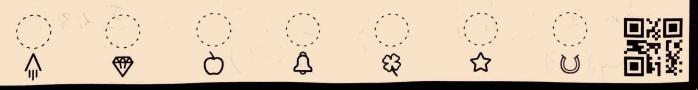
Theorem - 1: U1, U2 GIRM V1, V2 EIRM and U1 I U2, then i) (A, B) = Tr(ATB) = 0 where A = U, V, T, B = U, V_2 T ii) (C,D) = Tr(CTD) = 0 where (= V, u, D = V2 u2 U, IU2 / UTU2 = 0 = UZU1 i) $\langle A, B \rangle = \langle u, v_1^T, u_2 v_2^T \rangle = Tr ((u, v_1^T)^T u_2 v_2^T)$ = Tx (v, u, u, v, T) = Tx (v, 0. v, T) = Tr(0) = 0 (C,D)=(AT,BT)=Tx(ATTBT)=Tr(AB) = Tr (N, V, U2 V2) = Tr (u, V, TV2 U2) 0 = Tr(0) = Tr(uzu, v, v2) Alternatively, notice < AT, BT = < A, B7. Orethonormal CP - decomposition

Orthonormal CP - decomposition

Let $T \in \mathbb{R}^{m \times n \times p}$, then $T = \sum_{i} \forall_{i} (\vec{a}_{i} \circ \vec{b}_{i} \circ \vec{c}_{i})$ is called the rank-8 orthonormal CP-decomposition of T iff $a_{i} \perp a_{j} \neq i \neq j$, $C_{i} \perp C_{j} \neq i \neq j$, and $||a_{i}||_{2} = 1$, $||b_{i}||_{2} = 1$ and $||C_{i}||_{2} = 1$.

This can be said more compactly as $C_{i}^{T}C_{j} = \delta_{ij}^{T} = a_{i}^{T}a_{j}^{T}$ where $\delta_{ij} = \begin{cases} 0 & 2 & i \neq j \\ 1 & 0 & 0 \end{cases}$

Theorem - 2: - Let $\vec{u} \notin \vec{V}$ be in $IR^m \& IR^n$ respectively. Let $\vec{u} \cdot \vec{u} = 1 = \vec{V} \cdot \vec{V}$ Then $||A||_F = 1 = ||Vec(A)||_2$



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Proof: A = UVT, 1A11= (A,A7 = Tr(ATA)=Tr((UV)TUVI)
                                                                          1 = T_{\delta}(v^{T}v) = T_{\delta}(vv^{T}) = T_{\delta}(vu^{T}u^{T}v^{T})
            Rank Y - Orthonormal CP decomposition = rank & SVD
    Let T= Zx; & ob; oci) be the orthonormal CP decomposition
        of TEIRMENER. Let A_i = a_i \cdot b_i = a_i \cdot b_i^T. Let \overline{Z}_i = \text{vec}(A_i)
               ZiZj = < Ai, Aj7 = 0 as ai Laj (theorem-1)
                             and \|Ai\|_F^2 = \|Zi\|_2^2 = \langle Ai, Ai \rangle = 1 (theorem -2)
                 Hence Z_i^T Z_j = S_{ij} = S_
                                                                                                                                                                              Corollary
Let R. > afflate(T); i = . vec (T:,:,i). | Iflate(aoboc) = vec (a
                                                                                                                                                                                           = Vec (a ob) oc
                   Such that M=dflate(T) ERmnxp
           Linearity of vec() & fflate():
                    It isn't hard to see Vec(\alpha A + \beta B) = \angle Vec(A) + \beta Vec(B)
                                                          4 Aflate (9, T1+ 42 T2) = xydflate(T1)+ x2offlate(T2)
                   M= of late(T)= of late(E'a; a; ob; oci) = Exidilate(a; ob; oci)
                            = \sum_{i=1}^{n} \langle x_i^* | \operatorname{vec}(a_i \circ b_i) \circ C_i = \sum_{i=1}^{n} \langle x_i^* | \operatorname{vec}(A_i) \circ C_i = \sum_{i=1}^{n} \langle x_i^* | Z_i \circ C_i \rangle
                                                                                                            SZXCT = ZXIZICT
(SVD)
              where Z = [ = ]

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Let VE 1R9P.
        define mat (V) EIRaxp the matrix such that
            V = vec (mat (V)) and A = mat (vec (A)) for A = Raxp
               mat = vec 1
⇒ Let M ∈ IR mn xP be any matrix.
→ Define T= nflate (M) & IR MXNXP Such that
                 oflate (M);; = mat (M;;)
→ Clearly offate is linear, i.e. offate (J1M, + J2M2) = f, offate (M,)
                                                           + g2 reflate (M2)
                 or nflate ( \(\mathbb{Z}_1; \text{Mi}) = \(\mathbb{Z}_7; \text{ nflate(Mi)} \) for \(\mathbb{S}_i \in \mathbb{R}. \)
Ikemark: dflate (nflate (M)) = vec (nflate (M):,,i)
                                    = Vec ( met (M:,i)) = M:,i
             Hence, offate (nflate (M)) = M
   Similarly reflate (dflate (T));; i = mat (dflate (T):,i)
                                        = mat ( vec (T:,:,i))
                  Hence, nflate (dflate (T)) = T
        So, we have nflate = altate -1
(orallary: If \vec{W} = \text{Vec}(\vec{x} \circ \vec{g}), then relate (\vec{w} \circ \vec{z}) = \vec{x} \circ \vec{y} \circ \vec{z}
                                      nflate(vec(nog) oz) = nogoz
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Let $D_i = mat(\vec{d_i}) \in \mathbb{R}^{m \times n} \Rightarrow vec(D_i) = \vec{d_i}$ Let $D_i = \sum_{j=1}^k a_j b_j = \sum_{j=1}^k \vec{a}_j \cdot \vec{b}_j$ be any rank- k factorization of D_i Hence $M = \sum_{i=1}^{8} \vec{d_i} \circ \vec{e_i} = \sum_{i=1}^{8} \text{vec}(D_i) \circ \vec{e_i}$ = Ž vec (£ a, o b,) oe; 1 = \frac{7}{2} \frac{k}{2} \text{ vec (a; o b;) o \vec{e}; \\
i=1 \frac{7}{2} \text{ vec (a; o b;) o \vec{e}; \\
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i=1 \frac{7}{2} \text{ vec (a; o b;) o \vec{e => nflate (M) = nflate (\(\frac{\gamma}{\Sigma} \frac{\gamma}{\sigma} \gamma \text{vec}(ajobj) o ei) T = Z Z nflate[vec(ajobj) oei)] T = $\sum_{i=1}^{\infty} \vec{a}_{i} \circ \vec{b}_{j} \circ \vec{e}_{i}$ "Corollary on prev. page. Let S = rk, then $T = \sum_{s=1}^{\infty} \vec{a}_{s} \circ \vec{b}_{s} \circ \vec{e}_{s} \circ \vec{b}_{s} \circ \vec{e}_{s} \circ \vec{b}_{s} \circ \vec{b}_{s}$ where T. 7 is the ceil function or the "Smallest integer value" nflate (M)=T = \frac{7}{s=1} \frac{1}{s} = \ decomposition/factors zation of T where all of the tensor atoms are unique but the factors \vec{a}_i , \vec{b}_i & \vec{c}_i are sometimes repeated and chosen out of k of as / Bs and