cup_{I \in D} I = \cup_{I \in C} I = S = O$. Thus, O can be written as the disjoint open intervals provided in D.

Thus, letting $O \in \mathcal{G}$ be some arbitrary open set in \mathbb{R} , where we know \mathcal{G} generates $\mathcal{B}(\mathbb{R}^d)$. Thus, the set of open intervals, call it \mathcal{E} , generates $\mathcal{B}(\mathbb{R})$. Yet also, any interval (a,b) can be written as:

$$(a,b) = \bigcup_{n=1}^{\infty} (a,b-1/n]$$

Which is in $\sigma(\mathcal{I})$. Thus, $\mathcal{E} \subseteq \sigma(\mathcal{I})$, so $\mathcal{B}(\mathbb{R}) = \sigma(\mathcal{E}) \subseteq \sigma(\mathcal{I})$. This is sufficient to prove the claim in dimension d = 1. It remains to prove it for higher dimensions.

Proposition 8. Let \mathcal{E} generate \mathcal{F} . Then

$$\sigma(\{A_1 \times A_2 \dots \times A_n : A_1 \dots A_n \in \mathcal{E}\}) = \sigma(\{A_1 \times A_2 \dots \times A_n : A_1 \dots A_n \in \mathcal{F}\})$$

Proof. Exercise. It is best to prove this when d=2 and proceed by induction.

Corollary 2.4.1.1. If $\mathcal{E}_1, \mathcal{E}_2$ both generate \mathcal{F} , then,

$$\sigma(\{A_1 \times A_2 ... \times A_n : A_1 ... A_n \in \mathcal{E}_1\}) = \sigma(\{A_1 \times A_2 ... \times A_n : A_1 ... A_n \in \mathcal{F}\})$$
$$= \sigma(\{A_1 \times A_2 ... \times A_n : A_1 ... A_n \in \mathcal{E}_2\})$$

Proposition 9. Every open set in \mathbb{R}^d can be written as the (not necessaarily disjoint) union of countably many open rectangles

Proof. Following the same outline as before, use the fact that \mathbb{Q}^d is dense in \mathbb{R}^d and the definition of the open sets. The reason we no longer have disjointness is that the union of two connected open rectangles may not be an open rectangle in dimension greater than 1.

A corollary of this is that $\mathcal{B}(\mathbb{R}^d)$ is generated by the set of open rectangles.

Corollary 2.4.1.2. $\sigma(\mathcal{I}) = \mathcal{B}(\mathbb{R}^d)$ for all d.

Proof. Let $\mathcal{E}_1 = \{(a, b] : a, b \in \mathbb{R}\}$, which is simply \mathcal{I} in dimension 1. Also let $\mathcal{E}_2 = \{(a, b) : a, b \in \mathbb{R}\}$. Then,

$$\begin{split} \sigma(\mathcal{I}) &= \sigma(\{I_1 \times I_2 ... \times I_d : I_1, ... I_d \in \mathcal{E}_1\}) \\ &= \sigma(\{A_1 \times A_2 ... \times A_d : A_1 ... A_d \in \sigma(\mathcal{E}_2)\}) = \mathcal{B}(\mathbb{R}^d) \end{split}$$

And of course, $\sigma(\mathcal{I}) = \sigma(\mathcal{J})$. This concludes the proof.

2.4.2 Step 2

Theorem 2.4.2. $\mathcal{J} \subseteq \mathcal{L}$

Proof. Consider arbitrary $E \in \mathcal{J}$. Now consider arbitrary $A \subseteq \mathbb{R}^d$. We desire to show that

$$\mu^{\star}(A) = \mu^{\star}(A \cap E) + \mu^{\star}(A \cap E^{c})$$

We will prove this by showing the two corresponding inequalities. Let J_1, J_2 be such that,

$$\mu(J_1) < \mu^{\star}(A \cap E) + \epsilon/2$$

$$\mu(J_2) < \mu^{\star}(A \cap E^c) + \epsilon/2$$

Let $J=J_1\cup J_2$. It's clear that $J\in\mathcal{J}$. Furthermore, as $A\cap E\subseteq J, A\cap E^c\subseteq J, A=(A\cap E)\cup(A\cap E^c)\subseteq J$. So then we have,

$$\mu^{\star}(A) \leq \mu^{\star}(J) \leq \mu(J_1) + \mu(J_2) < \mu^{\star}(A \cap E) + \mu^{\star}(A \cap E^c) + \epsilon$$

Taking $\epsilon \to 0$, we have side of the equality. Now, we show the reverse inequality. We seek to show,

$$\mu^{\star}(A \cap E) + \mu^{\star}(A \cap E^c) \leqslant \mu^{\star}(A)$$

Suppose that $A \subseteq J$. Then $A \cap E \subseteq J \cap E$. Furthermore, $A = (A \cap E) \cup (A \cap E^c) \subseteq (J \cap E) \cup (J \cap E^c)$. And thus,

$$\mu^{\star}(A) + \epsilon \geqslant \mu(J) = \mu(J \cap E) + \mu(J \cap E^c)$$

But note that $J \cap E, J \cap E^c \in \mathcal{J}$, so,

$$\geqslant \mu(A \cap E) + \mu(A \cap E^c)$$

Taking $\epsilon \to 0$, we're done.

2.4.3 Step 3

Theorem 2.4.3. μ^* is countably additive on \mathcal{L}

Proof. First, observe that $\mu^{\star}(\emptyset) = \emptyset$ trivially, as $\emptyset \in \mathcal{J}$ and $\mu(\emptyset) = 0$. Now, assume $A, B \in \mathcal{L}$ with $A \subseteq B$. Note that for any $J \in \mathcal{J}$ with $B \subseteq J$, $A \subseteq J$. And thus,

$$\mu^{\star}(A) = \inf\{\mu(J) : A \subseteq J\} \leqslant \inf\{\mu(J) : B \subseteq J\} = \mu^{\star}(B)$$

It remains to verify that μ^* is countably additive. Let us begin with finite additivity. It remains to show that for any $A, B \in \mathcal{L}$ that $\mu^*(A \cup B) = \mu^*(A) + \mu^*(B)$. Fix $\epsilon > 0$. First, let $J_A, J_B \in \mathcal{J}$ be such that, $\mu(J_A) - \mu^*(A) < \epsilon/2$ and likewise for J_B . It then follows that, $J_A \cup J_B$ is a valid cover of $A \cup B$, and so:

$$\mu^{\star}(A \cup B) \leqslant \mu(J_A \cup J_B) \leqslant \mu(J_A) + \mu(J_B) < \mu^{\star}(A) + \mu^{\star}(B) + \epsilon$$

Taking $\epsilon \to 0$, it's clear that $\mu^*(A \cup B) \leq \mu^*(A) + \mu^*(B)$. Now, we would like the reverse inequality: $\mu^*(A) + \mu^*(B) \leq \mu^*(A \cup B)$. To see this, suppose that J is such that $\mu(J) < \mu^*(A \cup B) + \epsilon$. Consider any J_A, J_B s.t. $A \subseteq J_A$ and $B \subseteq J_B$. Now, let $J_B' = J_B \setminus J_A$. We still have $J_B' \supseteq B$. So then,

$$\mu^{\star}(A) + \mu^{\star}(B) < \mu(J_A \cap J) + \mu(J_B' \cap J)$$

By additivity on the ring and monotonicity,

$$= \mu((J_A \cap J) \cup (J_B' \cap J)) \leqslant \mu(J) \leqslant \mu^*(A \cup B) + \epsilon$$

Taking $\epsilon \to 0$, we have proven finite additivity in the n=2 case; the general finite case follows easily by induction.

Now, we proceed to countable additivity. Suppose that $A_1, A_2... \in \mathcal{L}$ are all disjoint. Let $A = \bigcup_i A_i$. First, observe by finite addivity and monotonicity that,

$$\mu^{\star}(A) \geqslant \mu^{\star}(\bigcup_{i=1}^{n} A_i) = \sum_{i=1}^{n} \mu^{\star}(A_i)$$

Taking $n \to \infty$, we have one inequality. It remains to show the opposite. Again, fix $\epsilon > 0$. We can this by showing that, for all $\epsilon > 0$,

$$\mu^{\star}(A) \leqslant \sum_{i=1}^{\infty} \mu^{\star}(A_i) + \epsilon$$

To see this, let J_i be such that $\mu(J_i) < \mu^*(A_i) + \epsilon/2^i$. And let $A \subseteq J$. It follows that $A_i \subseteq J \cap J_i \subseteq J_i$, so $\mu(J \cap J_i) < \mu(A_i) + \epsilon/2^i$. And thus, by countable additivity on the ring \mathcal{J} , we obtain,

$$\mu^{\star}(A) \leqslant \mu(J) = \sum_{i=1}^{\infty} \mu(J \cap J_i) \leqslant \sum_{i=1}^{\infty} \mu^{\star}(A_i) + \epsilon/2^i = \sum_{i=1}^{\infty} \mu^{\star}(A_i) + \epsilon$$

Taking $\epsilon \to 0$, we conclude the desired result.

2.4.4 Step 4

Theorem 2.4.4. \mathcal{L} is a σ -algebra

Proof. First, clearly $\emptyset \in \mathcal{L}$. Additionally, note that if $E \in \mathcal{L}$, then, for all $A \subseteq \mathbb{R}^d$, we have,

$$\mu^{\star}(A) = \mu^{\star}(A \cap E) + \mu^{\star}(A \cap E^{c})$$

Which also implies that E^c is Lebesuge-measurable. Thus, \mathcal{L} is closed under complement. Let us now assume that $E_1, E_2... \in \mathcal{L}$. We then have that, letting $E = \bigcup_i E_i$,

$$\mu^{\star}(A) = \mu^{\star}(\cup_{i} A_{i}) = \sum_{i} \mu^{\star}(E_{i}) = \sum_{i} \mu^{\star}(A \cap E_{i}) + \mu^{\star}(A \cap E_{i}^{c})$$
$$= \sum_{i} \mu^{\star}(A \cap E_{i}) + \sum_{i} \mu^{\star}(A \cap E_{i}^{c})$$
$$= \mu^{\star}(\cup_{i} A \cap E_{i}) + \mu^{\star}(\cup_{i} A \cap E_{i}^{c}) = \mu^{\star}(A \cap E) + \mu^{\star}(A \cap E^{c})$$

And thus E is Lebesgue measurable. This concludes the proof.

2.4.5 Step 5

Now, we have that $J \subseteq \mathcal{L}$ and $\sigma(\mathcal{J}) = \mathcal{B}(\mathbb{R}^d)$. And so, $\mathcal{B}(\mathbb{R}^d) \subseteq \sigma(\mathcal{J}) \subseteq \sigma(\mathcal{L}) = \mathcal{L}$. And thus, $\mathcal{B}(\mathbb{R}^d) \subseteq \mathcal{L}$. And since μ^* is a countably additive measure on \mathcal{L} , we find that μ^* is also a countably additive measure on $\mathcal{B}(\mathbb{R}^d)$. This is the desired result.

2.5 The π - λ Theorem and Uniqueness

We will define two families of sets, state & prove the π - λ theorem, and give an application w.r.t. the Lebesgue measure.

Definition 11 (π -System). Say P is a π system if it is closed under intersection

Definition 12 (λ -System). Say L is a λ system if,

- $\varnothing \in L$
- L is closed under complement
- If $A_1..A_n \in L$ and the A_i 's are pairwise disjoint, then $\bigcup_{i=1}^n A_i \in L$

Theorem 2.5.1 (The π - λ Theorem). Say P is a π system contained in a λ system L. Then $\sigma(P) \subseteq L$.

Proof. We show that $\lambda(P)$, the smallest λ system containing P, is a σ algebra. Thus, $\sigma(P) \subseteq \lambda(P) \subseteq L$, since L is already a λ system. Thus, it remains to prove that $\lambda(P)$ is a σ algebra.

Proposition 10. A family of sets which is a π and λ system is also a σ algebra.

Proof. The closure properties of a σ algebra can be easily checked

Thus, it remains to show that $\lambda(P)$ is a π -system, i.e. it is closed under intersection.

Lemma 2.5.2. Let L be a λ system. For $A \in L$, let,

$$L_A = \{ B \in L : A \cap B \in L \}$$

Then L_A is a λ system.

Proof. Check the properties of a λ system

Lemma 2.5.3. The intersections of a λ system is a λ system

Proof. Check the properties of a λ system (not hard)

Consider the following set G:

$$G = \{A \in \lambda(P) \ s.t. \ A \cap E \in \lambda(P) \ , \forall E \in P\}$$

Obviously,

$$G = \bigcap_{E \in P} (\lambda(P))_E$$

Combining the above two lemmas, it follows that G is a λ system. As P is a π system, $P \subseteq G$, so $\lambda(P) \subseteq \lambda(G) \subseteq \lambda(P)$, and thus $\lambda(P) = G$. Thus,

$$G = \lambda(P)$$
.

Now, we work out a little more. Write,

$$H = \{ A \in \lambda(P) : A \cap B \in \lambda(P), \forall B \in \lambda(P) \}$$

Now we find that,

$$H = \cap_{A \in \lambda(P)} (\lambda(P))_E$$

And thus again, H is a λ system. We find that $\lambda(P)=H$. But obviously, H is a π system, so we are done.

We will now show that the restriction of μ^* to $\mathcal{B}(\mathbb{R}^d)$ is the only thing we can do. Suppose there is a second measure μ' which respects μ over \mathcal{J} ; we can show that $\mu' = \mu^*$ over $\mathcal{B}(\mathbb{R}^d)$. With one assumption: assume μ^* and μ' are σ -finite. How will this work? We proceed in the following steps:

- Let $\mathcal{D} = \{A \in \mathcal{B}(\mathbb{R}^d) : \mu^{\star}(A) = \mu'(A)\}$
- Argue \mathcal{D} is a σ algebra.
- Observe $\mathcal{J} \subseteq \mathcal{D}$
- Deduce $\mathcal{B}(\mathbb{R}^d) = \sigma(\mathcal{J}) \subseteq \sigma(\mathcal{D}) = \mathcal{D}$
- Conclude $\mu^* = \mu'$ over all of $\mathcal{B}(\mathbb{R}^d)$.

The only real work here is to show that \mathcal{D} is in fact a σ algebra, as the other steps are self explanatory. Because μ is σ -finite, let us write that $\Omega = \cup_j B_j$, where $B_j \in \mathcal{J}$ is countable and $\mu(B_j) < \infty$ for all j.

We first do the proof for finite measures. First, note that we can consider the λ system \mathcal{I} . Clearly, if $\mu^* = \mu'$ over \mathcal{J} , the same holds true over \mathcal{J} . Now, we show \mathcal{D} is a λ system. Clearly, $\emptyset \in \mathcal{D}$. Furthermore, \mathcal{D} is closed under complement, since,

$$\mu^{\star}(A^c) = \mu^{\star}(\Omega) - \mu^{\star}(A)$$
$$= \mu'(\Omega) - \mu'(A) = \mu'(A^c)$$

As μ', μ^{\star} are countably (and thus finitely) additive, L is obviously closed under disjoint unions as well, as,

$$\mu^{\star}(\cup_{i=1}^{n} A_{i}) = \sum_{i=1}^{n} \mu^{\star}(A_{i}) = \sum_{i=1}^{n} \mu'(A_{i}) = \mu'(\cup_{i=1}^{n} A_{i})$$

Thus, \mathcal{D} is a λ system. We conclude from the π lambda theorem that $\mathcal{B}(\mathbb{R}^d) = \sigma(\mathcal{I}) \subseteq \mathcal{D}$, so $\mu^* = \mu'$ over $\mathcal{B}(\mathbb{R}^d)$.

The general σ -finite is simple. Let B_1, B_2 . be disjoint in \mathcal{J} with $\cup_i B_i = \Omega$ and $\mu'_i(B_i) = \mu^*(B) < \infty$. Then define $\mu_i^*(A) = \mu^*(A \cap B_i), \mu'_i(A) = \mu'(A \cap B_i)$ for al $A \in \mathcal{B}(\mathbb{R}^d)$. It follows that,

$$\mu' = \sum_{i} \mu'_{i} \quad \mu^{\star} = \sum_{i} \mu^{\star}_{i}$$

And since each μ'_i , μ^{\star}_i is a finite measure, by our prior work, they must agree. And so, all of μ' , μ^{\star} agree. This proves the unqiqueness, as desired!

2.6 Consequences

We should pat ourselves on the back and say.... whew. We are basically done with the hard work. For example, we can now define probability measures to our heart's content! For example, if we say,

$$\mu((a_1, b_1] \dots \times (a_d, b_d]) = \int_{a_1}^{b_1} \dots \int_{a_d}^{b_d} \left(\frac{1}{2\pi}\right)^{-d/2} \prod_{i=1}^d e^{-\frac{1}{2}x_i^2} dx_i$$

Then we know μ is the unique measure on $\mathcal{B}(\mathbb{R}^d)$ corresponding to the normal distribution!

Chapter 3

Measurable Functions and Integrating Functions

We will now devote ourselves to the study of functions acting on measure spaces. First, we define what it means for a function to be measurable. Then, we build up our study of how to integrate functions. Throughout the chapter, we let $(\Omega, \mathcal{F}, \mu)$ be a fixed measure space.

3.1 Measurable Functions

3.1.1 Intuition

Let us return to chapter 1. There, we said that Ω could be an incredibly rich universe of possible events, but \mathcal{F} is a subset of interest. For example, in a dice roll, Ω could differentiate the outcomes of the dice roll, the weather tomorrow, and what you eat for lunch tomorrow. But we may let $\mathcal{F} = \sigma(\bigcup_{i=1}^{6} \{\omega : \text{dice roll at } \omega \text{ is } i\})$ be the σ -algebra which captures enough richness for our purposes. We think of measurable functions as those which compose well with the set of events we care about. This is a sort of necessary but sufficient condition for our study of probability.

Example 4. Let
$$\Omega = \{1, 2, 3, 4, 5, 6\}$$
, $\mathcal{F} = \sigma(\{\{1, 2\}, \{3, 4\}, \{5, 6\}\})$ and $\mu(\{1, 2\}) = \mu(\{3, 4\}) = \mu(\{5, 6\}) = 1/3$. Finally, let $X(\omega) = 2\omega$.

In this example, X is not measurable in some sense. Think about it. What is the probability that X=2? Our measure is underspecified! Just because we know $\mu(X \in \{2,4\}) = 1/3$ doesn't mean we can determine $\mu(\{X \in 2\}) = \mu(\{1\})$. It could be that we have a biased die in which $\mu(\{1\}) = 3/24$, $\mu(\{2\}) = 1/24$. So what is the expected value of X? There really isn't enough information! On the other hand, if X=1 if $\omega \in \{1,2,3,4\}$ and is 0 otherwise, we can determine the expected value of X, because $X^{-1}(\{1\}) = \{1,2,3,4\} \in \mathcal{F}$; likewise, $X^{-1}(\{0\}) = \{5,6\} \in \mathcal{F}$.

3.1.2 Definition of Measurability

Suppose $(\Omega, \mathcal{F}, \mu)$ is a measure space and $(\mathcal{X}, \mathcal{A})$ is a family of sets equipped with a σ -algebra.

Definition 13. A function $X : \Omega \to \mathcal{X}$ is said to be \mathcal{F}/\mathcal{A} measurable, or simply measurable, if for all $A \in \mathcal{A}$, $X^{-1}(A) \in \mathcal{F}$. One may write $X : (\Omega, \mathcal{F}) \to (\mathcal{X}, \mathcal{A})$.

Definition 14. If $\mathcal{X} = \mathbb{R}$, $\mathcal{A} = \mathcal{B}(\mathbb{R})$, the set of all $\mathcal{F}/\mathcal{B}(\mathbb{R})$ measurable functions is denoted $\mathcal{M}(\Omega, \mathcal{B}(\mathbb{R}))$. The set of all such nonnegative functions is $\mathcal{M}^+(\Omega, \mathcal{B}(\mathbb{R}))$.

3.1.3 Determining Measurability

Certainly, we could check 13 by simply taking arbitrary elements of \mathcal{A} and checking $X^{-1}(\mathcal{A}) \in \mathcal{F}$. This may prove to be a difficult task, however. For example, recall from our previous study of the Lebesgue measure that $\mathcal{B}(\mathbb{R})$ is complicated! We will show that it suffices to check a generating class.

Theorem 3.1.1. If $A = \sigma(\mathcal{E})$ and for all $E \in \mathcal{E}$, $X^{-1}(E) \in \mathcal{F}$, then X is \mathcal{F}/A measurable.

Proof. We proceed via a generating class argument. Let,

$$\mathcal{D} = \{ A \in \mathcal{A} : X^{-1}(A) \in \mathcal{F} \}$$

We shall show that \mathcal{D} is a σ algebra. First, observe that $X^{-1}(\emptyset) = \emptyset \in \mathcal{D}$. Furthermore, if $A \in \mathcal{D}$, as $X^{-1}(A^c) = X^{-1}(A)^c$, $X^{-1}(A) \in \mathcal{F}$, and \mathcal{F} is closed under complement, $A^c \in \mathcal{D}$. Thus \mathcal{D} is closed under complement. Finally, suppose $A_1, A_2 \dots \in \mathcal{D}$. One can check that $X^{-1}(\bigcup_{i=1}^{\infty} A_i) = \bigcup_{i=1}^{\infty} X^{-1}(A_i)$. And as each $X^{-1}(A_i) \in \mathcal{F}$, the whole countable union is as well. Thus, $\bigcup_{i=1}^{\infty} A_i \in \mathcal{D}$. We conclude that \mathcal{D} has the desirable closure properties of a σ algebra.

By assumption, $\mathcal{E} \subseteq \mathcal{D}$. Therefore, $\mathcal{A} = \sigma(\mathcal{E}) \subseteq \sigma(\mathcal{D}) = \mathcal{D}$. Also, $\mathcal{D} \subseteq \mathcal{A}$ by definition, so $\mathcal{A} = \mathcal{D}$. We conclude that X is measurable.

3.1.4 Examples

If $\mathcal{F} = \mathcal{B}(\mathbb{R}^n)$, $\mathcal{A} = \mathcal{B}(\mathbb{R}^d)$ and X is continuous, then X is measurable. It is a standard fact that continuous functions map open sets to open sets, and the preimage of an open set is open. Thus, let \mathcal{G}_n be the open sets of \mathbb{R}^n and \mathcal{G}_d be the open sets of \mathbb{R}^d . Clearly, by this fact, for each $E \in \mathcal{G}_d$, $X^{-1}(E) \in \mathcal{G}_n$. And since \mathcal{G}_d generates $\mathcal{B}(\mathbb{R}^d)$, by theorem 3.1.1, X is measurable.

3.1.5 Properties

Theorem 3.1.2. If $X:(\Omega,\mathcal{F})\to (\mathcal{X},\mathcal{A})$ and $Y:(\mathcal{X},\mathcal{A})\to (\mathcal{Y},\mathcal{B})$, then $Y\circ X:\Omega\to\mathcal{Y}$ is \mathcal{F}/\mathcal{B} measurable.

Proof. This is perfectly straightforward to check using the definitions.

Theorem 3.1.3. If $X, Y \in \mathcal{M}(\Omega, \mathcal{F})$ are both bounded and measurable, then so is X + Y and XY

Proof. First, define T = X + Y. First, observe for any interval (a, b),

$$T^{-1}(a,b) = \{\omega: X(\omega) + Y(\omega) > a\} \cap \{\omega: X(\omega) + Y(\omega) < b\}$$
 Note that,

$$\{\omega : X(\omega) + Y(\omega) > a\} = \bigcup_{q \in \mathbb{Q}} \{\omega : X(\omega) > q\} \cap \{\omega : Y(\omega) > a - q\}$$
$$= \bigcup_{q \in \mathbb{Q}} X^{-1}(q, \infty) \cap Y^{-1}(a - q, \infty)$$

Note that $X^{-1}(q, \infty) \in \mathcal{F}, Y^{-1}(a-q, \infty) \in \mathcal{F}$ by measurability. And by closure properties of σ algebras, the above is in \mathcal{F} . Likewise, $\{\omega : X(\omega) + Y(\omega) < b\} \in \mathcal{F}$. Again, by closure under intersection, $T^{-1}(a,b) \in \mathcal{F}$. Since the open intervals generate $\mathcal{B}(\mathbb{R})$, this is sufficient for measurability by theorem 3.1.1.

Now, we show XY is measurable in a somewhat similar fashion. We proceed like so:

- Consider the map $T(\omega) = (X(\omega), Y(\omega))$ and $\psi(u, v) = uv$. Note $XY = \psi \circ T$.
- As $\{A \times B : A \in \mathcal{B}(\mathbb{R}), B \in \mathcal{B}(\mathbb{R})\}$ generates $\mathcal{B}(\mathbb{R}^2)$, and X and Y are measurable, T is measurable. Why? Because, for $A, B \in \mathcal{B}(\mathbb{R})$,

$$T^{-1}(A \times B) = \underbrace{X^{-1}(A)}_{\in \mathcal{F}} \cap \underbrace{Y^{-1}(B)}_{\in \mathcal{F}} \in \mathcal{F}$$

So by theorem 3.1.1, this is sufficient to say that T is measurable.

- As $\psi: \mathbb{R}^2 \to \mathbb{R}$ is continuous, it is measurable
- \bullet Thus, XY can be regarded as the composition of measurable functions, so it is measurable.

Theorem 3.1.4. If X_1, X_2 .. is a sequence of measurable functions, then $X = \sup_i X_i$ is measurable.

Proof. Note intervals of the form (a, ∞) generate $\mathcal{B}(\mathbb{R})$. Furthermore,

$$X^{-1}(a, \infty) = \{\omega : X(\omega) > a\} = \bigcup_{i=1}^{n} X_i^{-1}(a, \infty)$$

Thus, $X^{-1}(a, \infty) \in \mathcal{F}$. Since these generate $\mathcal{B}(\mathbb{R})$, we are done.

Theorem 3.1.5. If X_1, X_2 . is a sequence of measurable functions, then $X = \inf_i X_i$ is measurable.

Proof. The proof is analogous.

Proposition 11. The lim sup and lim inf of measurable functions is measurable.

Proof. We will show the proof for the \limsup case as the \liminf case is analogous. Recall if $X_1, X_2...$ are measurable functions, then if $X = \limsup_i X_i$,

$$X(\omega) = \inf_{n} \sup_{m \geqslant n} X_i(\omega)$$

As $\sup_{m \geqslant n} X_i(\omega)$ is measurable for each n, and the infimum of measurable functions is measurable, X is measurable.

3.2 The Integral

We will now develop the notion of integrals of functions, from the ground up. First, we begin with a measure space $(\Omega, \mathcal{F}, \mu)$. Think of integrals as functionals: maps from the space of measurable functions to \mathbb{R} . While notation varies, we will adopt two ways of denoting the integral of a function X with respect to a measure μ :

$$\int X d\mu$$
 and $\mu(X)$

While the $d\mu$ does relate to the dx from Riemannian integration, ignore this for now. Think of the $d\mu$ merely as a symbol which says we are integrating with respect to μ , rather than some other measure. When $\mu = \lambda$, λ is assumed to be the measure / integral corresponding to the Lebesgue measure.

3.2.1 Simple Functions

A simple function will be of the form,

$$X(\omega) = \sum_{i=1}^{n} \alpha_i \mathbb{I}\{A_i\}$$

Where each $\alpha_i \ge 0$ and $A_i \in \mathcal{F}$. For such an X, we will define its integral like so:

$$\int X d\mu = \sum_{i=1}^{n} \alpha_i \mu(A_i)$$

If $\mu(A_i) = \infty$, $\alpha_i = 0$, adopt the convention that $\alpha_i \mu(A_i) = 0$ — this is the natural thing to do, as we don't want our integral to depend on sets which don't contribute to our function. It remains to verify consistency.

Proposition 12. Suppose that X can be written as $X = \sum_{j=1}^{m} \beta_{j} \mathbb{I}\{B_{j}\} = \sum_{i=1}^{n} \alpha_{i} \mathbb{I}\{A_{i}\}$. Then, $\sum_{i=1}^{n} \alpha_{i} \mu(A_{i}) = \sum_{j=1}^{m} \beta_{j} \mu(B_{j})$. And so, the integral of a simple function is a well-defined object.

Proof. Assume without loss of generality that $\bigcup_{j=1}^m B_j = \bigcup_{i=1}^n = A_i$. Otherwise, we could simply consider $\sum_{i=1}^n \alpha_i \mathbb{I}\{A_i\} + 0 \cdot \mathbb{I}\{\Omega - \bigcup_{i=1}^n A_i\}$ without changing X or its integral. Furthermore, assume without loss of generality that the A_i 's are disjoint, as are the B_j 's. Let $\gamma_{i,j} = X(\omega)$ for $\omega \in A_i \cap B_j$. First, note that X can be written as:

$$X = \sum_{i=1}^{n} \sum_{j=1}^{m} \alpha_{i} \mathbb{I}\{A_{i} \cap B_{j}\} = \sum_{j=1}^{m} \sum_{i=1}^{n} \beta_{j} \mathbb{I}\{B_{j} \cap A_{i}\} = \sum_{i=1}^{n} \sum_{j=1}^{m} \gamma_{i,j} \mathbb{I}\{A_{i} \cap B_{j}\}$$

Note for fixed $i, \gamma_{i,j} = \alpha_i$. For fixed $j, \gamma_{i,j} = \beta_j$. And so,

$$\sum_{i=1}^{n} \alpha_{i} \mu(A_{i}) = \sum_{i=1}^{n} \sum_{j=1}^{m} \alpha_{i} \mu(A_{i} \cap B_{j})$$

$$= \sum_{i=1}^{n} \sum_{j=1}^{m} \gamma_{i,j} \mu(A_{i} \cap B_{j}) = \sum_{j=1}^{m} \sum_{i=1}^{n} \gamma_{i,j} \mu(A_{i} \cap B_{j})$$

$$= \sum_{j=1}^{m} \sum_{i=1}^{n} \beta_{j} \mu(A_{i} \cap B_{j}) = \sum_{j=1}^{m} \beta_{j} \mu(B_{j})$$

3.2.2 Properties of Integrals of Simple Functions

Proposition 13. $\int \alpha X + \beta Y d\mu = \alpha \int X d\mu + \beta \int Y d\mu$. Thus, the integral is a linear functional.

Proof. Let,

$$X = \sum_{i=1}^{n} \alpha_{i} \mathbb{I}\{A_{i}\}, Y = \sum_{j=1}^{m} \beta_{j} \mathbb{I}\{B_{j}\}$$

Again, assume without loss of generality that the A_i 's are pairwise disjoint and span Ω . Then,

$$\alpha X + \beta Y = \sum_{i=1}^{n} \sum_{j=1}^{m} (\alpha \alpha_i + \beta \beta_j) \mathbb{I} \{ A_i \cap B_j \}$$

Thus,

$$\int \alpha X + \beta Y d\mu = \sum_{i=1}^{n} \sum_{j=1}^{m} (\alpha \alpha_i + \beta \beta_j) \mu(A_i \cap B_j)$$

$$= \sum_{i=1}^{n} \sum_{j=1}^{m} \alpha \alpha_{i} \mu(A_{i} \cap B_{j}) + \sum_{j=1}^{m} \sum_{i=1}^{n} \beta \beta_{j} \mu(A_{i} \cap B_{j})$$
$$= \alpha \sum_{i=1}^{n} \alpha_{i} \mu(A_{i}) + \beta \sum_{j=1}^{m} \beta_{j} \mu(B_{j}) = \alpha \int X d\mu + \beta \int Y d\mu$$

3.2.3 Extension to All Measurable Functions

For a general measurable function $X \in \mathcal{M}^+(\Omega, \mathcal{F})$, we define its integral to be the highest among those simple functions which are less than X:

$$\int X d\mu = \sup_{s_n \leqslant X \text{ simple}} \int s_n d\mu$$

Theorem 3.2.1 (This Integral is Nice). Suppose X and Y are measurable functions. Then,

- 1. $\int \alpha X + \beta Y d\mu = \alpha \int X d\mu + \beta \int Y d\mu$
- 2. If X = Y almost everywhere, then $\int X d\mu = \int Y d\mu$.
- 3. If $X \leq Y$ almost everywhere, then $\int X d\mu \leq \int Y d\mu$

Proof. **Proof of 1**: Let x_n, y_n be simple functions such that $\int X d\mu < \int x_n d\mu + 1/(2\alpha n)$, $\int Y d\mu < \int y_n d\mu + 1/(2\beta n)$. Then, note $\alpha X + \beta Y \ge \alpha x_n + \beta y_n$. So,

$$\int \alpha X + \beta Y d\mu \le \int \alpha x_n + \beta y_n d\mu = \alpha \int x_n d\mu + \beta \int y_n d\mu$$
$$\le \alpha \left(\int X d\mu + 1/(2\alpha n) \right) + \beta \left(\int Y d\mu + 1/(2\beta n) \right)$$
$$= \alpha \int X d\mu + \beta \int Y d\mu + 1/n$$

Taking $n \to \infty$, we have $\int \alpha X + \beta Y d\mu \leq \alpha \int X d\mu + \beta \int Y d\mu$. For the reverse inequality,

$$\int \alpha X + \beta Y d\mu = \sup_{n} \left\{ \int z_n d\mu : z_n \leqslant \alpha X + \beta Y \right\}$$

$$\geqslant \sup_{n} \left\{ \int \alpha x_n + \beta y_n d\mu : x_n \leqslant X, y_n \leqslant Y \right\}$$

Since x_n, y_n can vary freely,

$$= \alpha \sup_{n} \left\{ \int x_n d\mu : x_n \leqslant X \right\} + \beta \sup_{n} \left\{ \int y_n d\mu : y_n \leqslant Y \right\}$$

$$= \alpha \int X d\mu + \beta \int Y d\mu$$

Which gives the other side of the inequality. So we are done.

Proof of 2: Let $N = \{\omega : X(\omega) \neq Y(\omega)\}$. By assumption, $\mu(N) = 0$, so N is negligible. Let $\tilde{X} = X\mathbb{I}\{N^c\}$. We show that $\int X d\mu = \int \tilde{X} d\mu$. It then follows from symmetry and the fact that $\tilde{Y} = \tilde{X}$ that the desired result is true. Note for any simple function $x = \sum_{i=1}^{n} \alpha_i \mathbb{I}\{A_i\}$,

$$\int x d\mu = \sum_{i=1}^{n} \alpha_i \mu(A_i) = \sum_{i=1}^{n} \alpha_i \mu(A_i \cap N^c) = \int x \mathbb{I}\{N^c\} d\mu$$

Thus, taking supremums,

$$\int X d\mu = \sup \left\{ \int x d\mu : x \leqslant X \right\} = \sup \left\{ \int x \mathbb{I}\{N^c\} d\mu : x \leqslant X \right\}$$
$$= \sup \left\{ \int x d\mu : x \leqslant X \mathbb{I}\{N^c\} \right\} = \int X \tilde{d}\mu$$

And thus,

$$\int X d\mu = \int \tilde{X} d\mu = \int \tilde{Y} d\mu = \int Y d\mu$$

Proof of 3: First, suppose $X \leq Y$ everywhere. The property will hold by definition of supremum. Note since $X \leq Y$,

$$\int X d\mu = \sup \left\{ \int x : x \leqslant X \right\} \leqslant \sup \left\{ \int x : x \leqslant Y \right\} = \int Y d\mu$$

Now, if X > Y on a negligible set N. Consider, $\tilde{X} = X\mathbb{I}\{N^c\}$. Then $\int \tilde{X} d\mu = \int X d\mu$ by property 2. And $\int \tilde{X} d\mu \leqslant \int Y d\mu$ by our earlier work, so we are done!

Definition 15 (Convergence Definitions). We use the following conventions from here on:

- Numbers: Say $a_1, a_2... \uparrow a$ if $a_1 \leq a_2...$ and $\lim_{n\to\infty} a_n = a$
- Sets: Say $A_1, A_2 \uparrow A$ if $A_1 \subseteq A_2 \subseteq A_3...$ and $\bigcup_{i=1}^{\infty} A_i = A$
- Sets: Say $A_1, A_2 \downarrow A$ if $A_1 \supseteq A_2 \supseteq A_3...$ and $\bigcap_{i=1}^{\infty} A_i = A$
- Functions: Say $X_n \uparrow X$ if $X_n \leqslant X_{n+1}$ for all n and $X_n \to X$ pointwise

The monotone convergence theorem is a fundamental result in the theory of integration. To prove it, we will use the so called continuity of a measure:

Theorem 3.2.2. If $A_n \downarrow \emptyset$ with at least one $\mu(A_i) < \infty$, then $\mu(A_n) \downarrow 0$. Also, if $A_n \uparrow A$, then $\mu(A_n) \uparrow \mu(A)$.

Proof. Assume WLOG that $\mu(A_1) < \infty$. Let $B_1 = A_1 \setminus A_2$, $B_2 = A_2 \setminus A_3$, and so on: $B_i = A_{i-1} \setminus A_i$. It's clear that $\cup_i B_i = A_1$. Thus, by countable additivity,

$$\mu(A_1) = \sum_{i=1}^{\infty} \mu(B_i)$$

On the other hand,

$$\mu(A_1) = \sum_{i=1}^{n} \mu(B_i) + \sum_{i=n+1}^{\infty} \mu(B_i) = \sum_{i=1}^{n} \mu(B_i) + \mu(A_n)$$

Taking $n \to \infty$, it must be that $\sum_{i=1}^{n} \mu(B_i) \to \mu(A_1)$. And thus, for equality to hold, $\mu(A_n) \downarrow 0$. The proof of the second statement works in much the same way.

Theorem 3.2.3 (The Monotone Convergence Theorem). If $X_n \uparrow X$ pointwise almost everywhere, then X is measurable and $\int X_n d\mu \uparrow \int X d\mu$

Proof. First, assume without loss of generality that $X_n \uparrow X$ everywhere, as theorem 3.2.1 would readily imply the desired result. Also, the measurability of X has already been proven, as it is the sup of measurable functions. Furthemore, for any n, $\int X_n d\mu \leqslant \int X d\mu$ as $X_n \leqslant X$. So taking $n \to \infty$, we find $\lim_n \int X_n d\mu \leqslant \int X d\mu$. It remains to show that $\lim_n \int X_n d\mu \geqslant \int X d\mu$. Indeed, let X_m be a sequence of simple functions such that $\int X_m d\mu > (\int X d\mu) - 1/m$. Now define $X_{n,m} = X_m(1 - \frac{1}{m})\mathbb{I}\{X_n \geqslant X_m(1 - \frac{1}{m})\}$. Note that $X_{n,m}$ is simple, and $X_{n,m} \leqslant X_n$. And thus,

$$\int X_{n,m} d\mu \leqslant \int X_n d\mu$$

Now write that $X_m = \sum_{i=1}^{n_m} \alpha_{i,m} \mathbb{I}\{A_{i,m}\}$ so that $X_{n,m} = (1 - \frac{1}{m}) \sum_{i=1}^{n_m} \alpha_{i,m} \mathbb{I}\{A_{i,m} \cap \{X_n \ge (1 - \frac{1}{m}X_m)\}\}$. Thus,

$$\int X_n d\mu \ge (1 - \frac{1}{m}) \sum_{i=1}^{n_m} \alpha_{i,m} \mu(\{A_{i,m} \cap \{X_n \ge (1 - \frac{1}{m} X_m)\}\})$$

Taking $n \to \infty$, the continuity of measures implies that $A_{i,m} \cap \{X_n \ge (1 - \frac{1}{m}X_m)\} \uparrow A_{i,m}$. Thus,

$$\lim_{n \to \infty} \int X_n d\mu \ge (1 - \frac{1}{m}) \int X_m d\mu \ge (1 - \frac{1}{m}) \left(\int X d\mu - \frac{1}{m} \right)$$

Taking $m \to \infty$, we are done!

3.2.4 Integrals of More General Functions

Our last iteration of building the integral is that for possibly negative functions. For $X \in \mathcal{M}(\Omega, \mathcal{F})$, let $X^+ = X\mathbb{I}\{X \ge 0\}$ and $X^- = |X|\mathbb{I}\{X \le 0\}$. It follows that $X = X^+ - X^-$. If at least one of $\int X^+ d\mu$, $\int X^- d\mu$ is finite, we define $\int X d\mu = \int X^+ d\mu - \int X^- d\mu$. Otherwise, the integral is not defined. If the quantity is finite, the function is said to be integrable. One can easily verify the same niceness properties as before by splitting arbitrary functions into their positive and negative parts.

3.2.5 Riemann Integration is a Special Case of Lebesgue

One of the nice properties of Lebesgue integration is that, if $f: \mathbb{R} \to \mathbb{R}$ is Riemann integrable, then it is Lebesgue integrable. That is, $\int_{\mathbb{R}} f(x)dx = \lambda(f)$. This follows as a simple consequence of the monotone convergence property.

Theorem 3.2.4. Let $f: \mathbb{R} \to \mathbb{R}$ be Riemann integrable and $\int_{\mathbb{R}} f(x)dx$ be its Riemannian integral, and $\lambda(f)$ be its integral with respect to the Lebesgue measure. Then $\int_{\mathbb{R}} f(x)dx = \lambda(f)$.

Proof. Recall, by the definition of Riemann integration, that if we let Π be the set of partitions of \mathbb{R} into finitely many intervals,

$$L(f) = \sup_{\pi \in \Pi} \left\{ \sum_{I = (a,b] \in \pi} (b-a) \inf_{a < x < b} f(x) \right\}$$

$$U(f) = \inf_{\pi \in \Pi} \left\{ \sum_{I=(a,b] \in \pi} (b-a) \sup_{a < x < b} f(x) \right\}$$

And if L(f) = U(f), then $\int_{\mathbb{R}} f(x)dx = L(f) = U(f)$. To show equality, we will apply the monotone convergence theorem to $f^+ = |f|\mathbb{I}\{f(x) \ge 0\}$ and $f^- = |f|\mathbb{I}\{f(x) \le 0$. Recall that if f is Riemann integrable, then f^+ and f^- are Riemann integrable as well. Furthermore, observe that for some fixed $\pi \in \Pi$, if we define,

$$s_{\pi} = \sum_{I=(a,b] \in \pi} \mathbb{I}\{x \in I\} \inf_{a < x < b} f^{+}(x)$$

Then we recognize that,

$$\lambda(s_{\pi}) = \sum_{I=(a,b] \in \pi} \lambda((a,b]) \inf_{a < x < b} f(x) = \sum_{I=(a,b] \in \pi} (b-a) \inf_{a < x < b} f(x)$$

Now, let $\{\pi_n\}_n$ such that $\lambda(s_\pi) \uparrow \int f(x) dx$. Furthermore, assume without loss of generality that for $m \leq n$, any $I \in \pi_m$ can be written as the union of intervals of π_n , i.e. that π_n just refines the intervals already in π_m . It therefore follows that $s_{\pi_m} \leq s_{\pi_n}$. Furthermore, $\lambda(s_{\pi_n}) \uparrow \int f^+(x) dx$, by assumption. Furthermore, by the monotone convergence theorem, $\lambda(s_{\pi_n}) \uparrow \lambda(f^+)$. And therefore, $\int f(x) dx = \lambda(f^+)$. A similar argument yields that $\lambda(f^-) = \int f^-(x) dx$. And therefore, $\lambda(f) = \lambda(f^+(x) - f^-(x)) = \lambda(f^+) - \lambda(f^-) = \int f^+(x) dx - \int f^-(x) dx = \int f(x) dx$.

3.3 Limit Theorems

3.3.1 Fatou's Lemma

Fatou's Lemma is a relatively simple theorem to prove which will allow us to prove many limit results down the road.

Lemma 3.3.1 (Fatou's Lemma). For $\{X_n\}_n \in \mathcal{M}^+(\Omega, \mathcal{F})$, $\int \liminf_n X_n d\mu \leq \liminf \int X_n d\mu$.

Proof. First, to remember this inequality, think of the liminf of a function as containing many more degrees of freedom than the liminf of the integral, and thus we are lower. Note first that, for all n, $\inf_n X_n \leq X_n$. Define $Y_m = \inf_{n \geq m} X_n$. The monotone convergence theorem implies,

$$\lim_{m \to \infty} \int Y_m = \int \sup Y_m$$

And thus, substituting our definitions,

$$\lim_{m\to\infty}\int\inf_{n\geqslant m}X_nd\mu=\int\sup_{m}\inf_{n\geqslant m}X_n=\int\liminf_{n}X_nd\mu$$

Note also that for all $m, Y_m \leq X_m$. Thus,

$$\lim\inf_{m} \int Y_m d\mu \leqslant \lim\inf_{m} \int X_m d\mu$$

But when a limit exists, it is equal to the liminf, so,

$$\int \liminf_{n} X_{n} d\mu = \lim \inf_{m} \int Y_{m} d\mu \leqslant \lim \inf_{m} \int X_{m} d\mu$$

And we're done!

3.3.2 The Dominated Convergence Theorem

Next comes one of the most important results yet! It comes up time and time again and is arguably the most general tool or interchanging limits.

Theorem 3.3.2 (The Dominated Convergence Theorem). Let X_n converge pointwise to a function X almost everywhere. Assume $|X_n| \leq Y$ for some integrable function Y. Then $\lim_n \int X_n d\mu = \int X d\mu$.

Proof. As Y is integrable, each X_n is integrable. Furthermore, $Y - X_n, Y + X_n$ are integrable and nonnegative, by the tringle inequality. Therefore,

$$\int \liminf_{n} (Y - X_n) d\mu \le \liminf_{n} \int (Y - X_n) d\mu$$
$$\int \liminf_{n} (Y + X_n) d\mu \le \liminf_{n} \int (Y + X_n) d\mu$$

By linearity of the integral and the liminf, this implies,

$$\int \liminf_{n} (-X_n) d\mu \le \liminf_{n} \left(-\int X_n d\mu \right)$$
$$\int \liminf_{n} X_n d\mu \le \liminf_{n} \int X_n d\mu$$

Note the first line is equivalent to,

$$\int \lim \sup_{n} X_n d\mu \geqslant \lim \sup_{n} \int X_n d\mu$$

But we assumed that X_n converges, so $\liminf_n X_n = \limsup_n X_n = X$. Combining, we obtain,

$$\limsup_{n} \int_{n} X_{n} d\mu \leqslant \int X d\mu \leqslant \liminf_{n} \int X_{n} d\mu$$

But obviously, $\limsup_n \int_n X_n \ge \liminf_n \int_n X_n$. This forces their equality, and thus the assertion follows as claimed.

3.3.3 Application: Differentiation Under the Integral

Oftentimes, you will see something of the essence of:

$$\frac{\partial}{\partial t} \int f(x,t) dx = \int \frac{\partial}{\partial t} f(x,t) dx$$

How could this be true? It could be easily understood as an application of the dominated convergence theorem. Indeed, consider for some n,

$$X_{n,t}(x) = n(f(x,t+1/n) - f(x,t))$$

It is clear to see that, for fixed x, $\lim_{n\to\infty} X_n(x,t) = \frac{\partial}{\partial t} f(x,t)$. Thus, the tempting interchange of limits is:

$$\int \frac{\partial}{\partial t} f(x,t) dx = \int \lim_{n} X_{n,t} dx = \lim_{n} \int X_{n,t} dx = \lim_{n} \int X_{n,t} dx$$
$$= \lim_{n} n \left(\int f(x,t+1/n) dx - \int f(x,t) dx \right) = \frac{\partial}{\partial t} \int f(x,t) dx$$

How do we make this rigorous? Well first obesrve that, in a way, this is a claim about differentiation at each t. So fix t. For dominated convergence, we require that $X_{n,t}$ be dominated by an integrable function $Y_t(x)$, where this function is allowed to depend on t, (but not on n— so there is some dependence on t). If f is continuously differentiable with respect to t, it suffices to bound $\frac{\partial}{\partial t} f(x,t)$ at t, since then this can be extended to a more local bound. Of course, nothing is stopping us from collecting our bounding functions into a function of two variables. Summarizing our analysis into a theorem, we have:

Theorem 3.3.3. Let $f(x,t): \mathbb{R}^2 \to \mathbb{R}$ be a function which is continuous differentiable in an open set with respect to t. Suppose there exists a function F(x,t) which is integrable for fixed x and $|\frac{\partial}{\partial t}f(x,t)| \leqslant F(x,t)$. Then, $\frac{\partial}{\partial t}\int f(x,t)dx = \int \frac{\partial}{\partial t}f(x,t)dx$ for all t.

3.3.4 Integrating over Negligible Sets

This is a fact which will get used over and over again. Let $X \in \mathcal{M}(\Omega, \mathcal{F})$ be a measurable and integrable random variable. We will show the integral of X, restricted to smaller and smaller sets, must go to zero. First, as a matter of notation, for any set $A \in \mathcal{F}$, define,

$$\int_{A} X d\mu = \int X \mathbb{I}\{A\} d\mu$$

Theorem 3.3.4. Let $X \in \mathcal{M}^+(\Omega, \mathcal{F})$ have $\int |X| d\mu < \infty$ and suppose $\{B_n\}_n \in \mathcal{F}$ with $B_n \downarrow \emptyset$. Then, $\int_{B_n} X d\mu \to 0$

Proof. Define $C_0 = B_1^c$, $C_1 = B_1 \backslash B_2$, $C_2 = B_2 \backslash B_3$, etc. Observe that the C_n 's are disjoint and span Ω . Then, by the monotone convergence property,

$$\int |X| d\mu = \int |X| \sum_{n=0}^{\infty} \mathbb{I}\{C_n\} d\mu = \sum_{n=0}^{\infty} \int |X| \mathbb{I}\{C_n\} d\mu = \sum_{n=0}^{\infty} \int_{C_n} |X| d\mu$$

As these must all be finite, by integrability of |X|, it follows that $\lim_{m\to\infty}\sum_{n=m}^{\infty}\int_{C_n}|X|d\mu\to 0$. However, for m>0, $\sum_{n=m}^{\infty}\int_{C_n}|X|d\mu=\int_{B_m}|X|d\mu$, also by the monotone convergence property. Observe, from the proof, that the same would hold if $X\mathbb{I}\{B_n\}$ were integrable for any finite n.

To illustrate that integrability is necessary, we could consider, for example, the function X=1, the Lebesgue measure on the line μ , and $B_n=\bigcup_{m\in\mathbb{Z}}[2^nm,2^nm+1]$. You might suspect that this is a problem only with nonfinite measures, such as the Lebesgue measure. However, counterexamples exist for probability measures as well. For example, letting $X(\omega)=1/f(\omega)$, where f is the density function of the distribution \mathbb{P} with respect to the Lebesgue measure (see chapter 4 for greater explanation), then $\mathbb{P}(XB_n)=\lambda(f(\omega)1/f(\omega)B_n)=\lambda(B_n)=\infty$.

3.4 The Borel Cantelli Lemma

This is a bit of an aside about a probabilistic technique that will come up often. It works very simply.

Definition 16. As a matter of notation, for a countable family of sets $A_1, A_2...$, define,

$$\{A_n \ i.o.\} = \bigcap_{n=1}^{\infty} \bigcup_{m=n}^{\infty} A_m = \{\omega : \omega \ in \ infinitely \ many \ A_n\}$$

This set can be understood as those events which occur "infinitely" often in the sequence A_1, A_2 ..

Lemma 3.4.1 (The Borel Cantelli Lemma (Part 1)). Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a probability space. Then if $\sum_{n=1}^{\infty} \mathbb{P}(A_n) < \infty$, $\mathbb{P}(\{A_n \ i.o.\}) = 0$.

Proof. Note if $\sum_n \mathbb{P}(A_n) < \infty$, then $\mathbb{P}(A_n) \to 0$. Additionally, $\lim_n \sum_{m=n}^{\infty} \mathbb{P}(A_m) \to 0$. And thus, for any n,

$$\mathbb{P}\{A_n \ i.o.\} \leqslant \mathbb{P}\{\bigcup_{m=n}^{\infty} A_m\} \leqslant \sum_{m=n}^{\infty} \mathbb{P}(A_m)$$

Taking $n \to \infty$, the right hand side becomes 0. This proves part 1 of the lemma. We will be able to prove a converse in a Part 2 once we introduce notions of independence.

3.5 Special Case: Expectations

When $\mu = \mathbb{P}$ is a probability measure, the corresponding integral corresponds to an expectation. In this, we write,

$$\int X d\mathbb{P} = \mathbb{E}[X]$$

We will typically adopt the latter when the measure is unambiguous.

3.5.1 Important Inequalities: Markov's Inequality, Chebyshev's Inequality, & Chernoff Bounds

Theorem 3.5.1 (Markov's Inequality). Let X be nonnegative almost everywhere and integrable. Then,

$$\mathbb{P}(\{X > a\}) \leqslant \frac{\mathbb{E}[X]}{a}$$

Proof. The inequality follows from monotonicity and rearranging the following:

$$\mathbb{E}[X] = \mathbb{E}[X\mathbb{I}\{X \leqslant a\}] + \mathbb{E}[X\mathbb{I}\{X < a\}] \geqslant 0 + a\mathbb{P}(\{X > a\})$$

Recall that the variance of a random variable is defined as $\operatorname{Var}(X) = \mathbb{E}[(X - \mathbb{E}[X])^2]$.

Corollary 3.5.1.1 (Chebyshev's Inequality). Let X have finite variance σ^2 . Then,

$$\mathbb{P}(\{|X - \mathbb{E}[X]| > k\sigma\}) \leqslant \frac{1}{k^2}$$

Proof. Define $Z=\frac{(X-\mathbb{E}[X])^2}{\sigma^2}$. Observe $\mathbb{E}[Z]=1$. By Markov's Inequality, $\mathbb{P}(\{|X-\mathbb{E}[X]|>k\sigma\})=\mathbb{P}(\{Z>k^2\})\leqslant \frac{\mathbb{E}[Z]}{k^2}$.

Generically, Chernoff bounds can be thought of as applying Markov's Inequality to e^{tX} . Indeed, the generic Chernoff bound simply states that for a nonnegative random variable X, $\mathbb{P}(\{X \geq a\}) = \mathbb{P}(\{e^{tX} \geq e^{ta}\}) \leq \mathbb{E}[e^{tX}]/e^{ta}$. Once we introduce independence, we will show that Chernoff bounds can be used to prove Hoeffding's Inequality.

3.6 Convexity

3.6.1 Convex Combinations

Recall that a convex function $f: U \to V$, where $U, V \subseteq \mathbb{R}$, has the property that for all $x, y \in U, \lambda \in [0, 1]$,

$$f(\lambda x + (1 - \lambda)y) \le \lambda f(x) + (1 - \lambda)f(y)$$

Note that λ and $1 - \lambda$ provide a so called *convex combination* of numbers. In general, $a_1, a_2...a_n$ is called a convex combination if $a_i > 0$ for all i and $\sum_{i=1}^{n} a_i = 1$. One can easily verify that the above relation holds for more general convex combinations:

Lemma 3.6.1. Let $a_1..a_n$ be a convex combination with $x_1, x_2...x_n \in U$. Then, $f(\sum_{i=1}^n a_i x_i) \leq \sum_{i=1}^n a_i f(x_i)$.

Proof. We proceed by induction. The n=2 case is the direct definition of convexity. Now suppose the n-1 case is true. First, suppose $0 < a_n < 1$; otherwise, the inductive step is trivial. We have,

$$f(\sum_{i=1}^{n} a_i x_i) = f(\sum_{i=1}^{n-1} a_i x_i + a_n x_n)$$

$$= f((1 - a_n) \sum_{i=1}^{n-1} \frac{a_i}{1 - a_n} x_i + a_n x_n)$$

We recognize a_n and $1 - a_n$ as a convex combination, and so,

$$\leq a_n f(x_n) + (1 - a_n) f(\sum_{i=1}^{n-1} \frac{a_i}{1 - a_n} x_i)$$

We now recognize $\frac{a_1}{1-a_n}...\frac{a_{n-1}}{1-a_n}$ as a convex combination. And so,

$$\leq a_n f(x_n) + (1 - a_n) \sum_{i=1}^{n-1} \frac{a_i}{1 - a_n} f(x_i) = \sum_{i=1}^n a_i f(x_i)$$

This proves the lemma.

Corollary 3.6.1.1. If $a_1...a_n$ is a convex combination and $x_1...x_n > 0$, then,

$$\log(a_1x_1 + ...a_nx_n) \ge a_1\log(x_1) + ... + a_n\log(x_n)$$

Proof. This follows from the convexity of $-\log$.

Another fact about convex functions, which we will not prove, is that they are continuous.

3.6.2 Jensen's Inequality

Note that there is some sense in which a probability distribution provides a sort of generalized convex combination. From the above, it follows that if X is a discrete random variable with state space $\Omega = \{x_1...x_n\}$, then:

$$\mathbb{E}[f(X)] = \sum_{i=1}^{n} f(x_i) \mathbb{P}\{X = x_i\}$$

$$f(\mathbb{E}(X)) = f\left(\sum_{i=1}^{n} x_i \mathbb{P}\{X = x_i\}\right)$$

Note that we recognize $\mathbb{P}\{X=x_1\}...\mathbb{P}\{X=x_n\}$ as a convex combination. And thus,

$$f(\mathbb{E}[X]) \leqslant \mathbb{E}[f(X)]$$

The same is true more generally.

Theorem 3.6.2 (Jensen's Inequality). Let $(\mathbb{R}, \mathcal{B}(\mathbb{R}), \mathbb{P})$ be a probability space and f be a convex function. Then, $f(\mathbb{E}[X]) \leq \mathbb{E}[f(X)]$.

Proof. Bear in mind the finite case provided earlier. Intuiviely, you might imagine that the more general case is true by continuity. But to offer a reasonably concise proof, we will use another property of convex functions. A convex function f has, at each x, a support line ℓ_x such that $\ell_x(x) = f(x)$, and $\ell_x \leq f$ everywhere. So let $x_0 = \mathbb{E}[X]$ and let ℓ be the support line at x_0 . If we let $\ell(x) = ax + b$, it's clear that $\mathbb{E}[\ell(X)] = a\mathbb{E}[X] + b = \ell(x_0)$. But by the decreasing property, $\mathbb{E}[\ell(X)] \leq \mathbb{E}[f(X)]$. Putting this all together, we find,

$$f(\mathbb{E}[X]) = f(x_0) = \ell(x_0) = \mathbb{E}[\ell(X)] \leqslant \mathbb{E}[f(X)]$$

3.6.3 Hölder's Inequality

Conventional proofs of Hölder's Inequality typically rely on Young's Inequality. While these are generally faster, I think they are slightly less intuitive. Let us actually prove a general statement, from which Hölder's Inequality is a corollary.

Theorem 3.6.3. Let $X_1...X_n$ be nonnegative measurable functions and $a_1...a_n$ be a convex combination. Then,

$$\int \left(\prod_{i=1}^{n} X_{i}^{a_{i}} \right) d\mu \leqslant \prod_{i=1}^{n} \left(\int X_{i} d\mu \right)^{a_{i}}$$

Proof. It is simple to check that if $\left(\int X_i d\mu\right) = 0$ or ∞ for any i, then the corresponding inequality is trivial. Otherwise, assume all relevant integrals are finite and nonzero. We will first reduce the inequality to something simpler

$$\int \prod_{i=1}^{n} \left(\frac{X_i}{\int X_i d\mu} \right)^{a_i} d\mu \leqslant 1$$

So define $Y_i = \frac{X_i}{\int X_i d\mu}$. Clearly, each Y_i integrates to 1. It remains to show that $\int \prod_{i=1}^n Y_i^{a_i} d\mu \leq 1$. Indeed, we can check that, by the Corollary 3.6.1.1,

$$\prod_{i=1}^{n} Y_i^{a_i} = \exp\left(\log\left(\prod_{i=1}^{n} Y_i^{a_i}\right)\right) = \exp\left(\sum_{i=1}^{n} a_i \log(Y_i)\right)$$

$$\leq \exp\left(\log\left(\sum_{i=1}^{n} a_i Y_i\right)\right) = \sum_{i=1}^{n} a_i Y_i$$

The above is only rigorous when $\prod_{i=1}^n Y_i^{a_i} > 0$, but the inequality still holds trivially when $\prod_{i=1}^n Y_i^{a_i} = 0$. And so, by monotonicity,

$$\int \prod_{i=1}^{n} Y_{i}^{a_{i}} d\mu \leq \int \sum_{i=1}^{n} a_{i} Y_{i} d\mu = \sum_{i=1}^{n} a_{i} \int Y_{i} d\mu = 1$$

Which completes the proof.

Corollary 3.6.3.1 (Hölder's Inequality). If p, q > 0 s.t 1/p + 1/q = 1, then for all measurable f and g,

$$\int |fg|d\mu \leqslant \bigg(\int |f|^p d\mu\bigg)^{1/p} \bigg(\int |g|^q d\mu\bigg)^{1/q}$$

Proof. Let $X_1 = |f|^p$ and $X_2 = |g|^q$.

Corollary 3.6.3.2 (The Cauchy-Schwarz Inequality). If f and g are measurable, then,

$$\int |fg|d\mu \leqslant \left(\int f^2 d\mu\right)^{1/2} \left(\int g^2 d\mu\right)^{1/2}$$

Proof. Apply Hölder's Inequality with p = q = 2.

3.7 Hilbert Spaces and \mathcal{L}^p Spaces

The theory of Hilbert Spaces is quite general and far-reaching. A Hilbert space can be thought of as a generalization of Euclidean space, which includes the vector space \mathbb{R}^n and the Euclidean dot product. More generally, a Hilbert Space is a vector space \mathcal{H} with an inner product $\langle \cdot, \cdot \rangle$ which induces a complete metric space. Recall an inner product is a map $\mathcal{H} \times \mathcal{H} \to \mathbb{C}$ which satisfies,

- $\bullet \ \langle f,g\rangle = \overline{\langle g,f\rangle}$
- $\langle af_1 + bf_2, g \rangle = a \langle f_1, g \rangle + b \langle f_2, g \rangle$
- $\langle f, f \rangle \geqslant 0$

Where $\bar{\cdot}$ denotes complex conjugation. For our purposes though, we can ignore this distinction. If the inner product is a map to \mathbb{R} , we find it is symmetric and linear in both its arguments. The norm induced by the inner product is: $||f|| = \sqrt{\langle f, f \rangle}$.

3.7.1 The \mathcal{L}^p Spaces

Recall from our study of measurable functions that linear combinations of measurable functions are measurable. It is not hard to see from this that measurable functions constitute a vector space. In this space, we define the norm,

$$||X||_p = \left(\int X^p d\mu\right)^{1/p}$$

We show that this operation does induce a valid norm, and we construct the corresponding Hilbert space. We now prove the triangle inequality, which is a crucial step to verifying that we have a valid norm on our hands. A first step to realize is that, in the language of norms, Hölder's Inequality states that $|XY| \leq |X|_p |Y|_q$.

Theorem 3.7.1 (Minkowski's Inequality). The triangle equality holds in the norm $\|\cdot\|_p$:

$$||X + Y||_p < ||X||_p + ||Y||_p$$

Proof. We proceed in the usual fashion. For now, assume that $0 . The other cases are trivial. First, observe that <math>f(x) = x^p$ is convex for $x \ge 0$. And thus, for any $x, y, |x+y|^p = |\frac{1}{2}(2x) + \frac{1}{2}(2y)|^p \le \frac{1}{2}|2x|^p + \frac{1}{2}|2y|^p = 2^{p-1}(|x|+|y|)$. Note the same will hold true using 1/p.

$$\begin{split} \|X+Y\|_p &= \left(\int |X+Y|^p d\mu\right)^{1/p} \leqslant 2^{\frac{p-1}{p}} \left(\int |X|^p + |Y|^p d\mu\right)^{1/p} \\ &= 2^{1-\frac{1}{p}} \bigg(\|X\|_p^p + \|Y\|_p^p\bigg)^{1/p} \leqslant 2^{1-\frac{1}{p}} \bigg(\frac{1}{2} (2\|X\|_p^p)^{1/p} + \frac{1}{2} (2\|Y\|_p^p)^{1/p}\bigg) \\ &= 2^{1-\frac{1}{p}} \bigg(2^{\frac{1}{p}-1} \|X\|_p + 2^{\frac{1}{p}-1} \|Y\|_p\bigg) = \|X\|_p + \|Y\|_p \end{split}$$

To now address the $p \in \{0, \infty\}$ cases, recall that,

$$||X||_0 = \mu(\{|X| \ge 0\})$$
 $||X||_\infty = \text{ess-sup} |X|$

Where the ess-sup is defined as the smallest supremum of all functions Y equal to X almost everywhere:

$$\operatorname{ess-sup} X = \inf_{Y = X \ a.e.} \sup Y$$

So then, by subadditivity,

$$||X + Y||_0 = \mu(\{|X| \ge 0\} \cup \{|Y| \ge 0\})$$

$$\le \mu(\{|X| \ge 0\}) + \mu(\{|Y| \ge 0\}) = ||X||_0 + ||Y||_0$$

Now for $p = \infty$. Intuiviely, the idea is just that $\max(X + Y) \leq \max(X) + \max(Y)$, but the almost-everywhereness adds some subtleties. Indeed, note that for any X' = X a.e. and Y' = Y almost everywhere, X' + Y' = X + Y almost everywhere. Furthermore, $\sup\{X' + Y'\} \leq \sup\{X'\} + \sup\{Y'\}$. So then,

$$\begin{split} \|X+Y\|_{\infty} &= \inf_{Z=X+Y} \sup_{a.e.} \sup |Z| \leqslant \inf_{X'=X,Y'=Y} \inf_{a.e.} |X'+Y'| \\ &\leqslant \inf_{X'=X} \sup_{a.e.} \sup |X| + \inf_{Y'=Y} \sup_{a.e.} \sup |Y| = \|X\|_{\infty} + \|Y\|_{\infty} \end{split}$$

This proves the claim for all p.

we define the space $\mathcal{L}^p(\Omega, \mathcal{F}, \mu)$ as $\mathcal{L}^p(\Omega, \mathcal{F}, \mu) = \{X \in \mathcal{M}(\Omega, \mathcal{F}) : \|X\|_p < \infty\}$. Note it is possible for $\|X - Y\|_p = 0$ but for $X \neq Y$ everywhere. However, it is necessary and sufficient that X = Y almost everywhere. And thus, we think of $\|\cdot\|_p$ as operating on the equivalence classes of functions, with equivalence if two functions are equivalent almost everywhere. Thus, $\|\cdot\|_p$ is not truly a norm (rather it is a pseudonorm) since $\|X - Y\| = 0$ does not imply X = Y. To make it a norm, we let L^p be the equivalence classes of \mathcal{L}^p .

Theorem 3.7.2. $||X - Y||_p = 0$ if and only if X = Y almost everywhere.

Proof. Let $A=\{X\neq Y\}$. Now let $A_0=\{|X-Y|\geqslant 1/2\}$ and $A_n=\{1/2^n>|X-Y|\geqslant 1/2^{n-1}\}$. It is clear to see that $A=\bigcup_{i=0}^nA_n$ and also that all the A_n 's are disjoint. It therefore follows from countable additivity that $\mu(A)=\sum_{i=1}^n\mu(A_n)$. Then if If $\mu(A)>0$, then there must be some n^\star for which $\mu(A_{n^\star})>0$. Assume for now that $n^\star>0$. It follows that,

$$||X - Y||_p^p = \int_{A_{n^*}} |X - Y|^p d\mu + \int_{A_{n^*}^c} |X - Y|^p d\mu \geqslant \frac{1}{(2^{n^* - 1})^p} \mu(A_{n^*})$$

(Here, we use the notation that $\int_C X d\mu = \int X \mathbb{I}\{C\} d\mu$). The above expression is obviously nonzero. If $n^* = 0$, a similar analysis holds. Thus, it must be that $\mu(A) = 0$. This shows the "only if". For the "if", we have,

$$\|X - Y\|_p^p = \int |X - Y|^p d\mu = \int_A |X - Y|^p d\mu + \int_{A^c} |X - Y|^p d\mu$$

 $\int_A |X-Y|^p d\mu = 0$ because A is negligible. $\int_{A^c} |X-Y|^p d\mu = 0$ because X=Y everywhere in A^c . Thus the above is entirely nonzero.

From the above, it's clear that $\|\cdot\|_p$ is a valid norm acting on L^p . In order to verify that L^p is a Hilbert space, it is necessary to verify that $\|\cdot\|_p$ induces a complete metric.

Theorem 3.7.3. L^p is complete.

Proof. Recall a space is complete if Cauchy sequences converge to a limit function. So let $X_1, X_2...$ be a Cauchy sequence. Here's a first step. Let n_k be a sequence of numbers such that for $n, m \ge n_k, \|X_n - X_m\|_p < 1/2^k$. It then follows that $\{X_{n_k}\}_k$ is a Cauchy sequence and $\sum_{k=1}^{\infty} \|X_{n_{k+1}} - X_{n_k}\|_p \le 1$. Now, define $Y_k = \inf_{m \le k} X_{n_m}$.

Proposition 14. $\liminf_k X_{n_k} = \limsup_k X_{n_k}$

Proof. Define $L_{i,j} = \inf_{i \leq k \leq j} X_{n_k}$. First observe that,

$$\begin{split} \|X_{n_i} - L_{i,j}\|_p &= \left\| (X_{n_i} - Y_{i,j}) \sum_{k=i}^j \mathbb{I}\{Y_{i,j} = X_{n_k}\} \right\|_p \\ &\leq \sum_{m=i}^k \left\| (X_{n_i} - Y_{i,j}) \mathbb{I}\{Y_{i,j} = X_{n_k}\} \right\|_p \leqslant \sum_{m=i}^k \|X_{n_i} - X_{n_k}\|_p < \sum_{k=i}^j \frac{1}{2^i} \leqslant 2^{i-1} \end{split}$$

Now, taking $j \to \infty$, we find $Y_{i,j} \to \inf_{k>i} X_{n_k}$ and thus $\|X_{n_i} - \inf_{k>iX_{n_k}}\|_p \leqslant 2^{i-1}$. A similar argument yields $\|X_{n_i} - \sup_{k>iX_{n_k}}\|_p \leqslant \frac{1}{2^{i-1}}$. It follows that,

$$\begin{split} &\| \lim \inf_{k \geqslant i} X_{n_k} - \lim \sup_{k \geqslant i} X_{n_k} \|_p \leqslant \| \inf_{k \geqslant i} X_{n_k} - \sup_{k \geqslant i} X_{n_k} \|_p \\ & \leqslant \| \inf_{k \geqslant i} X_{n_k} - X_{n_i} \|_p + \| \sup_{k \geqslant i} X_{n_k} - X_{n_i} \|_p \leqslant 2 \bigg(\frac{1}{2^{i-1}} \bigg) = \frac{1}{2^{i-2}} \end{split}$$

Observe that, for all i, $\liminf_{k\geqslant i} X_{n_k} = \liminf_{k\geqslant 1} X_{n_k}$ and likewise for the lim sup. It thus follows that $\|\limsup_k X_{n_k} - \liminf_k X_{n_k}\|_p < \frac{1}{2^{i-2}}$ for all i, and thus, $\limsup_k X_{n_k} = \liminf_k X_{n_k}$ almost everywhere.

It follows that X_{n_k} converges to a limit; call it X_{∞} . We will now show that $X_n \to X_{\infty}$ as well. This follows as a simple consequence of the triangle inequality and the definition of a Cauchy sequence. Indeed, take M such that $\|X_n - X_m\|_p < \epsilon/2$ for all $n, m \geqslant M$. Now let K be such that $k \geqslant K$ implies that $\|X_{n_k} - X_{\infty}\|_p < \epsilon/2$. Letting $N = \max(N, n_K)$, it follows that for all $n \geqslant N$,

$$||X_n - X_{\infty}||_p \le ||X_n - X_{n_K}||_p + ||X_{n_K} - X_{\infty}||_p \le \epsilon/2 + \epsilon/2 = \epsilon$$

Taking $\epsilon \to 0$, we achieve the desired result.

3.7.2 Basic Functional Analysis & The Riesz Representation Theorem

We will sketch through several basic proofs in functional analysis, ultimately building up to the Riesz-Representation theorem. The Riesz-Representation theorem concerns itself with the representation of linear functions as an integral against a particular function. The key observation is that because $\mathcal{L}^2(\Omega, \mathcal{F}, \mu)$ is a Hilbert space, the Riesz-Representation theorem applies. We will use it most for L^2 , particularly in our construction of the Radon-Nikodym derivative.

Theorem 3.7.4 (The Parallelogram Law). In a Hilbert space \mathcal{H} with inner product $\langle \cdot, \cdot \rangle$, for any two vectors $a, b \in \mathcal{H}$, the following holds:

$$||a-b||^2 + ||a+b||^2 = 2||a||^2 + 2||b||^2$$

Proof.

$$\begin{split} \|a-b\|^2 + \|a+b\|^2 &= \langle a-b, a-b \rangle + \langle a+b, a+b \rangle \\ &= \langle a, a \rangle - 2 \langle a, b \rangle + \langle b, b \rangle + \langle a, a \rangle + 2 \langle a, b \rangle + \langle b, b \rangle \\ &= 2 \langle a, a \rangle + 2 \langle b, b \rangle = 2 \|a\|^2 + 2 \|b\|^2 \end{split}$$

Theorem 3.7.5 (The Projection Theorem). If \mathcal{H} is a Hilbert space, and $S \subseteq \mathcal{H}$ is a subspace, then for each $h \in \mathcal{H}$, there exists a unique vector $x \in S$ minimizing ||y - x||. Furthermore, $y - x \perp s$ for all $s \in S$.

Proof. Let us first show that such a minimizing vector exists for fixed y. Let $\delta = \inf_{s \in S} \|y - s\|$ and x_n be a sequence of vectors such that $\|y - x_n\| \to \delta$. First, note that $\|(x_n - y) + (x_m - y)\|^2 = 4\|\frac{x_m + x_y}{2} - y\|^2 \le 4\delta^2$, since $x_n, x_m \in S$, a subspace. By the parallelogram law,

$$||x_n - x_m||^2 + ||(x_n - y) + (x_m - y)||^2 = 2||x_n - y||^2 + 2||x_m - y||^2$$

Rearranging,

$$||x_n - x_m||^2 = 2||x_n - y||^2 + 2||x_m - y||^2 - 4\delta^2$$

Taking $n, m \to \infty$, we have $||x_n - x_m||^2 \to 0$. By completeness, $x_n \to x$. We now show that $y - x \in S^{\perp}$. Suppose by way of contradiction that there is an s for which $\langle y - x, s \rangle \neq 0$. Now observe that, letting $x(\epsilon) = x - \epsilon s$, we have,

$$||y - x(\epsilon)||^2 = ||y - x - \epsilon s||^2 = \langle y - x - \epsilon s, y - x - \epsilon s \rangle$$
$$= ||y - x||^2 - 2\epsilon \langle y - x, s \rangle + \epsilon^2 ||s||^2$$

Depending on the sign of $\langle y-x,s\rangle$, we either take $\epsilon\to 0$ from the right or from the left. In iether case, as $\epsilon>\epsilon^2$ for small ϵ , there is an ϵ for which $\epsilon^2\|s\|^2-2\epsilon\langle y-x,s\rangle<0$, meaning $\|y-x(\epsilon)\|<\|y-x\|$. As $x\in S$, $s\in S$, $x(\epsilon)=x+\epsilon s\in S$. This is a contradiction. Therefore, no such s exists. Furthermore, we may establish uniqueness like so. By the strict convexity of the norm $\|\cdot\|$, if x,x' are distinct minimizers of distance, a strictly lower distance will be achieved by a convex combination of x and x'. This would be a contradiction.

We say a map A is continuous if, for all $x \in \mathcal{H}$, $\epsilon > 0$, there exists a $\delta > 0$ such that $||y - x|| < \delta \implies |A(x) - A(y)| < \epsilon$. In other words, if x and y are close in norm, they are close in image.

Theorem 3.7.6 (The Riesz-Representation Theorem (for $\mathcal{L}^2(\Omega, \mathcal{F}, \mu)$)). Let $A: \mathcal{H} \to \mathbb{R}$ be bounded and linear. Then for a particular $x \in \mathcal{H}$, there exists a unique $a \in \mathcal{H}$ such that $A(x) = \langle a, x \rangle$.

Proof. First, if $A \equiv 0$, let $a \equiv 0$, and we are done. Otherwise, assume that $A(x) \neq 0$ for at least one function $f \in \mathcal{H}$ with $A(x) \neq 0$. Letting $N = \ker(A)$, we know that since f is bounded and linear, it is continuous; therefore, N is a closed subspace of \mathcal{H} , and so the projection theorem applies. Now, let x^{\perp} be the projection of x onto N, and $y = \frac{x-x^{\perp}}{A(x)}$, which is orthogonal to N by the projection theorem. Furthermore, $A(y) = \frac{A(x)}{A(x)} - \frac{A(x^{\perp})}{A(x)} = 1$. Now observe for all $h \in \mathcal{H}$, we have, A(h - A(h)y) = A(y) - A(y)A(a) = A(y)(1 - A(a)) = 0. Therefore, $h - A(h)y \in N$. Meaning $\langle h - A(h)y, y \rangle = 0$, so $\langle h, y \rangle = A(h)\|y\|^2$. If we simply let $a = \frac{y}{\|y\|^2}$, it follows that $A(h) = \langle a, h \rangle$ for all $h \in \mathcal{H}$, as desired.

3.8 Convergence Notions

The last topic in this chapter is what it means, exactly, for one random variable to converge to another. We have just seen one: convergence in L^p . There are two more we must consider: convergence in probability and almost sure convergence.

Definition 17 (Convergence in Probability). We say $X_n \to X$ in probability if, for all $\epsilon > 0$, $\mathbb{P}(\{|X_n - X| > \epsilon\}) \to 0$

Definition 18 (Almost Sure Convergence). We say $X_n \to X$ almost surely if $\mathbb{P}(\{\lim_n X_n = X\}) = 1$

Definition 19 (Convergence in L^1). We say $X_n \to X$ in L^1 if $||X_n - X||_1 \to 0$

Proposition 15. Almost sure convergence implies convergence in probability

Proof. We first show the statement about convergence in probability. Fix $\epsilon > 0$. First, we know that $\lim_n X_n$ exists almost surely. Simply write,

$$1 = \mathbb{P}(\lim_{n} X_n = X) = \mathbb{P}(\{\lim_{n} |X_n - X| = 0\})$$

$$\leq \mathbb{P}(\{\lim_{n} |X_n - X| < \epsilon\}) \leq \mathbb{P}(\lim_{n} \{|X_n - X| < \epsilon\})$$

$$= \lim_{n} \mathbb{P}(\{|X_n - X| < \epsilon\})$$

Where the last line is due to dominated convergence.

We will also show that convergence in probability implies convergence in L^1 , provided X_n is uniformly integrable. At a high level, the requirement of uniform integrability simply says that a family of random variables universally doesn't put too much oomph above higher and higher thresholds.

Definition 20. A family of random variables X_n is uniformly integrable if $\sup_n \mathbb{P}|X_n|\{|X_n| > M\} \to 0 \text{ as } M \to \infty.$

Theorem 3.8.1. If and only if (i) X_n is a set of uniformly integrable functions and (ii) X_n convergence in probability to X, then X_n converges in L^1 .

Proof. Suppose $X_n \to X$ in probability. First, fix $\epsilon > 0$. Now, fix M such that $\sup_n \mathbb{P}(|X_n|\mathbb{I}\{X_n > M\}) < \epsilon$. Finally, let N be such that $n \ge N$ implies $\mathbb{P}(\{|X_n - X| > M\}) < \epsilon/M$, which exists by convergence in probability. Then, for $n \ge N$,

$$\mathbb{P}(|X_n - X|) =$$

$$\mathbb{P}(|X_n - X|\{|X_n - X| < \epsilon\})$$

$$+ \mathbb{P}(|X_n - X|\mathbb{I}\{|X_n - X| > \epsilon\}\mathbb{I}\{|X_n - X| > M\})$$

$$+ \mathbb{P}(|X_n - X|\mathbb{I}\{|X_n - X| > \epsilon\}\mathbb{I}\{|X_n - X| < M\})$$

$$\leq \mathbb{P}(\epsilon\mathbb{I}\{|X_n - X| < \epsilon\})$$

$$+ \mathbb{P}(|X_n - X|\mathbb{I}\{|X_n - X| > M\}) + \mathbb{P}(M\mathbb{I}\{|X_n - X| > \epsilon\})$$

$$\leq \epsilon(1) + \epsilon + M(\epsilon/M)$$

$$= 3\epsilon$$

Of course, as ϵ was arbitrary, this completes the "if" direction. Now, we consider the "only if" direction. How do we gain uniform integrability from convergence in L^1 ? Observe that the following inequality always holds:

$$|X_n|\{X_n > M\} \le |X_\infty|\{|X_\infty| > M/2\} + 2|X_n - X_\infty|$$

It can be checked by considering cases in which (i) either $X_n \leq M$ or $X_{\infty} > M/2$ (ii) otherwise. Taking expectations, we find,

$$\mathbb{P}(|X_n|\{X_n > M\}) \leq \mathbb{P}(|X_{\infty}|\{|X_{\infty}| > M/2\}) + 2\mathbb{P}(|X_n - X|)$$

Thus, we could make all of this less than some ϵ by first taking n_0 such that $\mathbb{P}(|X_n-X|)<\epsilon/4$ for $n\geqslant n_0$. Then let M_1 be such that $\mathbb{P}(|X_\infty|\{|X_\infty|>M/2\})<\epsilon/2$ and $M_2=\max_{n< n_0}\{M_n:\mathbb{P}(|X_n|\{X_n>m\})\}<\epsilon/2$. Finally, let $M^\star=\max(M_1,M_2)$. Then for either $n< n_0$ or $n\geqslant n_0$, $\mathbb{P}(|X_n|\{X_n>M\})$ $\leqslant \epsilon$, which suffices to show uniform integrability! Now, it remains to show convergence in probability. Fix $\epsilon>0$. Then, by Markov's Inequality, $\mathbb{P}(|X_n-X|>\epsilon)\leqslant \frac{\mathbb{P}(|X_n-X|)}{\epsilon}$. Sending $n\to\infty$, we're all set.

3.9 Pushforward Measures

3.9.1 Measures on Outputs

Oftentimes, we are given a measure space $(\Omega, \mathcal{F}, \mu)$ and we are interested in the distribution \mathbb{Q} of a random variable X. For example, consider the simple dice roll, where $\Omega = \{1, 2, 3, 4, 5, 6\}$, \mathcal{F} is the usual power set of Ω , and μ is the fair distribution. X might be $X(\omega) = \mathbb{I}\{\omega \in \{1, 2, 3\}\}$, i.e. X is the indicator for an odd roll. Then the measure measure \mathbb{Q} says $\mathbb{Q}(\{1\}) = \mathbb{P}(\{X \in \{1, 2, 3\}\}) = 1/2$, and $\mathbb{Q}(\{0\}) = 1/2$ as well. That is, for a given *outcome* of X, we set the probability of that outcome to be the probability of the set of events which produce that outcome. We make this more formal with the following definition.

Definition 21 (Pushforward Meaasure). Suppose $X:(\Omega,\mathcal{F},\mu)\to(\mathcal{Y},\mathcal{A})$ is measurable. The pushforward measure \mathbb{Q} such that $Q(A)=\mathbb{P}(X^{-1}(A))$ for all $A\in\mathcal{A}$.

Lemma 3.9.1. The pushforward measure is a measure.

Proof. We simply check definition 2. First, observe that for all $A \in \mathcal{A}$, $\mathbb{Q}(A) = \mathbb{P}(X^{-1}(A)) \geq 0$, since \mathbb{P} is a measure. Likewise, $\mathbb{Q}(\emptyset) = \mathbb{P}(X^{-1}(\emptyset)) = \mathbb{P}(\emptyset) = 0$. Finally, we verify countable additivity. Let $A_1, A_2 ... \in \mathcal{A}$ be disjoint. Then, letting $A = \bigcup_n A_n$,

$$\mathbb{Q}(A) = \mathbb{P}\left(X^{-1}\left(\bigcup_{n} A_{n}\right)\right) = \mathbb{P}\left(\bigcup_{n} X^{-1}(A_{n})\right) = \sum_{n} \mathbb{P}(X^{-1}(A_{n})) = \sum_{n} \mathbb{Q}(A_{n})$$

And hence, we have verified the necessaary properties.

Occasionally, I will write \mathbb{P}_X in place of \mathbb{Q} , as to clarify the random variable in question.

Chapter 4

Densities & Conditional Expectation

In your ordinary probability class, you learned about "densities" as being a sort of continuous version of a Probability Mass Function. It was a sort of way to resolve the paradoxical fact that any outcome in a continuous distribution has zero probability, yet a point does have a notion of likelihood. If your random variable X has a distribution function F, the density f is defined as f(t) = F(t). The density then had the nice property that $\mathbb{P}((-\infty,a]) = \int_{-\infty}^a f(t)dt$, where this holds by the fundamental theorem of calculus. Why are densities useful? Because it let's us do interesting things! We can easily calculate the expected value of X by computing $\mathbb{E}[X] = \int t f(t) dt$. If g(X) were, say, some other function, we calculate $\mathbb{E}[g(X)] = \int g(t) f(t) dt$. At the time, this is perhaps how you learned to define the expectation of a random variable. Rather, we show this is an incredibly particular case of general densities between probability distributions. In this case, f is the density of the distribution of X with respect to the Lebesgue measure on \mathbb{R} . Thus, if λ is the integral representing the Lebesgue measure, we are truly saying $\mathbb{E}[X] = \lambda(f(\omega)X(\omega))$. Furthermore, as the Lebesgue measure of any interval [t,t+h] is h,

$$f(t) = F'(t) = \lim_{h \to 0^+} \frac{\mathbb{P}(X \in [t, t+h])}{\lambda([t, t+h])}$$

We this is also suggestive of the notation $f(t) = \frac{\partial \mathbb{P}}{\partial \lambda}(t)$. In some sense, f provides a measure of how quickly \mathbb{P} changes with respect to λ , so $\frac{\partial \mathbb{P}}{\partial \lambda}$ is a sort of derivative. Indeed, this is the right way to think about it. We show that this generalizes to a notoin of a Radon-Nikdoym derivative, a universal translator from one measure to another.

4.1 Densities

As you have already seen, the term *density* is usually thought of as a continuous form of a PMF. This does not generalize well to arbitary masures. Rather, it is appropriate to think of it as a function against which integration along measure yields integration along another. More formally,

Definition 22 (Density). If μ, ν are measures acting on (Ω, \mathcal{F}) , then ν is said to have a density f with respect to μ if $\int_F d\nu = \int_F f d\mu$ for all $F \in \mathcal{F}$. Furthermore, f is written as $\frac{d\nu}{d\mu}$, and is called the Radon-Nikodym derivative of ν with respect to μ .

Note that there are is an obvious condition for which such a function should exist: we require that if $\mu(F)=0$, then we absolutely must have that $\nu(F)=0$ as well. Otherwise, for such an F, $\int_F f d\mu=0$, while $\int_F d\nu>0$. We forbid this ugliness by requiring that ν 's support must be a subset of μ 's support.

4.1.1 Special Cases

Definition 23. When $\mu(F) = 0 \implies \nu(F) = 0$, we write $\nu \ll \mu$. And nu is said to be absolutely continuous with respect to μ .

Example 5 (Countable Ω). Let Ω is countable and \mathcal{F} be a σ algebra on subsets of Ω . Recall, from chapter 1, that \mathcal{F} can be written as the set of unions of an atomic set \mathcal{A} . Again, for $\omega \in \Omega$, let $A(\omega)$ be such that $A(\omega) \in \mathcal{A}$ and $\omega \in A(\omega)$. Clearly, by defining,

$$f(\omega) = \frac{\nu(A(\omega))}{\mu(A(\omega))}$$

Then for any $F = \bigcup_i A_i \in \mathcal{F}$, with each $A_i \in \mathcal{A}$,

$$\int_F d\nu = \nu(F) = \sum_i \nu(A_i) = \sum_i \frac{\nu(A_i)}{\mu(A_i)} \mu(A_i) = \mu\bigg(\sum_i \frac{\nu(A_i)}{\mu(A_i)} \mathbb{I}\{A_i\}(\omega)\bigg)$$

Observe that for all $\omega \in \Omega$, $\frac{\nu(A_i)}{\mu(A_i)} \mathbb{I}\{A_i\}(\omega) = \frac{\nu(A(\omega))}{\mu(A(\omega))} \mathbb{I}\{A_i\}(\omega)$,

$$=\mu\bigg(\sum_i\frac{\nu(A(\omega))}{\mu(A(\omega))}\mathbb{I}\{A_i\}(\omega)\bigg)=\mu(f\sum_i\mathbb{I}\{A_i\})=\mu(f\mathbb{I}\{F\})=\int_Fd\mu$$

Therefore, ν has density f with respect to μ . In a special case, if $\mathcal{F} = 2^{\Omega}$ (the powerset of Ω), we can simply define $f(\omega) = \frac{\nu(\{\omega\})}{\mu(\{\omega\})}$. Hopefully, this is indicative of our choice of notation.

Example 6 (Probability Density Functions). When $\mu = \lambda$, the Lebesgue measure, and ν is some continuous random variable, the pdf f is the same as the density f of ν with respect to λ .

Lemma 4.1.1. If $\frac{d\nu}{d\mu}$ and $\frac{d\mu}{d\nu}$ exist, then $\frac{d\nu}{d\mu} = (\frac{d\mu}{d\nu})^{-1}$ almost everywhere μ .

Proof. For any set $F \in \mathcal{F}$, we have, by definition of $\frac{d\mu}{d\nu}$,

$$\int_{F} \left(\frac{d\mu}{d\nu}\right)^{-1} d\mu = \int_{F} \left(\frac{d\mu}{d\nu}\right)^{-1} \frac{d\mu}{d\nu} d\nu = \int_{F} d\nu$$

Example 7 (Relative Entropy). If \mathbb{P} and \mathbb{Q} are two probability measures with Radon-Nikodym derivative $\frac{d\mathbb{P}}{d\mathbb{Q}}$, then the relative entropy between \mathbb{P} and \mathbb{Q} is defined as,

$$D(\mathbb{P}||\mathbb{Q}) = \mathbb{P}\bigg(\log_2\bigg(\frac{d\mathbb{P}}{d\mathbb{Q}}\bigg)\bigg) = \int \log_2\bigg(\frac{d\mathbb{P}}{d\mathbb{Q}}\bigg)d\mathbb{P}$$

Relative entropy is an information-theoretic quantity which measures the following quantity: when \mathbb{P} is the true distribution, how many more bits do you need to communicate the outcome in a code optimized for \mathbb{Q} as compared to a code optimized for \mathbb{P} ? A notable inequality in information theory is the so called information inequality, which says that relative entropy is positive, except for when $\mathbb{P} = \mathbb{Q}$ almost everywhere:

Theorem 4.1.2 (Gibbs Theorem / The Information Inequality). If \mathbb{Q} and \mathbb{P} are two probability measures such that $\mathbb{P} << \mathbb{Q}$, then $D(\mathbb{P}||\mathbb{Q}) \ge 0$.

Proof. This follows easily from the convexity of $-\log_2$ and Jensen's Inequality:

$$\begin{split} D(\mathbb{P}||\mathbb{Q}) &= \mathbb{P}\bigg(\log_2\bigg(\frac{d\mathbb{P}}{d\mathbb{Q}}\bigg)\bigg) = \mathbb{P}\bigg(\log_2\bigg(\frac{d\mathbb{Q}}{d\mathbb{P}}\bigg)^{-1}\bigg) \\ &= -\log_2\mathbb{P}\bigg(\frac{d\mathbb{Q}}{d\mathbb{P}}\bigg) = -\log_2\bigg(\int_{\Omega}d\mathbb{Q}\bigg) = 0 \end{split}$$

4.2 The Radon-Nikodym Theorem

The Radon-Nikodym Theorem Concerns itself with the existence of such densities. It establishes that such a $\frac{d\nu}{d\mu}$ exists whenever ν and μ are σ -finite and $nu << \mu$.

Theorem 4.2.1 (The Radon-Nikodym Theorem). For all σ -finite measures μ and ν defined on a measure space (Ω, \mathcal{F}) such that $\nu << \mu$, the Radon Nikdoym derivative $\frac{d\nu}{d\mu}$ exists and is unique almost surely.

Proof

Lemma 4.2.2. Suppose μ and ν are finite measures with $\nu(F) \leq \mu(F)$ for all $F \in F$. Then, ν has a density Δ with respect to mu, where $0 \leq \Delta \leq 1$, and Δ is unique μ almost everywhere.

Proof. We first note that for any $g \in \mathcal{L}^2(\Omega, \mathcal{F}, \mu)$, $g \mapsto \int g d\nu$ is a continuous linear functional. First, since,

$$|\nu(g)| \le |\nu(g^2)^{1/2} \nu(\Omega)| \le \mu(g^2)^{\frac{1}{2}} |\mu(\omega)|^{\frac{1}{2}}$$

We find that ν is bounded. And ν is linear, as it is an integral. Therefore, ν is a continuous map. By the Riesz Representation theorem, we know that there exists a $\kappa \in \mathcal{L}^2(\Omega, \mathcal{F}, \mu)$ such that $\nu(g) = \mu(\kappa g)$ for all g. In particular, this holds true of indicator functions $g = \mathbb{I}\{F\}$. We show that $0 \le \kappa \le 1$ almost everywhere. Observe for any $\epsilon > 0$,

$$\nu(\{\kappa \leqslant \epsilon\}) = \mu(\kappa\{\kappa \leqslant -\epsilon\}) \leqslant -\epsilon\mu(\{\kappa \leqslant \epsilon\}) \leqslant 0$$

But measures are nonnegative. Therefore, for $\nu(\{\kappa \leq \epsilon\}) \leq 0$, it must be zero. And thus $\nu(\{\kappa \leq \epsilon\}) = 0$ as well. Likewise, as $\nu \leq \mu$,

$$\nu(\{\kappa \geqslant 1 + \epsilon\}) = \mu(\kappa\{\kappa \geqslant 1 + \epsilon\}) \geqslant (1 + \epsilon)\mu(\{\kappa \geqslant 1 + \epsilon\}) \geqslant (1 + \epsilon)\nu(\{\kappa \geqslant 1 + \epsilon\})$$

Implying that $\mu(\{\kappa \ge 1 + \epsilon\}) = 0$ for all ϵ . Therefore, there is no harm in setting $\Delta = \kappa \mathbb{I}\{\kappa \in [0, 1]\}$. For uniqueness, if $\tilde{\Delta}$ were a second density, then we have,

$$\mu(\Delta \mathbb{I}\{\Delta > \tilde{\Delta}\}) = \nu(\{\Delta > \Delta\}) = \mu(\tilde{\Delta}\mathbb{I}\{\Delta > \Delta\})$$

And thus, $\mu(\{\Delta - \tilde{\Delta}\}\mathbb{I}\{\Delta > \tilde{\Delta}\}) = 0$, so $\{\Delta > \tilde{\Delta}\}$ is negligible. Symmetrically, $\{\Delta < \tilde{\Delta}\}$ is negligible. Thus, $\Delta = \tilde{\Delta}$ almost everywhere μ .

Lemma 4.2.3. The Radon-Nikodym Theorem is true in the case of finite measures μ and ν .

Proof. We define $\lambda = \mu + \nu$, where $\mu + \nu$ is the measure such that $\lambda(F) = \mu(F) + \nu(F)$ for $F \in \mathcal{F}$. Obviously, ν and λ satisfy the conditions of our lemma. And so, there exists a Δ such that $\nu(g) = \mu(g\Delta)$ for all $g \in \mathcal{M}(\Omega, \mathcal{F})$. Recall from the proof of the lemma that $\Delta \geqslant 1$ almost surely ν . We also show $\Delta < 1$ almost surely ν . Let $N = \{\Delta = 1\}$:

$$\nu(N) = \lambda(\Delta\{\Delta = 1\})$$

$$= \nu(\Delta\{\Delta = 1\}) + \mu(\Delta\{\Delta = 1\}) \geqslant \nu(N) + \mu(N)$$

Which, as $\mu(\{\Delta \ge 1\}) \ge 0$, leaves only that $\nu(\{\Delta \ge 1\}) = 0$. Define,

$$\frac{d\nu}{d\mu} = \frac{\Delta}{1 - \Delta} \mathbb{I}\{\Delta < 1\}$$

Now, observe for any measurable g, letting $g \wedge n = \min(g, n)$,

$$\nu(g \wedge n) = \nu((g \wedge n)\Delta\{\Delta < 1\}) + \mu((g \wedge n)\Delta\{\Delta < 1\})$$

Since our measures are finite, $\nu(g \wedge n), \mu(g \wedge n) \leq n$. And thus, we are free to rearrange:

$$\nu((g \wedge n)(1-\Delta)\{\Delta < 1\}) = \mu((g \wedge n)\Delta\{\Delta < 1\})$$

Two appeals to monotone convergence yields, as $0 \le \Delta \le 1$:

$$\nu((g \wedge n)(1-\Delta)\{\Delta < 1\}) \leqslant \lim_{n} \mu((g \wedge n)\Delta\{\Delta < 1\}) = \mu(g\Delta\{\Delta < 1\})$$

$$\nu(g(1-\Delta)\{\Delta<1\}) = \lim_{n} \nu((g \land n)(1-\Delta)\{\Delta<1\}) \geqslant \mu((g \land n)\Delta\{\Delta<1\})$$

And thus $\nu(g(1-\Delta)\{\Delta<1\}) = \mu(g\Delta\{\Delta<1\})$. In particular, for any function g, this holds of $\frac{g}{1-\Delta}\{\Delta<1\}$ as well:

$$\int \frac{g(1-\Delta)}{1-\Delta} \{\Delta < 1\} d\nu = \int \frac{g\Delta}{1-\Delta} \{\Delta < 1\} d\mu$$
$$\int gd\nu = \int g\{\Delta > 1\} d\mu = \int g\frac{d\nu}{d\mu} d\mu$$

This proves the existence of the Radon-Nikodym derivative. Uniqueness is quite easy to show - follow the same argument as in the end of the Lemma.

The General Case: We now show the Radon-Nikodym theorem is true for σ -finite measures. If Ω is the disjoint union of B_1, B_2 such that $\mu(B_n) < \infty, \nu(B_n) < \infty$ for all n. Then if we let μ_n, ν_n be measures such that, for all measurable g,

$$\int g d\mu_n = \int_{B_n} g d\mu \qquad \int g d\nu_n = \int_{B_n} g d\nu$$

Then the μ_n, ν_n 's are all obviously finite measures, to which the weaker Radon-Nikodym theorem applies. From this, we extract a set of countable derivatives $\frac{d\nu_n}{d\mu_n}$. And clearly, if we let $\frac{d\nu}{d\mu} \triangleq \sum_n \frac{d\nu_n}{d\mu_n}$,

$$\int g d\nu = \sum_{n} \int_{B_{n}} g d\nu = \sum_{n} \int g d\nu_{n}$$
$$= \sum_{n} \int g \frac{d\nu_{n}}{d\mu_{n}} d\mu_{n} = \sum_{n} \int_{B_{n}} g \frac{d\nu}{d\mu} d\mu = \int g \frac{d\nu}{d\mu} d\mu$$

And thus, we have a derivative of ν with respect to μ , as desired

The Radon-Nikdoym theorem has a wide variety of applications. For one, we have given a sort of rigorous justification for continuous derivatives with respect to the Lebesgue measure, from which the theory of continuous distributions follows. But, in some sense, we had already defined these distributions by such a density, defined by a Riemannian integral over intervals, and extended it to the Borel σ -field via Caratheodory's extension theorem. So our work is somewhat circular. What about a more novel application? it can be applied to prove the existence of Kolmogorov's abstract conditional expectation.

4.3 Conditional Expectation

4.3.1 What is a conditional expectation?

Typically, we define conditional expectations in terms of conditional probabilities. We say something of the essence of,

$$\mathbb{P}(A|B) = \frac{\mathbb{P}(A,B)}{\mathbb{P}(B)}$$

This quantity is supposed to represent the fraction of the times that A occurs when B occurs. In the continuous case, we replace the above probabilities with densities p(a|b) = p(a,b)/p(b). Already, we are in somewhat murky territory. Why would we do such a thing? The probability of a particular a,b occuring is zero, but so is the probability of a particular b. While replacing pmfs with pdfs seems reasonable, it's essentially arbitrary from a microscopic point of view. But such conditional densities have nice macroscopic properties.

• p(a|b) = 0 when p(a, b) = 0.