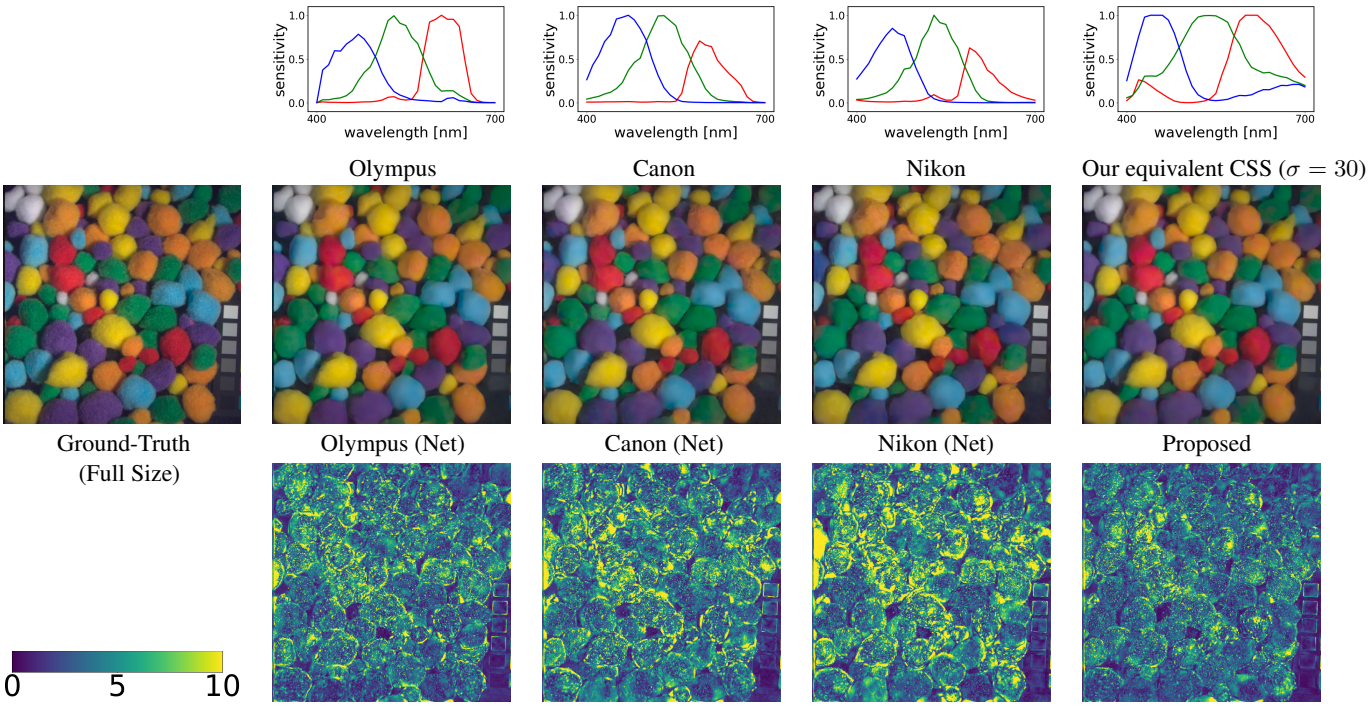

Fig. 1: Visual comparisons and RMSE maps of CAVE dataset for noise level $\sigma = 30$, where Noisy, SP, and Net represent signal processing imaging without denoising, signal processing imaging, and network-based imaging, respectively.

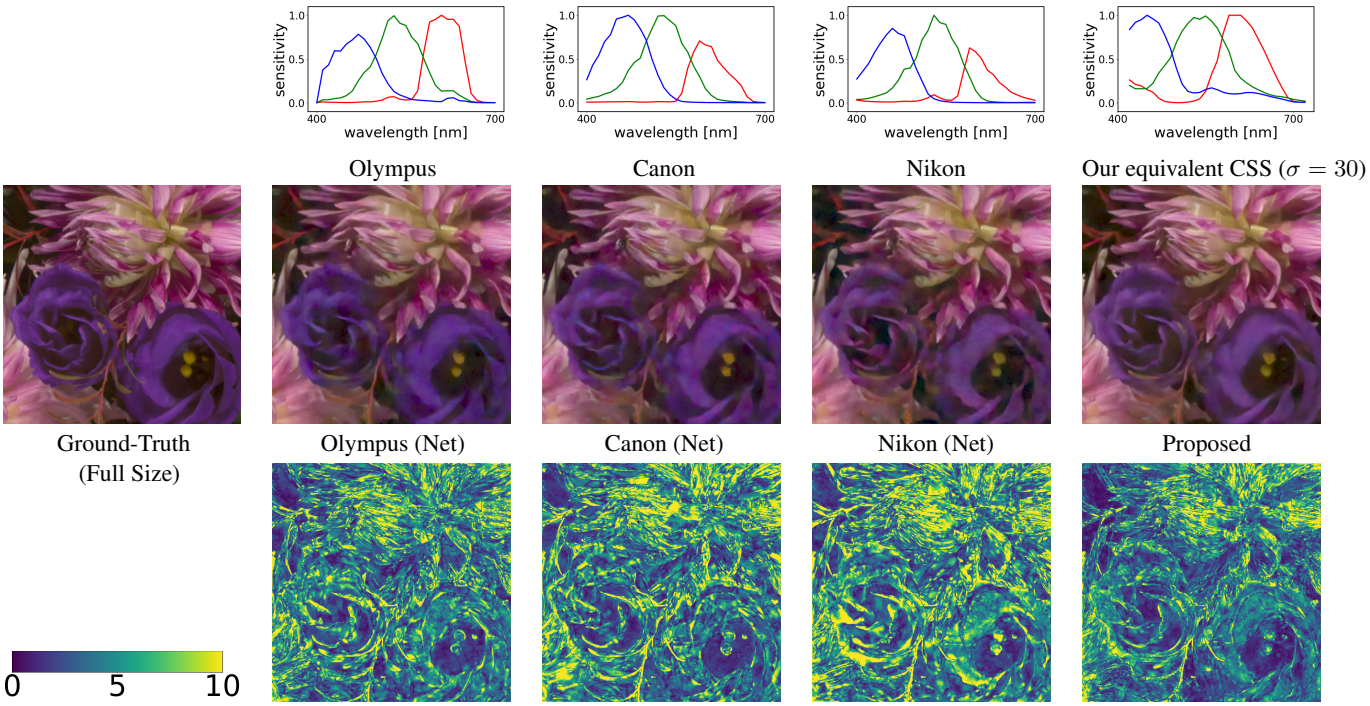

Fig. 2: Visual comparisons and RMSE maps of TokyoTech dataset for noise level $\sigma = 30$, where Noisy, SP, and Net represent signal processing imaging without denoising, signal processing imaging, and network-based imaging, respectively.

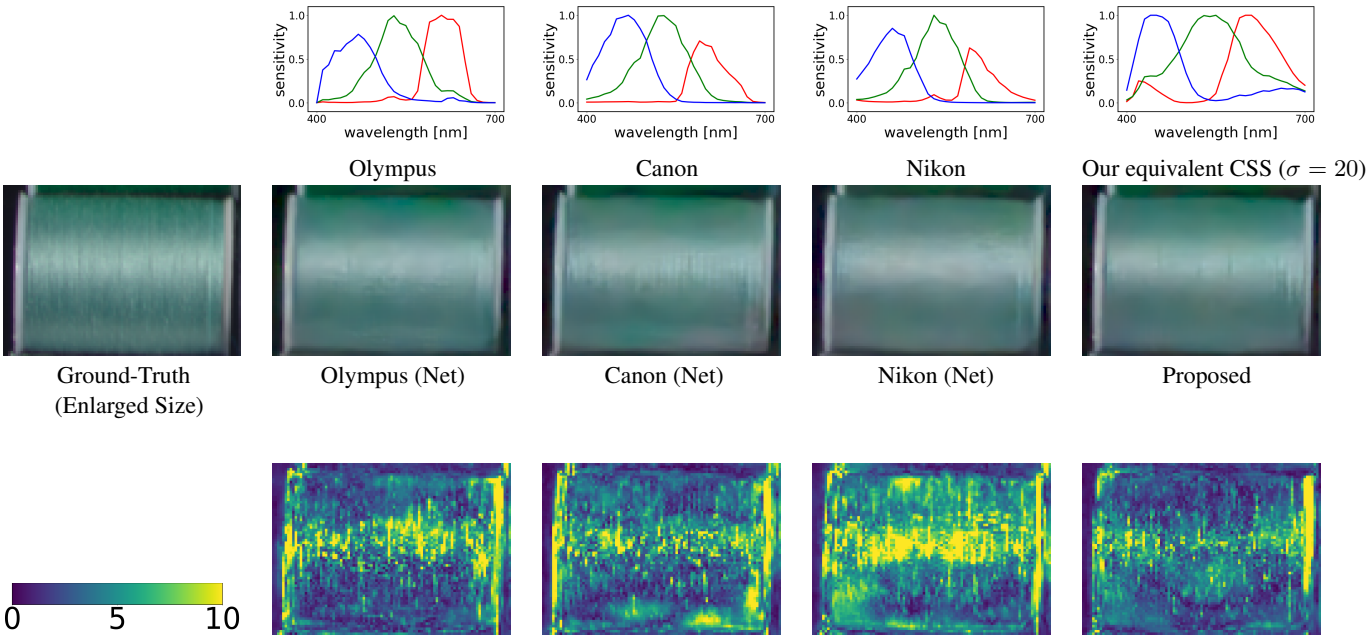

Fig. 3: Visual comparisons and RMSE maps of CAVE dataset for noise level $\sigma = 20$, where Noisy, SP, and Net represent signal processing imaging without denoising, signal processing imaging, and network-based imaging, respectively.

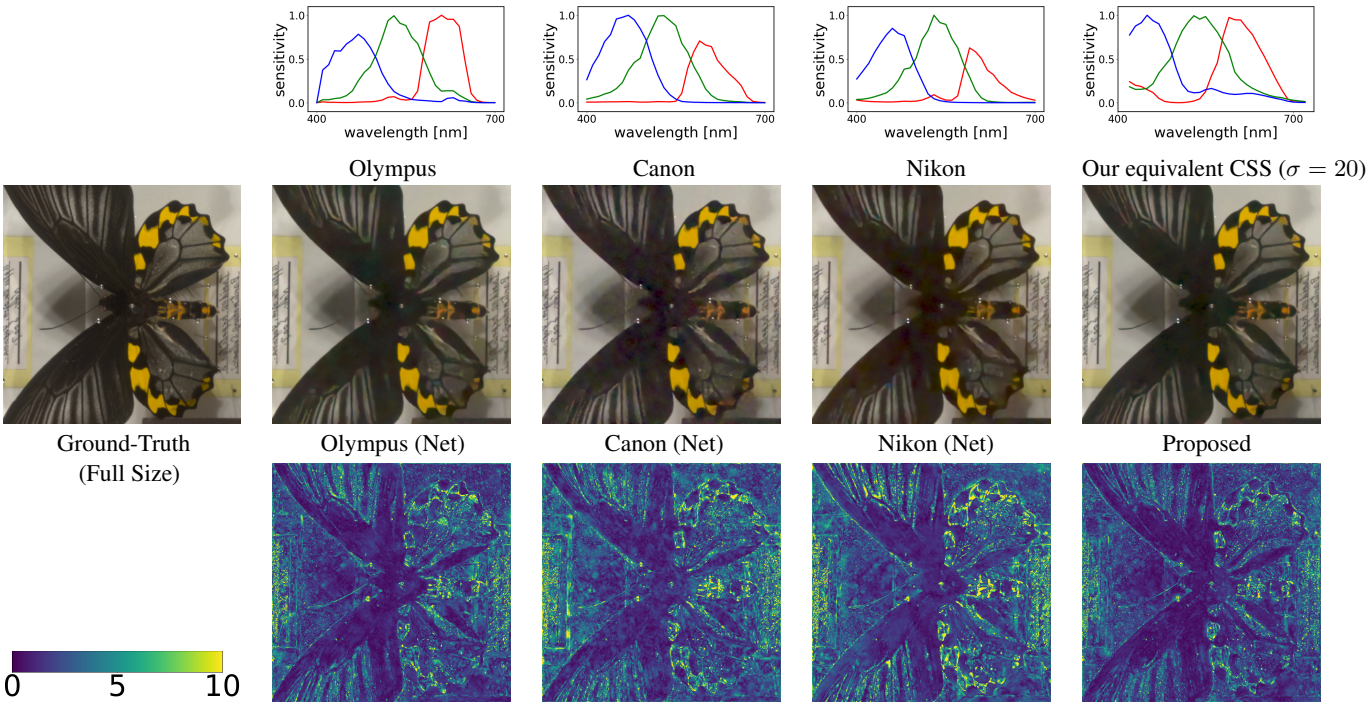

Fig. 4: Visual comparisons and RMSE maps of TokyoTech dataset for noise level $\sigma = 20$, where Noisy, SP, and Net represent signal processing imaging without denoising, signal processing imaging, and network-based imaging, respectively.

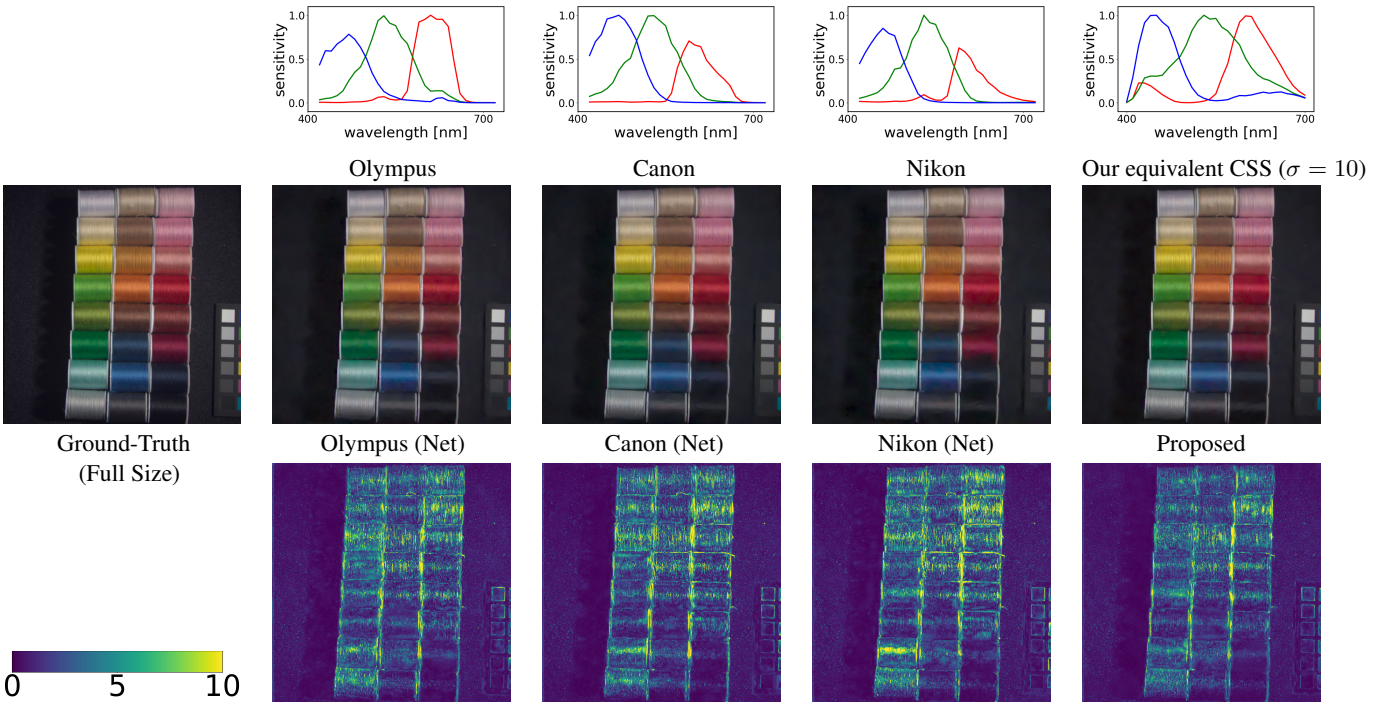

Fig. 5: Visual comparisons and RMSE maps of CAVE dataset for noise level $\sigma = 10$, where Noisy, SP, and Net represent signal processing imaging without denoising, signal processing imaging, and network-based imaging, respectively.

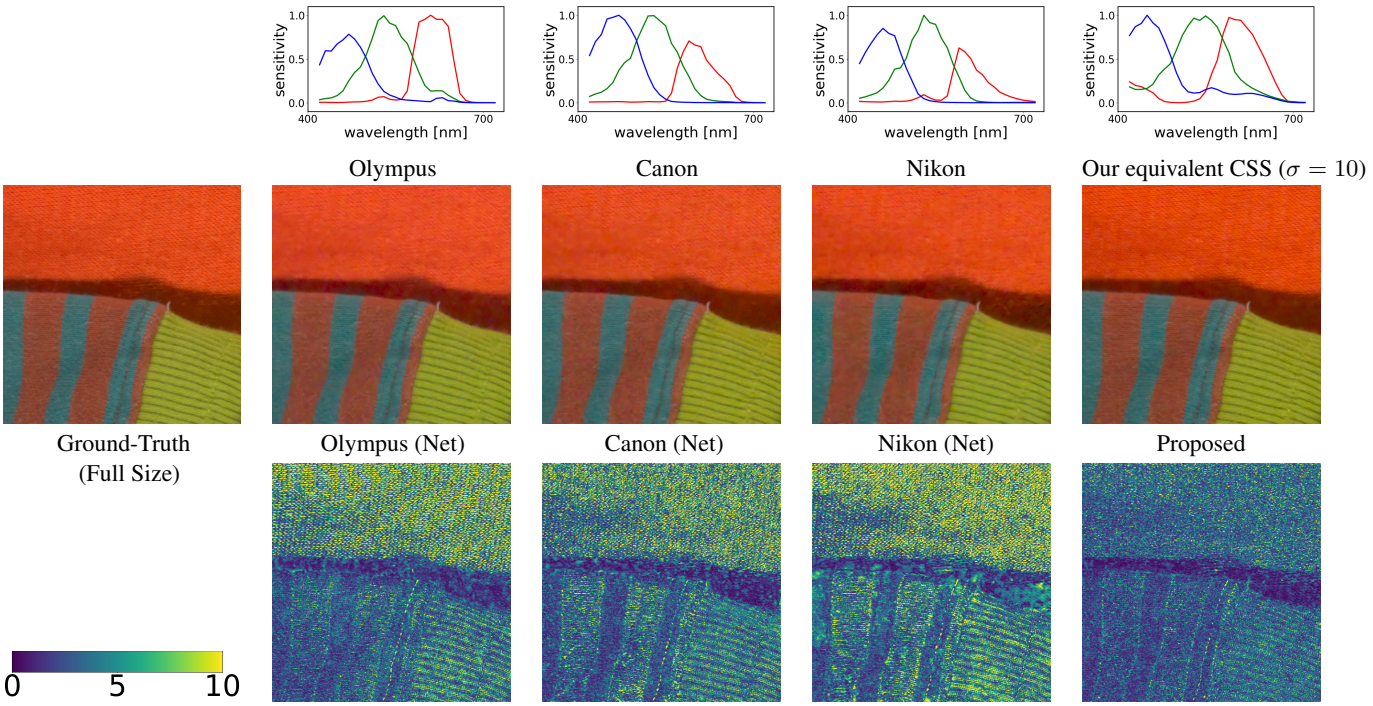

Fig. 6: Visual comparisons and RMSE maps of TokyoTech dataset for noise level $\sigma = 10$, where Noisy, SP, and Net represent signal processing imaging without denoising, signal processing imaging, and network-based imaging, respectively.