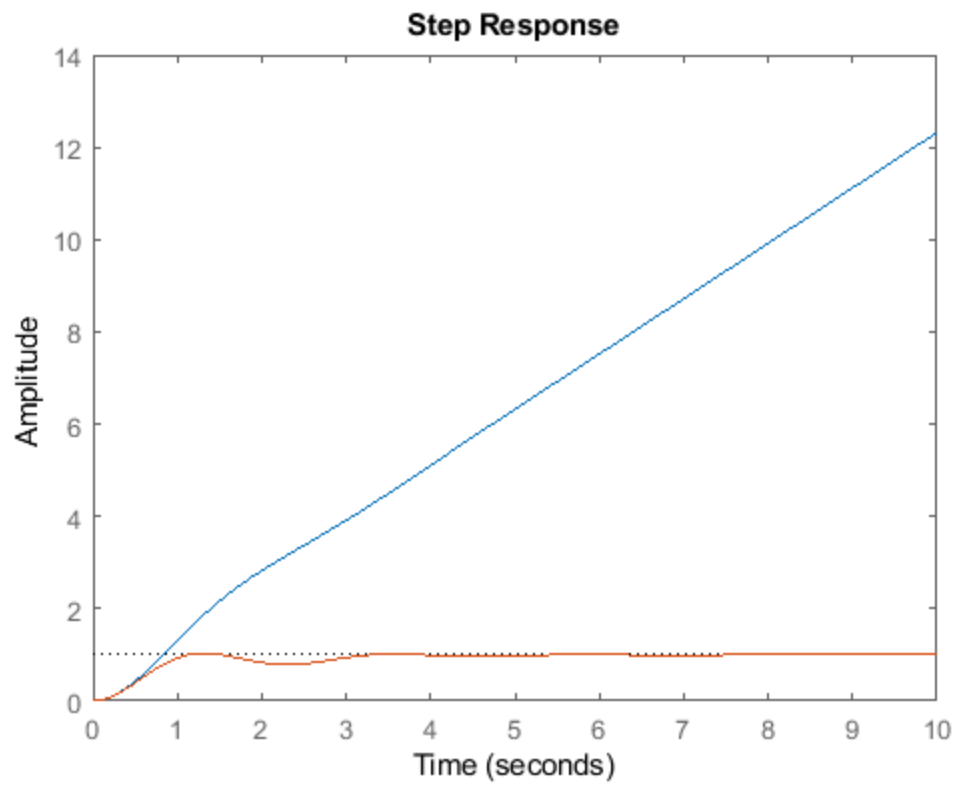

```
Kp=2;  
Ki=3;  
P=tf(2,[1 2 5]);  
C=tf([Kp Ki],[1 0]);  
  
CP=series(C,P);  
H_cl=feedback(CP,1);  
  
time = 0:0.1:10;  
  
step(CP,H_cl,time)
```



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