Lecture 2 - Regression

Goal: learn real valueding mapping $f: \mathbb{R}^d \to \mathbb{R}$



$$x = \begin{bmatrix} x_1, \dots, x_d \end{bmatrix}^{\mathsf{T}}, \quad f : \mathbb{R}^d \to \mathbb{R}$$

$$\omega = \begin{bmatrix} \omega_1, \dots, \omega_d \end{bmatrix}^{\mathsf{T}}, \quad f(x) = \underline{\omega}^{\mathsf{T}} x$$

$$1-\dim: y = f(x) = ax+b$$

2-dim:
$$y = w_1 x_1 + w_2 x_2 + w_0$$



$$= \sum_{i=1}^{d} \omega_i x_i + \omega_0$$
$$= \omega^T x + \omega_0$$

Homogeneous Representation

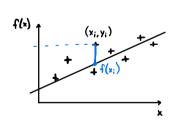
$$\tilde{\mathbf{x}} = \begin{bmatrix} \mathbf{w}_1, \dots, \mathbf{w}_d, \mathbf{w}_o \end{bmatrix} = \begin{bmatrix} \mathbf{w}^\mathsf{T}, \mathbf{w}_o \end{bmatrix}^\mathsf{T}$$

$$\tilde{\mathbf{x}} = \begin{bmatrix} \mathbf{x}_1, \dots, \mathbf{x}_d, \mathbf{1} \end{bmatrix} = \begin{bmatrix} \mathbf{x}^\mathsf{T}, \mathbf{1} \end{bmatrix}$$

$$f(x) = x_{\perp}x$$

* this is just a may to simplify what we write by eliminating the need to separately tack on the wo

Quantifying goodness of Pit



$$D = \{(x_{1}, y_{1}), ..., (x_{n}, y_{n})\}$$

$$x_{i} \in \mathbb{R}^{d} \quad y_{i} \in \mathbb{R}$$
Residual: $f_{i} = y_{i} - w^{T}x_{i}$

cost:
$$\hat{R}(\underline{\omega}) = \sum_{i=1}^{n} r_i^2$$

by 1: we square each residual 4) 2: we sum the squeres

least-squeres ...!

Least-squares linear regression optimization $x. \in \mathbb{R}^d$ Ly given data set $D = \{(x_1, y_1), ..., (x_n, y_n)\}$ y: ∈ 1R Lo how do we find optimal weight vector?

Method 1: Closed form solution

$$w^* = \arg\min_{i=1}^{n} \left(y_i - w^T x_i \right)^2$$
 Empirical Risk Minimizer

defination
$$R(\omega) = \sum_{i=1}^{N} (y_i - \omega^T x_i)^2$$

2. Take gradient with respect to w and set to O.

$$\nabla_{\omega} R(\omega) = -2x^{T}(Y - X\omega)$$
$$-2x^{T}(Y - X\omega) = 0$$

3. Rearrange...

XTXW = XTY

$$X^TX = X^TY$$

4. Now, if XTX is invertible ...

$$(x^{T}x)^{-1}(x^{T}x)_{\omega} = (x^{T}x)^{-1}(x^{T}Y)$$

$$\omega^* = (\chi^T \chi)^{-1} \chi^T \gamma$$

Time Complexity of $\omega^* = (X^T X)^{-1} X^T y$

$$\begin{array}{c}
\left(\begin{array}{c} X^{T} X_{nxd} \right)^{-1} X_{nxd} Y_{nxl} \\
\bigcirc (nd^{2}) \bigcirc (d^{3}) \bigcirc (nd) \\
\Rightarrow \bigcirc (nd^{2} + d^{3})
\end{array}$$

Graduent Descent Method 2: Optimization The objective function $\hat{R}(w) = \sum_{i=1}^{\infty} (y_i - w^T x_i)^2$ is convex! · Start at arbitrary wo E Re for weight vector Gradient Descent · For t=1,2,...do w = w - 7+ VR (w) 1 for each iteration, 1 learning rate (e.g. 1 for least squeres) opdate the weight vector by taking a step in the opposite direction of the gradient of the objective function Convergence Ly converges to stationary point $\nabla = 0$ La optimal! Lo $O(\log \frac{1}{\epsilon})$ to get within ϵ of the minimum of objective function. Time Complexity: O(nd) to compute gradient Adaptive Step Size La line search Lo "bold driver" heuristic La if function 1, step size 1 Closed form us Gradient Descent?

- compostational complexity

- don't always need 100% optimal

- not all problems of closed form solution

Linear regression for polynomials

Us we can fit non-linear functions via linear regression using non-linear features of our data

$$f(x) = \underbrace{\sum_{i=1}^{D} \omega_{i} \phi_{i}(x)}_{i} \qquad x \xrightarrow{\phi} \tilde{x} = \phi(x)$$

$$[-d: \phi(x) = [1, x, x^{2}, ... x^{k}], k = 0-1$$

2-d:
$$\phi(x) := \phi([x_1, x_2]) = [1, x_1, x_2, x_1, x_2, x_1^2, x_2, ...]$$

$$\vdots$$

$$\rho\text{-dim } \phi(x) = O(\rho^k) \text{ vs } O(k^p)$$