GENERATE

Generating Software for Well-Understood Domains

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Old Fashioned?

I enjoyed reading this short paper. It is a very classical paper, reminiscing of the DSL systems of the early days, like Neighbor's Draco and Baxter's DMS. Indeed, it is an old vision to represent domain knowledge first-class, to avoid duplication, and offer variation points to make engineering trade-offs.

- Referee 2

As general feedback, the paper's message reads a bit "old-fashioned". The "well-understood" qualification is nice (because it qualifies what would otherwise be overly-general statements) but the actual benefit claimed is straight out of the playbook of the "automatic programming" community of the 80s and 90s. For instance, I was strongly reminded of Novak's GLisp...

— Referee 3

Well Understood?

Given F, Q, κ , ϕ , γ calculate:

$$\mathbf{K} = \int_{V} \mathbf{B}^{T} \mathbf{D}^{vp} \mathbf{B} dV; \mathbf{F} = \mathbf{R}_{i} - \int_{V} \mathbf{B}^{T} \sigma_{i} dV + \int_{V} \mathbf{B}^{T} \Delta \sigma^{vp} dV \quad (1)$$

with

$$\mathbf{D}_{vp} = \mathbf{D} \left[\mathbf{I} - \Delta t C_1 \lambda' \frac{\partial Q}{\partial \sigma} \left(\frac{\partial F}{\partial \sigma} \right)^T \mathbf{D} \right], \lambda' = \frac{d\lambda}{dF}$$
 (2)

$$\Delta \sigma^{vp} = \Delta t C_1 \lambda \mathbf{D} \frac{\partial Q}{\partial \sigma}$$
 (3)

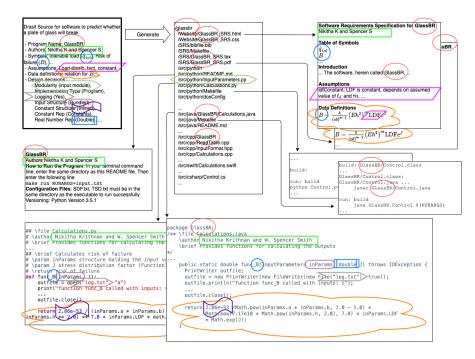
$$C_1 = [1 + \lambda' \Delta t (H_e + H_p)]^{-1}$$
 (4)

$$H_{e} = \left(\frac{\partial F}{\partial \sigma}\right)^{T} \mathbf{D}\left(\frac{\partial Q}{\partial \sigma}\right) \tag{5}$$

$$H_{p} = -\frac{\partial F}{\partial \kappa} \left(\frac{\partial \kappa}{\partial \epsilon^{vp}} \right)^{T} \frac{\partial Q}{\partial \sigma}$$
 (6)

Well

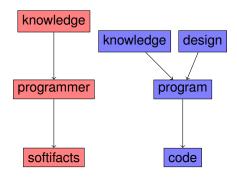
Understood!



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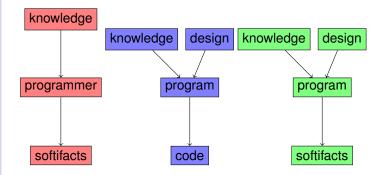


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Process



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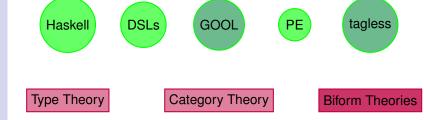
Key Philosophical Differences

```
Documentation Types
                                                Software
                                             documentation
                             Product
                                                                     Process
                         documentation
                                                                 documentation
                                                                 Plans
    System
                                           User
                                                                 Schedules
documentation
                                      documentation
                                                                 Reports
                                                                 Working papers
Requirement document
Design and Architecture
Source Code
Validation, Verification and
                                                   System
                              End User
Maintenance or beln
                                                Administrators
guide
```

```
## \file Projectile.py
# \author Samuel J. Crawford, Brooks MacLachlan, and W. Spencer Smith
# \brief Contains the entire Projectile program
import math
import sys
# \brief Calculates flight duration: the time when the projectile lands (s)
# \param v_launch launch speed: the initial speed of the projectile when launched (m/s)
# \param theta launch angle: the angle between the launcher and a straight line from the launcher to
# \param quect gravitational acceleration (m/s'2)
# \return flight duration: the time when the projectile lands (s)
def func_t_flight(v_launch, theta, g_vect):
    return 2.0 * v_launch * math.sin(theta) / g_vect
```

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Better Technology & Theory



Lenses

What if we generated it all*?



* when it makes sense do to so

ALLTHETHINGS