# CS CM 182 Homework 9

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I completed this written part of the homework, lab report, or exam entirely on my own.

Suli

Problem 1 SI for linear model

a) Derive the TF for the model given

$$\dot{x}(t) = -p_1 x(t) + p_2 u(t)$$

$$\dot{y}(t) = p_3 x(t)$$
Show  $H(s, p_1, p_2, p_3) = \frac{p_2 p_3}{(s+p_1)}$ 

$$\frac{dx(t)}{dt} = -p_1 x(t) + p_2 u(t)$$

$$\frac{dx(t)}{dt} + p_1 x(t) = p_2 u(t)$$

$$\frac{dx(t)}{dt} = \frac{dy(t)}{dt} \xrightarrow{p_3} (plug into \dot{x}(t))$$

$$\frac{dy(t)}{dt} \xrightarrow{p_3} + p_1 (\frac{y(t)}{p_3}) = p_2 u(t)$$

$$\frac{dy(t)}{dt} \xrightarrow{p_3} + p_1 (y(t)) = p_2 \int_{\mathbb{R}} [u(t)]$$

$$\frac{dy(t)}{dt} \xrightarrow{p_3} f[y(t)] = p_2 \int_{\mathbb{R}} [u(t)]$$

$$\frac{Y(s)}{P_{3}}(S+P_{1}) = P_{2}U(S)$$

$$\frac{Y(s)}{P_{3}} = \frac{P_{2}U(s)}{(s+P_{1})}$$

$$\frac{Y(s)}{U(s)} = \frac{P_{2}P_{3}}{(s+P_{1})} = H(s,P_{1},P_{2},P_{3})$$
all  $P_{i} > 0$ 

## Part (b) Evaluate the SI of this model from the TF

partb) continue

$$\dot{x}(t) = -p, x(t) + p, u(t) \qquad y(t) = p, x(t)$$

$$y(t) = p, x(t) + p, u(t) \qquad y(t) = p, x(t)$$

$$y(t) = p, x(t) + p, u(t) \qquad defined cour (to, t_{max})$$

$$(to, t_{max}) = (T, t)$$

$$\frac{dx(t)}{dT} = (t - T)(-p, x(T) + p, u(T))$$

$$\frac{dx(T)}{dT} = -(t - T)p, x(T) + (t - T)p, u(T)$$

$$y(t) = p, x(T) + (t - T)p, u(T)$$

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part (c)

A semi-logarithmic plot of the data  $y(t) = p_2 p_3 e^{-p_1 t}$  is a straight line, yielding the coefficient  $A = p_2 p_3$  from the intercept and the exponent  $\lambda = -p_1$  from the slope. Thus, only  $p_1$  and the product  $p_2 p_3$  can be determined are SI and not  $p_2$  or  $p_3$  individually. The model is unidentifiable. For any u(t), it is because neither  $p_2$  nor  $p_3$  can be separated from the product  $p_2 p_3$  in the solution y(t) for any input u.

Problem 2

$$v = \frac{dx}{da}$$

$$\dot{v} = \frac{dv}{dt} = \frac{d}{dt} \frac{dx}{da} = \frac{dx}{dt} \cdot \frac{d}{da} = \frac{d}{da} \times \dot{x} = \frac{d\dot{x}}{da}$$

$$\dot{v} = \frac{d}{da} \left( -\alpha_{x}(t, \alpha) + u(t) \right)$$

$$\dot{v} = -(x(t, \alpha) + \alpha v) + 0$$

$$\dot{v} = -(\alpha v + x) + 0$$

$$\dot{v} = -\alpha v - x$$

$$\dot{v} = \left( \frac{df}{dx} \right) v + \frac{df}{dp}$$

$$\dot{v} = \frac{d(-\alpha x + u)}{dx} v + \frac{d(-\alpha x + u)}{da}$$

$$\dot{v} = \frac{d(-\alpha x + u)}{dx} v + \frac{d(-\alpha x + u)}{da}$$

$$\dot{v} = (-\alpha) v + (-x) = [-\alpha v - x]$$

### Problem 3 - App for SI analysis

Part (a) - 1 compartment model with M-M elimination and show that all 3 parameters are uniquely SI

# COMBOS: Web App for Finding Identifiable Parameter Combinations in...

ODEs: dx/dt = f(x,p,u), with Outputs: y = g(x,p)Parameters p and f, x, p, y and u vectors

# **Structurally Identifiable Parameters & Parameter Combinations All Solutions** A is uniquely identifiable B is uniquely identifiable V1 is uniquely identifiable COMBOS Runtime = 0.37 seconds **Model Entered** dx[1](t)/dt = -(A\*x[1](t)) / (B + x[1](t))+u[1](t)y[1](t) = x[1](t)/V1Model in Copy/Paste Format dx1/dt = -(A\*x1) / (B + x1)+u1; y1 = x1/V1;**Mapped Parameters** p1 p2 В V1 p3 (Process another model with COMBOS!)

## Part (b) 3-compartment model for SI analysis

Froblem 3 b)

First, list out the equations

$$\hat{q}_2 = u_2 - k_{12}q_2 + k_{21}q_1$$
 $\hat{q}_1 = u_1 - k_{01}q_1 + k_{12}q_2 - k_{21}q_1 - k_{31}q_1 + k_{13}q_3$ 
 $\hat{q}_3 = k_{31}q_1 - k_{13}q_3$ 
 $y = q_1$ 

i didilictors p dild i, n, p, j dild d rectors

#### **Structurally Identifiable Parameters & Parameter Combinations**

#### **All Solutions**

k1,2 is uniquely identifiable

k2,1 is uniquely identifiable

k0,1 is uniquely identifiable

k3,1 is uniquely identifiable

k1,3 is uniquely identifiable

COMBOS Runtime = 0.65 seconds

#### **Model Entered**

$$\begin{aligned} &dx[1](t)/dt = u[2](t) - (k1,2*x[2](t)) + (k2,1*x[1](t)) \\ &dx[2](t)/dt = u[1](t) - (k0,1*x[1](t)) + (k1,2*x[2](t)) - (k2,1*x[1](t)) - (k3,1*x[1](t)) + (k1,3*x[3](t)) \\ &dx[3](t)/dt = (k3,1*x[1](t)) - (k1,3*x[3](t)) \\ &y[1](t) = x[1](t) \end{aligned}$$

#### Model in Copy/Paste Format

dx1/dt = u2-(k1,2\*x2)+(k2,1\*x1); dx2/dt = u1-(k0,1\*x1)+(k1,2\*x2)-(k2,1\*x1)-(k3,1\*x1)+(k1,3\*x3); dx3/dt = (k3,1\*x1) - (k1,3\*x3); y1 = x1;

#### **Mapped Parameters**

k1,2 p1

k2,1 p2

k0,1 p3

k3,1 p4

k1,3 p5

(Process another model with COMBOS!)