

## **CODE:**

```
int pirsensor =5;
int buzzer =13;
int pirvalue =0;
float temperature=A1;
float analog;
float voltage;
float celcius;
void setup()
 pinMode(pirsensor, INPUT);
 pinMode(temperature, INPUT);
 pinMode(buzzer, OUTPUT);
 Serial.begin(9600);
}
void loop()
 analog=analogRead(temperature);
  voltage=analog*5.0/1023;
 celcius=(voltage-0.5)*100.0;
 Serial.print("temperature:");
 Serial.println(celcius);
 if (celcius >=60)
```

```
tone(buzzer, 200, 100);

} delay(100);

pirvalue = digitalRead(pirsensor);

if (pirvalue == HIGH)
{
  tone(buzzer, 1000, 500);
}

delay(100);
}
```