```
%Generic ODE45 code
%create time domain
clc
clear
tspan=[0 20];
% For loop for repeated tests
for ii = 1:100
   %Random system constants
   a=rand+0.5;
   c=rand+0.5;
   m=rand+0.5;
   g=9.81;
   k=rand+0.5;
   alpha=rand+0.5;
   beta=rand+0.5;
   phi=rand+0.5;
   mu=0;
   xd=rand;
   %Initial conditions
   x0=[rand+0.2,rand+0.2,rand+0.2];
   %Use an ode solver ie ode45
   [t,y]=ode45(@(t,x)odefcn(t,x,a,c,m,g,k,alpha,beta,phi,xd),tspan,x0);
   %Plot results
   figure(1)
   plot(t,y(:,1))
   xlabel('t');
   ylabel('x1_dot');
   hold on
   figure(2)
   plot(t,y(:,2))
   xlabel('t');
   ylabel('x2_dot');
   hold on
   figure(3)
   plot(t,y(:,3))
   xlabel('t');
   ylabel('x3_dot');
   hold on
   figure(4)
   plot(t,y(:,4))
   xlabel('t');
   ylabel('x4_dot');
   hold on
end
function dxdt=odefcn(t,x,a,c,m,g,k,alpha,beta,phi,xd)
dxdt=zeros(4,1);
%ODES
%Ud_dot=0;
% Ud=0
Ud\_dot=dxdt(2)*(-c+m*alpha+beta)+dxdt(1)*(c*alpha-k-m*alpha^2+1)+dxdt(3);
mu=Ud_dot+a+Ud;
dxdt(1)=x(2)-alpha*x(1);
```

```
dxdt(2)=(-c*dxdt(1)+k*xd-k*x(1)-(m*g*sin(phi))+x(3)-Ud)/m+alpha*dxdt(1);
dxdt(3)=Ud_dot+a*Ud-a*x(3)-mu;
dxdt(4)=mu;
end
```







