# MSiA 400 Lab 3 Monte Carlo Methods & MCMC

Huiyu Wu

10/17/2022



#### Monte Carlo Methods

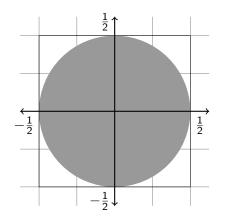
- Rely on random sampling to obtain numerical results
- Use randomness to solve problems that may be deterministic
- Common applications
  - Optimization
  - Numerical Integration
  - Generating draws from probability distributions

## Monte Carlo Integration

- Goal: compute  $I = \int_{a}^{b} h(x) dx$
- Monte Carlo Method
  - Let h(x) = g(x)p(x), where p(x) is a pdf defined on [a, b]
  - $I = \int_{a}^{b} h(x)dx = \int_{a}^{b} g(x)p(x)dx = E_{p}[g(x)]$   $x_{1}, \dots, x_{n} \sim p(x)$  iid

  - $I = E_p[g(x)] \approx \frac{1}{n} \sum_{i=1}^n g(x_i)$

## Monte Carlo Integration Estimating Pi



- Circle inscribed in unit square
- Area of circle  $=\frac{\pi}{4}$
- Area of square = 1
- $X = (X_1, X_2)$ , drawn iid from unif  $\left(-\frac{1}{2}, \frac{1}{2}\right)$
- $P(X_1^2 + X_2^2 \le \frac{1}{4}) = \frac{\pi}{4}$
- $\pi \approx \frac{4}{n} \sum_{i=1}^{n} \mathbb{1} \left( x_{1i}^2 + x_{2i}^2 \le \frac{1}{4} \right)$

## Monte Carlo Integration Estimating Pi in R

```
set.seed(400) # Seed RNG
n = 10000
x1 = runif(n, -0.5, 0.5)
x2 = runif(n, -0.5, 0.5)
z = x1^2 + x2^2
Pi = 4*sum(z <= 0.25)/n
Ρi
## [1] 3.1412
рi
## [1] 3.141593
```

## Markov Inequality

- Statement:  $P(Y \ge a) \le \frac{E(Y)}{a}$
- Conditions: Y is non-negative and a > 0.
- What if:  $Y = (X \mu)^2$  and  $a = \delta^{-1}\sigma^2$

#### **Error Estimation**

- Chebyshev Inequality:  $P\left((X-\mu)^2 \geq \frac{\sigma^2}{\delta}\right) \leq \delta$
- This implies:  $P\left(\left(\text{error}\right)^2 \ge \frac{\text{var}[p(x)]}{n\delta}\right) \le \delta$
- Number of samples needed to n to meet tolerance with  $(1 \delta)$  confidence:  $n \ge \frac{\text{var}[p(x)]}{(\text{tolerance})^2 \delta}$
- How many samples do we need to 99% confident that we can compute pi to 2 decimal places? Note:  $var[p(x)] = \frac{1}{12^2}$

$$n \ge \frac{100 * 100^2}{144} \approx 6944$$

## Markov Chain Monte Carlo (MCMC)

- What if  $p(\cdot)$  is difficult to sample from?
- Idea: construct a Markov chain, where the equilibrium distribution is the desired distribution  $p(\cdot)$ .
- Detailed balance:  $\pi_i p_{ij} = \pi_j p_{ji}$
- Bayes' Theorem:  $p(x|y) = \frac{p(y|x)p(x)}{\int p(y|x)p(x)dx} \propto p(y|x)p(x)$

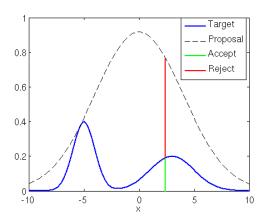
## Rejection Method

### **Algorithm 1:** Rejection Methods

- 1 Choose  $q(\cdot)$ , approximation of  $p(\cdot)$
- 2 Find M st  $p(x) \leq Mq(x)$ ,  $\forall x$
- 3 Draw y from  $q(\cdot)$
- 4 Draw  $u \sim \text{unif}(0,1)$
- **5** Compute acceptance ratio  $\alpha = \frac{p(x)}{Mq(x)}$
- 6 if  $u \leq \alpha$  then
- 7 Accept x = y
- 8 else
- 9 Reject: return to line 3, and try again

MSiA 400 Lab 3

## Intuition



## Metropolis Algorithm

### **Algorithm 2:** Metropolis Algorithm

```
Choose x_0
2 Choose q(x|y) symmetric (i.e., q(x|y) = q(y|x))
3 Choose f(x) \propto p(x)
4 for t = 0, 1, \cdots do
       Draw x' from g(\cdot|x_t)
 5
       Compute acceptance ratio \alpha = \frac{f(x')}{f(x)}
6
       Draw u \sim \text{unif}(0, 1)
 8
       if u < \alpha then
            Accept x_{t+1} = x'
 9
       else
10
11
            Reject, set x_{t+1} = x_t
```

## Metropolis-Hastings Algorithm

### Algorithm 3: Metropolis-Hastings Algorithm

```
Choose x_0
 2 Choose q(x|y) (general)
 3 Choose f(x) \propto p(x)
 4 for t = 0, 1, \cdots do
        Draw x' from g(\cdot|x_t)
 5
        Compute acceptance ratio \alpha = \frac{f(x')q(x_t|x')}{f(x_t)g(x'|x_t)}
 6
        Draw u \sim \text{unif}(0,1)
 8
        if u < \alpha then
             Accept x_{t+1} = x'
 9
        else
10
11
             Reject, set x_{t+1} = x_t
```

### **MCMC**

- Metropolis & Metropolis-Hastings algorithms generate sample points  $\{x_0, \dots, x_t, \dots\}$
- These form a Markov chain as the probability  $\alpha$  of transitioning from  $x_{t-1}$  to  $x_t$  does not depent on  $\{x_0, \dots, x_{t-2}\}$
- Stationary distribution of Markov chain equals target distribution p(·)

#### **MCMC**

- Typical implementation
  - Burn-in period k samples for algorithm to approach desired distribution
  - Keep every m samples thinning method to reduce auto-correlation
- Diagnostics
  - Plot of sample points: poor mixing and/or patterns vs. well mixing
  - Serial autocorrelations, time lag
  - Formal tests: Geweke test, Raftery-Lewis test

#### **MCMC**

- Choice of  $q(\cdot|\cdot)$ 
  - Random-walk chain: new value  $x' = x_t + z$ ,

$$q(x'|x_t) = r(x'-x_t) = r(z)$$

If r(z) = r(-z), then  $q(\cdot|\cdot)$  is symmetric.(ex: normal)

 Independent chain: new value x' drawn independent from previous point

$$q(x'|x_t) = s(x')$$
 for any distribution  $s(x')$ 

Generally not symmetric

## Gibbs Sampling

• Simpler to sample from conditional than from joint.

### Algorithm 4: Gibbs Sampler

1 Choose  $\mathbf{x}^{(0)} = \left(x_1^{(0)}, \cdots, x_n^{(0)}\right)$ 2 **for**  $t = 0, 1, \cdots$  **do** 3 **for**  $j = 0, \cdots, n$  **do** 4 Draw  $x_j^{(t+1)}$  from  $p\left(\cdot | x_1^{(t+1)}, \cdots, x_{j-1}^{(t+1)}, x_{j+1}^{(t)}, \cdots, x_n^{(t)}\right)$ 

## MCMC Example

- Poisson regression
- No closed-form solution for optimal weights  $\beta^*$ , must be found using numerical methods

$$y_i | x_i \sim \mathsf{Poisson}\left(\mu_i = \exp\left(x_i^T \beta\right)\right)$$

$$p\left(\beta | y, X\right) \propto \exp\left(\sum_{i=1}^n \left[-\exp\left(x_i^T \beta\right) + y_i x_i^T \beta\right]\right) \pi\left(\beta\right)$$

## MCMC Example in R

- Puffin Dataset (38 observations at Great Island, Newfoundland)
  - Nest nesting frequency (burrows per 9 square meters)
  - Grass grass cover (percentage)
  - Soil mean soil depth (in centimeters)
  - Angle angle of slope (in degrees)
  - Distance distance from cliff edge (in meters)

#### library(LearnBayes)

```
puffin[1:5,]
```

##		Nest	${\tt Grass}$	Soil	Angle	${\tt Distance}$
##	1	16	45	39.2	38	3
##	2	15	65	47.0	36	12
##	3	10	40	24.3	14	18
##	4	7	20	30.0	16	21
##	5	11	40	47.6	6	27

MSiA 400 Lab 3

## MCMC Framnle in R

##

## Number of Fisher Scoring iterations: 6

```
pfit = glm(Nest~Grass+Soil+Angle+Distance,poisson,data=puffin)
summary(pfit)
##
## Call:
## glm(formula = Nest ~ Grass + Soil + Angle + Distance, family = poisson,
      data = puffin)
##
## Deviance Residuals:
      Min
               10 Median
                                3Q
                                       Max
## -2 3262 -1 2984 -0 6617 0 8119
                                     2.5304
##
## Coefficients:
##
              Estimate Std. Error z value Pr(>|z|)
## (Intercept) 3.069973 0.452568 6.783 1.17e-11 ***
          0.005441 0.003104 1.753 0.07960 .
## Grass
## Soil 0.033441 0.010822 3.090 0.00200 **
## Angle -0.030077 0.010724 -2.805 0.00504 **
## Distance -0.089399 0.010680 -8.371 < 2e-16 ***
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## (Dispersion parameter for poisson family taken to be 1)
##
##
      Null deviance: 310.427 on 37 degrees of freedom
## Residual deviance: 68.765 on 33 degrees of freedom
## ATC: 183.38
```

#### MCMC Frample in R

#### #Bayesian method library(MCMCpack)

#Assumes normal prior

Bpfit = MCMCpoisson(Nest-Grass+Soil+Angle+Distance, data=puffin, burnin=1000, mcmc=25000, thin=25)
summary(Bpfit)

```
##
## Iterations = 1001:25976
## Thinning interval = 25
## Number of chains = 1
## Sample size per chain = 1000
##
## 1. Empirical mean and standard deviation for each variable.
##
     plus standard error of the mean:
##
                            SD Naive SE Time-series SE
##
                  Mean
## (Intercept) 3.066791 0.468017 1.480e-02
                                             0.0164472
## Grass 0.005422 0.003108 9.827e-05 0.0001072
## Soil 0.033598 0.011199 3.541e-04 0.0004051
## Angle -0.030116 0.011293 3.571e-04 0.0004012
## Distance -0.090009 0.011227 3.550e-04 0.0004010
##
## 2. Quantiles for each variable:
##
##
                  2.5%
                            25%
                                     50%
                                               75%
                                                      97.5%
## (Intercept) 2.196294 2.734165 3.059824 3.364891 3.993143
## Grass
             -0.000678 0.003212 0.005457 0.007519 0.011188
## Soil 0.010709 0.026503 0.034166 0.041186 0.055244
## Angle -0.051478 -0.037771 -0.029952 -0.022732 -0.007356
## Distance -0.111761 -0.097584 -0.089772 -0.082416 -0.067911
```