

CMP_SC 3050: Connected Components of Directed Graphs

Rohit Chadha

September 18, 2014

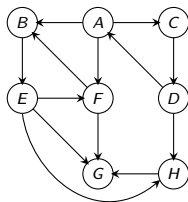
Strongly connected component of a digraph

- u is said to **strongly connected** to v if there is a directed path from u to v and from v to u .

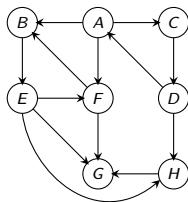
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- u is said to **strongly connected** to v if there is a directed path from u to v and from v to u .
- The **strongly connected component** (SCC) of u is the set of all vertices strongly connected to u . We shall write the SCC of u as $\text{SCC}(u)$

Example



Example



$$\text{SCC}(A) = \{A, C, D\}$$

$$\text{SCC}(B) = \{B, E, F\}$$

$$\text{SCC}(C) = \{A, C, D\}$$

$$\text{SCC}(D) = \{A, C, D\}$$

$$\text{SCC}(E) = \{B, E, F\}$$

$$\text{SCC}(F) = \{B, E, F\}$$

$$\text{SCC}(G) = \{G\}$$

$$\text{SCC}(H) = \{H\}$$

Properties of Strongly Connected Components

- For any two vertices u, v , either they have the same SCC or their SCCs have no vertex in common

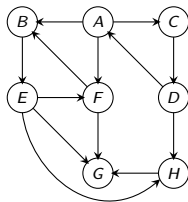
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- For any two vertices u, v , either they have the same SCC or their SCCs have no vertex in common
- In a dag, for every vertex u , $\text{SCC}(u) = \{u\}$.
- Strongly connected component of a graph G is the set of all SCCs. We shall call this set $\text{SCC}(G)$

Example



The strongly connected components are $\{B, E, F\}$, $\{A, C, D\}$, $\{G\}$ and $\{H\}$

Component graph of digraph

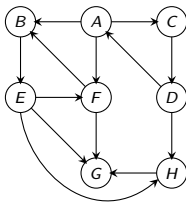


Figure : Graph G

Let C_1, C_2, \dots, C_k be the SCCs of G . The **component graph** of G is the graph where

Component graph of digraph

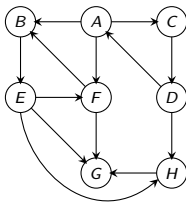
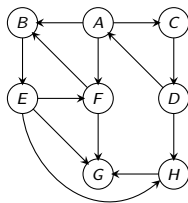


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- Vertices are C_1, C_2, \dots, C_k

Component graph of digraph



B, E, F

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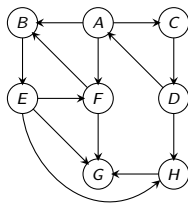
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Let C_1, C_2, \dots, C_k be the SCCs of G . The **component graph** of G is the graph where

- Vertices are C_1, C_2, \dots, C_k
- There is an edge (C_i, C_j) if $i \neq j$ and there is some $u \in C_i$ and $v \in C_j$ such that (u, v) is an edge in G .

Component graph of digraph

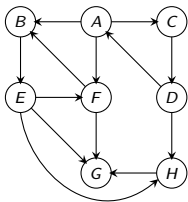


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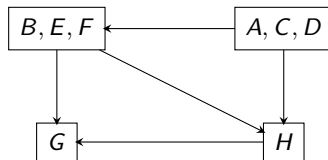


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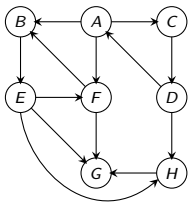


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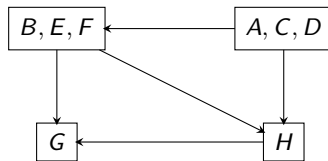


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Component graph is always a dag

Strongly connected graphs

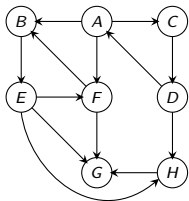


Figure : Not strongly connected

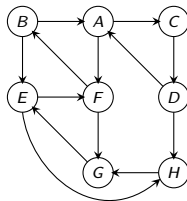


Figure : Strongly connected

A graph is **strongly connected** if it has exactly one strongly connected component.

Algorithmic questions

- 1 Give an algorithm that given a graph G , vertices u and v checks if u is connected to v
- 2 Give an algorithm that given a graph G and vertex u , outputs $\text{SCC}(u)$ (the strongly connected component of u)
- 3 Give an algorithm that given a graph G , outputs $\text{SCC}(G)$

Algorithmic questions

- ① Give an algorithm that given a graph G , vertices u and v checks if u is connected to v
 - (a) Check if v is reachable from u (use BFS or DFS)?
 - (b) Check if u is reachable from v ?
 - (c) u is connected to v iff the answers to the questions (a) and (b) is Yes
 - (d) Runs in $O(|V| + |E|)$ time
- ② Give an algorithm that given a graph G and vertex u , outputs $\text{SCC}(u)$ (the strongly connected component of u)
- ③ Give an algorithm that given a graph G , outputs $\text{SCC}(G)$

Transpose of a digraph

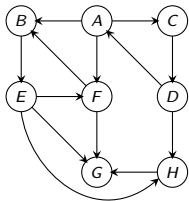


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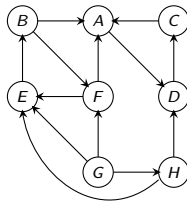


Figure : G^T

The **transpose** of digraph G is the digraph G^T in which all the edges of G are **reversed**

- The set of vertices of G^T is the same as the set of vertices of G
- u is adjacent to v iff v is adjacent to u

Properties of transpose of a digraph

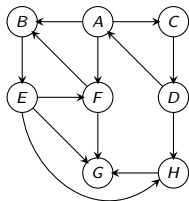


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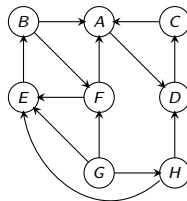


Figure : G^T

- If u is reachable from v in G then v is reachable from u in G^T

Properties of transpose of a digraph

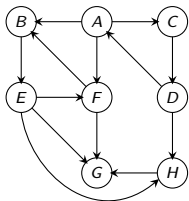


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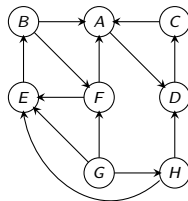


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- If u is reachable from v in G then v is reachable from u in G^T
- u is connected to v in G iff u is connected to v in G^T

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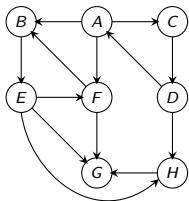


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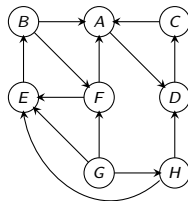


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- If u is reachable from v in G then v is reachable from u in G^T
- u is connected to v in G iff u is connected to v in G^T
- The connected components of G and G^T are exactly the same

Properties of transpose of a digraph

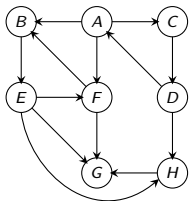


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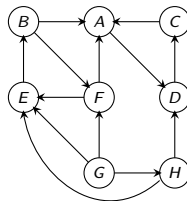


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- If u is reachable from v in G then v is reachable from u in G^T
- u is connected to v in G iff u is connected to v in G^T
- The connected components of G and G^T are exactly the same
- The component graph of SCCs of G^T is the same as the transpose of component graph of G

Connected component of a vertex u in G

Algorithm

- 1 Output all vertices reachable from u (run BFS or DFS on source vertex u)

Connected component of a vertex u in G

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- 2 Compute the adjacency list representation of G^T

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- ➊ Output all vertices reachable from u (run BFS or DFS on source vertex u)
- ➋ Compute the adjacency list representation of G^T
- ➌ Output all vertices reachable from u in G^T

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- ➍ The vertices that are output in both steps 1 and 3 constitute $\text{SCC}(u)$

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- ➍ The vertices that are output in both steps 1 and 3 constitute $\text{SCC}(u)$
- ➎ Runs in $\Theta(|V| + |E|)$ time

An Example

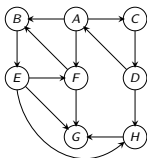


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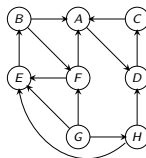


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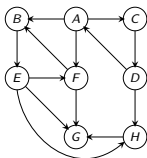


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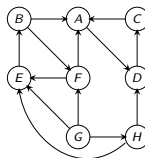


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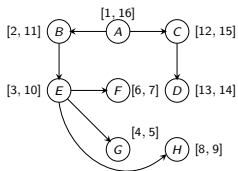


Figure : DFS of G with source A

An Example

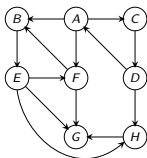


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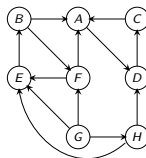


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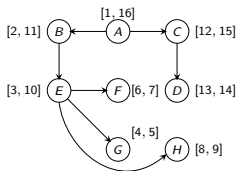


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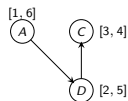


Figure : DFS of G^T with source A

An Example

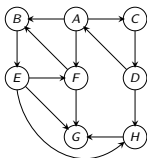


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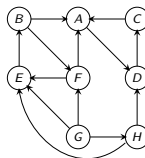


Figure : G^T

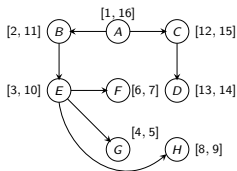


Figure : DFS of G with source A

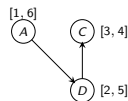


Figure : DFS of G^T with source A

$$\text{SCC}(A) = \{A, C, D\}$$

Computing all Strongly Connected Components

- 1 Initially the set of all SCCs is empty
- 2 Pick a vertex u which is not in a previously computed SCC. If there is no such u , then we are done
- 3 Compute $\text{SCC}(u)$ and add it to the set of all SCCs
- 4 Go back to step 2

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Running time is $O(|V| \cdot (|V| + |E|))$

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There is an algorithm to compute **all** SCCs using just 2 DFSs!

Recall: DFS of a graph

We extend DFS to the whole graph!

- 1 Pick a vertex
- 2 Perform a DFS on the picked vertex
- 3 Pick a new vertex which has not been reached as yet and repeat Step 2

Computing all Strongly Connected Components using 2 DFSs

- 1 Compute the DFS of the whole graph G

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- 5 Output the vertices in each tree of the depth-first forest formed in second DFS as a separate SCC

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Runs in $O(|V| + |E|)$ time

An Example

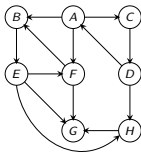


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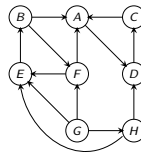


Figure : G^T

Components of G are

An Example

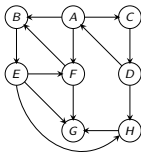


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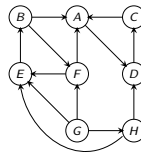


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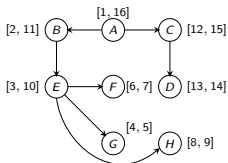


Figure : DFS of G

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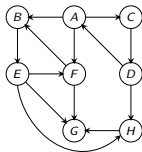


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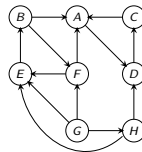


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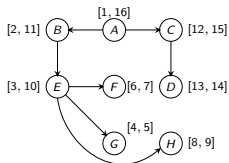


Figure : DFS of G



Figure : DFS of G^T

Components of G are $\{A, D, C\}$;

An Example

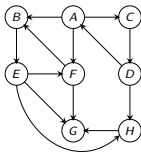


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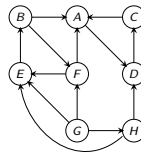


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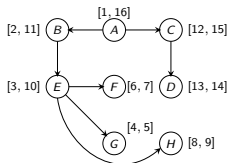


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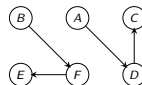


Figure : DFS of G^T

Components of G are $\{A, D, C\}; \{B, F, E\};$

An Example

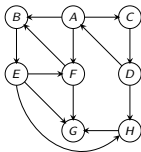


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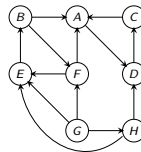


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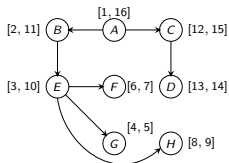


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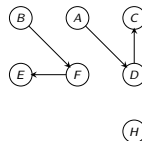


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Components of G are $\{A, D, C\}$; $\{B, F, E\}$; $\{H\}$;

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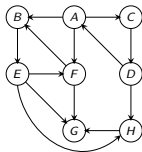


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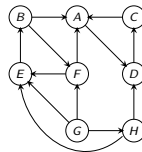


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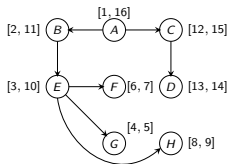


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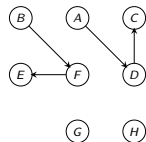


Figure : DFS of G^T

Components of G are $\{A, D, C\}$; $\{B, F, E\}$; $\{H\}$; and $\{G\}$

Why does this algorithm work?

Extend start times and finish times to a component C as follows:

- $C.d$ is the smallest starting time of vertices in C in the DFS of G , and
- $C.f$ is the largest finish time of vertices in C in the DFS of G

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Key Idea: By considering vertices in second DFS in decreasing order of finishing times from first DFS, we are visiting vertices of the component graph in topological sort order

Example

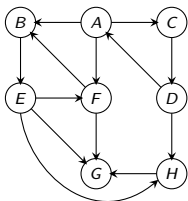


Figure : Graph G

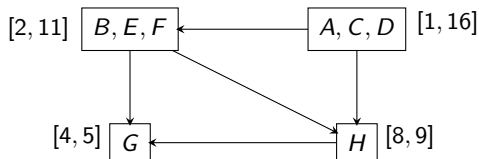


Figure : Component Graph of G

In the example, we first found $\{A, C, D\}$ then $\{B, E, F\}$ then $\{H\}$ and finally G

Component graph of G and finish times

Fact: If C_1 and C_2 are distinct SCCs in G and there is an edge from C_1 to C_2 in the component graph of G then $C_1.f > C_2.f$

Back to Example

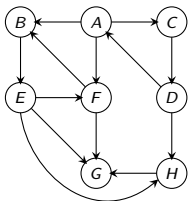


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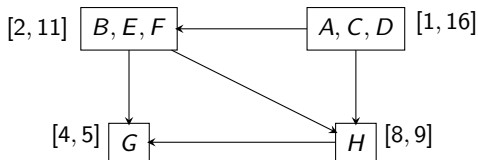


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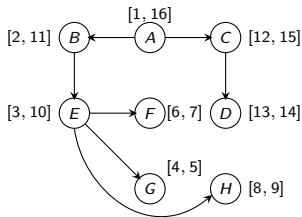


Figure : DFS of G

Component graph of G and finish times

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Why is this fact true?

Let u be first vertex amongst those in C_1 or C_2 that is visited.

- If $u \in C_1$ then all of C_2 will be explored before $\text{DFS}(u)$ completes
- If $u \in C_2$ then all of C_2 will be explored before any of C_1

Why does the algorithm for connected components work?

From the previous fact, we get a **new fact**:

If C_1 and C_2 are distinct SCCs in G such that $C_1.f > C_2.f$ then there cannot be an edge from C_1 to C_2 in G^T

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- Thus DFS now visits all vertices in C_1
- The only edges out of C_1 in G^T go to C which we have already visited
- Therefore, tree edges will be only to vertices in C_1
- The process continues

Summary

- We have several studied fundamental graph algorithms
- DFS and BFS are the two basic strategies for traversing a graph
- BFS was used to find distances from a vertex in a graph
- We have seen applications of DFS to finding topological sort of dag and also to find connected components in a graph
- We have finished Chapter 22 of the book. We shall start Sections 16.1 and 16.2 next week before coming back to graphs