



Data Structures

Lecture 7: Graph

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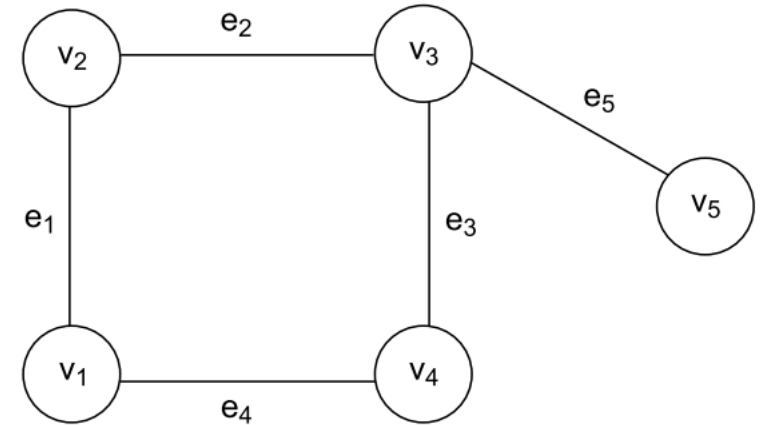
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Contents

- Concept of Graphs
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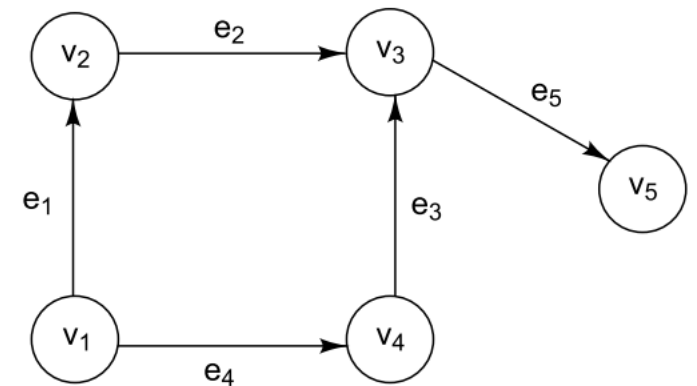
Graph definition

- A Graph is a non-linear data structure that consists of vertices (nodes) and edges.
- A graph **G** consists of the following elements:
 - A set **V** of vertices or nodes, where **V**={v1, v2, v3,.....vn}
 - A set **E** of edges also called arcs where, **E**={e1, e2, e3,, en}
 - Hence, **G**=(**V**,**E**)
- *If $e=(u,v)$ and $e=(v, u)$ means same then the graph is **undirected**.*

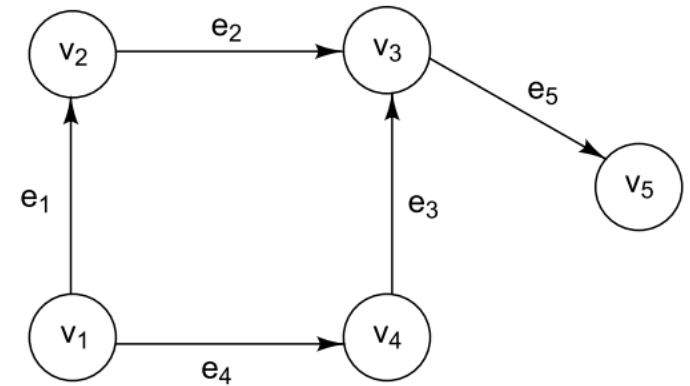
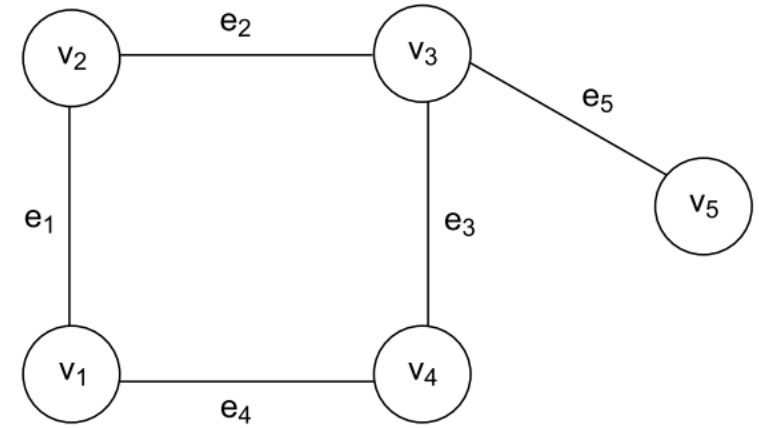


Directed Graph

- If we replace each edge of the Graph **G** with **arrows**, then it will become a **directed graph or digraph**.
- In this graph, the set of vertices and edges are:
 - $V(G) = \{v1, v2, v3, v4, v5\}$
 - $V(E) = \{(v1, v2), (v2, v3), (v1, v4), (v4, v3), (v3, v5)\}$



Key Terms	Description
Adjacent node	If $e(u, v)$ represents an edge between u and v vertices then both u and v are called adjacent to each other. That means, u is adjacent to v and v is adjacent to u .
Predecessor node	If $e(u, v)$ represents a directed edge from u to v then u is a predecessor node of v .
Successor node	If $e(u, v)$ represents a directed edge from u to v then v is a successor node of u .
Degree	Degree of a vertex is the number of edges connected to a vertex. For example, in the graph shown in Fig. 9.1, the degree of vertex v_3 is 3.
Indegree	In a directed graph, indegree of a vertex is the number of edges ending at the vertex.
Outdegree	In a directed graph, outdegree of a vertex is the number of edges beginning at the vertex.
Path	A path is a sequence of vertices each adjacent to the next. For example, in the graph shown in Fig. 9.2, the path between the vertices v_1 and v_5 is $v_1-v_2-v_3-v_5$.
Cycle	It is a path that starts and ends at the same vertex.
Loop	It is an edge whose endpoints are same that is, $e = (u, u)$.
Weight	It is a non-negative number assigned to an edge. It is also called length.
Order	Order of a graph is the number of the vertices contained in the graph.
Labeled Graph	It is a graph that has labeled edges.
Weighted Graph	It is a graph that has weights assigned to each of its edges.
Connected Graph	It is an undirected graph in which there is a path between each pair of nodes.
Strongly Connected Graph	It is a directed graph in which there is a route between each pair of nodes.
Complete Graph	It is an undirected graph in which there is a direct edge between each pair of nodes.
Tree	It is a connected graph with no cycles.



Types of Graphs

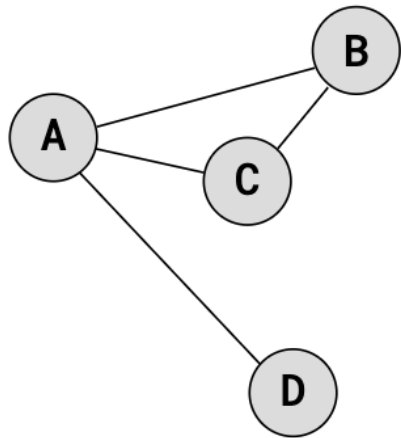
- Based on Edge Direction
 - Undirected Graph
 - Directed Graph
- Based on Weight of Edges
 - Weighted Graph
 - Unweighted Graph

Graph Representation

- Adjacency Matrix (2D Array)
- Adjacency List (Linked List)

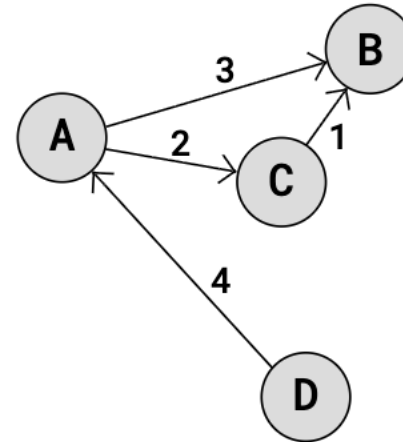
Adjacency Matrix

- The Adjacency Matrix is a **2D array (matrix)** where each cell on index **(i,j)** stores information about the edge from vertex **i** to vertex **j**.
- 2D array $\rightarrow A[V][V]$
- $A[i][j] = 1$, if edge exists between vertex **i** and **j**, else **0**.



	A	B	C	D
A	0	1	1	1
B	1	0	1	0
C	1	1	0	0
D	1	0	0	0

*An undirected Graph
and the adjacency matrix*

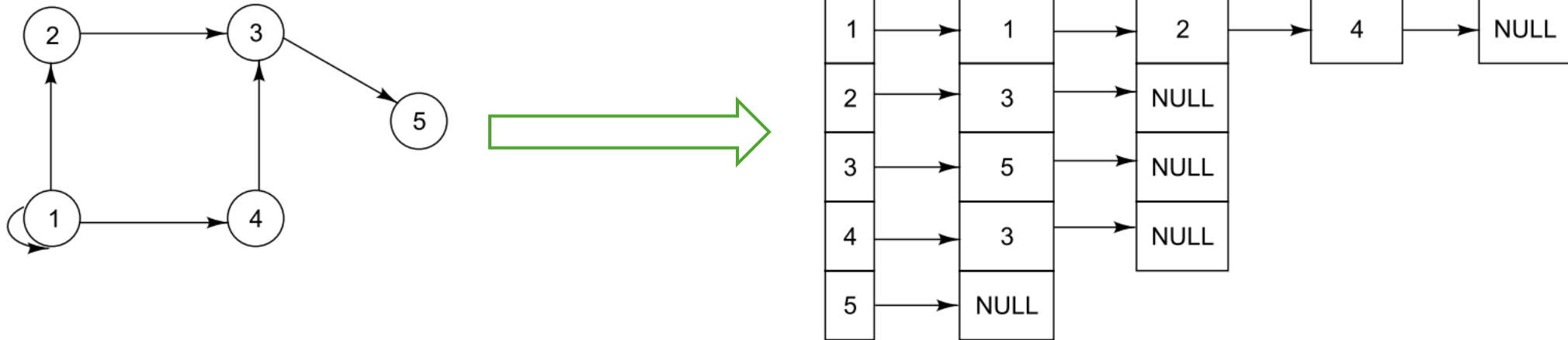


	A	B	C	D
A	0	3	2	0
B	0	0	0	0
C	0	1	0	0
D	4	0	0	0

*A directed and weighted Graph,
and its adjacency matrix.*

Adjacency List

- Array of ***linked lists (or dynamic arrays)***
- Each vertex stores a list of its adjacent vertices.
- Suitable for ***sparse*** graphs.



Graph Traversal Techniques

- **Depth First Search (DFS):**

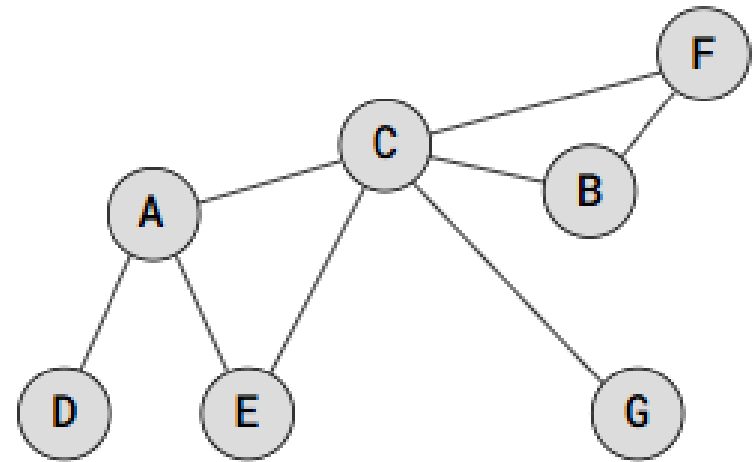
- Explores as far as possible along each branch before backtracking.
- Uses a stack (or recursion).

- **Breadth First Search (BFS)**

- Explores all neighbors of a vertex before moving to the next level.
- Uses a queue.

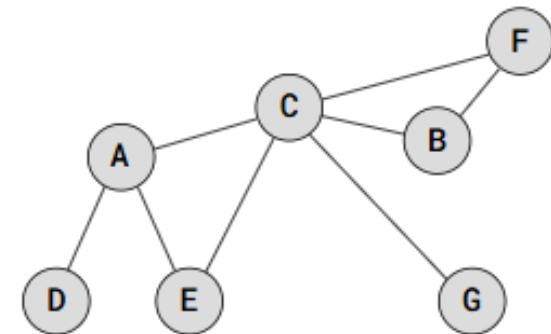
Depth First Search (DFS)

- Start DFS traversal on a vertex.
- Uses a stack (or recursion).
- Do a recursive DFS traversal on each of the adjacent vertices as long as they are not already visited.
- Path: **D,A,C,B,F,E,G**



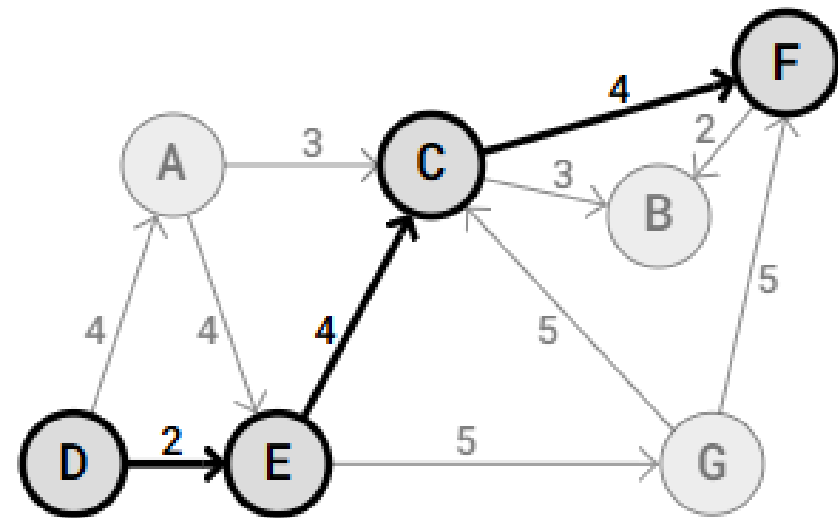
Breath First Search (BFS):

- Put the starting vertex into the **queue**.
- For each vertex taken from the queue, visit the vertex, then put all unvisited adjacent vertices into the queue.
- Continue as long as there are vertices in the queue.
- Path: **D,A,C,E,B,F,G**



Shortest Path

- To solve the shortest path problem means to find the **shortest possible route or path** between two vertices (or nodes) in a Graph.
- In the shortest path problem, a Graph can represent anything from a **road network** to a communication network, where the vertices can be intersections, cities, or routers, and the edges can be **roads, flight paths, or data links**.
- **Solutions (SPP):** **Dijkstra's algorithm** and the **Bellman-Ford algorithm** find the shortest path from one start vertex, to all other vertices.



Graph Algorithms

Algorithm	Purpose	Concept
Dijkstra's Algorithm	Shortest path (single source)	Greedy algorithm
Floyd-Warshall	All-pairs shortest paths	Dynamic programming
Prim's Algorithm	Minimum Spanning Tree	Greedy (build tree step-by-step)
Kruskal's Algorithm	Minimum Spanning Tree	Greedy (sort edges, union-find)
Topological Sort	Ordering in a DAG	DFS-based sorting
Bellman-Ford	Shortest path (with negative weights)	Dynamic programming

Real life applications of Graphs

- ***Social Networks***: Each person is a vertex, and relationships (like friendships) are the edges. Algorithms can suggest potential friends.
- ***Maps and Navigation***: Locations, like a town or bus stops, are stored as vertices, and roads are stored as edges. Algorithms can find the shortest route between two locations when stored as a Graph.
- ***Internet***: Can be represented as a Graph, with web pages as vertices and hyperlinks as edges.
- ***Biology***: Graphs can model systems like neural networks or the spread of diseases.

References

- **Chapter 9:**
 - **Data Structures using C** by E. Balagurusamy

Thank You