

Practical.

Comparison Theorems to Slice Sampling

Slice Sampling is a popular algorithm for approximate sampling from intractable probability ~~distributions~~ distributions, used in JAGS, Matlab, ...

Its popularity stems from its wide applicability, and robustness, in both practice and theory. intuitive geometric formulation

One ^{outstanding} theoretical challenge has been that while the ideal slice sampler ~~has~~ admits a robust and elegant convergence theory, practical implementations ~~typically~~ typically involve additional approximations, ~~which~~ which prevents the existing theory from holding as is.

In recent work, we develop a theoretical framework for the analysis of such "hybrid" slice samplers, ~~facilitating~~ facilitating novel convergence results for slice sampling as implemented in practice.

We provide a number of concrete examples which illustrate the flexibility and practicality of our approach, including i) stepping-out and shrinkage procedures, ii) hit-and-run "on the slice",

No prior knowledge of the slice sampling algorithm will be assumed, and relevant notions of Markov chain convergence ~~with~~ will be ~~introduced~~ introduced as appropriate in the text.

Optimality of MLE

↓
in what sense? → MLE is typically consistent,
asymptotically unbiased, good
variance.
↓
want a finite-n comparison.

simplify: think about unbiased estimators; what is possible?
(good estimators might be close to unbiased)
c.e.f. Gauss-Markov.
mathematically, convenient family.

Start with
$$\begin{cases} \int P_\theta(x) dx = 1 \\ \int P_\theta(x) \hat{\theta}(x) dx = \theta \end{cases} \Rightarrow \theta\text{-independent relation.}$$

~~general~~
$$\int P_\theta(x) F(x) = G(\theta).$$

define
$$F(\theta) = \int P_\theta(x) f(x) dx \in \mathbb{R}^p$$

$$\begin{aligned} \frac{\partial F}{\partial \theta_k} &= \frac{\partial}{\partial \theta_k} \int P_\theta(x) f(x) dx \\ &= \int P_\theta(x) \frac{\partial}{\partial \theta_k} \log P_\theta(x) \cdot f(x) dx \end{aligned}$$

$$\nabla_\theta F(\theta) = \text{COV}_\theta(\nabla_\theta \log P_\theta(x), f(x)) \in \mathbb{R}^p.$$

$$f(x) = 1 \Rightarrow \theta = \text{COV}_\theta \nabla$$

① MCMC

$$\pi \rightarrow [x_1 \rightarrow x_2 \rightarrow \dots]$$

$$\text{Law}(x_t) \rightarrow \pi$$

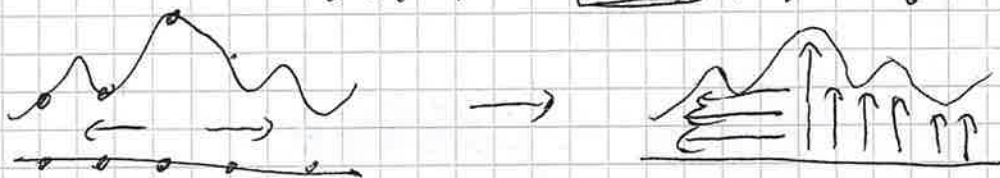
$$\frac{1}{T} \sum_{t=1}^T f(x_t) \rightarrow \int \pi(dx) f(x)$$

oracle $\log \pi$ (up to a constant), [more]

② Slice Sampling

$$\pi(dx) = \omega(x) \lambda^d(dx)$$

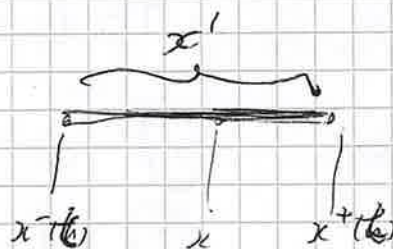
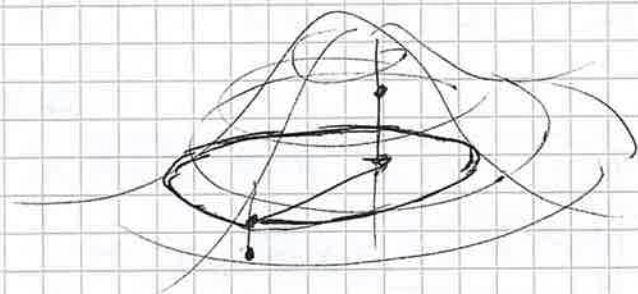
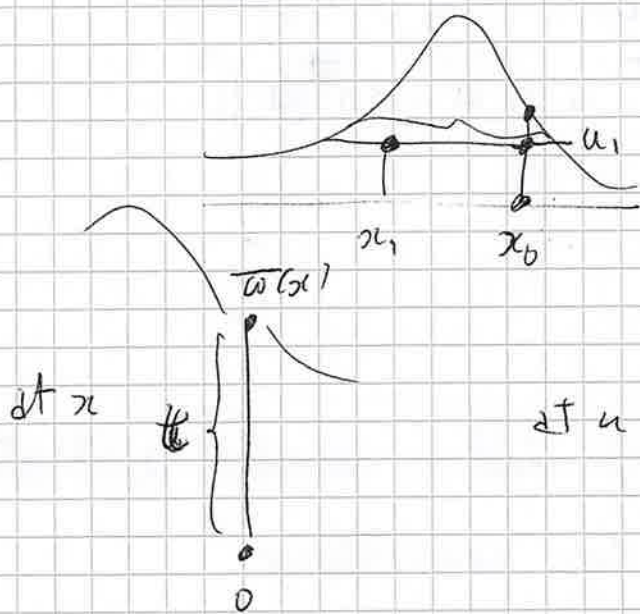
$$\Pi(d\mu, \mu) = \boxed{\omega(x)} \mathbb{I}[0 \leq \mu \leq \omega(x)] \lambda^{d+1}(d(x, \mu))$$



"iterated conditional simulation".

(1) at x , $u \sim \Pi(d\mu|x) = \text{Unif}([0, \omega(x)])$
(sample a height)

(2) at μ , $x \sim \Pi(dx|\mu) = \text{Unif}(\{x : \omega(x) \geq \mu\})$
(sample a point ~~at~~ of this height)



$$x \longrightarrow x'$$

$$x' \sim U(x, dx'). \quad [\text{Markov kernel}]$$

①

$$\begin{pmatrix} a \\ b \end{pmatrix}^T - \begin{pmatrix} a \\ b \end{pmatrix} = a^T I(\theta) a + 2a^T b + b^T \text{cov}(\hat{\theta}(x)) b$$

$$\frac{d}{da} : I(\theta) a + b = 0, a = -I(\theta)^{-1} b$$

$$\Rightarrow b^T (\text{cov} \hat{\theta}(x) - I(\theta)) b \geq 0.$$

$$\begin{pmatrix} -I(\theta)^{-1} b \\ \downarrow \end{pmatrix}$$

Caveats let $E \hat{\theta}(x) = (\cancel{1-\epsilon}) \theta$

$$E \|(1-\epsilon) \hat{\theta}(x) - \theta\|^2 = (1-\epsilon)^2 E \|\hat{\theta}(x) - \theta\|^2$$

$$\text{cov}((1-\epsilon)\theta)$$

$$\text{cov}(A \hat{\theta}(x)) = A \text{cov}(\hat{\theta}(x)) A^T$$

$$E (A \hat{\theta}(x) - \theta)^{\otimes 2} = E (A(\hat{\theta}(x) - \theta) + (A-1)\theta)^{\otimes 2} \\ = A C A^T + \|(A-1)\theta\|^2$$

$$\boxed{\begin{matrix} \frac{\partial}{\partial A} A \rightarrow A + \delta A \\ \frac{\partial}{\partial A} (A C A^T) \rightarrow (C \delta A + \delta A C) \end{matrix}}$$

Bias-Variance Tradeoff

One approach

- ① come up with a sensible estimator
- ② check for consistency
- ③ check that bias is sub-dominant
- ④ apply shrinkage/regularisation to control variance

(other stuff)

Thm^(M) SS leaves π invariant \Rightarrow valid for MCMC

Thm^(rel) weak conditions \Rightarrow SS is geometrically ergodic \Rightarrow more than
observation I know no example where SS is not geometrically ergodic

Thm (NRS). π spherically symmetric, log-concave

\Rightarrow convergence is like $e^{-t/d}$, t iterations

also: π itself doesn't matter, just mass of level sets

Thm (Sch) π = student-t \Rightarrow convergence like e^{-t/d^2}
(heavy tails but still geometric)

\exists other examples.

\Rightarrow When implementable, SS is robust and
handles ^{high} dimensionality well, for a 0th-order method.

Issue "sample $x \sim \text{Unif}(\{x: \pi(x) > \epsilon\})$.
 $= \text{Unif}(G(t))$

• If $G(t) \in \mathcal{O}, \square, \dots$, sure

• If $G(t)$ is more arbitrary ... work for it.

Let $v_f(dx) = \text{Unif}(dx; G(t))$

SS: $t \sim \text{Unif}([0, \pi(m)])$

$x' \sim v_f$

HSS: replace $x' \sim v_f$

with $x' \sim \text{MCMC}(x \rightarrow x'; \text{target} = v_f)$

Usually easier to implement, slower Markov chain.
(examples!)

Question: how much slower?

how do we trade off ease/efficiency in practice?

what price are we currently paying?

"comparison theory"

Fixed $p, n \rightarrow \infty$: bias not always an issue.
 $p \propto n, (p, n) \rightarrow (\infty, \infty)$: more subtle.

$$MSE(\hat{\theta}(x)) = \|E\hat{\theta}(x) - \theta\|_2^2 + \text{Tr}(\text{Cov}(\hat{\theta}(x)))$$

statistical "efficiency" : $\text{Var} \approx \text{Var}_{\text{CRLB}}$
 (asymptotic)

(often only asymptotically unbiased)
 (in practice, want "bias is not an issue")

Proof Elements

$$(1) \int P_{\theta}(x) \nabla_{\theta} \log P_{\theta}(x) dx = 0.$$

$$(2) \int P_{\theta}(x) \nabla_{\theta}^2 \log P_{\theta}(x) dx \\ = \int P_{\theta}(x) (\nabla_{\theta} \log P_{\theta}(x)) (\nabla_{\theta} \log P_{\theta}(x))^T dx$$

$$(3) \int P_{\theta_*}(x) \log \frac{P_{\theta_*}(x)}{P_{\theta}(x)} dx \geq 0.$$

$$(4) \ell(\theta, x) = \log P_{\theta}(x) \\ \ell(\theta) = E_{\theta_*}[\log P_{\theta}(x)] \leq \ell(\theta_*).$$

Proof let $\hat{\theta}(x)$ be unbiased for θ .

$$\Rightarrow \forall \theta \in \Theta, \int P_{\theta}(x) \hat{\theta}(x) dx = \theta.$$

$$\frac{\partial}{\partial \theta_i} \Rightarrow \int P_{\theta}(x) \left(\frac{\partial}{\partial \theta_i} \log P_{\theta}(x) \right) \hat{\theta}_j(x) dx = \delta_{ij}$$

$$\text{Cov}(\nabla_{\theta} \log P_{\theta}(x), \hat{\theta}(x)) = I.$$

$$\text{Cov} \left(\nabla_{\theta} \log P_{\theta}(x), \hat{\theta}(x) \right) = \begin{pmatrix} I(\theta) & I_p \\ I_p & \text{Cov}(\hat{\theta}(x)) \end{pmatrix} \succeq 0.$$

$$\begin{pmatrix} v_1 \\ v_2 \end{pmatrix}^T \begin{pmatrix} 0 \\ v \end{pmatrix} = \begin{pmatrix} 0 \\ v \end{pmatrix}^T \begin{pmatrix} v \\ \text{Cov}(\hat{\theta}(x)) v \end{pmatrix} =$$

Convergence of Markov chains

$$\left(\begin{aligned} \mu_n &= \mu P^n \\ d(\mu, \pi) &= \int \pi(dx) \left(\frac{d\mu}{d\pi}(x) - 1 \right)^2 \\ &= \left\| \frac{d\mu}{d\pi} - 1 \right\|_{L^2(\pi)}^2 \end{aligned} \right)$$

$$\|f\|_{L^2(\pi)}^2 = \int \pi(dx) f(x)^2$$

$$Pf(x) = \int P(x, dy) f(y).$$

$$P^n f(x) \rightarrow \pi(f) \quad (\text{ergodicity})$$

$$\|P^n f - \pi(f)\|_{L^2(\pi)}^2 \rightarrow 0 \quad \text{"L}^2 \text{ convergence"}$$

(tends to $\pi(f) = 0$)

Best case : $\|P f\|_2^2 \leq (1 - \lambda) \|f\|_2^2 \quad \forall f \in L_0^2(\pi)$

\Rightarrow exponential rate.

actually, equivalent to

$$\mathcal{E}(P^* P, f) \geq \lambda \|f\|_2^2$$

$$\frac{1}{2} \int \pi(dx) (P^* P)(x, dy) (f(x) - f(y))^2 \quad \uparrow \text{remaining energy}$$

$$(I - P^2) = (I + P)(I - P) = (I - P)$$

energy dissipation

Fact P "positive" $\mathcal{E}(P, f) \geq \gamma \|f\|^2$

reversible

$$\Rightarrow \|P^n f\|^2 \leq (1 - \gamma)^n \|f\|^2$$

"good energy dissipation \Rightarrow good convergence" (3)

CRAMÉR-RAO LOWER BOUND

Gauss-Markov: Estimator \wedge Linear \wedge Unbiased
 \Rightarrow OLS is minimum variance

Same for MLE?

$$l(\theta; \mathbf{x}_{1:n}) = \log P_\theta(\mathbf{x}_{1:n})$$

$$\hat{\theta}_n = \operatorname{argmax}_\theta l(\theta; \mathbf{x}_{1:n})$$

$$x_1, \dots, x_n \stackrel{\text{iid}}{\sim} P_{\theta_*}$$

assumptions $\hat{\theta}_n \stackrel{d}{\sim} N(\theta_*, (nI_{\theta_*})^{-1})$

$$I_{\theta_*} = \mathbb{E}_{\theta_*} [\nabla_{\theta}^2 \log P_{\theta}(X)]$$

$$= \operatorname{Cov}_{\theta_*} [\nabla_{\theta} \log P_{\theta}(X)]_{\theta=\theta_*}$$

$$\approx \operatorname{Cov}_{\hat{\theta}_n} [\nabla_{\theta} \log P_{\theta}(X) |_{\theta=\hat{\theta}_n}]$$

don't do
it with n ?

$$\Rightarrow \operatorname{Var}(\hat{\theta}_{MLE}) = 1/n \cdot I_{\theta_*}^{-1} (1+o(1))$$

Can we find $\hat{\theta}$ s.t. $\operatorname{Var}(\hat{\theta}_{MLE}) \ll 1/n I_{\theta_*}^{-1}$?

Cramér-Rao: Let $\hat{\theta}$ be unbiased for θ , i.e.

$$\forall \theta \in \Theta, \int P_\theta(x) \hat{\theta}(x) dx = \theta.$$

$$\text{Then } \operatorname{Cov}_\theta(\hat{\theta}(x)) \geq I(\theta)^{-1}$$

$$\text{so, } \forall v, \operatorname{Cov}_\theta(\hat{\theta}(x), v) \geq v^T I(\theta)^{-1} v \in \mathbb{R}$$

Intuition If $\mathcal{E}(P, f) \geq \gamma \|f\|^2$,
 then $P \approx \gamma$ independent samples from π .
~~decorrelation~~ time $\approx \gamma^{-1}$ to equilibrium

Comparison If $\mathcal{E}(P_1, f) \geq K \mathcal{E}(P_2, f)$
 then $P_1 \approx K$ steps of P_2

We will follow in this direction.

P_1 = implementable algorithm
 P_2 = ideal slice sampling

(actually: more generally, $\|f\|^2 \leq \mathcal{E}(P, f) + \beta \|f\|_\infty^2$)

even if ~~$\beta > 0$~~ ~~$(\alpha, \beta) \leq \dots$~~ ~~still get~~

$\beta(\omega) > 0$, (non-exp) convergence, eg

$$\|P^n f\|_2^2 \leq \gamma(n) \cdot \|f\|_\infty^2$$

Examples

so, we might instead prove

$$\mathcal{E}(P_2, f) \leq s \mathcal{E}(P_1, f) + \beta(s) \cdot \|f\|_\infty^2$$

$\approx P_1$ not much worse than P_2 (depending on β)

let H_t be k_t -rev, pos. $m(t) = \nu(G(t))$

$$\forall t, \forall s \quad \|f\|_{H_t}^2 \leq s \cdot \mathcal{E}(H_t, f) + \beta(t, s) \|f\|_{\text{osc}}^2$$

$$\text{define } \beta(s) = \int_0^{\|f\|_\infty} \beta(s, t) m(t) dt$$

$$\Rightarrow \boxed{\mathcal{E}(U, f)} \leq s \cdot \mathcal{E}(H, f) + \beta(s) \|f\|_{\text{osc}}^2$$

$$\mathcal{E}(U, f)$$

$$\Rightarrow \forall v \in \mathbb{R}^p, \quad v^T (\mathcal{I}(\theta) - C(\theta)^{-1}) v \geq 0$$

$$\mathcal{I}(\theta) \succeq C(\theta)^{-1}$$

$$C(\theta) \preceq \mathcal{I}(\theta)^{-1}$$

variance
of unbiased
estimator

"Cramér-Rao
lower bound"

Current reaction: is this lower bound achievable?

roughly: asymptotically (large- n),
for reasonable models, yes,
and the MLE does so.



The MLE is almost unbiased (as $n \rightarrow \infty$),
almost minimal-variance (w.r.t. CRLB)
 \Rightarrow "optimal".

Caveats: At {finite n / large p / ...}, more to life
than ~~unbiasedness~~ unbiasedness, variance.

• All relies on correct model specification.

If $P_* \notin \{P_\theta : \theta \in \Theta\}$, no luck

\rightarrow doesn't say much about robustness.

• Sharp when $\eta(x)$ is parallel to $\nabla_\theta \log P_\theta(x)$.

\rightarrow exponential families (can develop)

• needs "regular" model (no unit...)

\Rightarrow (1) study ~~$U^n \rightarrow \pi$~~ $U^n \rightarrow \pi$
 (2) study $H^n \rightarrow V_k$
 \Rightarrow study $H \rightarrow \pi$.

Is the ideal slice sampler good?
 Is the approximation good?

Metropolis (π, ν, Q) , $\nu \otimes Q$ symmetric
 { RWM: $(\pi, \text{Leb}, Q_{RW})$
 IMM (π, q, q)
 pCN $(\pi, \gamma_{m,c}, Q_U)$

Metropolis \subseteq HybridSlice

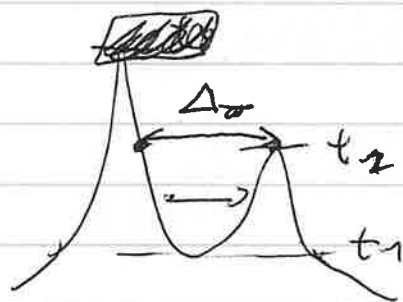
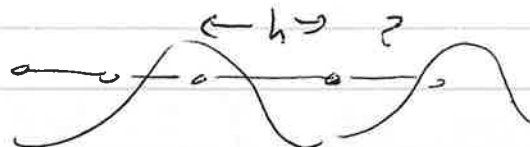
Metropolis \subseteq HybridSlice

RWM \subseteq Slice (π, Leb)

IMM \subseteq Slice (π, q)

pCN \subseteq Slice $(\pi, \gamma_{m,c})$

Stepping-out + Shrinkage



$$\begin{aligned}
 \mathcal{E}(M_t, f) &\geq \lambda(t) \|f\|_{\nu_t}^2 \\
 \lambda(t) &= \frac{h - \delta(t)}{h} \times \frac{m(t)}{m(t) + \delta(t)} \\
 &\geq \frac{h - \Delta}{h} \times \frac{m(t)}{m(t) + \Delta}
 \end{aligned}$$

$$\Rightarrow \mathcal{E}(H, f) \geq \frac{h - \Delta}{h} \times \frac{m_-}{m_- + \Delta} \mathcal{E}(U, f)$$

$$h = 2\Delta \Rightarrow \geq \frac{1}{2} \frac{m_-}{m_- + \Delta}$$

$$\text{So, } \mathbb{E}_\theta [\nabla_\theta \log P_\theta(X)] = 0$$

$$\begin{aligned} \mathcal{I}(\theta) &= \mathbb{E}_\theta [\nabla_\theta \log P_\theta(X) \cdot \nabla_\theta \log P_\theta(X)^T] \\ &= \text{Cov}_\theta [\nabla_\theta \log P_\theta(X)] \\ &= \mathbb{E}_\theta [\nabla_\theta^2 (-\log P_\theta(X))] \end{aligned}$$

(do examples)

One more:

$$\textcircled{3} \text{ Since } \int P_\theta(x) \eta(x) dx = \theta \quad (\text{by assumption})$$

$$\frac{d}{d\theta} \Rightarrow \int P_\theta(x) \eta(x) \nabla_\theta \log P_\theta(x) dx = I_p$$

$$\mathbb{E}_\theta \left[\underbrace{\eta(X)}_{\text{mean } \theta} \underbrace{\nabla_\theta \log P_\theta(X)^T}_{\text{mean } 0} \right] = I_p$$

$$\text{Cov}_\theta [\eta(X), \nabla_\theta \log P_\theta(X)] = I_p.$$

Now, let $Y = \begin{pmatrix} \eta(X) \\ \nabla_\theta \log P_\theta(X) \end{pmatrix}.$

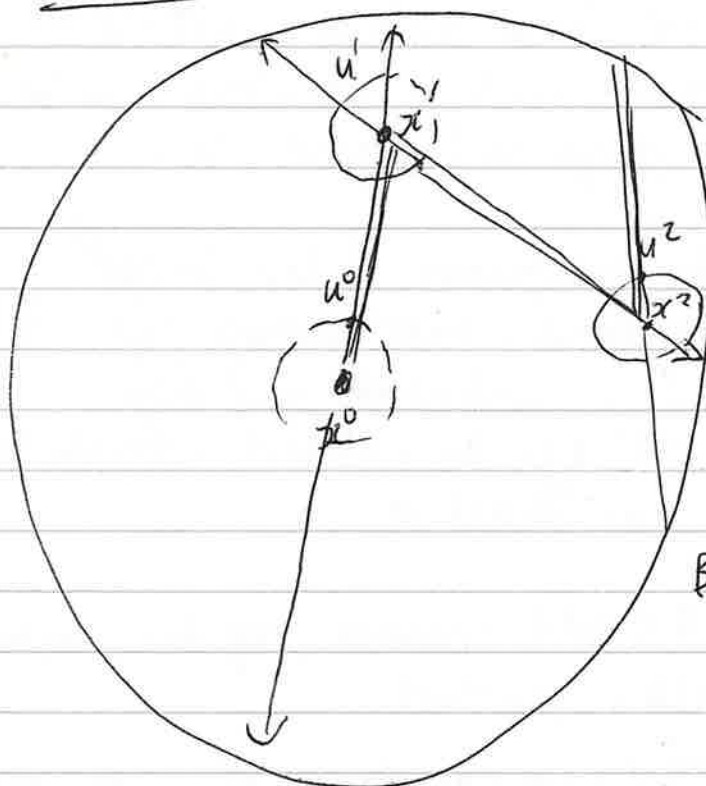
$$\text{Compute } \text{Cov}_\theta(Y) = \begin{pmatrix} C(\theta) & I_p \\ I_p & \mathcal{I}(\theta) \end{pmatrix} \succeq 0.$$

$$\begin{pmatrix} u \\ v \end{pmatrix}^T \text{Cov}_\theta(Y) \begin{pmatrix} u \\ v \end{pmatrix} = u^T C(\theta) u + 2u^T v + v^T \mathcal{I}(\theta) v \geq 0$$

$$\text{min wrt } u \Rightarrow u^* = -C(\theta)^{-1} v$$

$$\Rightarrow \begin{pmatrix} -C(\theta)^{-1} v \\ v \end{pmatrix}^T \text{Cov}_\theta(Y) \begin{pmatrix} -C(\theta)^{-1} v \\ v \end{pmatrix} = v^T \{ \mathcal{I}(\theta) - C(\theta)^{-1} \} v$$

Hit-and-Run $\text{Unif}(K)$, also d^{th} -order.



$$B(x, R) \supseteq K \supseteq B(x, r)$$

LV: Hit-and-Run has $\gamma \geq 2^{-33} \cdot \frac{1}{d^2} \left(\frac{r_K}{R_K} \right)^2$

dimension /
conditioning

\Rightarrow Slice Sampling w/ quasi-concave π .

738 $m \leq V'' \leq L \Rightarrow \mathbb{E}(U, f) \leq 2^{33} \cdot d^2 \cdot \left(\frac{L}{m} \right) \mathbb{E}(H, f)$

739 $\pi_{d,m} \Rightarrow \|f\|_{d,m}^2 \leq 2^{33} \cdot d^2 \cdot \frac{(d+1)(d+m-1)}{m-1} \mathbb{E}(H, f)$

740 : $U(x) \in \|\cdot\|^{p_1, p_2}$ at 0, $\|\cdot\|^{q_1, q_2}$ at ∞

$$\Rightarrow K_q(t) \lesssim \left(\log \left(\frac{1}{t} \right) \right)^{\frac{1}{q_1} - \frac{1}{q_2}} \cdot t^+$$

$$\left(\log \left(\frac{1}{t} \right) \right)^{\frac{1}{p_1} - \frac{1}{p_2}} \cdot 1^-$$

\rightarrow $p_1 = p_2$, $\beta(\cdot) \lesssim e^{-\Omega(s^{q_1 q_2 (q_2 - q_1)})}$
 $p_1 \neq p_2$, $\beta(s) \lesssim s^{-(1 + \frac{d}{q_1}) \frac{p_1 p_2}{p_1 - p_2}}$

Parametric Estimation and the CRLB

OLS: model \rightarrow linear, unbiased estimation

Gauss-Markov \rightarrow OLS is minimum variance
not whole story, but a good start

general parametric estimation: too broad!

- finite-dimensional, fixed sample size $\{P_\theta(x)\}$

- "linear" = ?, unbiased: still okay

Q: how "good" can an unbiased estimator be?

A: CRLB: $\text{Var}(\hat{\theta}(x)) \geq \dots$

setting $\{P_\theta(x): \theta \in \Omega\}$ smooth, regular. may have $x = (x_1, \dots, x_n)$

let $\hat{\theta}(x) = \eta(x)$, so that

$\forall \theta \in \Omega, \int P_\theta(x) \eta(x) dx = \theta$ as vector

measure uncertainty via

$$\text{Cov}_\theta(\hat{\theta}(x)) = \int P_\theta(x) (\eta(x) - \theta)(\eta(x) - \theta)^T dx = C(\theta).$$

What can we say about $C(\theta)$?

Some basic results

$$\frac{d}{d\theta} f(\theta) = f'(\theta) = \frac{d}{d\theta} \log f(\theta)$$

$$\begin{aligned} \textcircled{1} \text{ Since } \int P_\theta(x) dx &= 1 \\ \frac{d}{d\theta} \Rightarrow \int P_\theta(x) \nabla_\theta \log P_\theta(x) dx &= 0_p \\ \mathbb{E}_\theta [\nabla_\theta \log P_\theta(x)] &= 0_p \end{aligned}$$

$$\begin{aligned} \textcircled{2} \text{ Since } \int P_\theta(x) dx &= 1 \\ \left(\frac{d}{d\theta}\right)^2 \Rightarrow \int P_\theta(x) \left[\nabla_\theta \log P_\theta(x) \nabla_\theta \log P_\theta(x)^T + \nabla_\theta^2 \log P_\theta(x) \right] dx &= 0_{p \times p} \end{aligned}$$

$$\begin{aligned} \mathcal{I}(\theta) &:= \int P_\theta(x) (\nabla_\theta \log P_\theta(x)) (\nabla_\theta \log P_\theta(x))^T dx \\ &= \int P_\theta(x) (-\nabla_\theta^2 \log P_\theta(x)) dx \end{aligned}$$

Takeaways

- SS: good in theory and practice
- HSS: used in practice, gap in theory
- Comparison: how well does H approximate U ?
- Applications: $H \preceq U$

If $H_f \preceq c$, then $H \preceq cU$

If H_f good, then H almost as good as U .

- We focus on $H_f = \text{Hit and Run}$, and similar.
Easy to combine bounds.
- General comparison framework valid beyond SS

Maximum Likelihood Inference

Linear Model: interpretable, fast / direct / transparent,
flexible, exact inference / pivots / conjugacy.

But, not always appropriate for problems / data / ..

Extension 1 Linear Mixed Models.

m subjects, n input-output pairs per subject

$$\text{for } j=1, \dots, m, \quad y_{ij} = \beta_0 + \beta_1 x_{ij} + \epsilon_{ij}$$

or: subject-wise intercept $\Rightarrow y_{ij} = \beta_0 + \beta_1 x_{ij} + \sum I[j=k] \gamma_k + \epsilon_{ij}$

can't estimate γ_k well if n is small (not identified)

shrinkage/sharing of information: $(\gamma_1, \dots, \gamma_m) \sim N(0, \Sigma(\phi))$

(\sim identifiability, regularisation) e.g. ϕI .

Extension 2 Non-Gaussian Input-Output Regression Models

count data: $y_i = \text{Poisson}(\lambda_i)$

$$\log \lambda_i = \beta_0 + \beta_1 x_i \quad (\Rightarrow \text{latent linear})$$

estimation by LS inappropriate \rightarrow \log nonlinear
 $\text{Var}(y_i)$ nonconstant

- instead of forcing problems into LS format, identify salient features of LS problem which are structurally important, beyond "full tractability"

- what principles do we have? how do we come up with OLS?