

# Weekly Progress Report

**Name:** 林廣軒      **Week:** Week 3 (2025/9/15 ~ 2025/9/21)

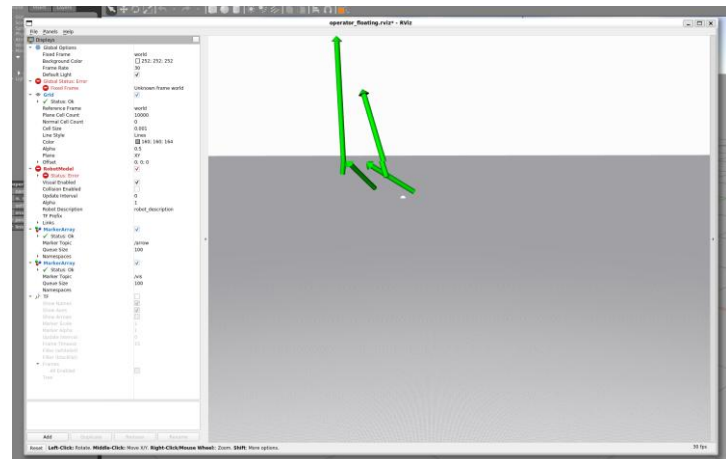
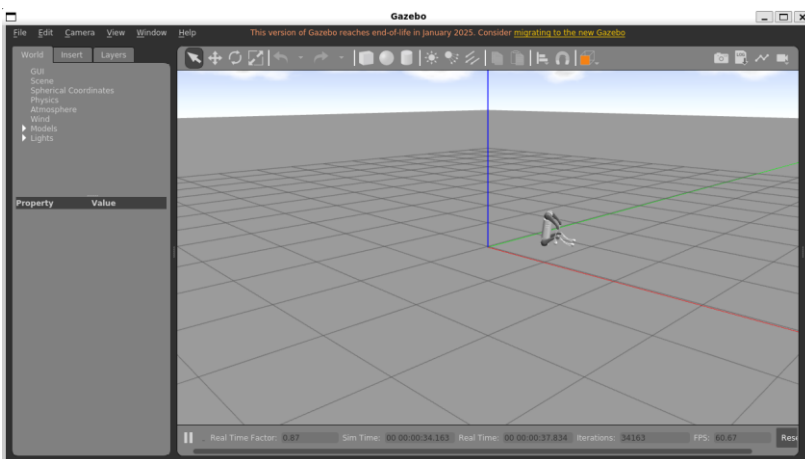
## 1. Summary of This Week's Work

This week, I focused on developing the controller script for the Go1 robot, with the goal of making it stand. In addition, I attended the weekly meeting on Wednesday and listened to a research paper presentation. Progress was slower than expected due to a heavy workload from other courses and commitments.

## 2. Tasks Completed

- Continued writing the controller script for Go1 robot.
- Attended the meeting on Wednesday and listened to paper presentation.

## 3. Task Screen Shots



## 4. In Progress / Ongoing Work

- Writing the control script to make the Go1 robot stand.
- Studying the control logic for Go1 robot.

## 5. Challenges / Issues

- *Time management.* This week, I had multiple academic and personal commitments, including:
  - Homework for Linear System, Control System, and Introduction to IoT courses.

- TOFEL Preparation for the 115-2 international exchange program.
- Another project under Prof. Ho-Lin Chen.

## **6. Next Steps (Plan for Next Week and Beyond)**

- Finish the control script and make Go1 stand.
- Reproduce the simulation result in the paper.

## **7. Additional Notes (Optional)**

- My notion page for this project (including meeting notes, tasks, and schedule):  
<https://notion.so>
- My GitHub repository for this project (including code, environment setup, etc.):  
<https://github.com>