

- 'votess: A multi-target, GPU-capable, parallel Voronoi
- ₂ tessellator'
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Statement of need

A Voronoi tessellation is a spatial decomposition that partitions space into a set of convex hulls based on proximity to a seed points with interesting to the applications in biology, data science, geography, and physics. One compute intensive application is its use in astrophysics, such as the analysis of matter distribution (Weygaert, 1994), optimal transport theory for early-universe reconstruction (Levy et al., 2021), and in observational data analysis and numerical simulations of cosmic structure formation (Springel, 2010).

The increasing size of datasets produced today have underscored the need for more efficient algorithms to both generate and analyse these datasets, and the rise of heterogenous computing facilities would enable such new algorithms to be run. There do exist several sequential and parallel implementations of the Voronoi diagram problem (Marot et al., 2019) (Wu et al., 2023) (The CGAL Project, 2018) (Inria, 2018), however, they are mostly restricted to CPU or specific GPU architectures, thus limiting their potential as a portable multi-architecture algorithm.

Summary

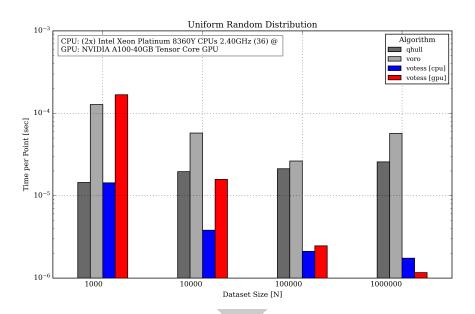
votess is a library, implementing Ray's meshless algorithm (Ray et al., 2018), for computing parallel three dimensional Voronoi tessellations using the C++/SYCL framework for CPU, GPUs and other future architectures.

One advantage of this algorithm is the ability for each cell to be computed independently (Ray et al., 2018), making it suitable for parallel execution. It also produces the geometry of the Voronoi cells via their neighbor connectivity information, rather than a full combinatorial mesh data structure, thus making it more ammenable to data parallel architectures than alternatives such as sequential insertion or the Bowyer-Watson algorithm (Bowyer, 1981) (Watson, 1981).

The core method of votess consists of two main steps. First, the input set of points is sorted into a grid, and a k-nearest neighbors search is performed. Once the k nearest neighbors are identified for each point, the Voronoi cell is computed by iteratively clipping a bounding box using the perpendicular bisectors between the point and the identified neighbors. A security radius condition (Lévy & Bonneel, 2013) ensures that the resulting Voronoi cell is valid, and if the cell cannot be validated, an CPU fallback mechanism is used.



35 Performance



In Figure 1, we show its performance compared to two other single-threaded Voronoi tessellation libraries: Qhull and Voro++. Both are well-tested and widely used. Qhull is a computational geometry library that constructs convex hulls and Voronoi diagrams using an indirect projection method (Barber et al., 1996), while Voro++ is a C++ library specifically designed for three-dimensional Voronoi tessellations, utilizing a cell-based computation approach that is well-suited for physical applications (Rycroft, 2009).

- From the graph above, votess outperforms single-threaded alternatives. We find that votess performs best on GPUs with large datasets. The CPU implementation can outperform other implementations by a factor of 10 to 100.
- Multithreaded Voronoi tesellelation codes do exist, and these include ParVoro++ (Wu et al., 2023), CGAL (The CGAL Project, 2018), and GEOGRAM (Inria, 2018). However, they do not natively support GPU architectures.

49 Features

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- votess is designed to be versatile. It supports various outputs, including the natural neighbor information for each Voronoi cell. This is a 2D jagged array of neighbor indices of the sorted input dataset.
- Users can invoke votess in three ways: through the C++ library, a command-line interface clvotess, and a Python wrapper interface pyvotess. The C++ library offers a simple interface with a tessellate function that computes the mesh. The Python wrapper, mirrors the functionality of the C++ version, with native numpy array support, providing ease of use for Python-based workflows.
- The behavior of votess can be fine-tuned with run time parameters in order to (optionally) optimize runtime performance.

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