

# Notes for ECE269 - Linear Algebra

## Chapter 3

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## 1 Determinants

Although many of the applications determinants were once used for are no longer applicable, they play a key role in many applications still. This chapter outlines relevant applications and derives extensions and ideas about determinants.

### 1.1 Introduction to Determinants

The determinant stems from the row reduction algorithm applied to a  $n \times n$  matrix. This algorithm applied to an "invertible" matrix requires there being pivot positions in each column. Due to this, as row reduction is applied, the determinant forms from the linear combination of row operations in the bottom right of the matrix.

For simplicity, the determinant of a 3D matrix is shown here before the general case:

$$\Delta = a_{11} \cdot \det A_{11} - a_{12} \cdot \det A_{12} + a_{13} \cdot \det A_{13}$$

In this case, the subscripts of the matrices refer to the row/column pair to be deleted when taken into the equation. This can be extended generally for  $n \geq 2$  by alternating the determinant being added to the equation and utilizing  $N-1$  determinants where  $N$  is the dimensionality of the matrix you are seeking the determinant.

$$\det A = a_{11} \cdot \det A_{11} - a_{12} \cdot \det A_{12} + \cdots + (-1)^{1+n} a_{1n} \cdot \det A_{1n}$$

This method of the determinant is also the cofactor expansion across the first row of the matrix. The cofactor expansion across any row and any column can be used to determine the determinant of the matrix. If the matrix is triangular, then the determinant is the product of the main entries down the diagonal of the matrix.

### 1.2 Properties of Determinants

If row operations are applied to a matrix, the determinant changes in the following ways:

Assuming there is a square matrix.

- If a multiple of one row of  $A$  is added to another row to form a matrix  $B$ , the determinant does not change.
- If two rows are interchanged to produce a new matrix  $B$ , then the determinant is the inverse of the determinant of  $A$ .
- If one row of  $A$  is multiplied by  $k$  to produce a new row in  $B$ , then the determinant of  $B$  is the determinant of  $A$  scaled by  $k$ .

Note - just adding one row to another does not change the determinant either. Factoring out a multiple of a row means that this factor needs to be included back into the final result. When the matrix is invertible, the determinant is the product of pivot positions multiplied with the number of row interchanges times  $-1$  for a echelon form matrix. This further proves that a matrix is invertible only if the determinant is non-zero, since the product of the pivot positions would yield zero when the matrix is not invertible. Linear dependence is obvious when two columns or rows are the same or there is a zero column or row. Cofactor expansion, row reduction to triangular matrices, and using the above theorems speeds up the operations to find a determinant. For a square matrix, the determinant of the transpose is equal to the determinant of the original matrix which yields the result that the row and column terms are interchangeable in the above theorem. Determinants also have multiplicative properties in that the determinant of the product of two matrices is the product of the individual determinants, while this does not hold true for the addition of the determinants

### 1.3 Cramer's Rule, Volume, and Linear Transformations

Cramer's Rule:

Let  $A$  be an invertible  $n \times n$  matrix. For any  $\mathbf{b}$  in the solution space, the unique solution for  $\mathbf{x}$  in the matrix equation has its  $i$ th entry given by the  $i$ th column of  $A$  replaced by  $\mathbf{b}$  divided by the determinant of  $A$ . For hand computation, this is only really useful for 2D or 3D applications. The inverse of a matrix is simply the inverse of the determinant of the matrix multiplied by the adjugate of the matrix (matrix of cofactors used for the determinant). Multiplying the adjugate by the initial matrix yields an expression for the determinant multiplied with the identity matrix, which is another form of the theorem just stated.

If  $A$  is a  $2 \times 2$  matrix, then the area of the parallelogram determined by the columns of  $A$  is the determinant of  $A$ . This can also be said for the area of the parallelepiped determined by the columns of a  $3 \times 3$  matrix. The areas and volumes of the objects just described can be multiplied with the determinants of 2D or 3D linear transformations in order to find the area or volume of the new object.