Sam Lobel

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EDUCATION

Brown University

Providence, RI 2019–Current

Ph.D. in Computer Science, Candidate

Doctoral Advisor: George Konidaris

- Research Area: Sparse-Reward Reinforcement Learning

- Funded by the NSF Graduate Research Fellowship

University of Pennsylvania

Philadelphia, PA

2011 - 2015

B.A. in Physics and Astronomy, GPA: 3.7/4.0

- Minors: Mathematics, Computer Science

Conference Publications

- 1. Cameron Allen*, Aaron Kirkland*, Ru Yu Tao*, **Sam Lobel**, Daniel Scott, Nicholas Petrocelli, Omer Gottesman, Ronald Parr, Michael Littman, George Konidaris. Resolving Partial Observability in Decision Processes via the Lambda Discrepancy. *Neural Information Processing Systems (Neurips)*, 2024.
- 2. **Sam Lobel**, Ronald Parr. An Optimal Tightness Bound for the Simulation Lemma. *Reinforcement Learning Conference (RLC)*, 2024.
- 3. Sam Lobel, Akhil Bagaria, George Konidaris. Flipping Coins to Estimate Pseudocounts for Exploration in Reinforcement Learning. *International Conference on Machine Learning (ICML)*, 2023. Oral Presentation (top 3% of submissions)
- 4. Sam Lobel*, Sreehari Rammohon*, Bowen He*, Shangqun Yu, George Konidaris. Q-Functionals for Value-Based Continuous Control. Association for the Advancement of Artificial Intelligence (AAAI), 2023. Oral Presentation (top 11% of submissions)
- 5. Omer Gottesman, Kavosh Asadi, Cameron Allen, **Sam Lobel**, George Konidaris. Coarse-Grained Smoothness for Reinforcement Learning in Metric Spaces. *International Conference on Artificial Intelligence and Statistics (AISTAT)*, 2023.
- 6. Sam Lobel, Akhil Bagaria, Cameron Allen, Omer Gottesman, George Konidaris. Optimistic Initialization for Exploration in Continuous Control. Association for the Advancement of Artificial Intelligence (AAAI), 2022.
- 7. Sam Lobel*, Chunyuan Li*, Jianfeng Gao, Lawrence Carin. RACT: Towards Amortized Ranking-Critical Training for Collaborative Filtering. *International Conference on Learning Representations (ICLR)*, 2020.
- 8. Matthew Gratale, Tim Still, Caitlin Matyas, Zoey Davidson, **Sam Lobel**, Peter Collings, Arjun Yodh. Tunable Depletion Potentials Driven by Shape Variation of Surfactant Micelles. *Physical Review E*, 2016.

INVITED TALKS

- Oral Presentation of Flipping Coins to Estimate Pseudocounts for Exploration in Reinforcement Learning at ICML 2023. Recording Link.
- Presented in-progress work relating to the paper Flipping Coins to Estimate Pseudocounts for Exploration in Reinforcement Learning for an exploration group at Deepmind, London. August 2022
- Presented overview of RACT: Towards Amortized Ranking-Critical Training for Collaborative Filtering for Aggregate Intellect. June, 2020. Recording Link.

TEACHING

• PhD Programming Exam Coordinator at Brown University

Along with one faculty member, created and administered month-long programming portion of PhD Comprehensive Exams, a requirement for candidacy.

• Volunteer Teacher And Coordinator at Sayre High School (Philadelphia, PA)

Created and independently taught the first programming course at a Philadelphia public school in a high-need Promise Zone. Mentored 6 seniors towards becoming proficient shell and Python programmers. Continued to advise one student as they entered college to study Computer Science.

• Physics and Computer Science TA and Tutor at University of Pennsylvania 2012-2015

Worked as a teaching assistant or tutor for 5 consecutive semesters in both Physics and Computer
Science. Acted as Head TA of the Physics Department's first experimental "flipped classroom" course.

INDUSTRY EXPERIENCE

Metametrics Inc
Software Developer

Durham, NC
2017 - 2019

Performed a mixture of machine learning and backend web development. Developed a genre-categorizor using a
private book-text dataset, an essay-scoring tool for standardized testing, and various interfaces for psychometric
analysis of student data.

Forward Philadelphia

Philadelphia, PA 2014 - 2017

2016-2017

Software Developer

— My first programming job. Advanced from internship to senior developer over course of hire. Automated collection and analysis of public property data from various Philadelphia government organizations, and created web interfaces for untangling complicated deed-ownership relations.

Programming Skills

Language: Python. ML Frameworks: PyTorch, JAX. RL tools: Acme, PFRL, Mujoco. Familiar but not proficient with: Rust, ROS.

Relevant Coursework

Robust Machine Learning, Nonlinear Dynamical Systems, Algorithmic Game Theory, Probabilistic Methods, Sequential Decision Making, Statistical Learning Theory, Statistical Mechanics