Samuel W. Crane

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Currently seeking full time employment in Robotics/Embedded Software Engineering in the Boston area.

Education:

B.S. in Computer Engineering, *University of North Carolina at Charlotte*

December 2023

GPA: 3.68 | Relevant Coursework: Embedded Systems, Artificial Intelligence for Robotics, VLSI

Work Experience:

Butlr - Systems Test Engineer Contractor

January 2024 - June 2024

- Spearheaded the design, review, and execution of over 10 comprehensive test plans
- Generated dashboard visualizations of sensor data retrieved via the MQTT protocol (Python)
- Analyzed sensor data with statistics to correct sensor errors and variance by >250%
- Collaborated with 2 other teams to determine objectives and testing requirements

iRobot - Systems Test Engineering Intern

July 2022 – December 2023

- Developed 1,500+ lines of Python code with object-oriented programming (OOP) to automatically evaluate robot performance across 5 tests using 6DOF data from a Ground Truth System (GTS) while providing modularity, maintainability, and readability
- Optimized the existing evaluators speed by 26x while improving its accuracy (Python)
- Integrated a GTS software into a **PyTest** automated robot testing software to automate 5 tests
- Triggered a GTS to start and stop capturing within 20 ms using logging firmware (C)
- Designed and troubleshooted software for robots in design challenges with 10 interns

UNCC - Undergraduate Research Assistant

June 2021 – August 2021

- Implemented and documented a dual camera SLAM algorithm in ROS C++ with Ubuntu Linux
- Recorded and presented data using real time SLAM algorithms and SSH remote connections
- Simulated environments using **Gazebo** to evaluate SLAM-based navigation algorithms

Projects and Skills:

Solar Panel Cleaning Robot

- Senior Capstone Project to design and build a robot to clean rows of solar panels in a desert
- Integrated OpenCV to quantify cleanliness of solar panels for autonomous cleaning routines
- Managed the team for 8 months while designing, fabricating, and programming the robot

Bluetooth Keyboard

- Successfully brought a unique 36-key keyboard concept to life, incorporating user-centric design principles for improved ergonomics and typing experience
- 2-Layer PCB Design (EasyEDA), Programming Microcontroller Firmware (C/C++), Soldering

Petri Dish Robot

- Created a robot to autonomously traverse the grid of a petri dish underneath a camera, increasing accuracy and cutting down time required to analyze one dish by 75%
- Arduino programming base, stepper motor control, CAD (Autodesk Inventor)

Programming Languages: Python (Intermediate), C/C++ (Intermediate), TypeScript (Beginner), Git

Awards & Leadership Experience:

Active member of IEEE RAS Charlotte Chapter

August 2019 - May 2023

Vice President

August 2021 - May 2023

• Placed 1st in the IEEE SoutheastCon Hardware Competition

April 2022

Boy Scouts of America Eagle Scout Award

May 2015