Get Start with CCS and eZdsp USB Stick

EXPERIMENT 1.1

Propose of the experiment

- Use CCS to create a workspace
- Create a new project
- Write a simple C program using CCS tools
- Setup CCS build environment
- Connect eZdsp USB Stick Hardware to CCS
- Set target configuration
- Build and run a C program using CCS

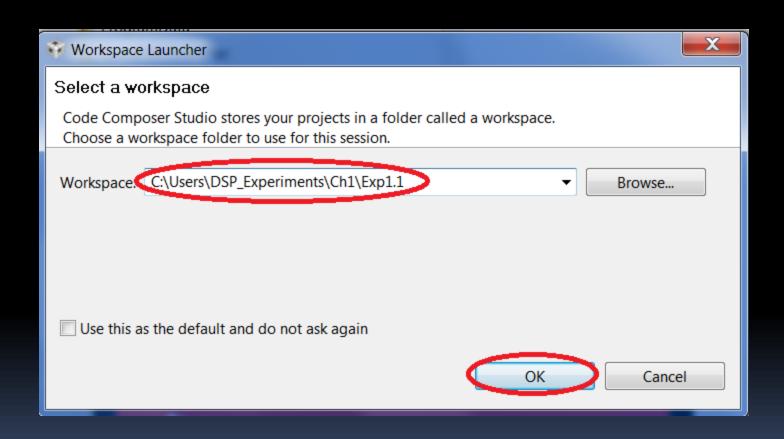
Start CCS

(Example: Code Composer Studio Version 5)



Create workspace

(Example: C:\User\DSP_Experiment\Ch1\Exp1.1)

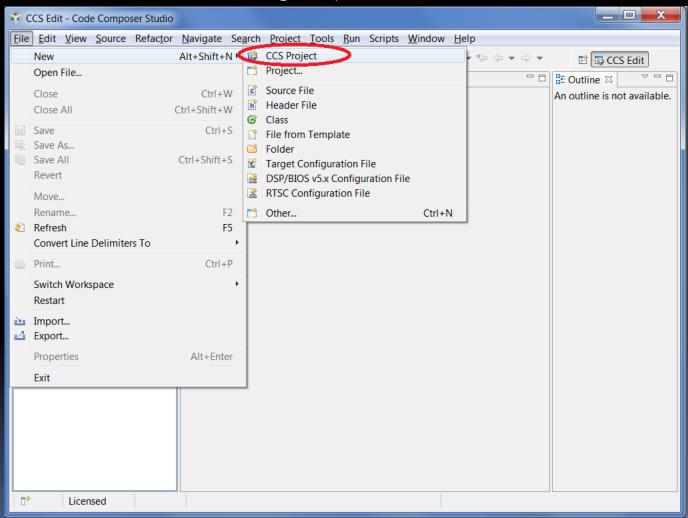


Go to CCS



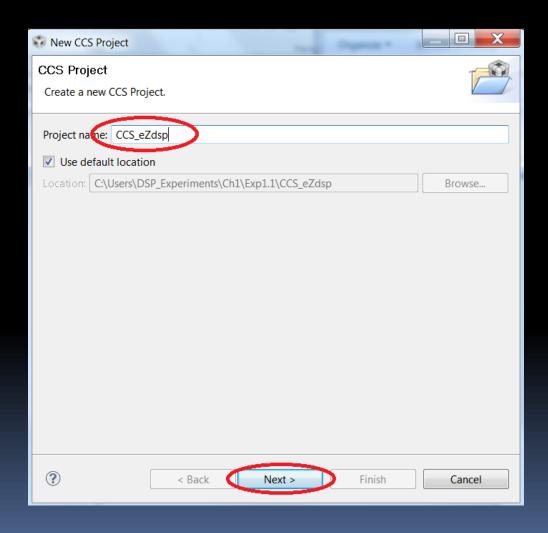
Create a new project

(File -> New -> CCS Project)

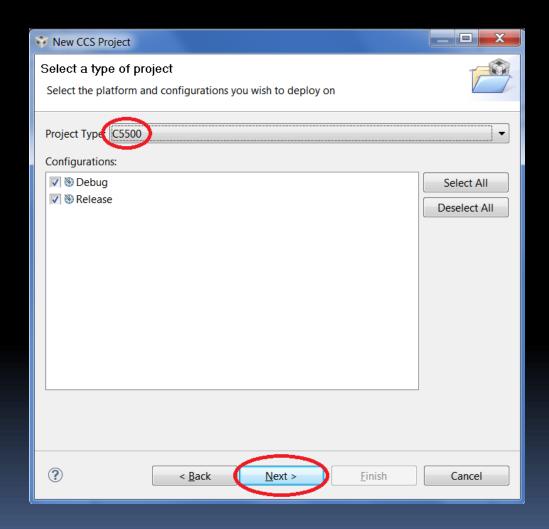


Create a new project name

(Example: CCS_eZdsp)

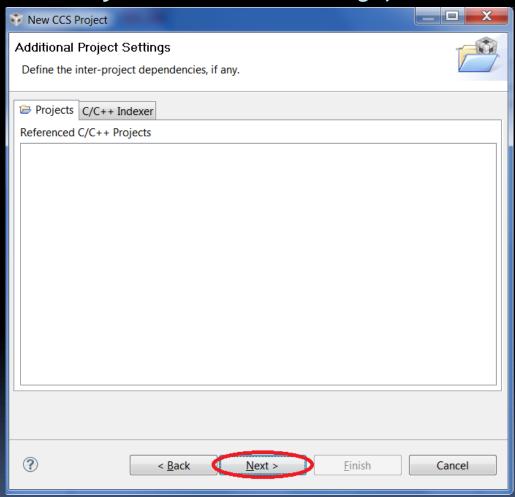


Select C5500 as the new project



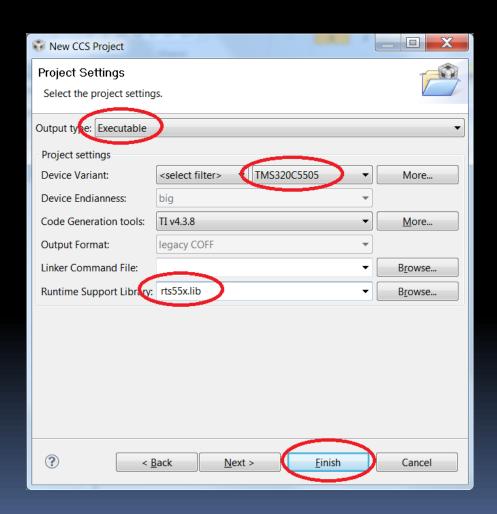
Go to next

(We do not need any additional settings)

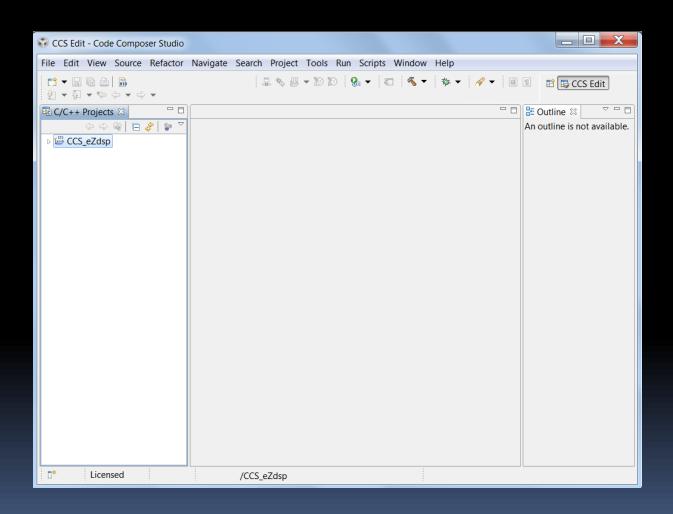


Set up the project

(Executable output, Device C5505, Library rts55h.lib)

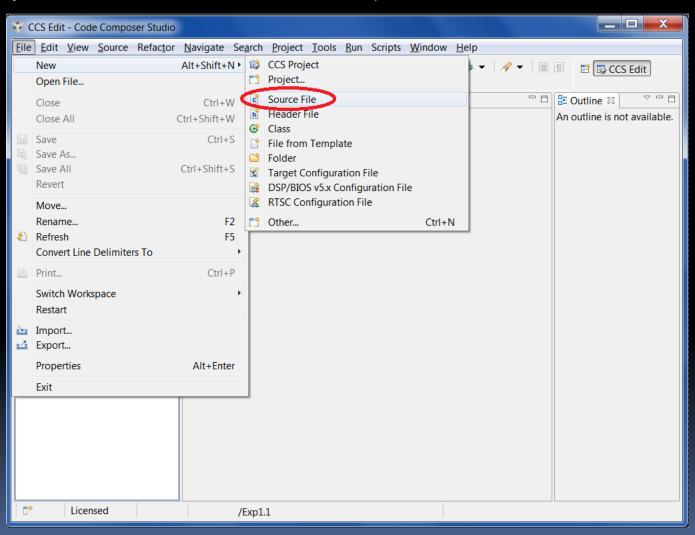


Project: CCS_eZdsp

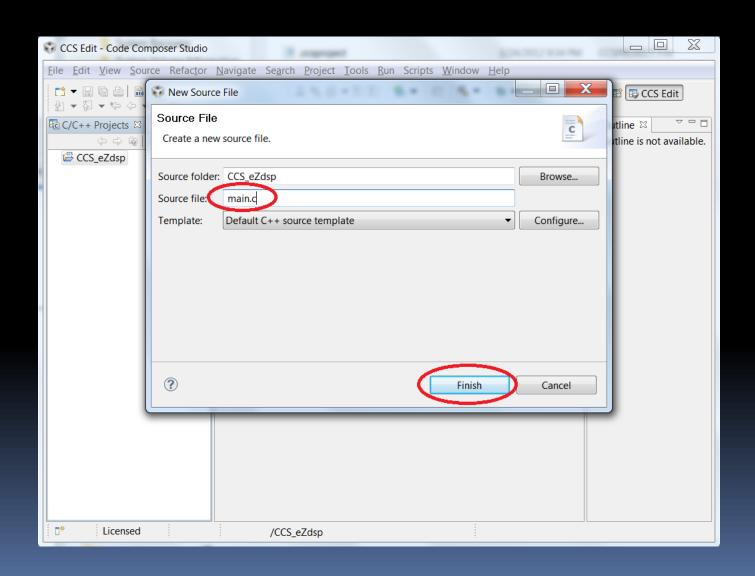


Add Source File

(Example: File->New->Source File)



Create C file main.c (1)

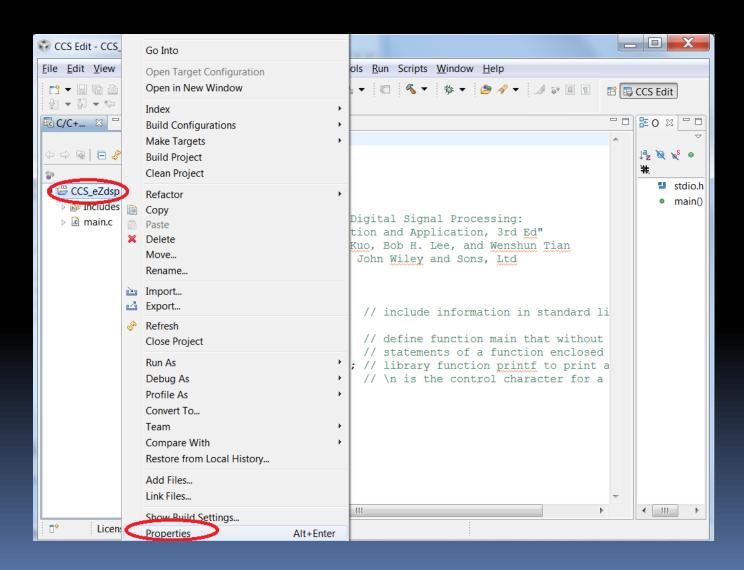


Create C file main.c (2)

```
CCS Edit - CCS_eZdsp/main.c - Code Composer Studio
File Edit View Source Refactor Navigate Search Project Tools Run Scripts Window Help
 E CCS Edit
 9 ▼ 2 ▼ 4 ♥ 4 ▼ 3 ▼
© C/C+... 🛛 🗀 🗀 main.c 🖾
                                                                              1/*
               2 * main.c
 ↓ª₂ 📎 🤘 🌼
                    Created on: MAR 10, 2012
                                                                                    stdio.h
  CCS_eZdsp
                        Author: BLEE
                                                                                    main()
                6 *
    Includes
               7 * For the book "Real Time Digital Signal Processing:
    main.c
                                Implementation and Application, 3rd Ed"
               9 *
                                By Sen M. Kuo, Bob H. Lee, and Wenshun Tian
              10 *
                                Publisher: John Wiley and Sons, Ltd
              11 */
              12
              13
              14 #include <stdio.h>
                                          // include information in standard li
                                           // define function main that without
              16 void main()
                                            // statements of a function enclosed
              17 {
              18
                    printf("Hello World!\n"); // library function printf to print a
              19}
                                           // \n is the control character for a
               21
                                                                                  ∢ | III |
        Licensed
```

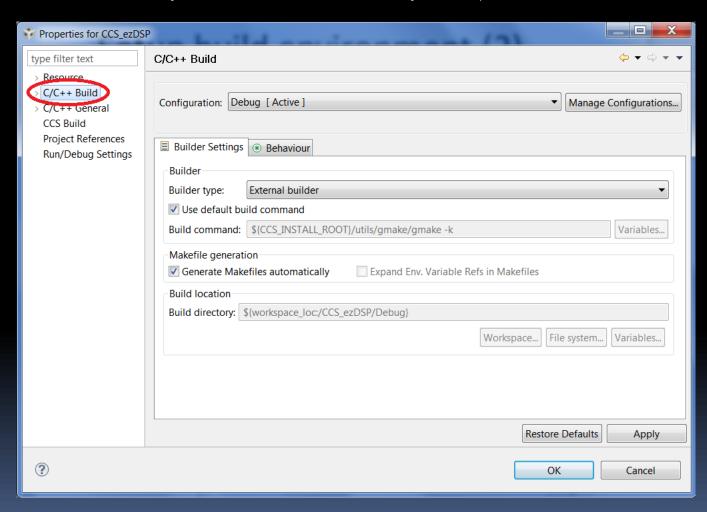
Setup build environment (1)

(Right click on CCS_eZdsp then select Property)



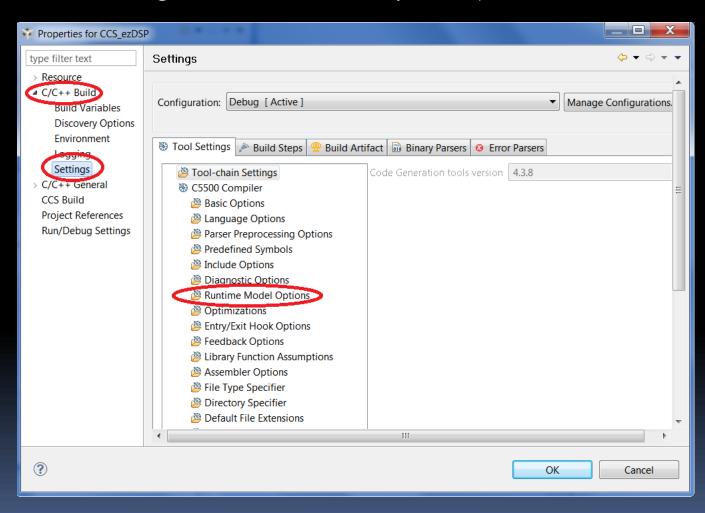
Setup build environment (2)

(Select and expand C/C++ Build option)



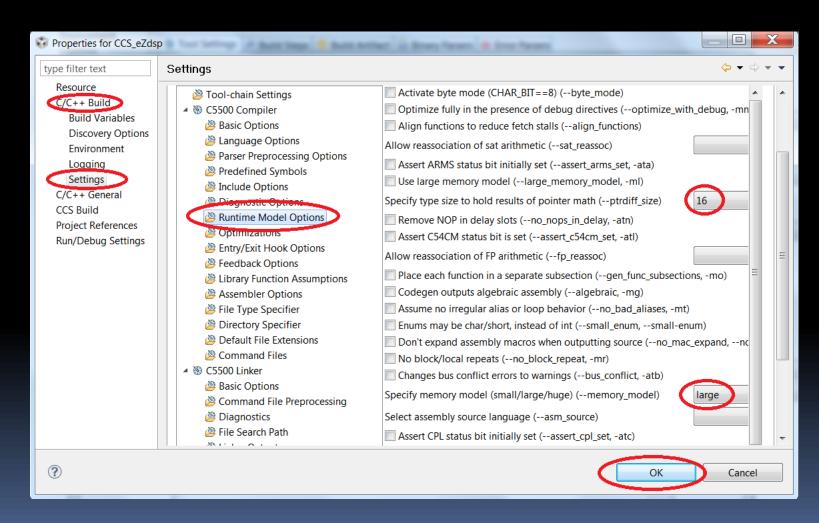
Setup build environment (3)

(Select Settings, then Runtime Options)



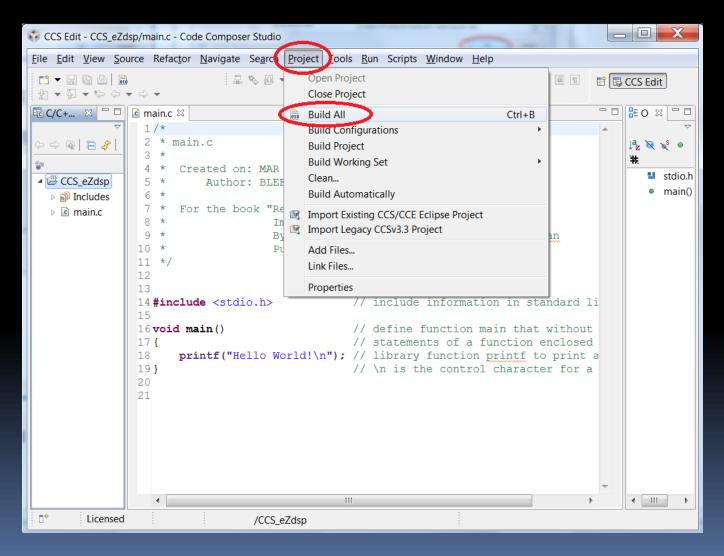
Setup build environment (4)

(Set type size to 32 and memory model to huge)



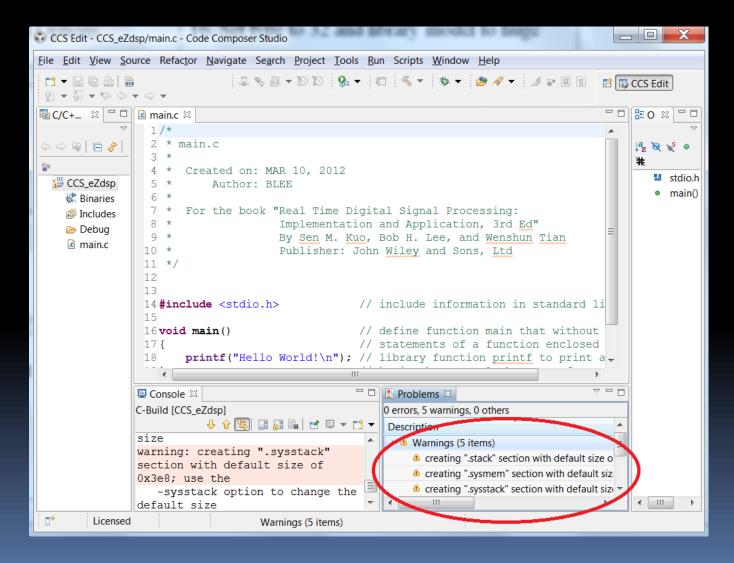
Build the project

(Project->Build All)



Build result

(No errors, but there are 5 warnings)



Correct warnings

- The warnings are due to undefined symbols for the memory sections during the program link time.
- The linker uses default settings for these missing sections.
- To correct this, copy the file, lnk.cmd, from CCS C55x folder to the project folder.
- The Project folder is:
 C:\Users\DSP_Experiments\Ch1\Exp1.1\CCS_eZdsp.
- CCS C55x folder could be at (depending your CCS version):
 - $C:\ti\ccsv5\ccs_base_5.o.3.ooo23\emulation\boards\usbstk55o5.$
- Or copy the lnk.cmd file from the software came with the book.

Create linker command file

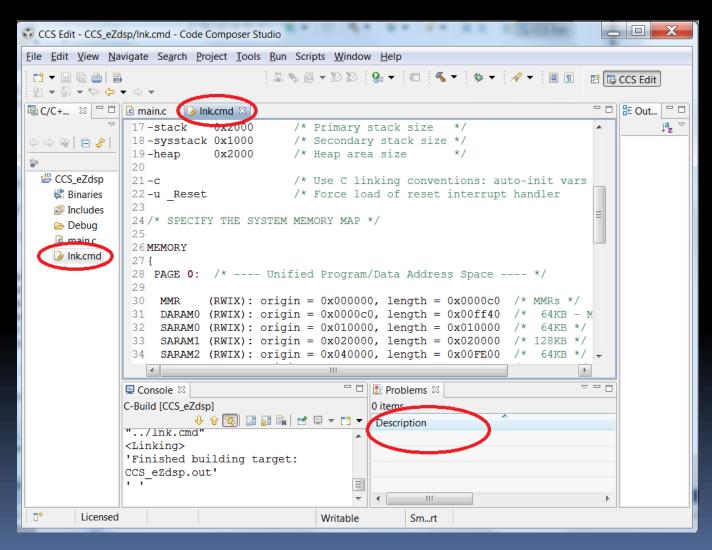
(Using a text editor create lnk.com as below)

```
/* C5505.cmd - COMMAND FILE FOR LINKING C PROGRAMS IN LARGE/HUGE MEMORY
MODEL */
-stack ox2000 /* Primary stack size */
-sysstack ox1000 /* Secondary stack size */
-heap ox2000 /* Heap area size */
         /* Use C linking conventions: auto-init vars at runtime */
-u Reset
            /* Force load of reset interrupt handler
MEMORY
 MMR (RW): origin = oooooooh length = oooocoh /* MMRs */
 DARAM (RW) : origin = ooooocoh length = ooff4oh /* on-chip DARAM */
 SARAM (RW): origin = oo3ooooh length = o1eoooh /* on-chip SARAM */
 SAROM o (RX): origin = ofeogooh length = oo8oooh
                                                  /* on-chip ROM o */
 SAROM_1 (RX) : origin = ofe8oooh length = oo8oooh
                                                  /* on-chip ROM 1 */
 SAROM 2 (RX): origin = offooooh length = oo8oooh
                                                  /* on-chip ROM 2 */
 SAROM 3 (RX): origin = off8000h length = 008000h
                                                  /* on-chip ROM 3 */
 EMIF_CSo (RW): origin = oo5ooooh length = o7Booooh /* mSDR */
 EMIF CS2 (RW): origin = o8oooooh length = o4oooooh /* ASYNC1: NAND */
 EMIF CS3 (RW): origin = oCoooooh length = o2oooooh /* ASYNC2: NAND */
 EMIF CS4 (RW): origin = oEoooooh length = o1oooooh /* ASYNC3: NOR */
 EMIF_CS5 (RW): origin = oFoooooh length = ooEooooh /* ASYNC4: SRAM */
```

```
SECTIONS
 vectors (NOLOAD)
      : > DARAM /* fill = o */
 vector : > DARAM ALIGN = 256
 .stack : > DARAM
 .sysstack : > DARAM
 .sysmem : > DARAM
 .text : > SARAM
 .data : > DARAM
 .cinit : > DARAM
 .const :> DARAM
      : > DARAM
 .usect :> DARAM
 .switch :> DARAM
 .emif_cso :> EMIF_CSo
 .emif cs2 :> EMIF CS2
 .emif_cs3 :> EMIF_CS3
 .emif_cs4 : > EMIF_CS4
 .emif_cs5 : > EMIF_CS5
```

Once lnk.cmd file is copied

(Rebuild the project and there are no warnings)



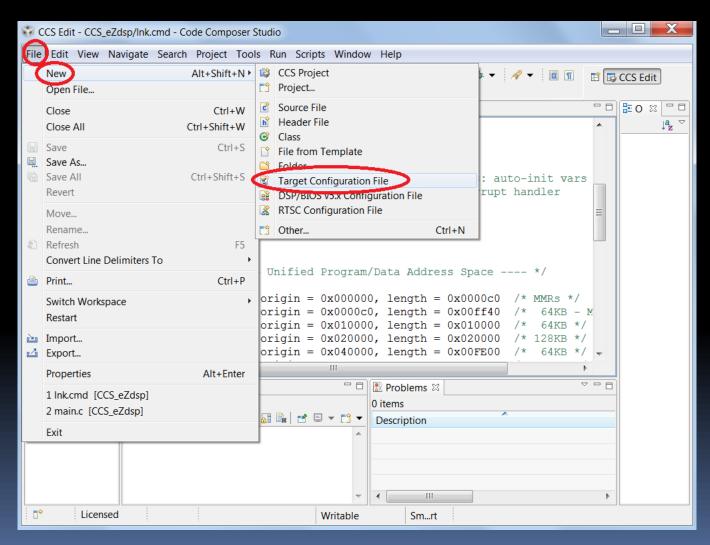
Connect eZdsp to PC

(Refer to eZdsp Start Guide for settings)



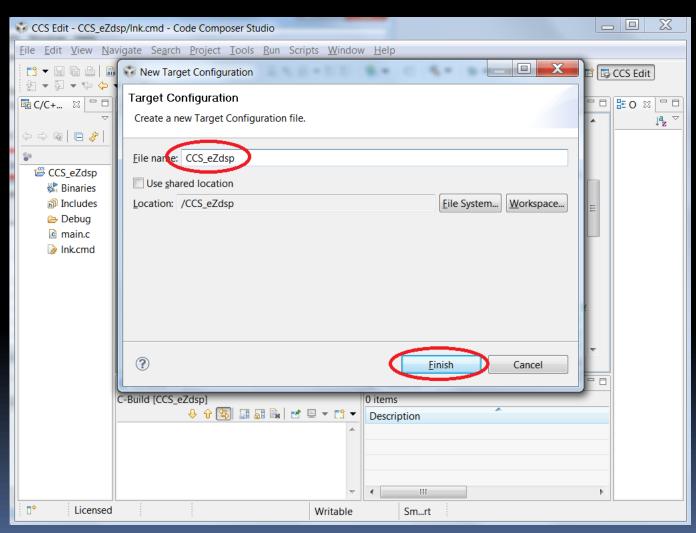
Set target configuration (1)

(Right click on File->New->Target Configuration File)



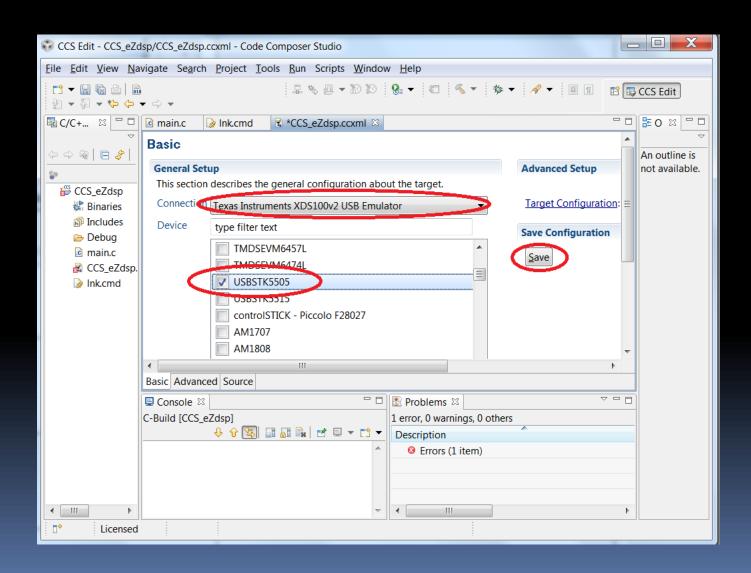
Set target configuration (2)

(Create a target configuration file name)



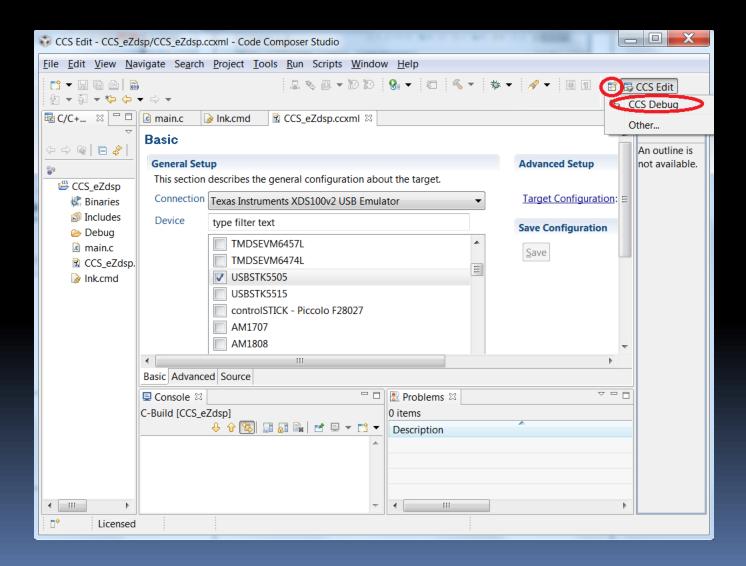
Set target configuration (3)

(Select XDS100v2 USB Emulator, USBSTK5505, & Save)



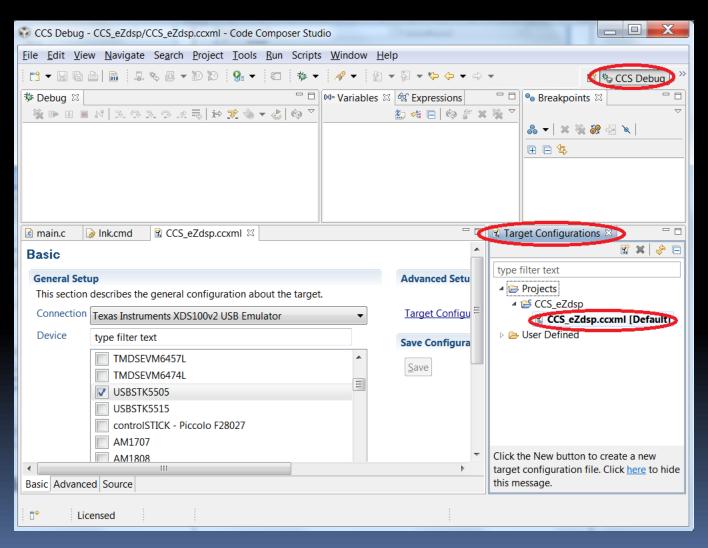
Change edit mode to debug mode

(Change from CCS Edit to CCS Debug Mode)



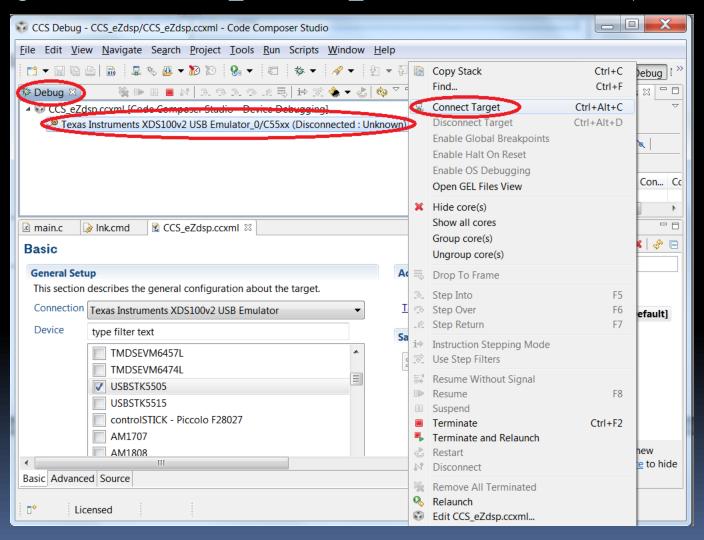
Launch selected configuration

(Target Configuration->Project->right click on ccs_ezdsp.ccxml)



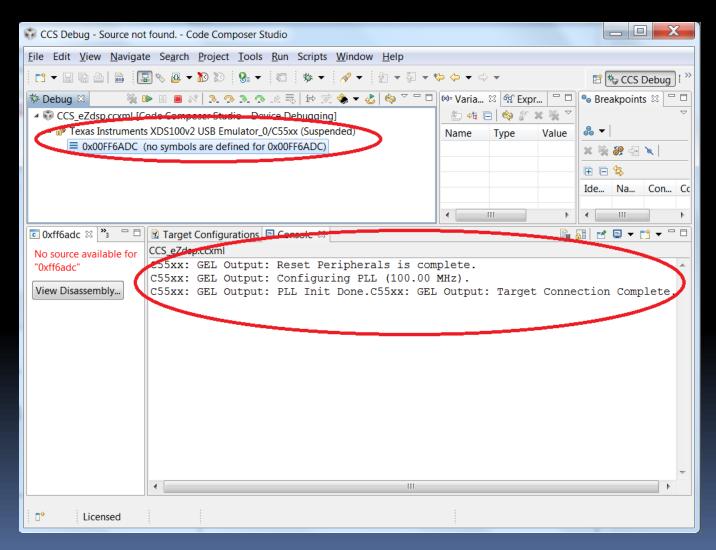
Connect eZdsp

(Right click on USB_Emulator_0, then Connect Tart)



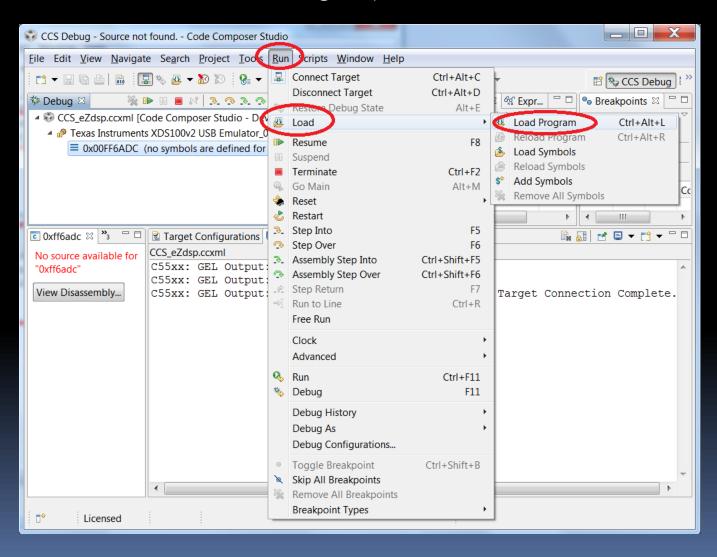
eZdsp connected

(Target reset and configured automatically)



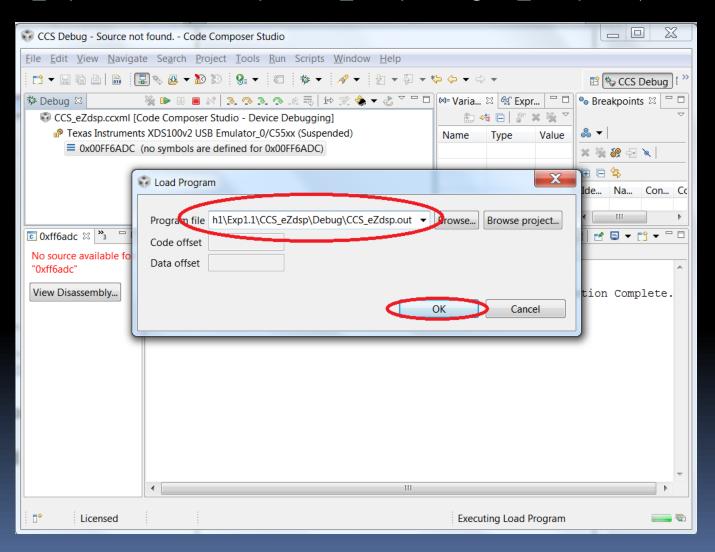
Load program CCS_eZdsp.out (1)

(From Run->Load->Load Program)



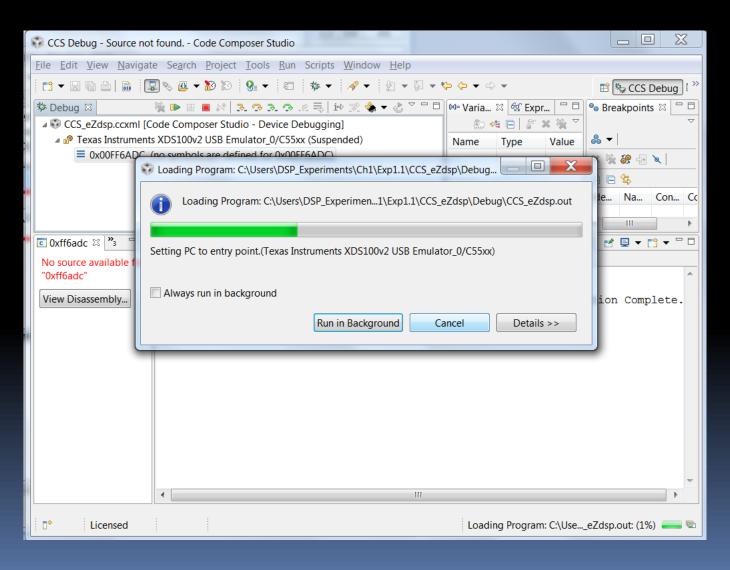
Load program CCS_eZdsp.out (2)

(...\DSP_Experiments\Ch1\Exp1.1\CS_eZdsp\DebugCCS_eZdsp.out)



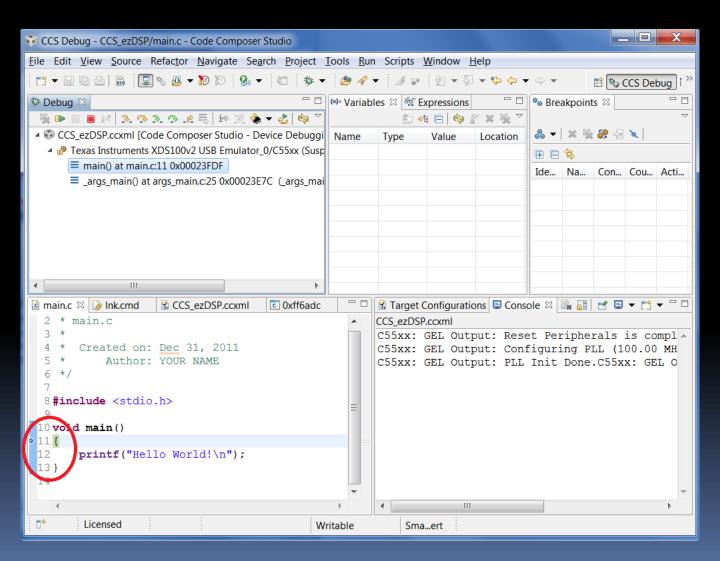
Load program CCS_eZdsp.out (3)

(CCS_eZdsp program is Loading)



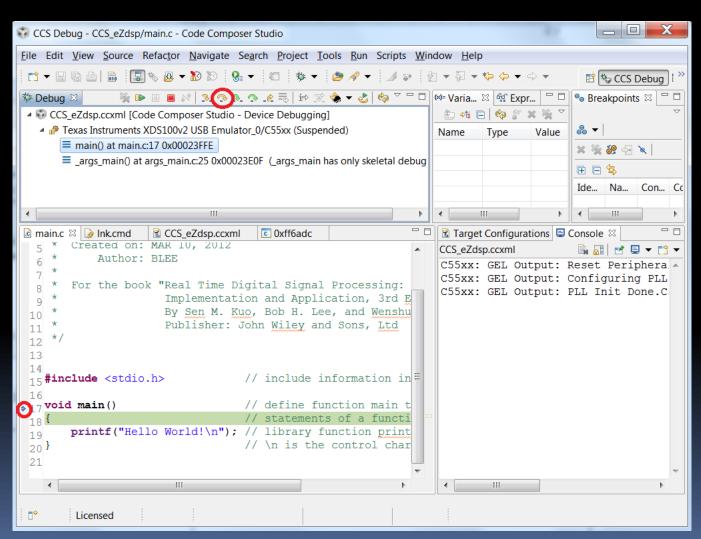
Once the program is loaded

(Program counter is at entry point of function main())



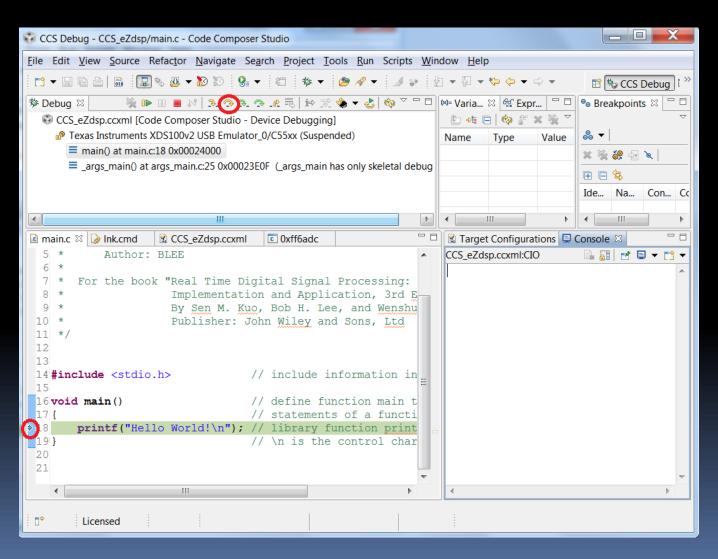
Once the program is loaded

(Program counter is at entry point of function main())



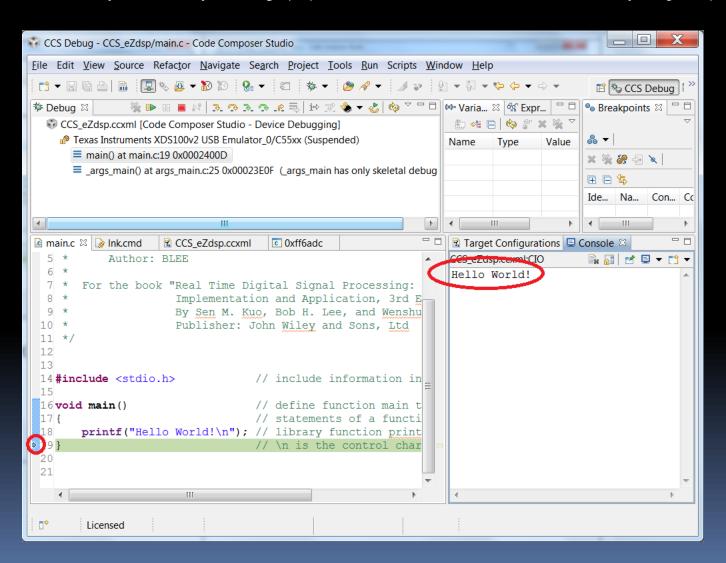
Step Over (F6) the program

(Watch program counter move through the program)



Step Over (F6) the program

(Once PC passed printf(), "Hello World!" is displayed)



New experimental assignments

- Load the CCS_eZdsp.out, Step Over (F6) through the program. Then, use CCS to Reload Program feature to load program again.
 - O1: where does the program counter point at in the *main()* after program has been reloaded?
- Use Resume (F8), instead of Step Over, to run the program again.
 - Q2: what will be showing on the Console display window?
- After running the program, use Restart and Resume (F8), run the program again.
 - Q3: what will be showing on the Console display window?
- Exit CCS, then restart CCS and create your own program that will display the message "C55 DSP eZdsp Test" on the console.

Programming quick review

- C program is one the most important programming languages for DSP applications.
- C program is written in a text file with file extension ".c", such as main.c in this experiment. The files with the ".c" extension are called C source files.
- C program start with a function called main, as in this experiment, main().
- Each function has a prototype, the example main() function used in this experiment declares the prototype of the function main() as void.
- The main() usually calls other functions to perform tasks. Some of the functions are from the libraries provided by the C compiler tools include in CCS, and others are written by users like you.
- The printf() is a function provided by the library, stdio.lib. The function printf is an input/output (CIO) function. It prints messages to the C output device.
- The function is defined by a name with a pair of (). Inside (), it may have one or more arguments, or no argument at all. For example, main() does not have an argument while printf() has a string argument "Hello World!" in it. When the function printf() is called, it prints the string "Hello World!" on the screen.
- The experiment C file, main.c, has a line "#include <stdio.h>". The file stdio.h contains the function definition of the printf function. It tells C compiler to include the information from C I/O libraries. The files with ".h" extensions are called header files, which are also source files like C files. The standard include files are placed inside < >, as <stdio.h> with #include to indicate to the complier this is an include file.
- The C program uses the "/*" and "*/" for comments. Anything inside the /* and */ will be ignored by compiler. It is a good programming practice to use comments to document the data flow and logic of the program. Another way for adding comments is to use double slash //. Anything after the // on that same line will be ignored by C compiler.

References

- http://processors.wiki.ti.com/index.php/Cate gory:CCS
- http://processors.wiki.ti.com/index.php/Cate
 gory:Code_Composer_Studio_v5
- C Programming Language (2nd Edition), by Brian Kernighan and Dennis Ritchie, Prentice Hall