

Calibration with Machine Learning in Astronomy

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tbd

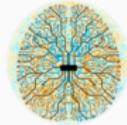
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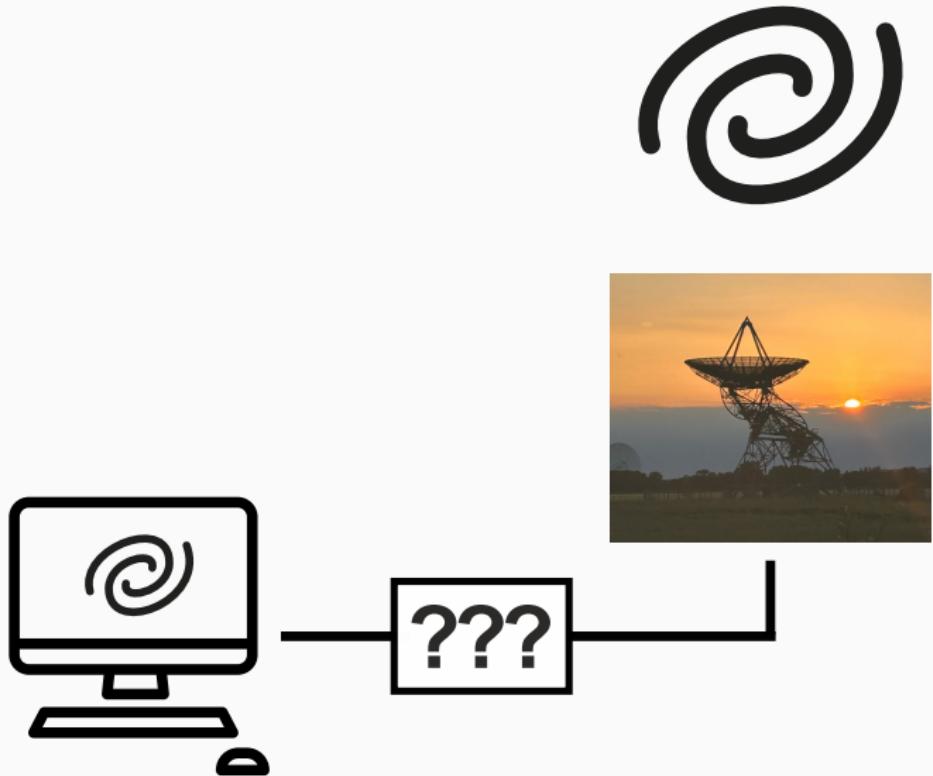
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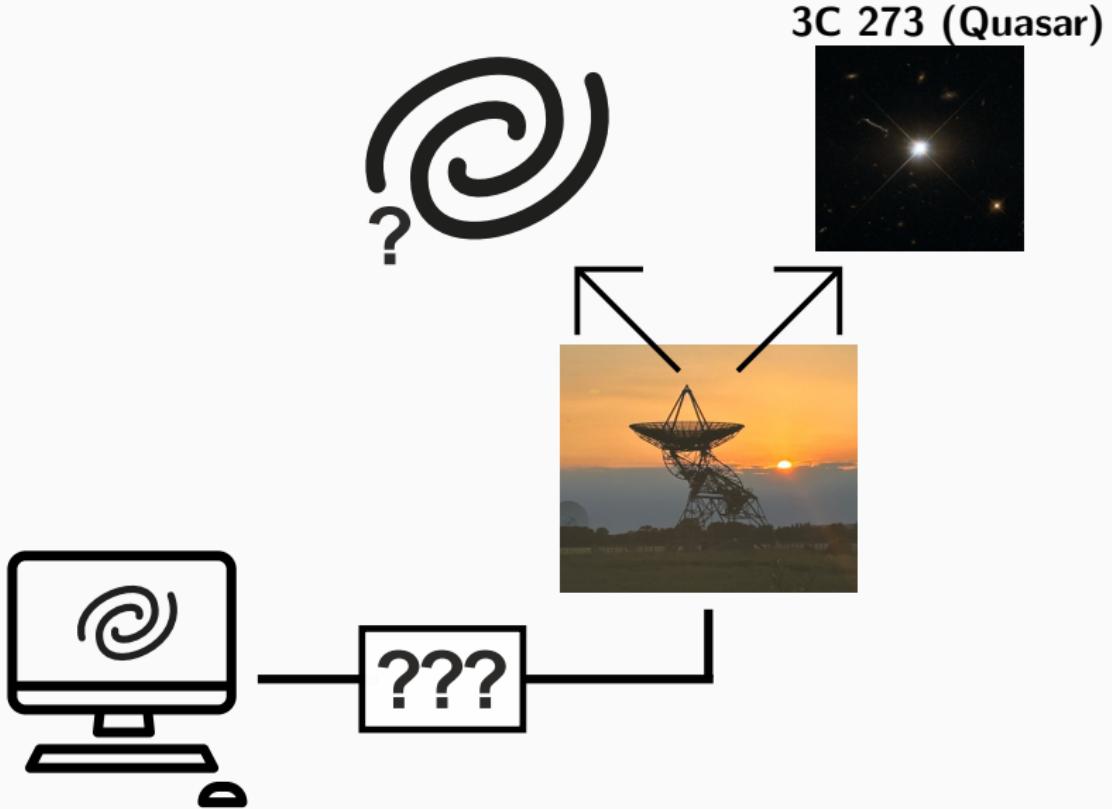
REACH



What is calibration?



How to calibrate?



Why is calibration in Global 21cm Cosmology difficult?



We measure *sky averaged* signal.

Antenna LNA
impedance mismatch

Very faint signal.

How to calibrate (in a bit more detail...)?

Objective: Map input temperature to output power.

Key Factors:

- LNA introduces time-dependent gain, $g(t)$.
- Impedance mismatch adds noise (T_{rec}) to the system.

Output Power Equation:

$$P_{\text{out}}^{\text{src}} = gM(T_{\text{in}}^{\text{src}} + T_{\text{rec}}) \quad (1)$$

Note: All parameters above are frequency-dependent, but the notation has been simplified here and thereafter for convenience.

Dealing with reflections...

$$P_{\text{out}}^{\text{src}} = g M (T_{\text{in}}^{\text{src}} + T_{\text{rec}}) \quad (1)$$

Noise Parameter Equation:

$$P_{\text{out}}^{\text{src}} = g M \left(T_{\text{in}}^{\text{src}} + T_{\text{min}} + T_0 \frac{4R_N}{Z_0} \frac{|\Gamma_{\text{src}} - \Gamma_{\text{opt}}|^2}{(1 - |\Gamma_{\text{src}}|^2)(1 + |\Gamma_{\text{opt}}|^2)} \right) \quad (2)$$

Noise Wave Equation:

$$\begin{aligned} P_{\text{out}}^{\text{src}} = & g \left[T_0 + T_{\text{unc}} |\Gamma_s|^2 \left| \frac{\sqrt{1 - |\Gamma_{\text{rec}}|^2}}{1 - \Gamma_s \Gamma_{\text{rec}}} \right|^2 \right. \\ & + T_s (1 - |\Gamma_s|^2) \left| \frac{\sqrt{1 - |\Gamma_{\text{rec}}|^2}}{1 - \Gamma_s \Gamma_{\text{rec}}} \right|^2 + T_{\cos} \Re \left(\Gamma_s \frac{\sqrt{1 - |\Gamma_{\text{rec}}|^2}}{1 - \Gamma_s \Gamma_{\text{rec}}} \right) \\ & \left. + T_{\sin} \Im \left(\Gamma_s \frac{\sqrt{1 - |\Gamma_{\text{rec}}|^2}}{1 - \Gamma_s \Gamma_{\text{rec}}} \right) \right] \end{aligned} \quad (3)$$

Calibration Equation

Typically, substitute in the noise wave parameter equation here (gains cancel)

$$T_{\text{cal}}^* = T_{\text{NS}} \frac{P_{\text{cal}} - P_L}{P_{\text{NS}} - P_L} + T_L \quad (4)$$

Make some matching assumptions and re arrange:

$$\begin{aligned} T_s = & \color{red} T_{\text{NS}} \left(\frac{P_s - P_L}{P_{\text{NS}} - P_L} \right) \frac{|1 - \Gamma_s \Gamma_{\text{rec}}|^2}{1 - |\Gamma_s|^2} + \color{red} T_L \frac{|1 - \Gamma_s \Gamma_{\text{rec}}|^2}{1 - |\Gamma_s|^2} - \color{red} T_{\text{unc}} \frac{|\Gamma_s|^2}{1 - |\Gamma_s|^2} + \\ & - \color{red} T_{\text{cos}} \frac{\Re \left(\frac{\Gamma_s}{1 - \Gamma_s \Gamma_{\text{rec}}} \right) |1 - \Gamma_s \Gamma_{\text{rec}}|^2}{(1 - |\Gamma_s|^2) \sqrt{1 - |\Gamma_{\text{rec}}|^2}} - \color{red} T_{\text{sin}} \frac{\Im \left(\frac{\Gamma_s}{1 - \Gamma_s \Gamma_{\text{rec}}} \right) |1 - \Gamma_s \Gamma_{\text{rec}}|^2}{(1 - |\Gamma_s|^2) \sqrt{1 - |\Gamma_{\text{rec}}|^2}} \end{aligned} \quad (5)$$

Note: We end up with 5 parameters that need to be estimated to calibrate the system.

Calculating the error

By partial derivatives

To find the error in T_s , we propagate the errors in Γ_s , Γ_{rec} , P_L , P_{NS} , and P_s :

$$(\Delta T_s)^2 = \left(\frac{\partial T_s}{\partial \Gamma_s} \Delta \Gamma_s \right)^2 + \left(\frac{\partial T_s}{\partial \Gamma_{rec}} \Delta \Gamma_{rec} \right)^2 + \left(\frac{\partial T_s}{\partial P_L} \Delta P_L \right)^2 + \left(\frac{\partial T_s}{\partial P_{NS}} \Delta P_{NS} \right)^2 + \left(\frac{\partial T_s}{\partial P_s} \Delta P_s \right)^2. \quad (6)$$

Calculating the error

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$$\frac{\partial T_s}{\partial P_L} = T_{NS} \frac{|1 - \Gamma_s \Gamma_{rec}|^2}{1 - |\Gamma_s|^2} \cdot \frac{P_s - P_{NS}}{(P_{NS} - P_L)^2}. \quad (1)$$

$$\frac{\partial T_s}{\partial P_{NS}} = -T_{NS} \frac{|1 - \Gamma_s \Gamma_{rec}|^2}{1 - |\Gamma_s|^2} \cdot \frac{P_s - P_L}{(P_{NS} - P_L)^2}. \quad (2)$$

Gamma error eqn's here

$$\frac{\partial T_s}{\partial P_s} = T_{NS} \left(\frac{1}{P_{NS} - P_L} \right) \frac{|1 - \Gamma_s \Gamma_{rec}|^2}{1 - |\Gamma_s|^2}. \quad (3)$$

Calculating the error

Using $T_{NS} \frac{P_{cal}-P_L}{P_{NS}-P_L} + T_L$

$$(\Delta T_s)^2 = \left(\frac{\partial T_s}{\partial P_s} \Delta P_s \right)^2 + \left(\frac{\partial T_s}{\partial P_L} \Delta P_L \right)^2 + \left(\frac{\partial T_s}{\partial P_{NS}} \Delta P_{NS} \right)^2 \quad (4)$$

$$+ \left(\frac{\partial T_s}{\partial \Gamma_s} \Delta \Gamma_s \right)^2 + \left(\frac{\partial T_s}{\partial \Gamma_{rec}} \Delta \Gamma_{rec} \right)^2. \quad (6)$$

Using noise wave parameters only

$$(\Delta T_s)^2 = \left(\frac{\partial T_s}{\partial P_s} \Delta P_s \right)^2 \quad (5)$$

$$+ \left(\frac{\partial T_s}{\partial \Gamma_s} \Delta \Gamma_s \right)^2 + \left(\frac{\partial T_s}{\partial \Gamma_{rec}} \Delta \Gamma_{rec} \right)^2. \quad (6)$$

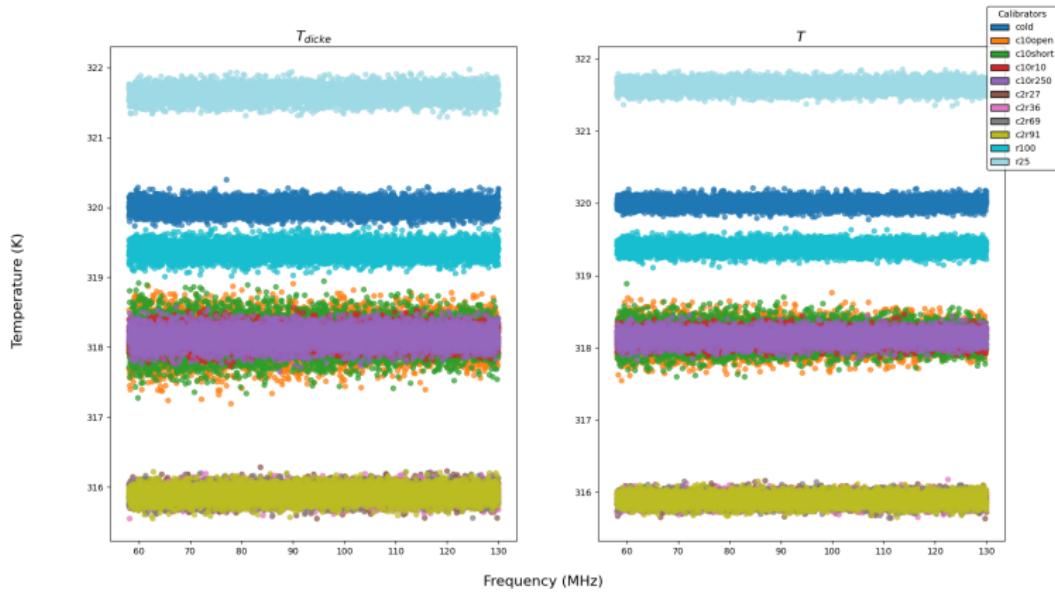


Figure 1: Caption for the image.

Combined Histograms of T_{dicke} and T for Each Calibrator

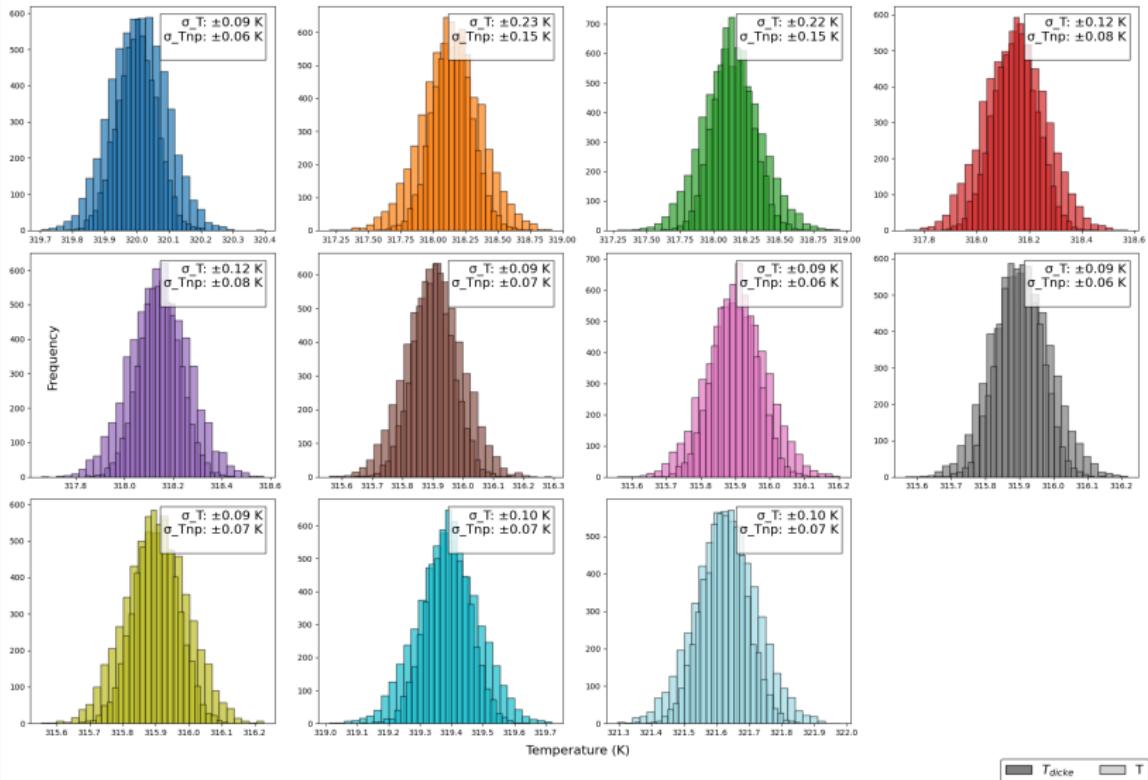


Figure 2: Caption for the image.

Why not fit noise (wave) parameters directly?

Noise Parameter Equation:

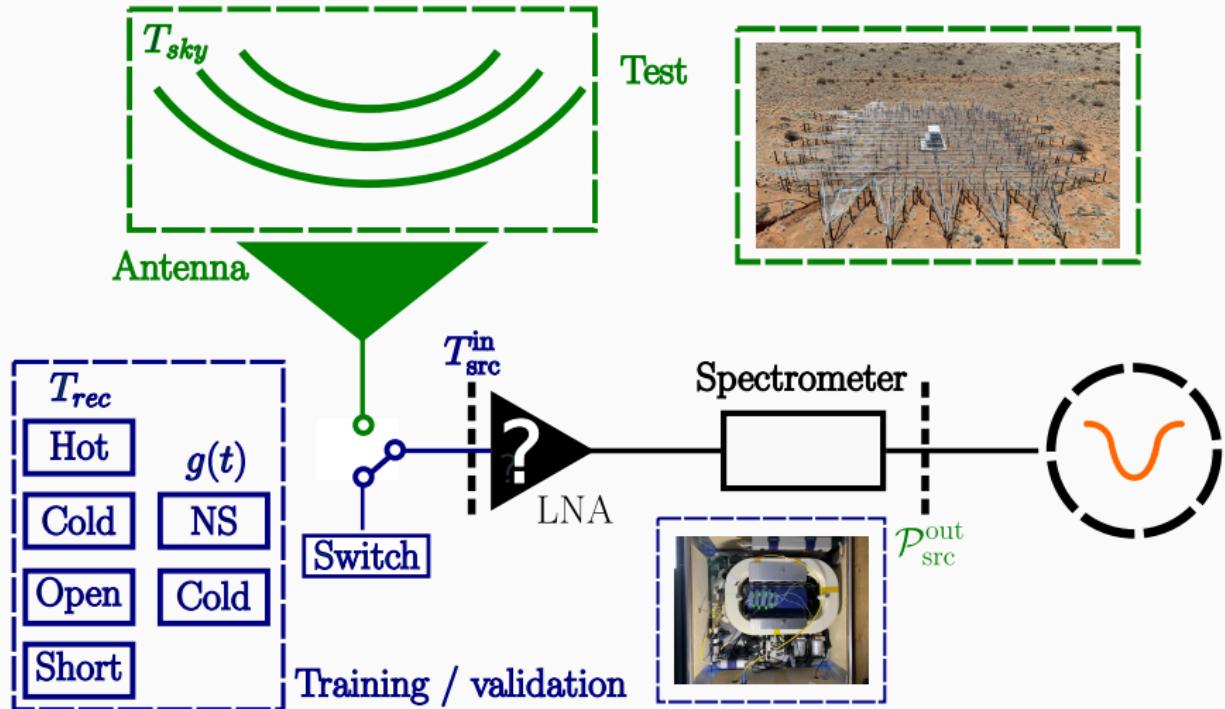
$$P_{\text{out}}^{\text{src}} = g M \left(T_{\text{in}}^{\text{src}} + T_{\text{min}} + T_0 \frac{4R_N}{Z_0} \frac{|\Gamma_{\text{src}} - \Gamma_{\text{opt}}|^2}{(1 - |\Gamma_{\text{src}}|^2)(1 + |\Gamma_{\text{opt}}|^2)} \right) \quad (2)$$

Noise Wave Equation:

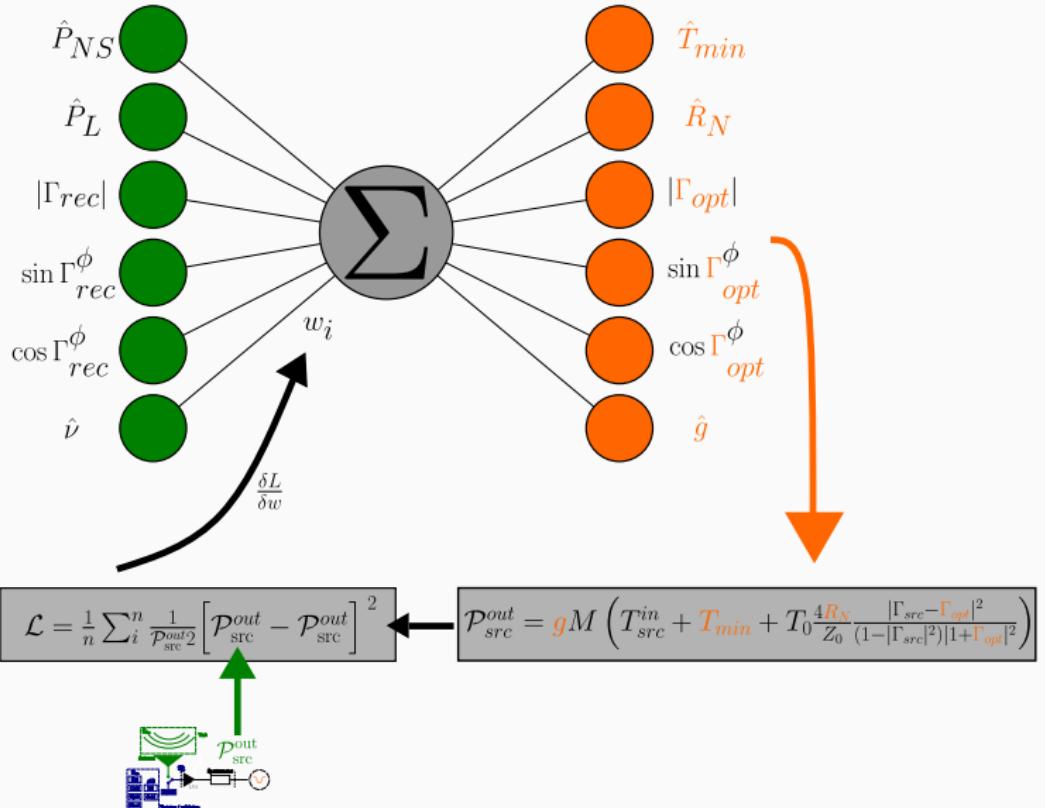
$$\begin{aligned} P_{\text{out}}^{\text{src}} = & g \left[T_0 + T_{\text{unc}} |\Gamma_s|^2 \left| \frac{\sqrt{1 - |\Gamma_{\text{rec}}|^2}}{1 - \Gamma_s \Gamma_{\text{rec}}} \right|^2 \right. \\ & + T_s (1 - |\Gamma_s|^2) \left| \frac{\sqrt{1 - |\Gamma_{\text{rec}}|^2}}{1 - \Gamma_s \Gamma_{\text{rec}}} \right|^2 + T_{\text{cos}} \Re \left(\Gamma_s \frac{\sqrt{1 - |\Gamma_{\text{rec}}|^2}}{1 - \Gamma_s \Gamma_{\text{rec}}} \right) \\ & \left. + T_{\text{sin}} \Im \left(\Gamma_s \frac{\sqrt{1 - |\Gamma_{\text{rec}}|^2}}{1 - \Gamma_s \Gamma_{\text{rec}}} \right) \right] \end{aligned} \quad (3)$$

We still end up with 5 unknowns, as before.

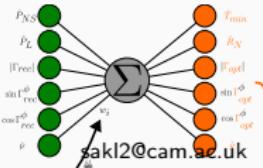
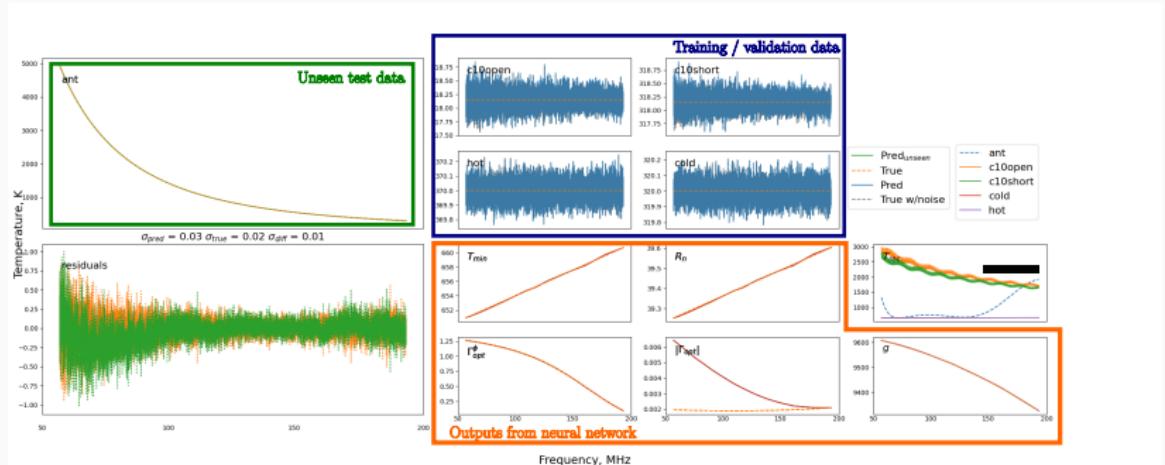
Machine learning for radiometer calibration in global 21cm cosmology



Machine learning for radiometer calibration in global 21cm cosmology



Machine learning for radiometer calibration in global 21cm cosmology



Thank you!



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