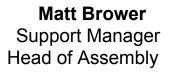
FI.N.N. R()H BIIIIER

### We are Team 82



Ricky Mangerie Project Manager Head of Planning







Samridh Prasad Developer Test Coordinator

Quinlan Morgheim Developer Issues Manager



## Project Request

WALL-@

- Our project, named "F.I.N.N. (Fully-integrated Nomadic Neotech) the Robot Butler", is a robot built using Raspberry Pi.
- The major components of the setup are:
  - Raspberry Pi
  - Robot arm
  - Chassis
  - Wii remote

## Original Scope

- Our original scope was to create a fully automated robot which could retrieve objects on a workstation.
- Our finished prototype for CI 103 is a user-controlled robot to retrieve objects.
- In the end, we ended up achieving all of the updated goals we set forth for the end of the CI cycle.

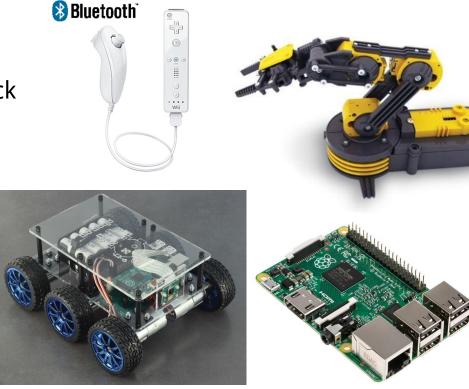


## The Components

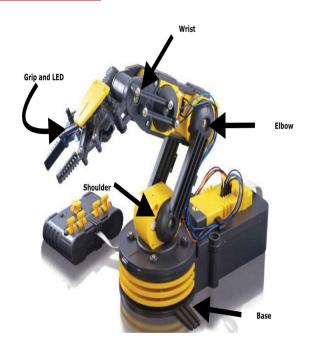
Raspberry Pi (with a Python compiler, Python pip, Pyusb and Cwiid

installed)

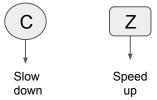
- Nintendo Wii remote and nunchuck
- Bluetooth module
- OWI-535 Robotic Arm Edge
- USB extension kit
- DiddyBorg Chassis

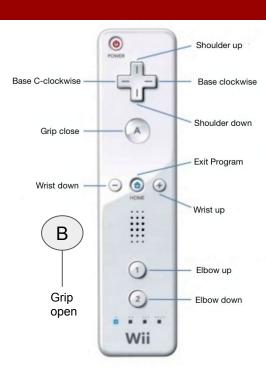


## Layout









## The Journey

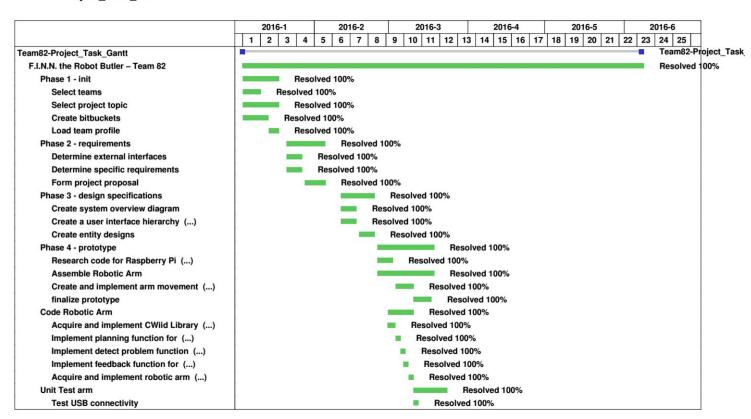
- Our prototype for CI 102 was focussed on getting the arm to work.
- Our prototype for CI 103 was making sure USPS delivered our chassis (and finishing the project on time).

## Key challenges faced

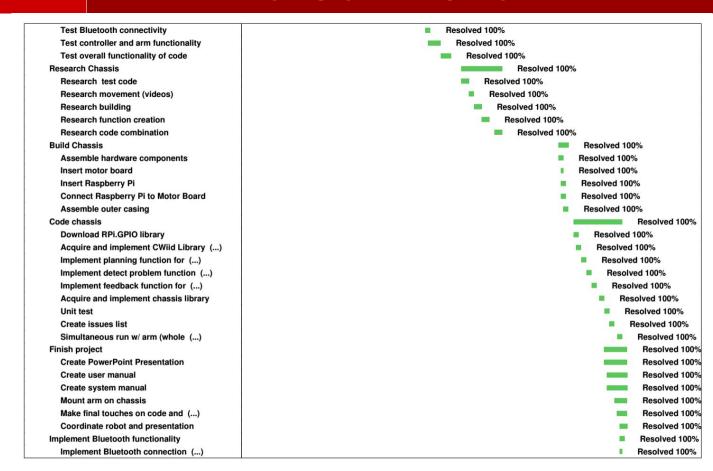
- Receiving the chassis in Week 8
- Configuring the wheels on the chassis
- Mounting the arm on the chassis
- Calibrating the remote to work with the arm and the chassis.
- Making turns smoother.
- Holding objects with the arm while moving the chassis.

#### The Gantt Chart

#### Team82-Project\_Task\_Gantt



#### The Gantt Chart



### The Gantt Chart



### Timeline

#### End of CI 102

Finished prototype : Arm

#### Week 8

Whole lotta documentation
// Finally received the chassis

#### Week 5

Extensively tested and debugged the arm

// Waited for the chassis

#### Week 9 - Week 10

- Built and coded the chassis
- Combined code for arm and chassis
- Assembled F.I.N.N.

## Beyond CI 103

- Future Endeavors which we couldn't fit in the scope of CI 103
  - Camera
  - Autonomous Movement
  - Sounds
  - Pretty lights



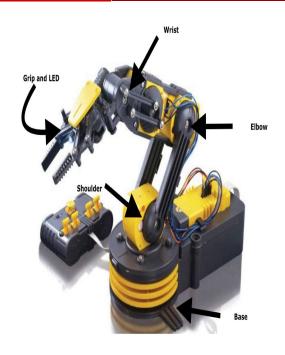




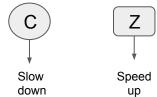
### **Lessons Learned**

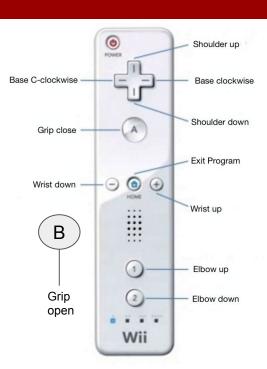
- Combining code seems simple but can be a lot more work than you think.
- Don't be too ambitious with the scope.
- You should never trust USPS.

### Demo

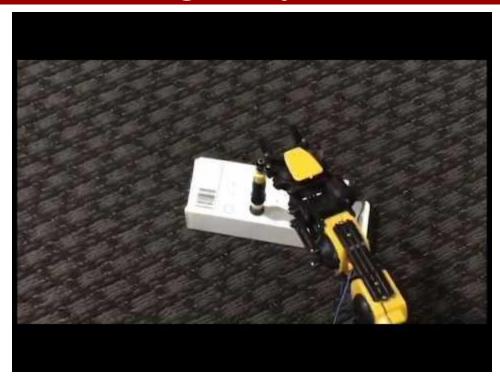








# Emergency Demo



### **Works Cited**

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