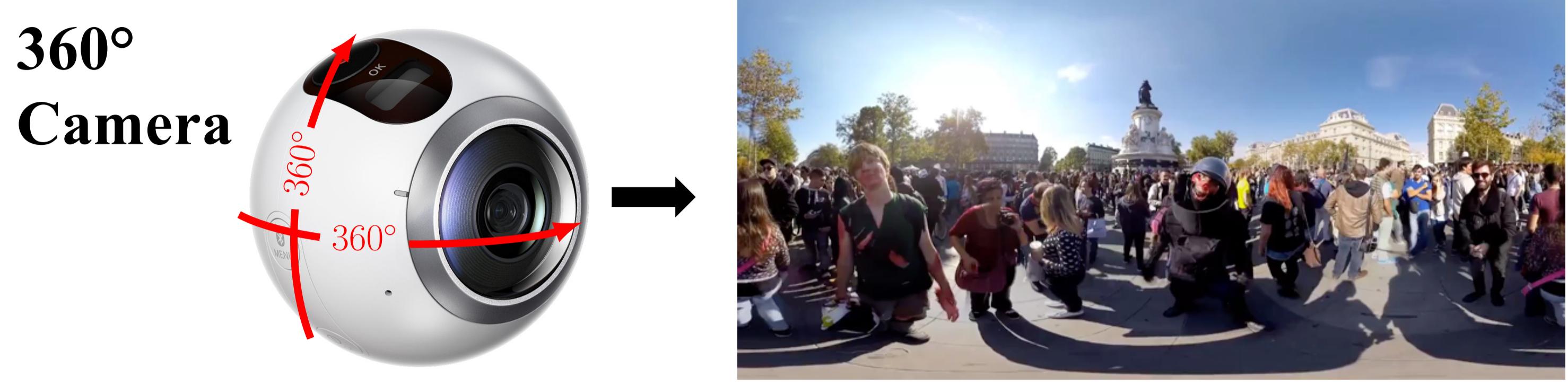


# Pano2Vid: Automatic Cinematography for Watching 360° Video

Yu-Chuan Su, Dinesh Jayaraman, and Kristen Grauman  
The University of Texas at Austin  
<http://vision.cs.utexas.edu/projects/Pano2Vid/>



## 1. Pano2Vid



### Challenge for watching 360° video:

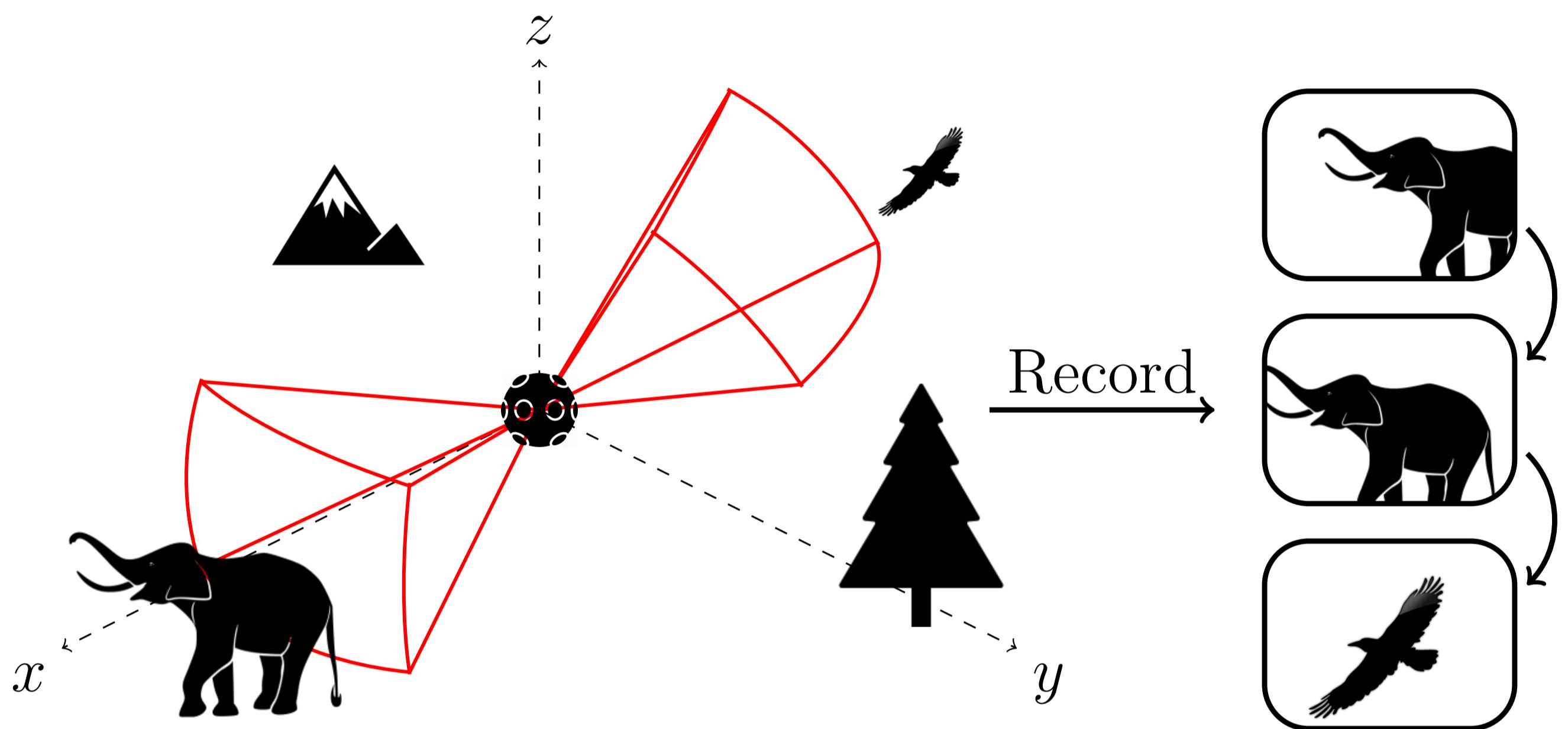
How to find the right direction to watch?

### Pano2Vid Definition

**Input:** 360° video

**Output:** “natural-looking” normal-field-of-view (NFOV) video

**Task:** control the virtual camera direction



## 2. Proposed Solution – AutoCam

**Key Idea:** Learn videography tendencies from Web videos

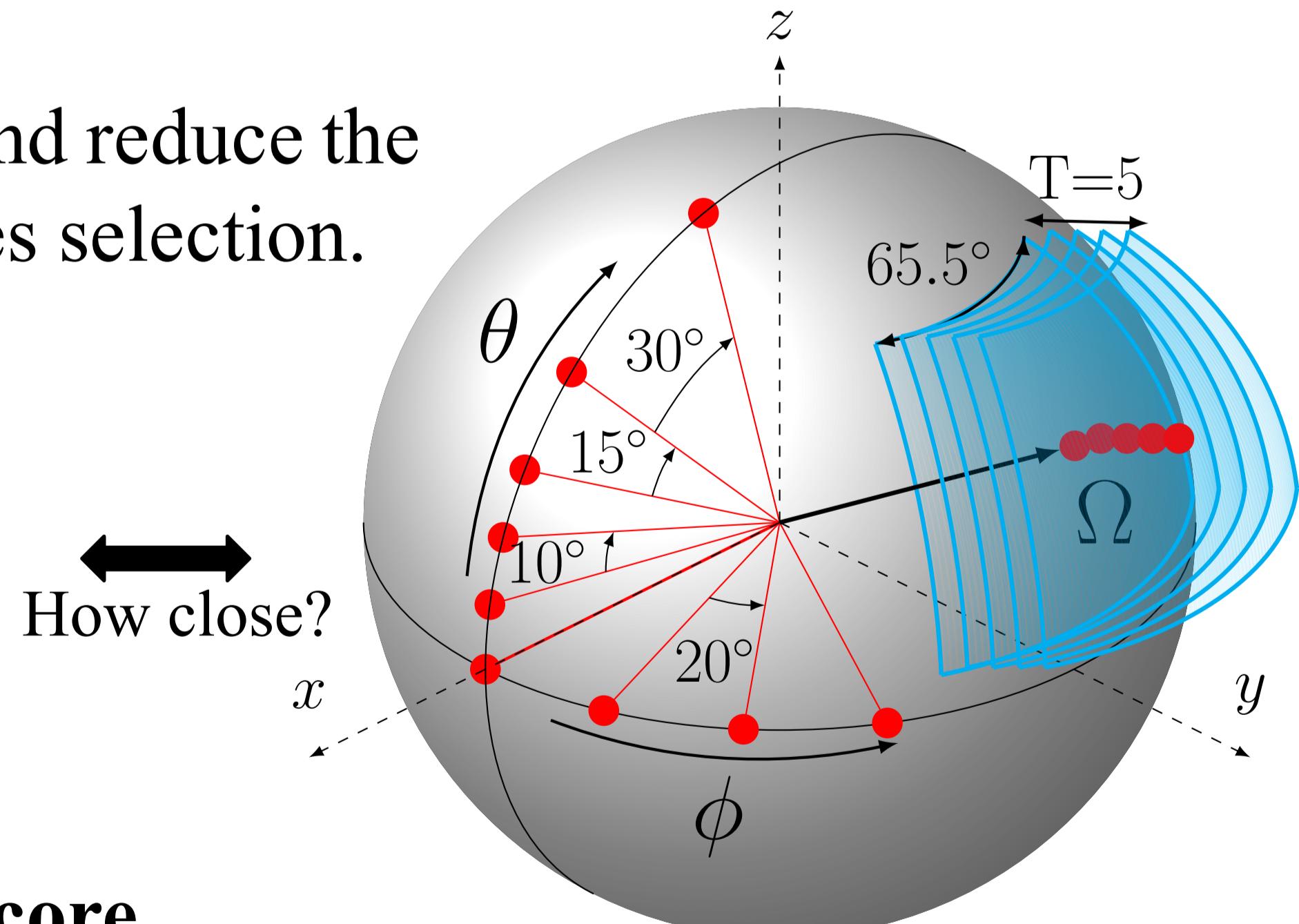
- Learn diverse capture-worthy content
- Pickup proper composition

### Spatio-Temporal Glimpses

- Short NFOV video extracted from 360° video
- Makes 360° content comparable with NFOV videos
- Fixed camera parameter & direction

### Sample ST-glimpses

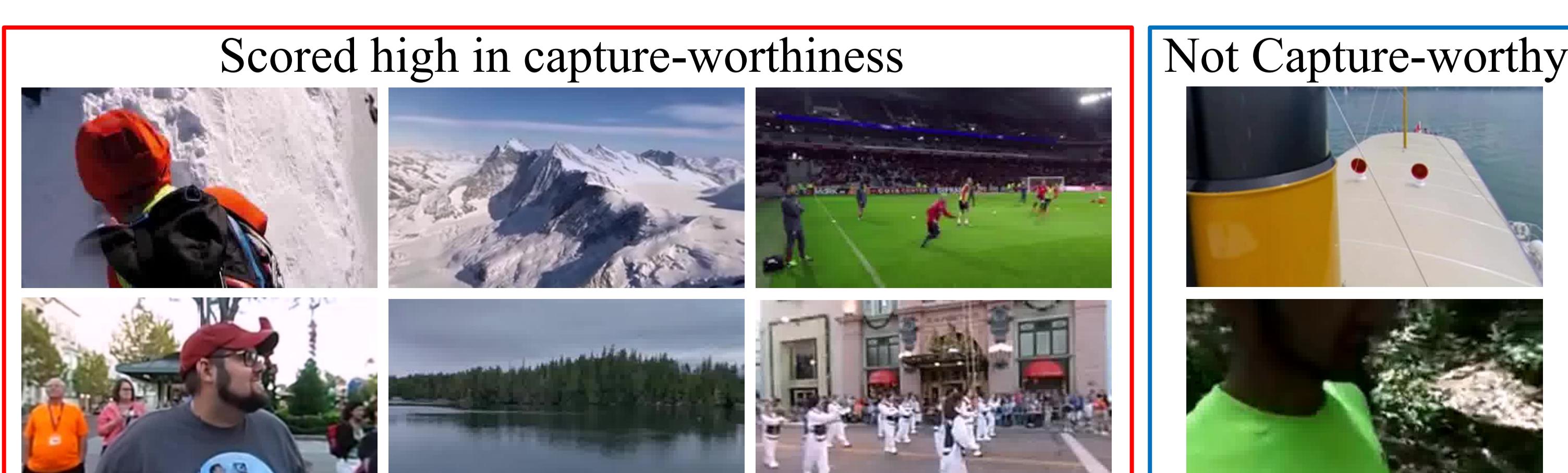
Sample ST-glimpses and reduce the problem to ST-glimpses selection.



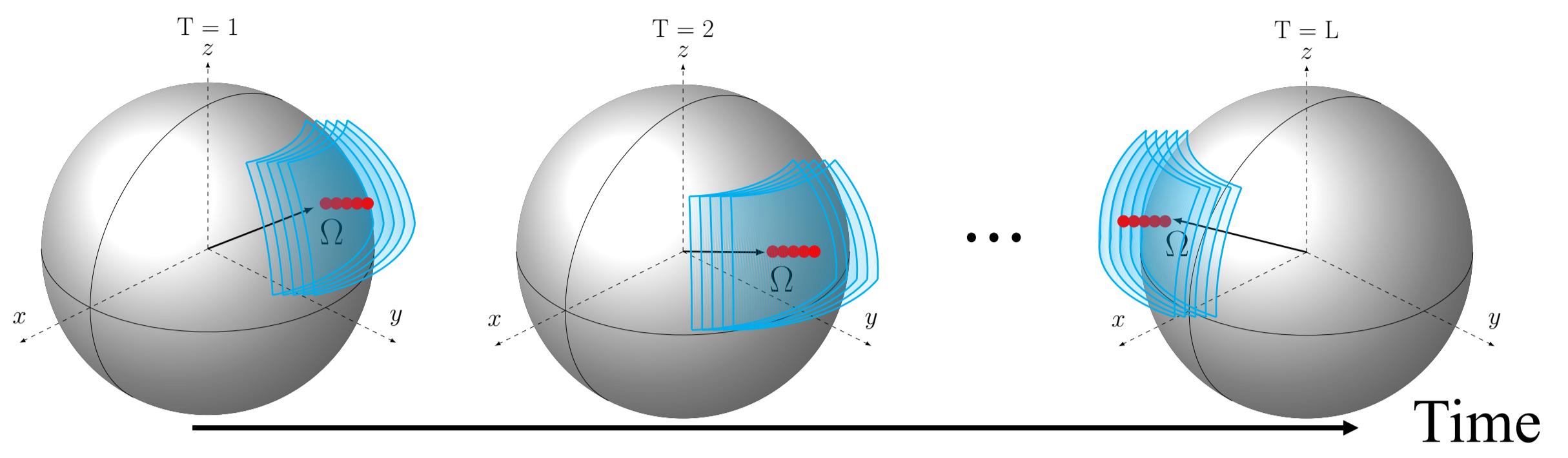
### Capture-worthiness score

- Does the ST-glimpse looks human-captured?
- Implement by discriminative classifier

### Example ST-glimpses



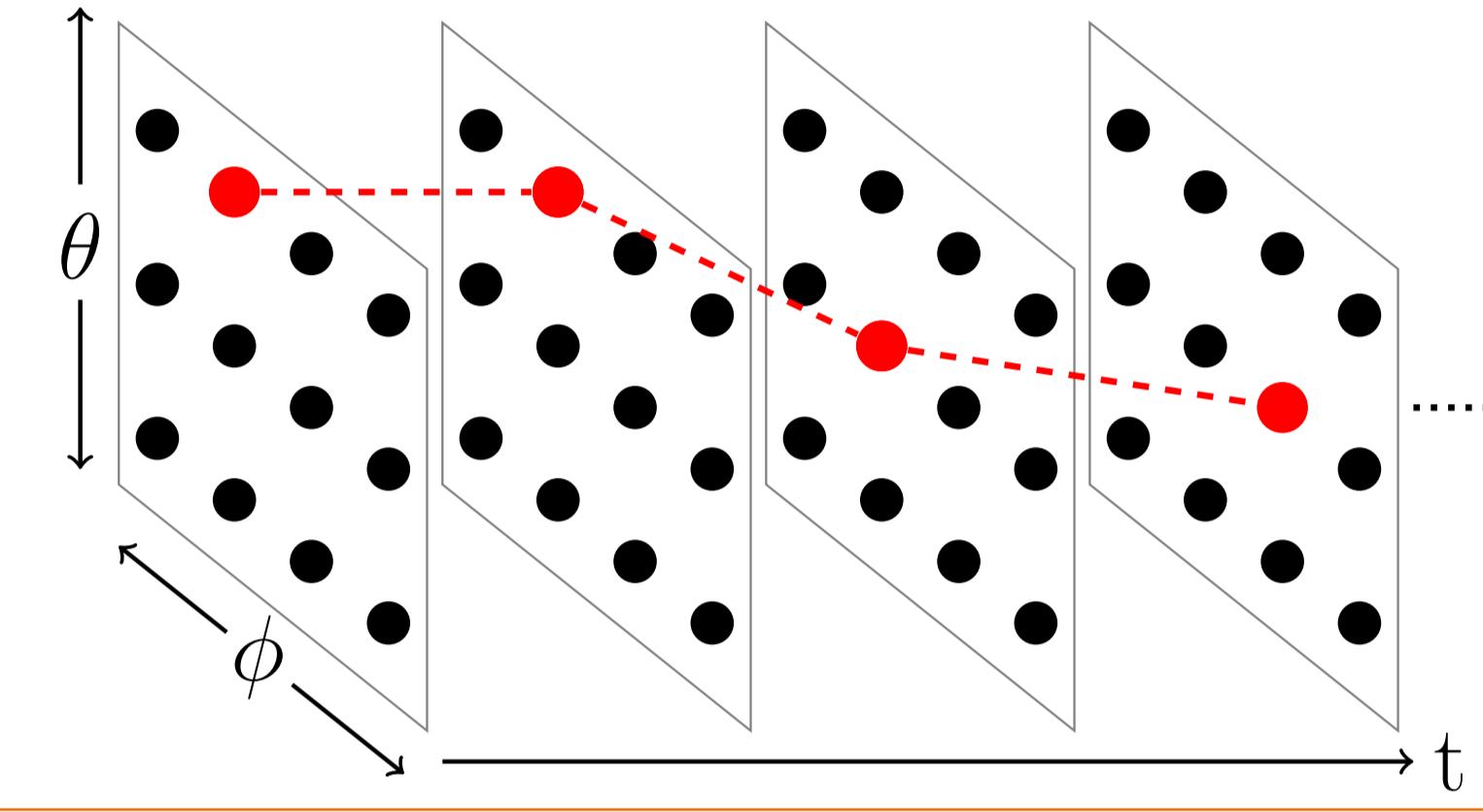
## Construct Virtual Camera Trajectory



- Maximize accumulated score
- Smooth camera motion

$$|\Delta\Omega_\theta| = |\theta_t - \theta_{t-1}| \leq \epsilon_\theta, |\Delta\Omega_\phi| = |\phi_t - \phi_{t-1}| \leq \epsilon_\phi$$

Reduce to shortest path problem



## 4. Evaluation Metrics

### HumanCam-based Metrics

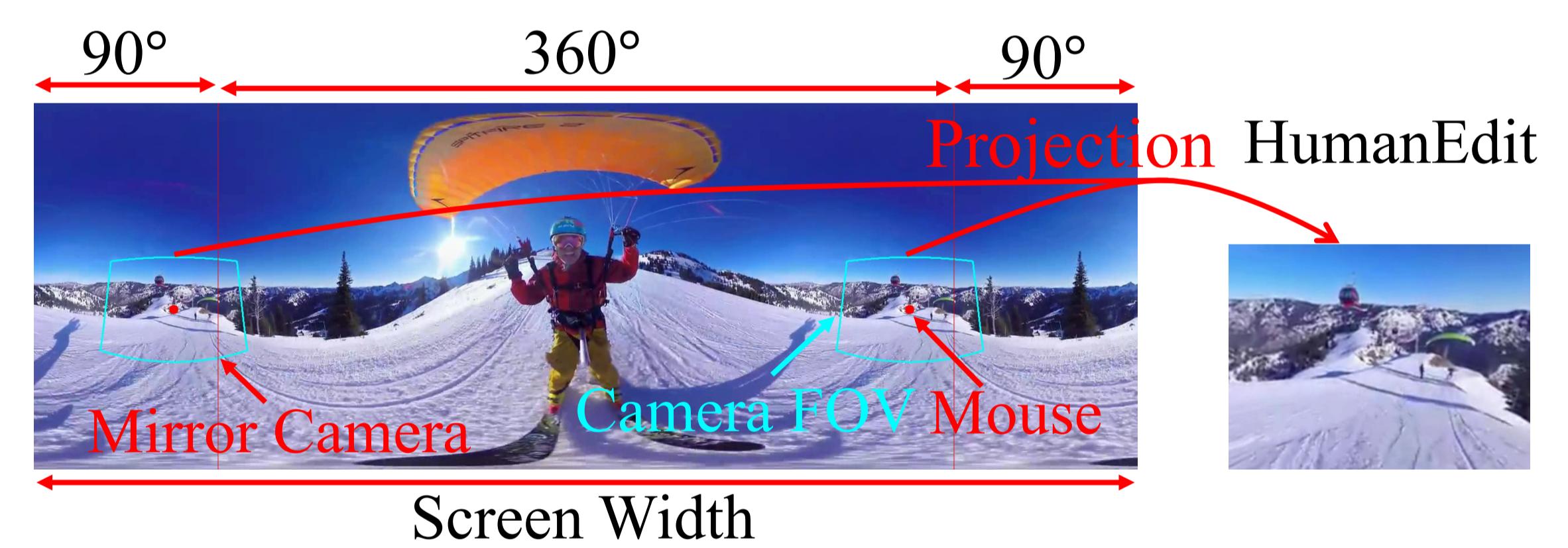
Output videos should look like human-captured videos.

- **Distinguishability**
- **HumanCam-likeness**
- **Transferability**

### HumanEdit-based Metrics

Virtual camera trajectories should be similar to human-selected ones.

- **Cosine similarity**
- **FOV overlap**



## 5. Experiments

**Dataset:** videos crawled from YouTube using keywords

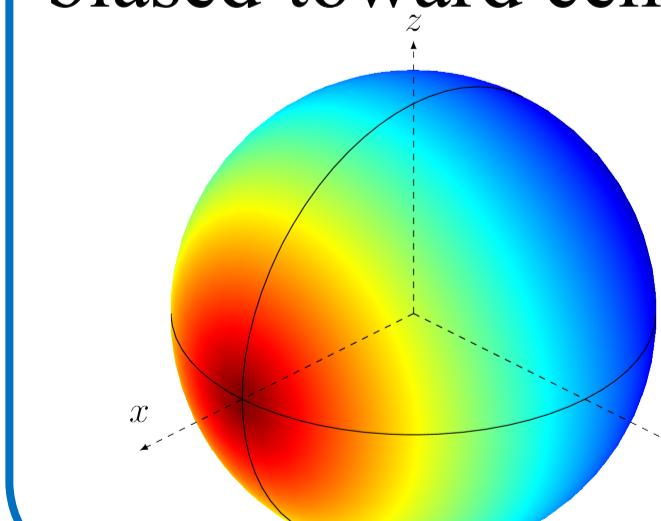
“Hiking”, “Mountain climbing”, “Parade”, “Soccer”

	# videos	Total length
360° videos*	86	7.3 hours
HumanCam	9,171	343 hours
HumanEdit	20 <sup>#</sup>	202 minutes

### Baselines

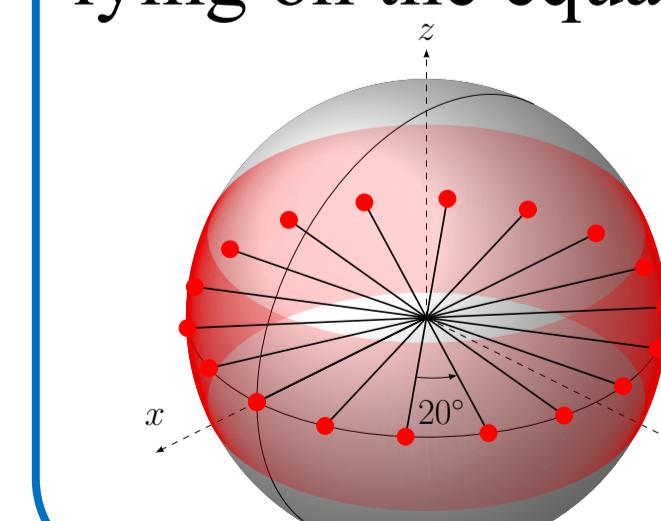
#### Center prior

Random trajectories biased toward center



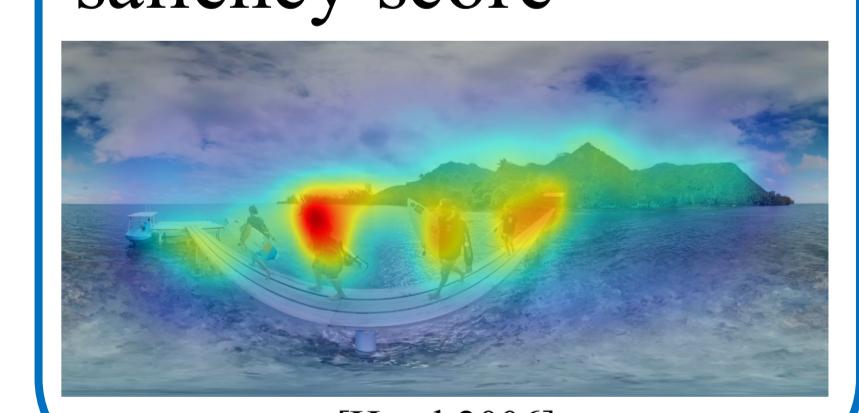
#### Eye-level prior

Static trajectories lying on the equator

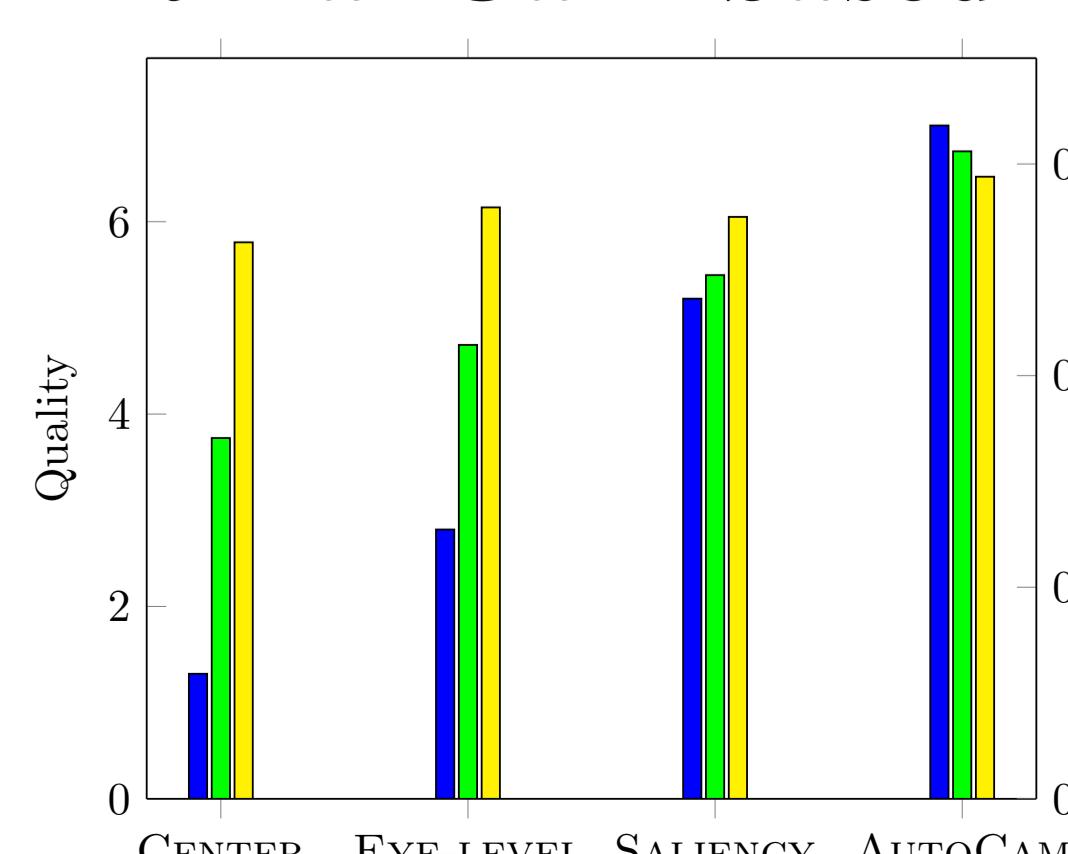


#### Saliency

Replace capture-worthiness with saliency score



### HumanCam-based Metrics



### HumanEdit-based Metrics

