

# Graphs

# Edge/Node Series

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## Tour

- A series of Nodes
- Adjacent Node pairs are connected by an edge (no edge is used twice)
  - From the first node of the series to the second in the case of directed edges



# Edge/Node Series (cont.)

Walk

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## Cycle

# Edge/Node Series (cont.)

## Walk

- A series of Nodes
- Adjacent Node pairs are connected by an edge
  - From the first node of the series to the second in the case of directed edges
- No other Constraints

## Cycle

- Path where the first and last Node are equal

# Graph Types

## Types we will see

- **Directed/Undirected**
  - If any edge has a direction, the graph is directed
  - Directed mixed with undirected edges is not uncommon
  - Directed Graphs are sometimes referred to as Digraphs
- **Weighted/Unweighted**
  - If an edge has a weight, the graph is weighted
  - Normally all edges will be weighted or unweighted
  - Unweighted graphs are sometimes referred to as Unit Distance Graphs
- **Connected**
  - A graph where a path exists between all pairs of nodes
  - The direction of the edges for the paths does not typically matter

# Graph Types (cont.)

- **Acyclic**
  - A graph with no cycles
- **Tree**
  - Undirected, Connected, Acyclic Graph
- **Rooted Tree**
  - Directed, Connected, Acyclic Graph
  - There exists some node (root) that can reach all other nodes using a path
  - Additionally, if the edges were consider undirected, no cycle would exist
- **DAG**
  - Directed, Acyclic Graph



# Searching Unit Distance Graphs

Suppose we are looking for our keys in a house. (hopefully not a strangers house)

We typically “search” the house for our keys.

Do we search the same location twice? I do, but it never works.

There are two common search methods:

- BFS - “Let’s split up and search for clues!”
- DFS - “No. That’s how people die in horror movies.”

# BFS

Breadth First Search

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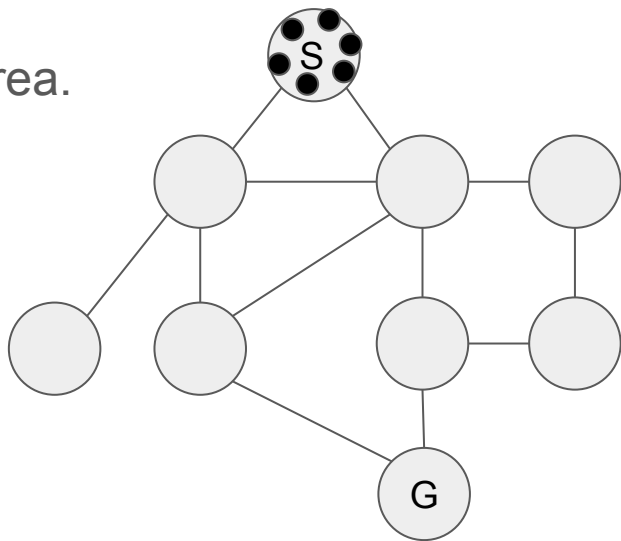
Think of it as groups of people sweeping an area.

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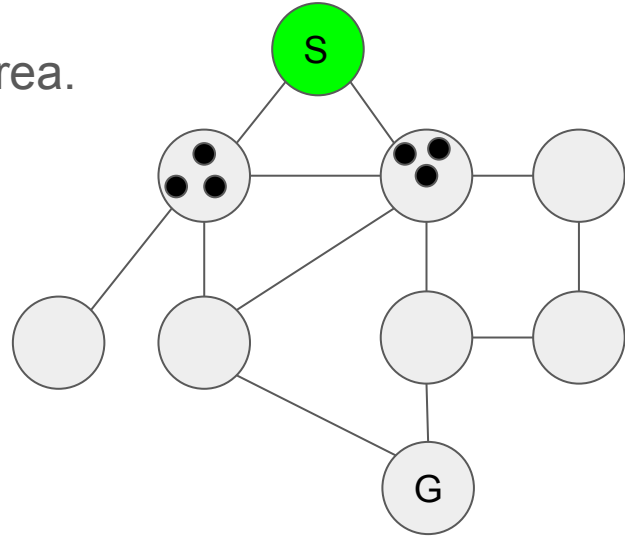


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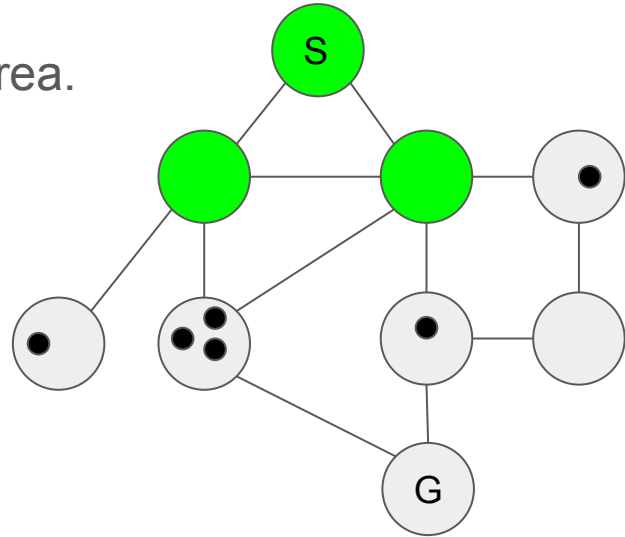


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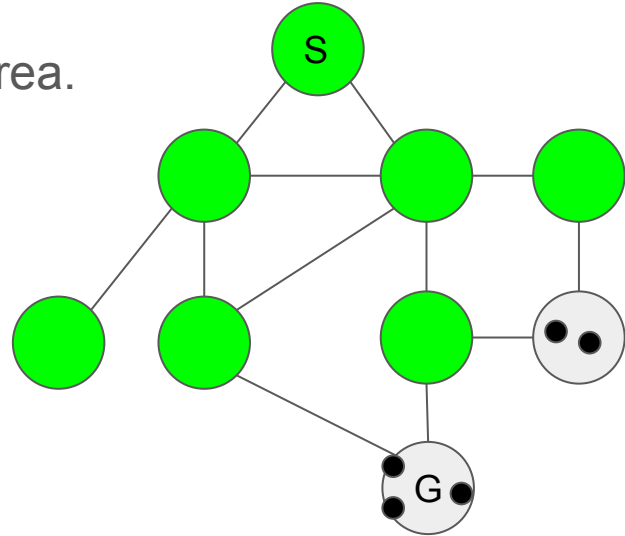


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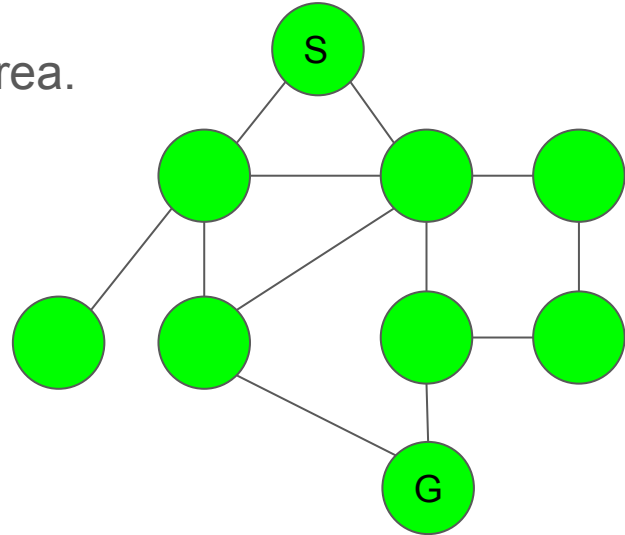


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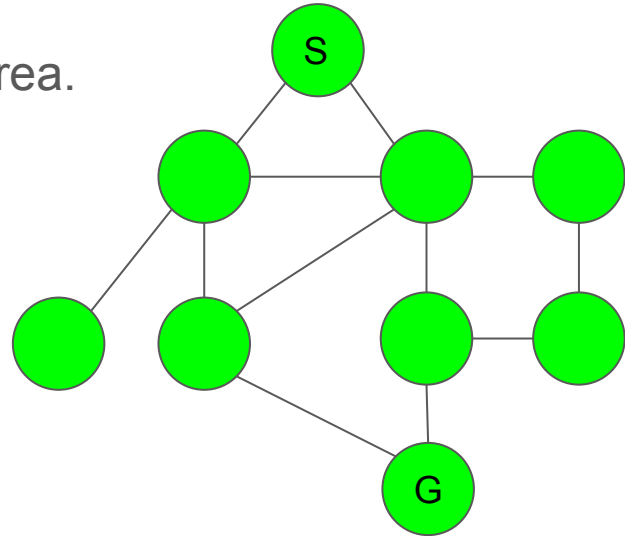
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Somewhat unrealistic because,



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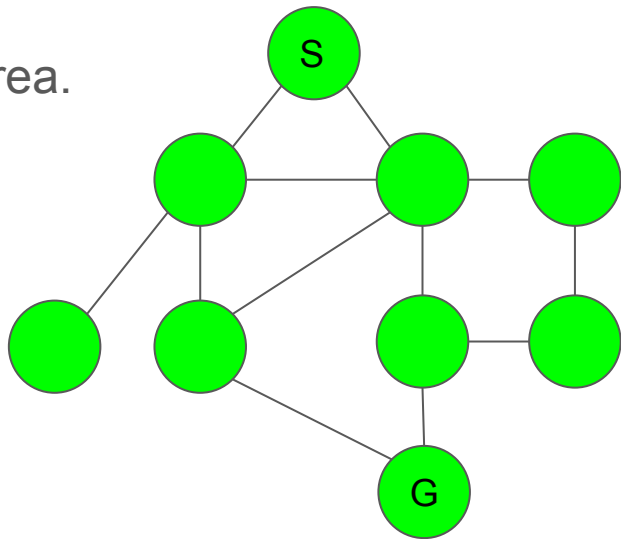
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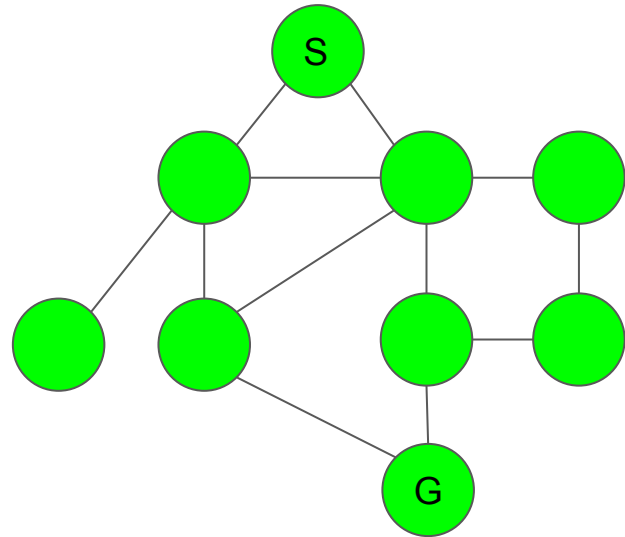
Somewhat unrealistic because,

- Typically not parallelized.
- Two different branches never merge.



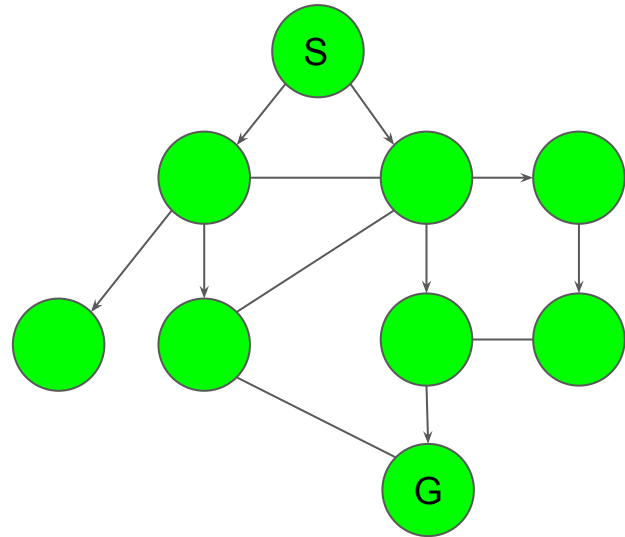
# BFS (cont.)

We create a Tree of edges (the tree edges) in our search.



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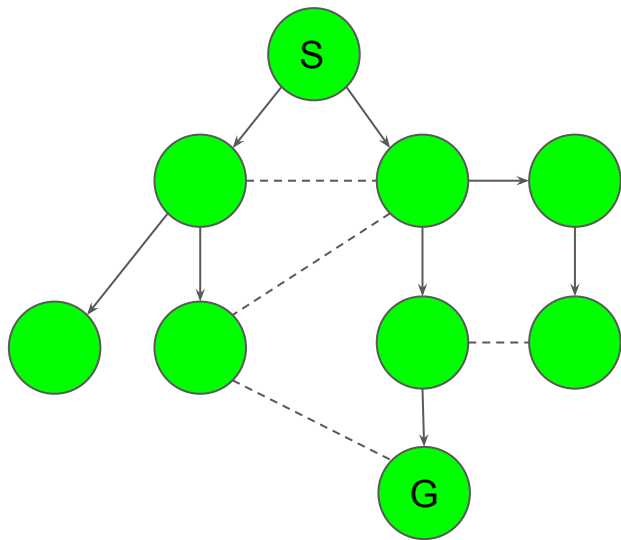
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# BFS (cont.)

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Unused edges are considered either cross or back edges.

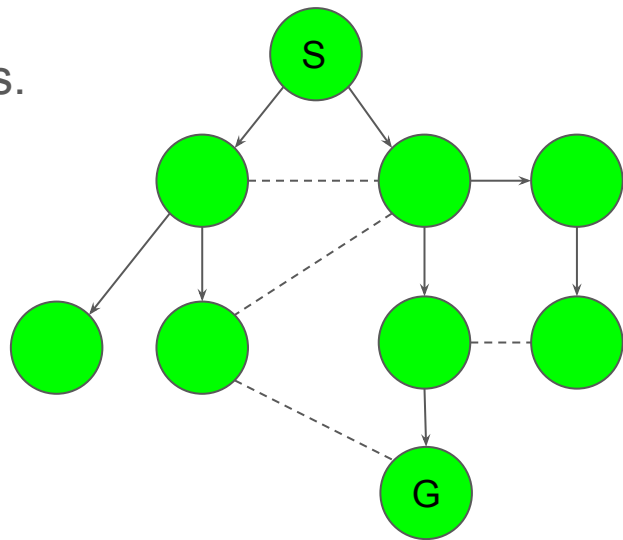


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Back edges are between nodes and ancestors.





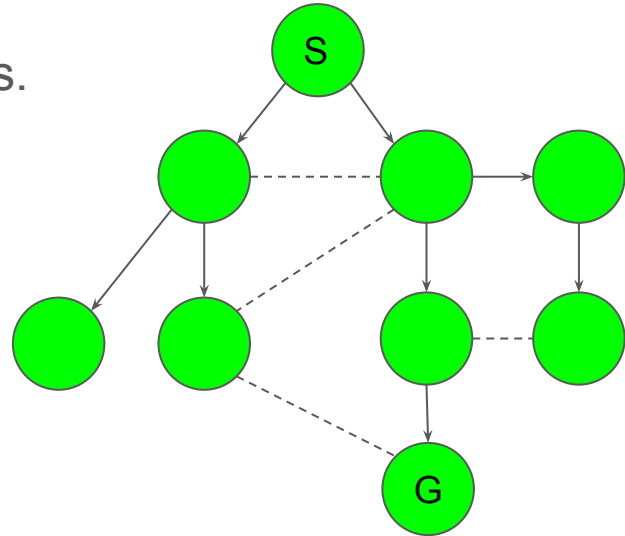
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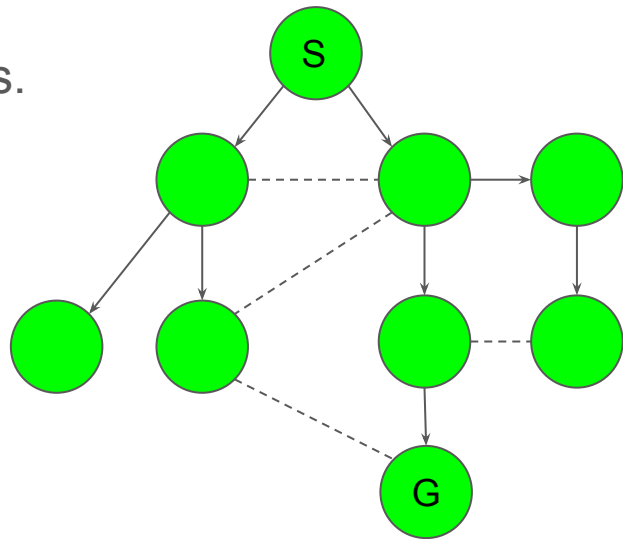
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Unused edges are considered either cross or back edges.

Back edges are between nodes and ancestors.

Cross edges are other untaken edges.

Undirected graphs without multi edges do not generate back edges in a BFS.



# BFS Algorithm

Create an initially empty list of visited nodes

Create an initially empty queue of to process nodes

Add the start node to the visited nodes and the to process nodes

While Not Done

    Let the current node be the front of the to process nodes

    Remove the front of the to process nodes

    // DO WORK HERE (sometimes after or in the For loop)

    For all new node adjacent to current

        If visited nodes does not contain the new node

            Add the new node to the visited nodes

            Add the new node to the back of the to process nodes

        End If

    End For

End While

# BFS Analysis

How many times will the While loop execute in the worst case?

How many times will the inner For loop execute in the worst case?

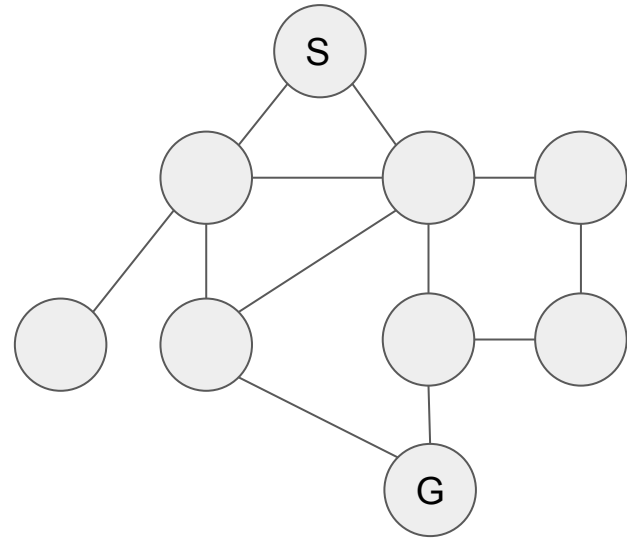
# BFS Usage

- Shortest path in a unit graph
- **\*\*Diameter of a tree finding\*\***
- Topological ordering
- Cycle detection
- 2 Coloring
- Connectivity check

Changing the queue to a priority queue enables using an algorithm called Dijkstra's

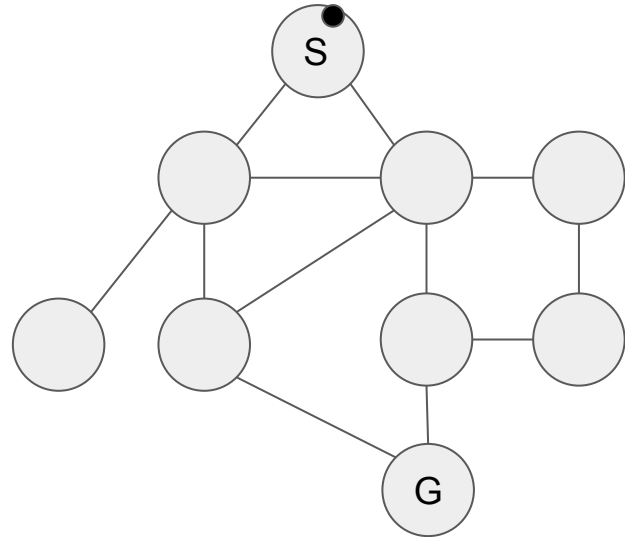
# DFS

Depth First Search (Maze Solving)



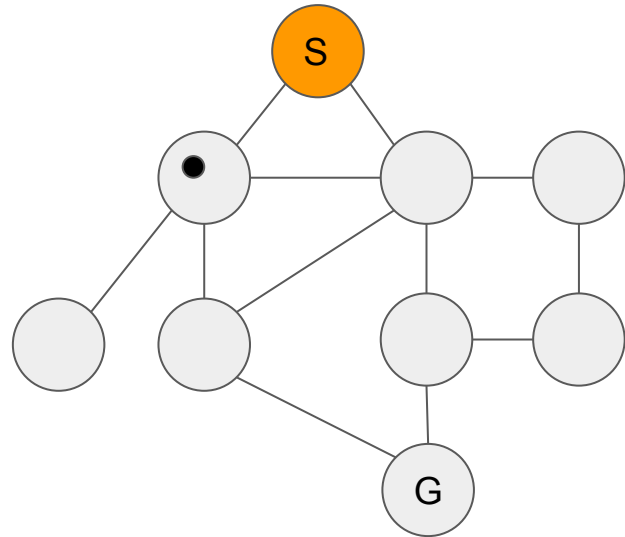
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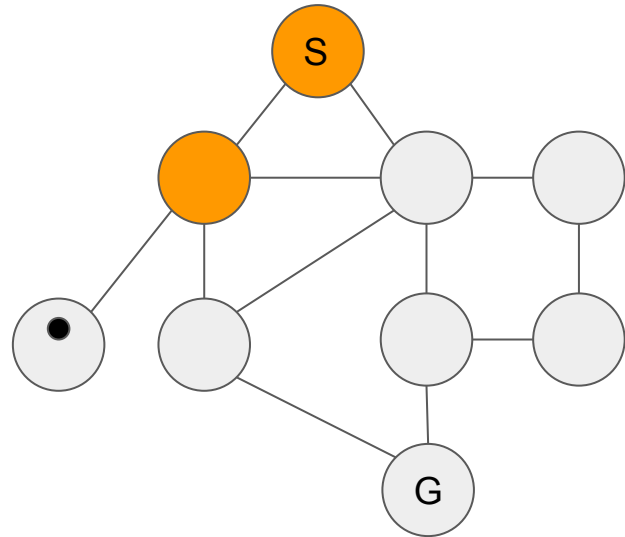
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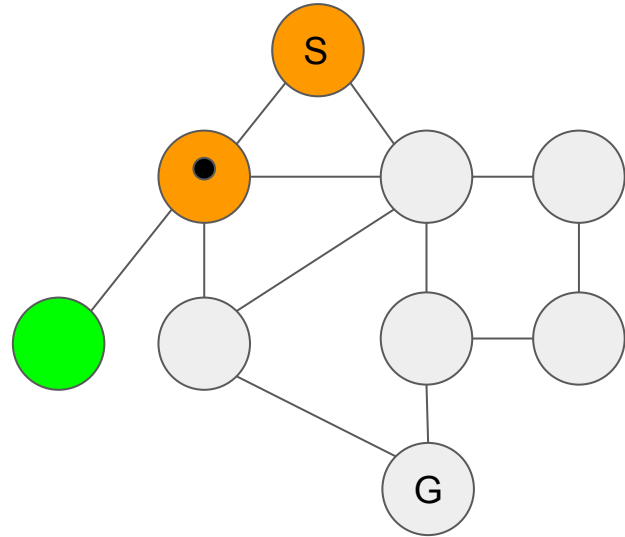
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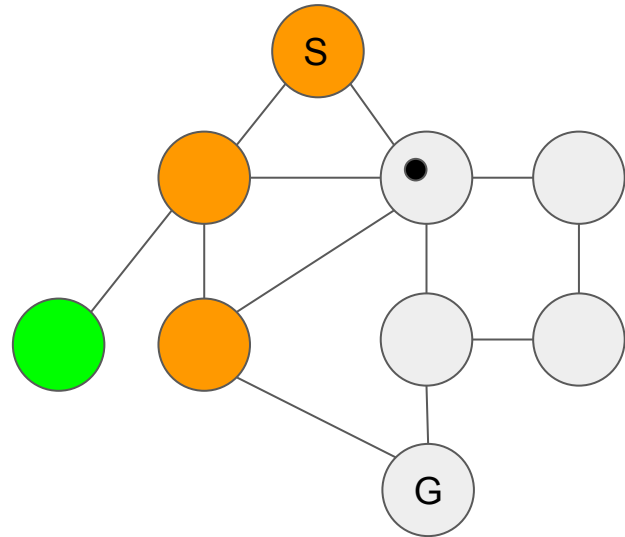




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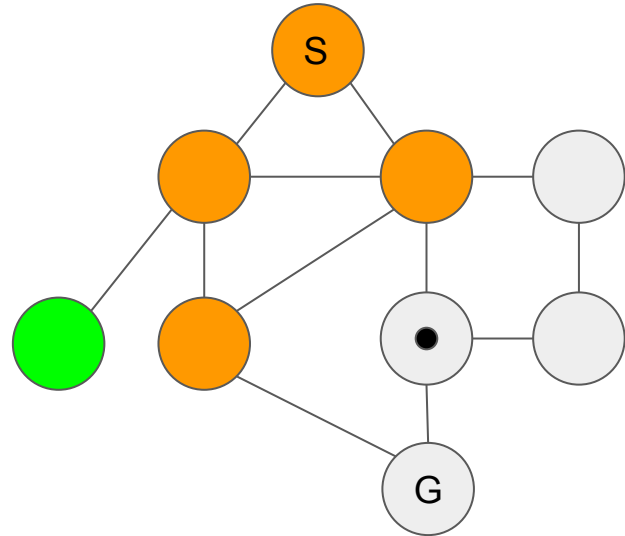
...



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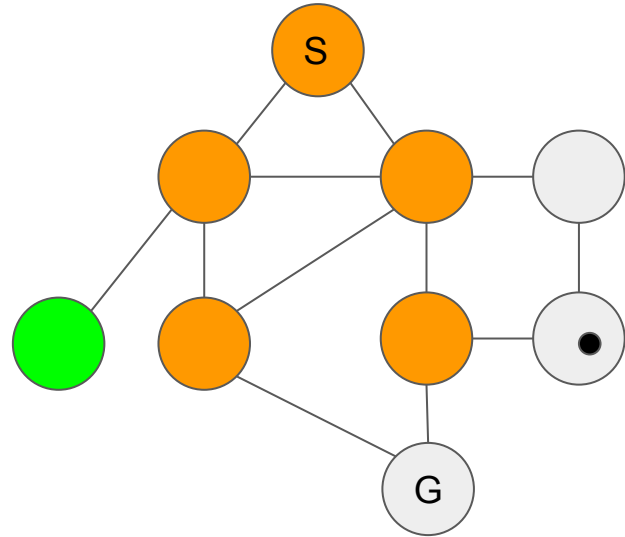
Almost There!!!



# DFS

Depth First Search (Maze Solving)

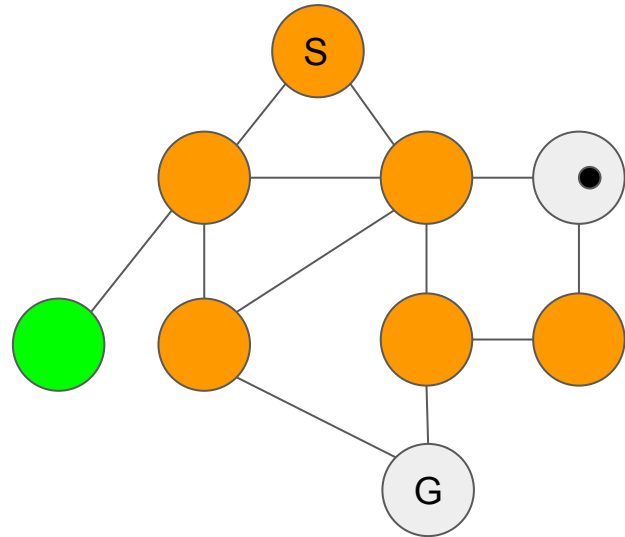
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# DFS

## Depth First Search (Maze Solving)

■ ■ ■



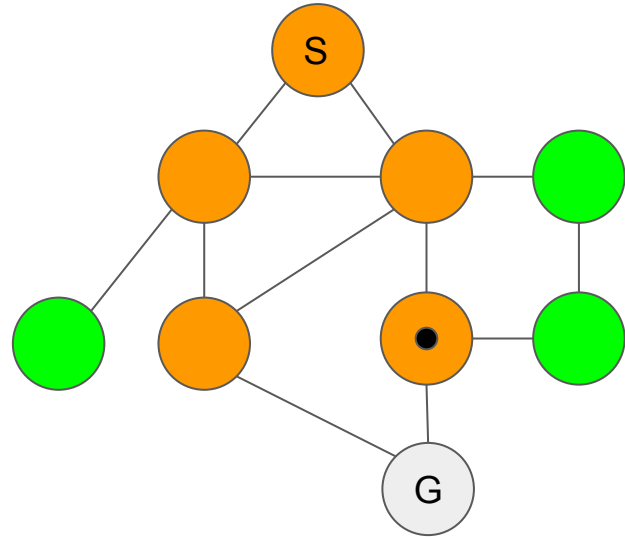




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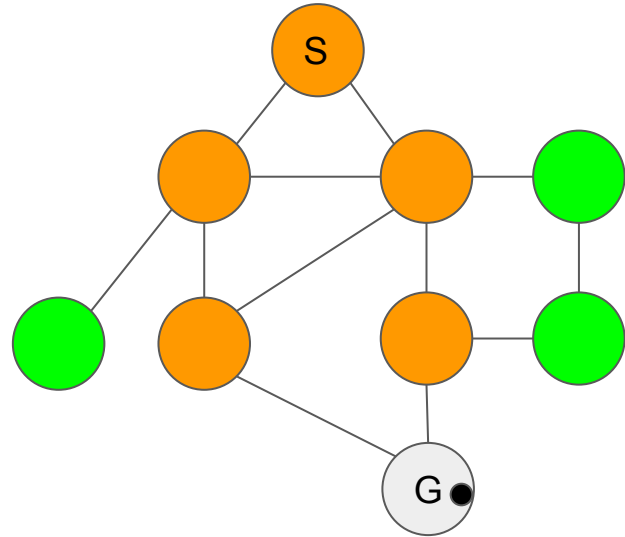
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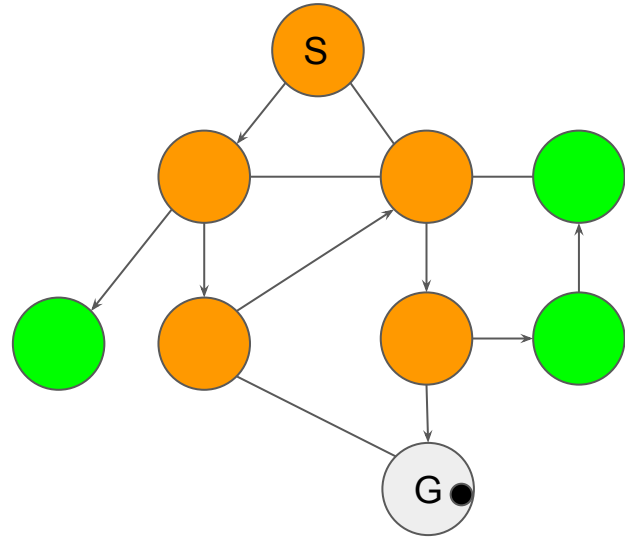
Finally!



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Depth First Search (Maze Solving)

This also produces a set of Tree Edges.

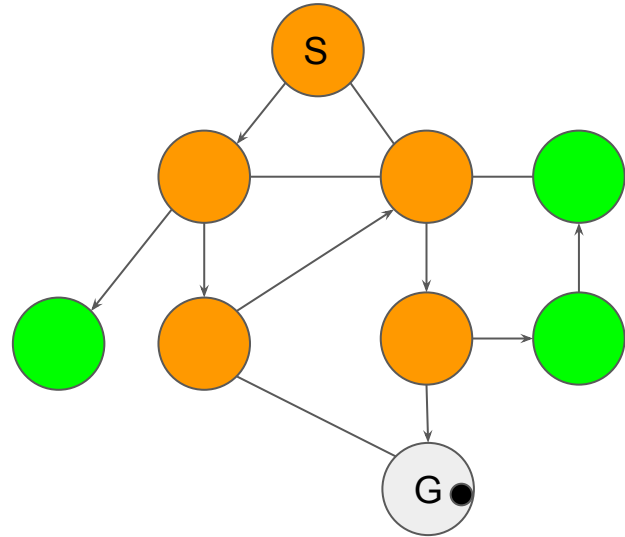


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This also produces a set of Tree Edges.

Unused edges are mostly back edges.

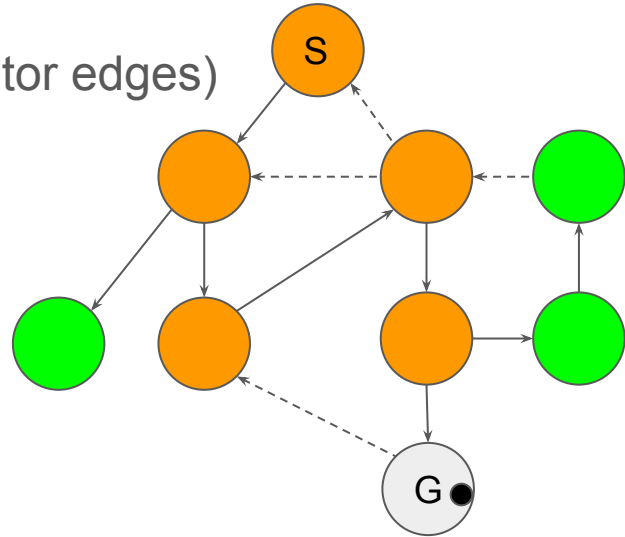


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Unused edges are mostly back edges. (ancestor edges)



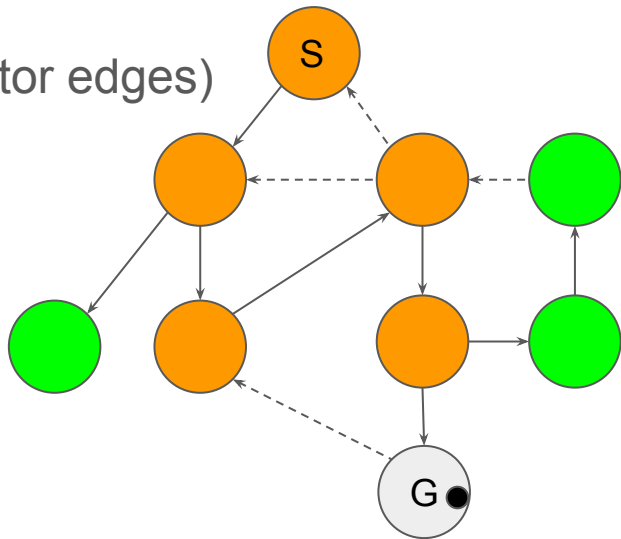
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Cross edges can appear in directed graphs.



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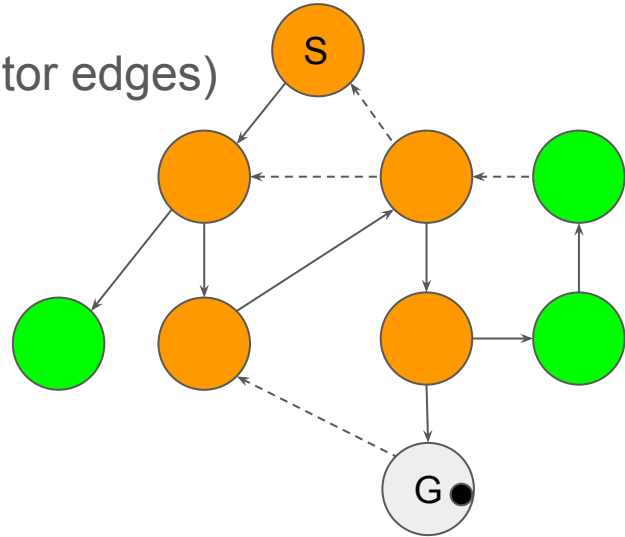
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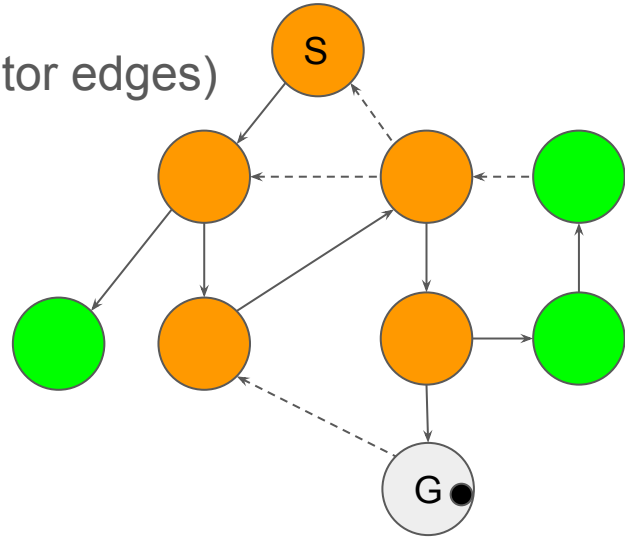
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Keep track of them using a stack.





# DFS Algorithm

Create an initially empty set of visited nodes

DFS(start node)

Function DFS(current node)

    // DO WORK HERE (sometimes in or after the For loop)

    Add current node to the set of visited nodes

    For all next node adjacent to the current node

        If next node is not in the set of visited nodes

            DFS(next node)

        End If

    End For

End Function

# DFS Analysis

How many times will DFS be called?

How many times will the inner for loop be called?

What is the worst case depth of the program stack?

# DFS Usage

- Low Link
  - Strongly Connected Component Finding
  - Bridge (cut edge) Finding
  - Articulation point (cut node) Finding
- Maze solving
- Topological ordering
- Cycle detection
- 2 Coloring
- Connectivity check

# Problem Talk

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Divide and conquer can give slight performance improvements depending on the network structure. Search from both ends and meet in the middle.



# Another Problem

Class scheduling is tricky. Suppose we have many classes in our degree program. Some classes have prerequisites. We want to know if we can actually take all the classes while abiding by the class prerequisite. We also want to know what is the fastest we can graduate (fewest semesters) while abiding by the class prerequisite.

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The prerequisite graph needs to be a DAG.

We can find the minimum by using a topological ordering algorithm.