

Problem 1:

If $f(x_1, x_2) = x_1^3 + x_2^3$

then $\nabla f = (3x_1^2, 3x_2^2)$

Let $\nabla f = 0 \Rightarrow (x_1, x_2) = (0, 0)$

And for the second derivative:

$$\nabla^2 f = \begin{pmatrix} 6x_1 & 0 \\ 0 & 6x_2 \end{pmatrix}$$

When $x^* = (x_1, x_2) = (0, 0)$

we will have

$$\nabla^2 f(x^*) = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$\nabla^2 f(x^*)$ is a positive semi-definite matrix because:

$$\forall x \neq 0, x^T \nabla^2 f(x^*) x = 0 \geq 0$$

Then we could tell that

$x^* = (0, 0)$ satisfies the second-order necessary conditions for optimality

However, as for points near x^* we could choose:

$$x_1 = (\varepsilon, \varepsilon) \text{ and}$$

$$x_2 = (-\varepsilon, -\varepsilon), \forall \varepsilon > 0$$

$$\text{Then } f(x_1) = 2\varepsilon^3 > 0$$

$$f(x_2) = -2\varepsilon^3 < 0$$

So x^* is not a local optimum

As a result,

$$f(x_1, x_2) = x_1^3 + x_2^3$$

is an example!

Problem 2:

$$\forall x_1, x_2 \in L(y) = \{x \in \mathbb{R}^n : f(x) \leq y\}$$

$$f(x_1) \leq y \quad \text{and} \quad f(x_2) \leq y$$

Since $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is a convex function,

$$\text{then } \forall \lambda \in [0, 1]$$

we have

$$\begin{aligned} f[(1-\lambda)x_1 + \lambda x_2] &\leq (1-\lambda)f(x_1) + \lambda f(x_2) \\ &\leq (1-\lambda)y + \lambda y \\ &= y \end{aligned}$$

So we prove that
 $(1-\lambda)x_1 + \lambda x_2 \in L(y)$

This means

$$L(y) = \{x \in \mathbb{R}^n : f(x) \leq y\}$$

is a convex set.

Problem 3 :

$$\forall x' \in L(y)$$

we have

$$f(x') \leq y = f(x)$$

Since $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is convex

then

$$f(x') \geq f(x) + \nabla f(x)^T (x' - x) \quad (*)$$

From (*) we know that

$$f(x) \geq f(x') \geq f(x) + \nabla f(x)^T (x' - x)$$

$$\Rightarrow \nabla f(x)^T (x' - x) \leq 0$$

$$\Rightarrow x' \in H(x)$$

That is to say,
 $\forall x' \in L(y)$,
we always have $x' \in H(x)$

As a result,

$$L(y) \subseteq H(x)$$

By the way, we could prove the equation (*) as below:

$$\text{let } z = tx' + (1-t)x$$

$$\text{then } z = x + t(x' - x)$$

Since f is convex

$$\begin{aligned}\Rightarrow f(z) &= f[x + t(x' - x)] \\ &= f[tx' + ((1-t)x)] \\ &\leq tf(x') + (1-t)f(x) \\ &= f(x) + t[f(x') - f(x)]\end{aligned}$$

That is to say,

$$f[x+t(x'-x)] \leq f(x) + t[f(x') - f(x)]$$

$$\Leftrightarrow \frac{f[x+t(x'-x)] - f(x)}{t} \leq f(x') - f(x)$$

$$\Leftrightarrow \frac{f[x+t(x'-x)] - f(x)}{t(x'-x)} (x'-x) \leq f(x') - f(x)$$

Let $t \rightarrow 0$ we will get

$$\nabla f(x)^T (x' - x) \leq f(x') - f(x)$$

Therefore

$$f(x') \geq f(x) + \nabla f(x)^T (x' - x)$$

Problem 4:

Since $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is a strictly convex function,

then $\nabla^2 f(x)$ is positive definite, $\forall x \in \mathbb{R}^n$
 $\forall x' \in L(f(x))$, we have

$$f(x') \leq f(x)$$

And we could do Taylor expansion to f :

$$f(x') = f(x) + \nabla f(x)^T (x' - x) + \frac{1}{2} (x' - x)^T \nabla^2 f(\xi) (x' - x)$$

if $x' \neq x$ then

$$(x' - x)^T \nabla^2 f(\xi) (x' - x) > 0$$

That is to say,

$$\begin{aligned}f(x') &= f(x) + \nabla f(x)^T(x' - x) + \\&\quad \frac{1}{2}(x' - x)^T \nabla^2 f(x)(x' - x) \\&> f(x) + \nabla f(x)^T(x' - x)\end{aligned}$$

Then we have:

$$f(x) \geq f(x') > f(x) + \nabla f(x)^T(x' - x)$$

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$$\nabla f(x)^T(x' - x) < 0$$

But if $x' = x$

$$\text{then } \nabla f(x)^T(x' - x) = 0$$

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$$L(f(x)) \cap \{x \in \mathbb{R}^n : \nabla f(x)^T(x' - x) = 0\} = \{x\}$$

Problem 5:

Since $p \in \mathbb{R}^n$ is a descent direction at x , then we have:

$$\nabla f(x)^T p < 0$$

Let's do Taylor expansion to f :

$$f(x + \alpha p) = f(x) + \frac{\partial}{\partial} \nabla f(x)^T p + \frac{\alpha^2}{2} p^T \nabla^2 f(\xi) p$$

if $f(x + \alpha p) < f(x)$

then $f(x) + \alpha \nabla f(x)^T p + \frac{\alpha^2}{2} p^T \nabla^2 f(\xi) p < f(x)$

$$\nabla f(x)^T p + \frac{\alpha^2}{2} p^T \nabla^2 f(\xi) p < 0$$

$$\Rightarrow \frac{\lambda^2}{2} P^T \nabla^2 f(\alpha) P < \lambda (-\nabla f(x)^T P)$$

$$\Rightarrow \lambda < \frac{-2 \nabla f(x)^T P}{P^T \nabla^2 f(\alpha) P}$$

since $\nabla f(x)^T P < 0$ and

$\nabla^2 f(\alpha)$ is positive definite

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$$\frac{-2 \nabla f(x)^T P}{P^T \nabla^2 f(\alpha) P} > 0$$

That is to say, $\lambda \in (0, \frac{-2 \nabla f(x)^T P}{P^T \nabla^2 f(\alpha) P})$

Therefore, there exists $\lambda > 0$
such that $f(x + \lambda P) < f(x)$

Problem b:

① We know that q_1, \dots, q_n form an orthonormal basis for \mathbb{R}^n

Then $q_i^T q_j = \begin{cases} 1, & i=j \\ 0, & i \neq j \end{cases}$

Let $Q = [q_1 \ q_2 \ \dots \ q_n]$
we have $QQ^T = I$

$$Q^{-1} = Q^T$$

Meanwhile,
since we have $Aq_i = \lambda_i q_i$,
 $i=1, 2, \dots, n$

then $AQ = [Aq_1 \ Aq_2 \ \dots \ Aq_n]$
 $= [\lambda_1 q_1 \ \lambda_2 q_2 \ \dots \ \lambda_n q_n]$

$$= [q_1 \ q_2 \dots q_n] \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}$$

$$= Q \Lambda$$

That is to say,

$$AQ = Q \Lambda$$

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$$A = Q \Lambda Q^{-1} = Q \Lambda Q^T$$

Therefore we prove that

a consequence of this is having an orthogonal eigenvalue decomposition of A:

$$A = Q \Lambda Q^T, Q = [q_1 \dots q_n], \Lambda = \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix}$$

$$\text{where } Q^{-1} = Q^T$$

$$\begin{aligned}
 ② A &= Q \Lambda Q^T \\
 &= [q_1 \dots q_n] \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix} \begin{bmatrix} q_1^T \\ \vdots \\ q_n^T \end{bmatrix} \\
 &= [\lambda_1 q_1 \dots \lambda_n q_n] \begin{bmatrix} q_1^T \\ \vdots \\ q_n^T \end{bmatrix} \\
 &= \lambda_1 q_1 q_1^T + \lambda_2 q_2 q_2^T + \dots + \lambda_n q_n q_n^T \\
 &= \sum_{i=1}^n \lambda_i q_i q_i^T
 \end{aligned}$$

So we show that we could write the eigenvalue decomposition in outer product form, i.e.:

$$A = \sum_{i=1}^n \lambda_i q_i q_i^T$$

③ (i) if $\lambda_i > 0$ ($i=1, 2, \dots, n$)

then $\forall x \neq 0$ we have

$$\begin{aligned} x^T A x &= x^T \left(\sum_{i=1}^n \lambda_i q_i q_i^T \right) x \\ &= \sum_{i=1}^n \lambda_i (x^T q_i) (q_i^T x) \\ &= \sum_{i=1}^n \lambda_i (q_i^T x)^T (q_i^T x) \\ &= \sum_{i=1}^n \lambda_i \|q_i^T x\|^2 \end{aligned}$$

Since q_1, \dots, q_n form an orthonormal basis for \mathbb{R}^n
then there is no possibility that

$$q_i^T x = 0, \quad \forall i \in \{1, 2, \dots, n\}$$

This means

there always exists $j \in \{1, 2, \dots, n\}$

$$\text{s.t. } q_j^T X \neq 0$$

That is to say

$$\sum_{i=1}^n \lambda_i \|q_i^T X\|^2 \geq \lambda_j \|q_j^T X\|^2 > 0$$

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$$X^T A X > 0, \forall X \neq 0$$

so A is positive definite

(ii) if A is positive definite

$$\text{then } \forall X \neq 0, X^T A X > 0$$

$$\text{let's choose } X = q_k, k=1, 2, \dots, n$$

then

$$\begin{aligned} X^T A X &= X^T \left(\sum_{i=1}^n \lambda_i q_i q_i^T \right) X \\ &= q_k^T \left(\sum_{i=1}^n \lambda_i q_i q_i^T \right) q_k \end{aligned}$$

$$= \sum_{i=1}^n \lambda_i (q_i^T q_k)^T (q_i^T q_k)$$

$$= \sum_{i=1}^n \lambda_i \|q_i^T q_k\|^2$$

And we know the truth:

$$q_i^T q_k = \begin{cases} 1, & i=k \\ 0, & i \neq k \end{cases}$$

$$\text{Then } x^T A x = \sum_{i=1}^n \lambda_i \|q_i^T q_k\|^2$$

$$= \lambda_k > 0, \quad k=1, 2, \dots, n$$

From (i) and (ii'),

we prove that

$\lambda_i > 0 \quad (i=1, 2, \dots, n)$ if and only if
 A is positive definite.

Problem 7:

$\forall x' \in S$ and $x' \neq x^* (x^* \in S)$

Since S is a convex set

then $x^* + \lambda(x' - x^*) = \lambda x' + (1-\lambda)x^* \in S$
(This is the property of convex set!)

$$f(x') = f(x^*) + \nabla f(x^*)^\top (x' - x^*)$$

$$+ \frac{1}{2} (x' - x^*)^\top \nabla^2 f[x^* + \lambda(x' - x^*)] (x' - x^*)$$

Since $x^* \in S$ is a local minimum

then $\nabla f(x^*) = 0$

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$$f(x') = f(x^*) + \frac{1}{2} (x' - x^*)^\top \nabla^2 f[x^* + \lambda(x' - x^*)] (x' - x^*)$$

Now we have

$\nabla^2 f(x)$ is positive definite
for all $x \in S$

then

$$\frac{1}{2}(x' - x^*)^T f[x^* + \lambda(x' - x^*)] (x' - x^*) > 0$$



$$f(x') > f(x^*) , \quad \forall x' \in S \text{ and} \\ x' \neq x^*$$

Therefore,

x^* is a global minimum of f
over S .

Problem 8

Let $y = Ax + b$

then $g(x) = f(Ax + b)$

So applying Newton step on g

will be

$$x' = x - (\nabla^2 g(x))^{-1} \nabla g(x)$$

$$= x - (\bar{A}^\top \nabla^2 f(Ax + b) A)^{-1} \bar{A}^\top \nabla f(Ax + b)$$

$$= x - A^{-1} (\nabla^2 f(Ax + b))^{-1} \nabla f(Ax + b)$$

Then

$$Ax' + b = (Ax + b) - (\nabla^2 f(Ax + b))^{-1} \nabla f(Ax + b)$$

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$$y' = y - (\nabla^2 f(y))^{-1} \nabla f(y)$$

That is to say
Newton's method has the
property of affine invariance

Therefore,

the Newton step for $g(x) = f(Ax + b)$
is the same as the Newton
step for $f(x)$

