

# **Artificial Intelligence**

## Lab 07 Tasks

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#### Task#1

#### **Solution:**

```
def bfs(graph, start): lusage
  queue = [start] # Initialize queue
  visited = set([start]) # Track visited nodes
  while queue:
    node = queue.pop(0) # Remove first element (FIFO)
    print(node, end=" ")

    for neighbor in graph[node]:
        if neighbor not in visited:
            queue.append(neighbor) # Add unvisited neighbors
            visited.add(neighbor)

graph = {
    "A": ["B", "C", "H"],
    "B": ["A"],
    "C": ["A", "D"],
    "D": ["C", "E", "F"],
    "E": ["D", "6", "H"],
    "F": ["D", "6"],
    "G": ["E", "F"],
    "H": ["A", "E"]
}

print("BFS Traversal [:")

bfs(graph, start ['A')
```

## **Output:**

```
BFS Traversal :
A B C H D E F G
Process finished with exit code 0
```

#### Task#2

```
graph = {
    "A": ["B", "C", "H"],
    "B": ["A"],
    "C": ["A", "D"],
    "D": ["C", "E", "F"],
    "E": ["D", "G", "H"],
   "F": ["D", "G"],
   "H": ["A", "E"]
visited = []
def dfs(graph, node): 2 usages
    if node not in visited:
        print(node, end=" ")
        visited.append(node)
        for neighbor in graph[node]:
            dfs(graph, neighbor)
print("Depth First Search Traversal:")
d≘s(graph, node: "A")
```

```
Depth First Search Traversal:
A B C D E G F H
```

Task#3

## **Dry Run:**

Initial state.
1 2 3
5 6 0 L Blank tile 0
7 8 4
Goal State:
1 2 3
7 8 0 C Blank tile 0
More 4 to blank position
1 2 3
4 5 6
780
more 6 to blank position
1 2 3'
5 0 4
7 8 6
More 5 to blank position
054
786
More 4 to blank position
1 2 3
450
286
More 6 to blank position (Goal regdred)
1 2 3
y 5 6
7 8 0
C MARKET TO A STATE OF THE PARTY OF THE PART

```
[1, 2, 3]
[5, 0, 6]
[7, 8, 4]
---
[1, 2, 3]
[0, 5, 6]
[7, 8, 4]
---
[1, 2, 3]
[7, 5, 6]
[0, 8, 4]
---
[1, 2, 3]
[7, 5, 6]
[8, 0, 4]
---
[1, 2, 3]
[7, 5, 6]
[8, 4, 0]
---
[1, 2, 3]
[7, 5, 6]
[8, 4, 0]
---
[1, 2, 3]
[7, 5, 6]
[8, 4, 6]
```

```
[1, 2, 3]
[7, 0, 5]
[8, 4, 6]
---
[1, 2, 3]
[7, 4, 5]
[8, 0, 6]
---
[1, 2, 3]
[7, 4, 5]
[0, 8, 6]
---
[1, 2, 3]
[0, 4, 5]
[7, 8, 6]
---
[1, 2, 3]
[4, 0, 5]
[7, 8, 6]
---
[1, 2, 3]
[4, 0, 5]
[7, 8, 6]
---
[1, 2, 3]
[4, 5, 0]
[7, 8, 6]
---
[1, 2, 3]
[4, 5, 0]
[7, 8, 6]
---
```

#### Task#4

```
graph = {
                                                                                                         A 2
    "Arad": [("Zerind", 75), ("Sibiu", 140), ("Timisoara", 118)],
    "Zerind": [("Arad", 75), ("Oradea", 71)],
    "Sibiu": [("Oradea", 151), ("Arad", 140), ("Fagaras", 99), ("Rimnicu Vilcea", 80)],
    "Rimnicu Vilcea": [("Sibiu", 80), ("Pitesti", 97), ("Craiova", 146)],
    "Pitesti": [("Rimnicu Vilcea", 97), ("Bucharest", 101), ("Craiova", 138)],
    "Lugoj": [("Timisoara", 111), ("Mehadia", 70)],
    "Mehadia": [("Lugoj", 70), ("Drobeta", 75)],
    "Craiova": [("Drobeta", 120), ("Rimnicu Vilcea", 146), ("Pitesti", 138)],
    "Giurgiu": [("Bucharest", 90)],
    "Urziceni": [("Bucharest", 85), ("Hirsova", 98), ("Vaslui", 142)],
def dfs(graph, start, goal, path=[], visited=set()): 2 usages
   path.append(start)
    visited.add(start)
   if start == goal:
```

```
def dfs(graph, start, goal, path=[], visited=set()): 2 usages
    path.append(start)
    visited.add(start)
    if start == goal:
        return path
    for neighbor, _ in graph[start]:
        if neighbor not in visited:
            new_path = dfs(graph, neighbor, goal, path.copy(), visited.copy())
        if new_path: # If a valid path is found, return it
            return new_path

return None # No path found

# Find path from Arad to Bucharest
result = dfs(graph, start "Arad", goal: "Bucharest")

if result:
    print("DFS Path from Arad to Bucharest:", " → ".join(result))
else:
    print("No path found.")
```

```
DFS Path from Arad to Bucharest: Arad \rightarrow Zerind \rightarrow Oradea \rightarrow Sibiu \rightarrow Fagaras \rightarrow Bucharest Process finished with exit code 0
```

#### Task#5

#### **Solution:**

```
graph_data = {
    'A': {'B': 4, 'C': 3},
    'B': {'A': 4, 'D': 5, 'E': 12},
    'C': {'A': 3, 'F': 7},
    'D': {'B': 5, 'E': 2, 'G': 9},
    'E': {'B': 12, 'D': 2, 'H': 5},
    'F': {'C': 7, 'I': 4},
    'G': {'D': 9, 'H': 6},
    'H': {'E': 5, 'G': 6, 'I': 3},
    'I': {'F': 4, 'H': 3}
}
h_values = {
    'A': 10, 'B': 8, 'C': 9, 'D': 7, 'E': 6,
    'F': 4, 'G': 5, 'H': 3, 'I': 0
}
def a_star_algorithm(graph_data, start_node, goal_node): 1usage
    open_nodes = [(0 + h_values[start_node], 0, start_node, [])]
    explored_nodes = set()
while open_nodes:
    open_nodes.sort(key=lambda x: x[0])
    f_value, g_value, current_node, current_path = open_nodes.pop(0)
    if current_node in explored_nodes:
        continue
    explored_nodes.add(current_node)
```

### **Output:**

```
Shortest Path: A → C → F → I
Total Cost: 14
```

#### Task#6

```
def check_winner(board): lusage
    for row in board:
        if row[0] == row[1] == row[2] and row[0] != ' ':
            return row[0]

        for col in range(3):
        if board[0][col] == board[1][col] == board[2][col] and board[0][col] != ' ':
            return board[0][col]
        if board[0][0] == board[1][1] == board[2][2] and board[0][0] != ' ':
            return board[0][0]
        if board[0][2] == board[1][1] == board[2][0] and board[0][2] != ' ':
            return board[0][2]
        return board[0][2]
        return None

def minimax(board, is_max): 3 usages
        winner = check_winner(board)
        if winner == 'X':
            return 1
        if winner == '0':
            return -1
        if all(board[i][j] != ' ' for i in range(3) for j in range(3)):
            return 0
        if is_max:
        best = -100
        for i in range(3):
            for j in range(3):
        }
```

```
if board[i][j] == ' ':
                  best = max(best, minimax(board, is_max: False))
               if board[i][j] == ' ':
                  board[i][j] = '0'
                  board[i][j] = '
       return best
def find_best_move(board): 1 usage
   best_val = -100
   best_move = (-1, -1)
           if board[i][j] == ' ':
              board[i][j] = 'X'
              move_val = minimax(board, is_max: False)
              board[i][j] = ' '
                         .........
                        if move_val > best_val:
                             best_val = move_val
                             best_move = (i, j)
          return best_move
     board = [['X', '0', 'X'],
               ['0', 'X', '0'],
[' ', ' ', ' ']]
     print("Best Move:", find_best_move(board))
```

```
Best Move: (2, 0)

Process finished with exit code 0
```