

COURSEWORK 1

IMPERIAL COLLEGE LONDON

DEPARTMENT OF COMPUTING

495 - Advanced Statistical Machine Learning and Pattern Recognition

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Figure 1: This is a figure.

Table 1: Notation

Scalars	x
Vectors	\mathbf{x}
Matrices	\mathbf{X}
Transpose	$^\top$
Inverse	$^{-1}$
Real numbers	\mathbb{R}
Expected values	\mathbb{E}

1 Introduction

This is a template for coursework submission. Many macros and definitions can be found in `notation.tex`. This document is not an introduction to LaTeX. General advice if get stuck: Use your favorite search engine. A great source is also <https://en.wikibooks.org/wiki/LaTeX>.

2 Basics

2.1 Figures

A figure can be included as follows: Fig. 1 shows the Imperial College logo. Some guidelines:

- Always use vector graphics (scale free)
- In graphs, label the axes
- Make sure the font size (labels, axes) is sufficiently large
- When using colors, avoid red and green together (color blindness)
- Use different line styles (solid, dashed, dotted etc.) and different markers to make it easier to distinguish between lines

2.2 Notation

Table 1 lists some notation with some useful shortcuts (see latex source code).

2.2.1 Equations

Here are a few guidelines regarding equations

- Please use the `align` environment for equations (`eqnarray` is buggy)
- Please number all equations: It will make things easier when we need to refer to equation numbers. If you always use the `align` environment, equations are numbered by default.
- Vectors are by default column vectors, and we write

$$\mathbf{x} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \quad (1)$$

- Note that the same macro (`\colvec`) can produce vectors of variable lengths, as

$$\mathbf{y} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} \quad (2)$$

- Matrices can be created with the same command. The `&` switches to the next column:

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 \\ 3 & 4 & 5 \end{bmatrix} \quad (3)$$

- Determinants. We provide a simple macro (`\matdet`) whose argument is just a matrix array:

$$\begin{vmatrix} 1 & 2 & 3 \\ 3 & 4 & 5 \\ 2 & 2 & 2 \end{vmatrix} \quad (4)$$

- If you do longer manipulations, please explain what you are doing: Try to avoid sequences of equations without text breaking up. Here is an example: We consider

$$U_1 = \left[\begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix} \right] \subset \mathbb{R}^4, \quad U_2 = \left[\begin{bmatrix} -1 \\ 1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} \right] \subset \mathbb{R}^4. \quad (5)$$

To find a basis of $U_1 \cap U_2$, we need to find all $\mathbf{x} \in V$ that can be represented as linear combinations of the basis vectors of U_1 and U_2 , i.e.,

$$\sum_{i=1}^3 \lambda_i \mathbf{b}_i = \mathbf{x} = \sum_{j=1}^2 \psi_j \mathbf{c}_j, \quad (6)$$

where \mathbf{b}_i and \mathbf{c}_j are the basis vectors of U_1 and U_2 , respectively. The matrix $A = [\mathbf{b}_1 | \mathbf{b}_2 | \mathbf{b}_3 | -\mathbf{c}_1 | -\mathbf{c}_2]$ is given as

$$A = \begin{bmatrix} 1 & 0 & 0 & 1 & 0 \\ 1 & 1 & 0 & -1 & -1 \\ 0 & 1 & 1 & -2 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{bmatrix}. \quad (7)$$

By using Gaussian elimination, we determine the corresponding reduced row echelon form

$$\begin{bmatrix} 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & -2 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}. \quad (8)$$

We keep in mind that we are interested in finding $\lambda_1, \lambda_2, \lambda_3 \in \mathbb{R}$ and/or $\psi_1, \psi_2 \in \mathbb{R}$ with

$$\begin{bmatrix} 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & -2 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \lambda_3 \\ \psi_1 \\ \psi_2 \end{bmatrix} = \mathbf{0}. \quad (9)$$

From here, we can immediately see that $\psi_2 = 0$ and $\psi_1 \in \mathbb{R}$ is a free variable since it corresponds to a non-pivot column, and our solution is

$$U_1 \cap U_2 = \psi_1 \mathbf{c}_1 = \begin{bmatrix} -1 \\ 1 \\ 2 \\ 0 \end{bmatrix}, \quad \psi_1 \in \mathbb{R}. \quad (10)$$

3 Exercise I

3.a

fdss

3.b

(ii) fsds

4 Exercise II

In Gaussian Mixture Models, assume given a set of N unlabelled data, there K gaussian distributed clustered with different centers $\mu_1 \dots \mu_k$ and same covariance matrix

Σ . The probability of a data belong in cluster l is $p(k = l) = \pi_l$. So we have our parameters:

$$\Sigma \quad (11)$$

$$\mu_1 \dots \mu_k \quad (12)$$

$$p(k = 1) \dots p(k = K) \quad (13)$$

And hidden variables:

$$\mathbf{Z}_n = \begin{bmatrix} Z_{n1} \\ Z_{n2} \\ \dots \\ Z_{nk} \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ \dots \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ \dots \\ 0 \end{bmatrix}, [\dots], \begin{bmatrix} 0 \\ 0 \\ 0 \\ \dots \\ 1 \end{bmatrix} \quad (14)$$

where the probability of a sample in clusters is

$$p(\mathbf{Z}_n) = \prod_{k=1}^K \pi_k^{Z_{nk}} \quad (15)$$

and the probability of a sample x_n given a cluster k is

$$p(x_n | Z_{nk} = 1, \theta) = N(X_n, \mu_k, \Sigma) \quad (16)$$

and the probability of a sample x_n is

$$p(x_n | \theta) = \sum_{k=1}^K p(Z_{nk} = 1) p(X_n | Z_{nk} = 1, \theta) = \sum_{k=1}^K \pi_k N(X_n | \mu_k, \Sigma) \quad (17)$$

Assume all data samples are independent, we first formulate the joint likelihood

$$p(X, Z | \theta) = p(x_1, x_2, \dots, x_n, z_1, z_2, \dots, z_n | \theta) \quad (18)$$

$$= \prod_{n=1}^N p(x_n | z_n, \theta_x) \prod_{n=1}^N p(z_n | \theta_z) \quad (19)$$

$$= \prod_{n=1}^N \prod_{k=1}^K N(x_n | \mu_k, \Sigma)^{z_{nk}} \prod_{n=1}^N \prod_{k=1}^K \pi_k^{z_{nk}} \quad (20)$$

where the parameters are

$$\theta_x = \Sigma, \mu_1, \mu_2, \dots, \mu_k \quad (21)$$

$$\theta_z = \pi_1, \pi_2, \dots, \pi_k \quad (22)$$

In the Expectation Step, we take the log of likelihood

$$\ln p(X, Z | \theta) = \sum_{n=1}^N \sum_{k=1}^K z_{nk} \{ \ln N(X_n | \mu_k, \Sigma) + \ln \pi_k \} \quad (23)$$

And then apply the operator $E_{p(Z|X,\theta)}$ which is expectation of the posterior:

$$E_{p(Z|X,\theta)}[\ln p(X, Z|\theta)] = \sum_{n=1}^N \sum_{k=1}^K E_{p(Z|X,\theta)}[Z_{nk}] \{\ln N(X_n|\mu_k, \Sigma) + \ln \pi_k\} \quad (24)$$

Now we need to compute $E_{p(Z|X,\theta)}[Z_{nk}]$:

$$E_{p(Z|X,\theta)}[Z_{nk}] = E_{p(Z|X,\theta)}[Z_{nk}] \quad (25)$$

$$= \sum_{z_1} \dots \sum_{z_n} p(Z|X, \theta_{old}) = \sum_{z_n} z_{nk} p(z_n|x_n, \theta^{old}) \quad (26)$$

where

$$p(z_n|x_n, \theta^{old}) = \frac{p(x_n, z_n|\theta^{old})}{p(x_n|\theta^{old})} \quad (27)$$

$$= \frac{p(x_n|z_n, \theta^{old})p(z_n|\theta^{old})}{p(x_n|\theta^{old})} \quad (28)$$

$$= \frac{\prod_{k=1}^K N(x_n|\mu_k, \Sigma)^{z_{nk}} p i_k^{z_{nk}}}{\sum_{z_n} \prod_{k=1}^K N(x_n|\mu_k, \Sigma)^{z_{nk}} \pi_k^{z_{nk}}} \quad (29)$$

which gives the expectation

$$E_{p(Z|X,\theta)}[Z_{nk}] = \frac{\sum_{z_{nk}} z_{nk} \prod_{k=1}^K N(x_n|\mu_k, \Sigma)^{z_{nk}} p i_k^{z_{nk}}}{\sum_{z_n} \prod_{k=1}^K N(x_n|\mu_k, \Sigma)^{z_{nk}} \pi_k^{z_{nk}}} \quad (30)$$

$$= \frac{\pi_k N(x_n|\mu_k, \Sigma)}{\sum_{l=1}^K \pi_l N(x_n|\mu_l, \Sigma)} \quad (31)$$

now we see that the expectation is the posterior

$$E_{p(Z|X,\theta)}[Z_{nk}] = p(z_{nk}|x_n) \quad (32)$$

now in the maximization step, we can define

$$G(\theta) = E_{p(Z|X,\theta)}[\ln p(X, Z|\theta)] = \quad (33)$$

$$\sum_{n=1}^N \sum_{k=1}^K E_{p(Z|X,\theta)}[Z_{nk}] \{\ln N(X_n|\mu_k, \Sigma) + \ln \pi_k\} = \quad (34)$$

$$\sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) \left\{ -\frac{1}{2}(x_n - \mu_k)^T \Sigma^{-1}(x_n - \mu_k) - \frac{1}{2}(F \ln 2\pi + \ln |\Sigma|) + \ln \pi_k \right\} \quad (35)$$

take the derivative of our cost function with respect to our parameters, and set them to zero:

$$\frac{dG(\theta)}{d\mu_k} = \sum_{n=1}^N \gamma(z_{nk}) \Sigma^{-1}(x_n - \mu_k) = 0 \quad (36)$$

$$\mu_k = \frac{\sum_{n=1}^N \gamma(z_{nk}) x_n}{\sum_{n=1}^N \gamma(z_{nk})} \quad (37)$$

$$\frac{dG(\theta)}{d\Sigma} = \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) \{ (x_n - \mu_k)^T (x_n - \mu_k) - \Sigma \} = 0 \quad (38)$$

$$\Sigma = \frac{\sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) (x_n - \mu_k)^T (x_n - \mu_k)}{\sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk})} \quad (39)$$

$$= \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) (x_n - \mu_k)^T (x_n - \mu_k) \quad (40)$$

Since we have the constraint that

$$\sum_{k=1}^K \pi_k = 1 \quad (41)$$

We can define the laplacian function:

$$L(\theta) = G(\theta) - \lambda \left(\sum_{k=1}^K \pi_k - 1 \right) \quad (42)$$

$$\frac{dL(\theta)}{d\pi_k} = \sum_{n=1}^N \frac{\gamma(z_{nk})}{\pi_k} - \lambda = 0 \quad (43)$$

$$\pi_k = \frac{\sum_{n=1}^N \gamma(z_{nk})}{\lambda} \quad (44)$$

$$(45)$$

Using the constraint, we can derive the value of λ

$$\sum_{k=1}^K \pi_k = 1 = \frac{\sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk})}{\lambda} \quad (46)$$

$$\lambda = \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) = N \quad (47)$$

$$\pi_k = \frac{\sum_{n=1}^N \gamma(z_{nk})}{N} \quad (48)$$