

Gradient Flows for Statistical Computation

Trends and Trajectories

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Main ideas today

- Many statistical tasks reduce to solution of an optimisation problem
- Many common methods for these problems have ‘gradient’ structure
- Identifying these commonalities is useful for analysis, synthesis, progress

Game Plan

- Describe a diverse variety of relevant statistical optimisation tasks
- Describe a consistent framework for solving them computationally
- Identify some ‘standard’ methods which come from this framework
 - ... and explain how some extensions can be derived
- Identify some open questions arising from these new methods

Collaborators



feel free to stop me at any point

ask me about references

Examples of Statistical Optimisation Problems

Three Main Characters

- Optimisation over Parameter Spaces (“ $\Theta \subseteq \mathbf{R}^d$ ”)
- Optimisation over Measure Spaces (“ $\mathcal{P}(\mathcal{X})$ ”; $\mathcal{X} \subseteq \mathbf{R}^d$)
- Optimisation over ‘Hybrid’ Spaces (“ $\Theta \times \mathcal{P}(\mathcal{X})$ ”)

Optimisation over Parameter Spaces

- Maximum Likelihood Estimation ('MLE'): $\max_{\theta} \sum_{i \in [N]} \log p_{\theta}(y_i)$
 - maybe add a penalty term ('penalised MLE')
 - maybe use a more general loss ('M-Estimation')
- Variational Approximation : $\min_{\theta} \text{KL} (p_{\theta}, \pi)$
 - e.g. $\theta = (m, C)$, $p_{\theta}(\mathrm{d}x) = \mathcal{N}(\mathrm{d}x; m, C)$; "best Gaussian fit"

Optimisation over Measure Spaces

- Sampling from an unnormalised distribution $\pi \propto \exp(-V)$

$$\min_{\mu} \text{KL}(\mu, \pi) \sim \min_{\mu} \left\{ \mathbf{E}_{\mu}[V] + \mathcal{H}(\mu) \right\}$$

with $\mathcal{H}(\mu) = \int (\mu \log \mu - \mu)$.

- (Nonparametric) Mean-Field Approximation

$$\min_{\mu_1, \dots, \mu_d} \text{KL}(\mu_1 \otimes \dots \otimes \mu_d, \pi) \sim \min_{\mu} \left\{ \mathbf{E}_{\mu_1 \otimes \dots \otimes \mu_d}[V] + \sum_{i \in [d]} \mathcal{H}(\mu_i) \right\}$$

- (other objectives involving integral probability metrics, information-theoretic divergences, etc.)

Optimisation over Hybrid Spaces

- Basic Example: Deconvolution
 - Model: draw $X \sim p_\theta$, but only *observe* $Y \sim \mathcal{N}(X, \sigma^2)$
 - In principle, can ‘just’ do MLE ...
 - ... but here, $p_\theta(y)$, $\nabla_\theta \log p_\theta(y)$ are likely unavailable
 - Coupled problem: impute $[x \mid \theta, y]$, optimise $[\theta \mid x; y]$
 - More generally: “EM Algorithm”, “Latent Variable Models”

More on Hybrid Spaces

- { ‘Energy-Based’ / ‘Unnormalised’ / ‘Pre-Normalised’ } Models
 - Specify $p_{\theta}(y) \propto \exp(-V(y; \theta))$; leave $Z(\theta)$ defined implicitly
 - In principle, can ‘just’ do MLE ...
 - ... but here, $p_{\theta}(y)$, $\nabla_{\theta} \log p_{\theta}(y)$ are likely unavailable
 - Coupled problem: Sample $x \sim p_{\theta}$, then optimise θ based on x, y
 - “Contrastive Divergence”, “MC-MLE”

Additional Comments on Hybrid Spaces

- Increasingly, clear that many problems have this two-scale structure
 - Adaptive MCMC (sample from π , optimise parameters of dynamics)
 - Distributed Inference (sample ‘locally’, ‘tilt parameters’ for consensus)
 - See also “MCMC-Driven Learning” chapter by Bouchard-Côté+++
 - “Markovian Optimisation-Integration” framework
- IMO: Worthy of serious consideration; not just hypothetical / edge case.

last chance to ask about examples

Metric Structures in Statistical Optimisation

Metrics

- Nothing too fancy - just want enough structure to ‘do good calculus’
- For parameter optimisation, $\Theta \subseteq \mathbf{R}^d$ can carry Euclidean metric.
- For measure optimisation, $\mathcal{P}(\mathcal{X})$ can carry transport metric.
- For hybrid optimisation, $\Theta \times \mathcal{P}(\mathcal{X})$ can carry ‘hybrid’ metric

$$d_h \left((\theta, \mu), (\theta', \mu') \right) = \sqrt{\|\theta - \theta'\|_2^2 + \mathcal{T}_2^2(\mu, \mu')}$$

- For the ambitious: { Riemannian, (Kernel) Stein, (Ensemble) Kalman, \dots }

Optimisation on Metric Spaces

Conceptual Optimisation Framework

1. Abstract Optimisation Problem

$$\min_{x \in \mathcal{X}} f(x)$$

2. Proximal Point Update

$$x_0 \mapsto_h \arg \min_{x \in \mathcal{X}} \left\{ f(x) + \frac{1}{2h} \cdot d(x, x_0)^2 \right\}$$

3. Gradient Flow

$$\dot{x}_t = -\nabla f(x_t)$$

4. (Discretisation)

From Gradient Flows to Algorithms

Gradient Flows on Parameter Spaces

- Task: $\min_{\theta \in \Theta} f(\theta)$
- Continuous Dynamics: $\dot{\theta}_t = -\nabla_{\theta} f(\theta_t)$
- Time-Discretised Method: “Gradient Method”
- Extremely well-understood for uniformly-convex f
- Further theory when $f - \inf f \lesssim \|\nabla f\|^2$; ‘Polyak-Łojasiewicz Inequality’

Gradients on Measure Spaces?

- Suppose that we are interested in a functional $\mathcal{F} : \mathcal{P}(\mathcal{X}) \rightarrow \mathbf{R}$
- Assume that it carries the Taylor expansion

$$\frac{\mathcal{F}((1-t) \cdot \mu + t \cdot \mu') - \mathcal{F}(\mu)}{t} \approx \int \left(\delta_{\mu} \mathcal{F} \right) (\mu, x) \cdot \left\{ \mu'(\mathrm{d}x) - \mu(\mathrm{d}x) \right\}$$

- Natural to decrease \mathcal{F} by pushing mass towards minima of $\left(\delta_{\mu} \mathcal{F} \right) (\mu, \cdot)$, i.e.

$$\dot{X}_t = - \nabla_x \delta_{\mu} \mathcal{F} (\mu_t, X_t)$$

A Special Case: Entropy

- A particularly special functional is the (shifted, negative) entropy

$$\mathcal{H}(\mu) = \int (\mu \log \mu - \mu)$$

- This satisfies $\delta_\mu \mathcal{H}(\mu, x) = \log \mu(x)$, so we could decrease it by evolving

$$\dot{X}_t = -\nabla_x \log \mu_t(X_t)$$

- Remarkably, the same path of measures is induced by instead evolving stochastically by

$$dX_t = \sqrt{2}dW_t$$

- “The gradient flow of the entropy can be realised by Brownian motion”

Gradient Flows on Measure Spaces

- Task: $\min_{\mu \in \mathcal{P}(\mathcal{X})} \left\{ \mathcal{F}(\mu) + \mathcal{H}(\mu) \right\}$

- Continuous Dynamics:

$$\partial_t \mu_t = - \nabla_{\mathcal{T}, \mu} \{ \mathcal{F} + \mathcal{H} \} (\mu_t)$$

$$\rightsquigarrow \quad dX_t = - \nabla_x \delta_\mu \mathcal{F} (\mu_t, X_t) dt + \sqrt{2} dW_t$$

- **Space-Time-Discretised Method:** (Mean-Field) “Langevin Monte Carlo”
- Extremely well-understood for uniformly-geodesically-convex \mathcal{F}
- Further theory for ‘well-connected’ \mathcal{F} ; { (Super-)Poincaré, Logarithmic Sobolev, ... } Inequalities

Gradient Flows on Hybrid Spaces

- Task: $\min_{\theta \in \Theta, \mu \in \mathcal{P}(\mathcal{X})} \left\{ \mathcal{F}(\theta, \mu) + \mathcal{H}(\mu) \right\}$

- Continuous Dynamics:

$$\dot{\theta}_t = - \nabla_{\theta} \mathcal{F}(\theta_t, \mu_t)$$

$$dX_t = - \nabla_x \delta_{\mu} \mathcal{F}(\theta_t, \mu_t, X_t) dt + \sqrt{2} dW_t$$

- Space-Time-Discretised Method: “Particle Gradient Descent”
- Very well-understood for uniformly-geodesically-convex \mathcal{F}
- Further theory currently missing; Open Questions

questions on the 'basic' methods?

Some New Directions

Beyond ‘Standard’ Gradient Flows

- In many applications, the ‘standard’ gradient flow is sub-optimal.
- This is true in both continuous and in discrete time.
- Some intuition has developed for how ‘optimal’ improvements look.
- A common (though not universal) theme seems to involve ‘momentum’.
 - “lifting the problem to the cotangent bundle”

Enriched Objective Functions

- For parameter optimisation, consider

$$\min_{(\theta, \varphi) \in \mathcal{T}^* \Theta} \left\{ h(\theta, \varphi) := f(\theta) + \frac{1}{2} \cdot \|\varphi\|_2^2 \right\}$$

- For measure optimisation, consider

$$\min_{\nu \in \mathcal{P}(\mathcal{T}^* \mathcal{X})} \left\{ H(\nu) := \mathcal{F}(\nu) + \mathcal{H}(\nu) + \mathbf{E}_\nu \left[\frac{1}{2} \cdot \|P\|^2 \right] \right\}$$

More Enriched Objective Functions

- For hybrid optimisation, consider

$$\min_{(\theta, \varphi) \in \mathcal{T}^* \Theta, \nu \in \mathcal{P}(\mathcal{T}^* \mathcal{X})} \left\{ H(\theta, \varphi, \nu) := \mathcal{F}(\theta, \nu) + \mathcal{H}(\nu) + \frac{1}{2} \cdot \|\varphi\|_2^2 + \mathbf{E}_\nu \left[\frac{1}{2} \cdot \|P\|^2 \right] \right\}$$

- N.B. These choices are not “automatic” / “canonical”, but appear to make sense in many examples.

Warm-Up: Hamiltonian Flows

- A sketchy idea in isolation: conserve the ‘Hamiltonian’
- Introduce skew-symmetric matrix

$$\mathbf{J} = \begin{pmatrix} 0 & \mathbf{I} \\ -\mathbf{I} & 0 \end{pmatrix}$$

- In abstract terms: instead of

$$\dot{x} = -\nabla f(x),$$

- take $z = (x, p)$ and do

$$\dot{z} = \mathbf{J} \nabla H(z)$$

Hamiltonian Flows in Action

- For parameter optimisation, obtain

$$\dot{\theta}_t = \varphi_t, \quad \dot{\varphi}_t = -\nabla f(\theta_t)$$

- For measure optimisation, obtain (omitting entropy term)

$$dX_t = P_t dt, \quad dP_t = -\nabla_x \delta_\mu \mathcal{F}(\mu_t, X_t) dt$$

- For hybrid optimisation, obtain

$$\begin{aligned} \dot{\theta}_t &= \varphi_t, & \dot{\varphi}_t &= -\nabla_\theta \mathcal{F}(\theta_t, \mu_t) \\ dX_t &= P_t dt, & dP_t &= \nabla_x \delta_\mu \mathcal{F}(\theta_t, \mu_t, X_t) dt \end{aligned}$$

- But ... why bother?

Conformal Hamiltonian Flows

- A recurrent phenomenon: it can be interesting to blend Hamiltonian circulation with gradient-type damping *only on the momentum term*
- With some consistency, this appears to yield improved (and even optimal) methods
- The key matrix is then (for some $\gamma > 0$)

$$\mathbf{D}_\gamma = \begin{pmatrix} 0 & -\mathbf{I} \\ \mathbf{I} & \gamma \cdot \mathbf{I} \end{pmatrix}$$

and we will (formally) construct dynamics according to

$$\dot{z} = -\mathbf{D}_\gamma \nabla H(z)$$

Conformal Hamiltonian Flows in Action

- For parameter optimisation, obtain

$$\dot{\theta}_t = \varphi_t, \quad \dot{\varphi}_t = -\nabla f(\theta_t) - \gamma \cdot \varphi_t$$

- \approx Nesterov's "Fast Gradient Method", rate-optimal for convex minimisation

- For measure optimisation, obtain

$$dX_t = P_t dt, \quad dP_t = -\nabla_x \delta_\mu \mathcal{F}(\mu_t, X_t) dt - \gamma \cdot P_t dt + \sqrt{2 \cdot \gamma} dW_t$$

- \approx (Kinetic, Underdamped, ...) Langevin Monte Carlo, improving upon LMC in many cases, "plausibly" optimal

- For hybrid optimisation, obtain

$$\begin{aligned} \dot{\theta}_t &= \varphi_t, & \dot{\varphi}_t &= -\nabla_{\theta} \mathcal{F}(\theta_t, \mu_t) - \gamma \cdot \varphi_t \\ dX_t &= P_t dt, & dP_t &= -\nabla_x \delta_\mu \mathcal{F}(\theta_t, \mu_t, X_t) dt - \gamma \cdot P_t dt + \sqrt{2 \cdot \gamma} dW_t \end{aligned}$$

- \approx our "Momentum Particle Gradient Descent", which empirically outperforms the original PGD

Recap and Open Questions

Main ideas today

- Optimisation problems are widespread in statistical tasks
 - ... and often involve more than ‘just’ fixed-dimensional parameters.
- It is often possible to solve such problems “with gradient descent”
 - ... and we can even systematically concoct improvements on GD.
- Identifying these commonalities is useful for analysis, synthesis, progress
 - ... and many interesting questions still remain.

Some Open Questions

- For optimisation problems on hybrid spaces,
 - Can we strengthen the theory outside of the uniformly-convex case?
 - Can we develop good principles for numerical discretisation?
 - What more shall be learned from “pure” optimisation and sampling?
- For momentum-enrichment,
 - How should we systematically construct ‘enriched’ objective functions?

Some Further Questions

- In general,
 - Which other practical tasks can be fruitfully interpreted as optimisation?
 - Should we ever look *beyond* gradient and conformal Hamiltonian flows?