

iMup: A Body Position Tracker

Sarah Moninger¹, Chandra Throckmorton, PhD⁴, Leighanne Davis, BS¹ Juliessa Pavon, MD, MHS^{2, 5}, Kevin Caves, ME, ATP, RET^{1,2,3}

Duke University

¹Department of Surgery; Division of Head and Neck Surgery & Communication Sciences ²Department of Medicine, ³Department of Biomedical Engineering

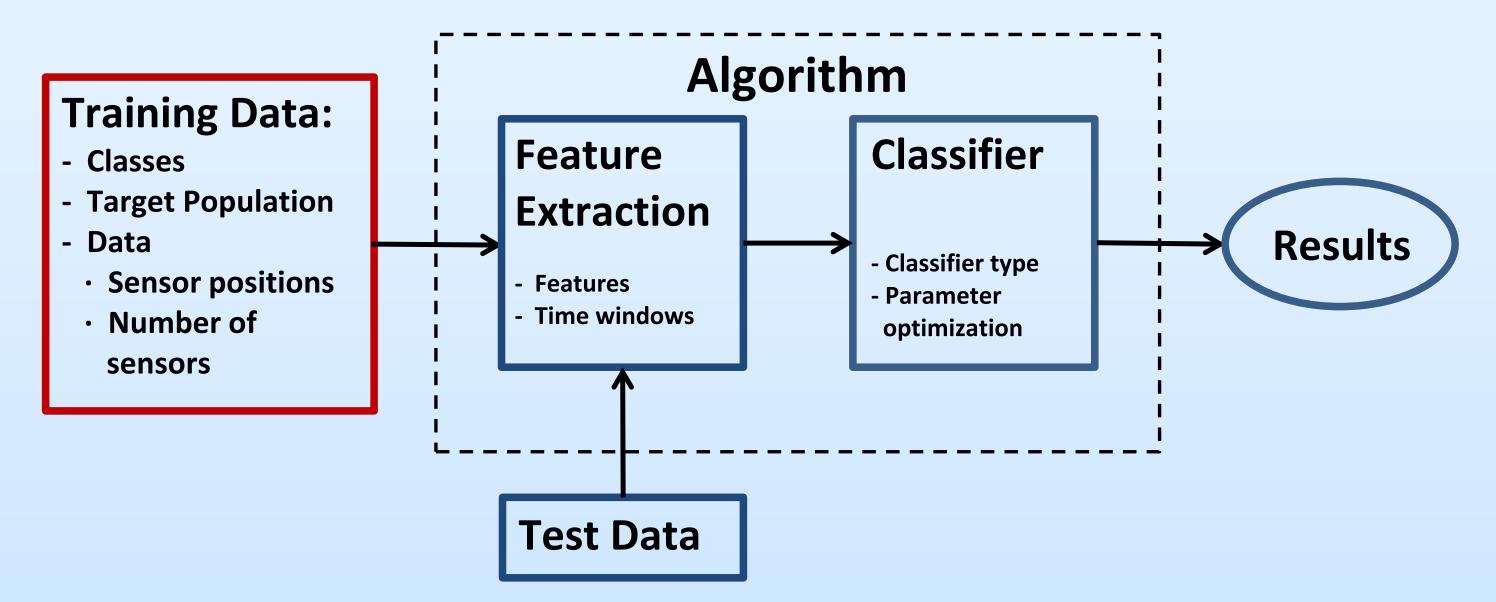
⁴Signal Analysis Solutions ⁵Durham VA Geriatrics (GRECC)





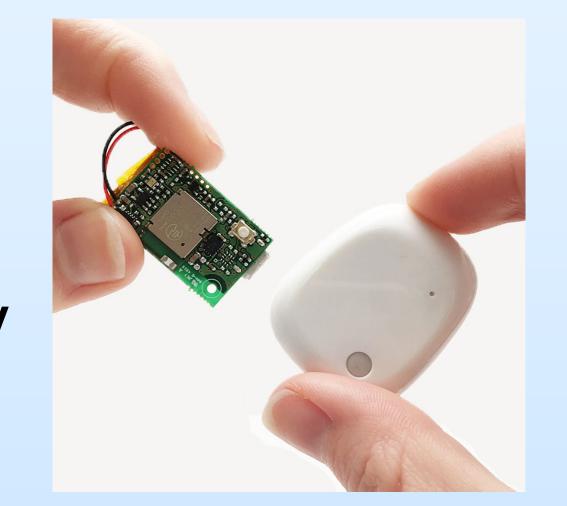
Research Objective

- To collect human data to train a machine learning algorithm to determine body position to help inform care
- To accurately determine laying, reclining, sitting, standing and walking



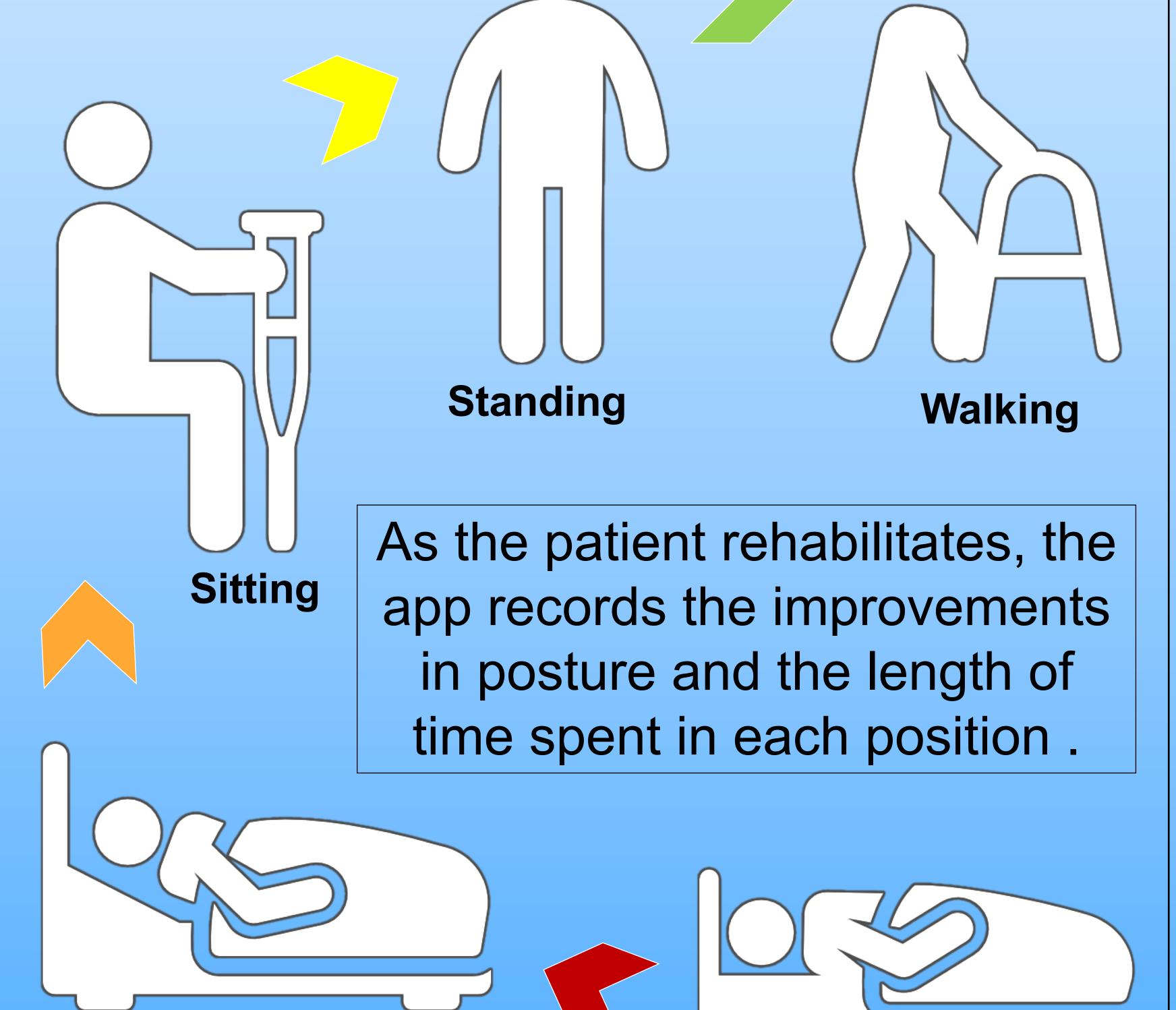
Data Collection & Design

- 15 healthy older adults (55 and older)
- 15 healthy adults (18 55 years old)
- Participants wore 2 sensors (Mbient MetaMotionR) on right thigh and right chest under clavicle
- 10 minutes of activity per subject
- Subjects directed through each position, maintaining for 1 minute, twice
- Data was captured remotely by iOS mobile application



MetaMotionR Sensor

Position Tracking



Reclining

Results of Initial Trials

Geriatric LOSO: 95% correct 84.7 14.6 0.7 0 [459] 95.1 3.6 1.3 0 Reclining [468] Truth 96.5 0.2 1.1 Sitting [461] 0.2 99.1 0.7 0 Standing [442] 0 99.4 0.6 0 Walking [475] Standing Reclining Sitting Walking Laying Response

Overall accuracy of ML algorithm is 95%

Conclusions

Preliminary studies show data from two worn accelerometers can determine an individual's body position. The algorithm will be used to inform future clinical movement analysis and clinician reporting based on custom trained data.

The Rehabilitation Engineering Research Center for Information and Communication Technology Access (LiveWell RERC) is funded by a 5-year grant from the National Institute on Disability, Independent Living and Rehabilitation Research in the U.S. Department of Health and Human Services (grant number 90RE502a3). The opinions are those of the LiveWell RERC and do not necessarily reflect those of the U.S. Department of Health and Human Services or NIDILRR.

Laying

For More information or if you have project ideas, contact: leighanne.davis@duke.edu or kevin.caves@duke.edu