Copy and paste the following code

Thank you, Samuel Leblanc



```
import matplotlib.pyplot as plt
import numpy as np
import math
exercise = input('Name of the exercise: ')
if 'preacher' in exercise:
  preacher = int(input('What is the angle of the "preacher bench" (in
degrees)? '))
else:
   preacher = 0
ROM = input('What range of motion are you using (in degrees)? Answer
with: "A to B". ')
Tempo = input('What tempo are you using? Please answer in the format
"0000". ')
Weight = input('What weight are you using? Please answer in kg. ')
Limb length = input('What is the length of the limb (in m) that is
moving? ')
ROM start = int(ROM[:2]) + preacher
ROM end = int(ROM[5:]) + preacher + 1
ROM in angle = np.arange(ROM start, ROM end, 1)
Max angle radiant = np.deg2rad(ROM end - 1)
ROM sine = np.sin(np.deg2rad(ROM in angle))
Mass Kg = int(Weight)
Radius = float(Limb length)
Radiant ROM = math.radians(ROM end - 1 - ROM start)
Concentric Velocity = Radiant ROM / int(Tempo[2])
Eccentric Velocity = Radiant ROM / int(Tempo[0])
Simple Pendulum = ((2 * math.pi) * math.sqrt(Radius / 9.8))
Complex Pendulum = Simple Pendulum * (1 + ((Max angle radiant ** 2) /
16) + ((11 / 3074) * (Max angle radiant ** 4)))
Used Amplitude = 0.25 - (ROM start / 360)
Gravitational Velocity = (Radiant ROM / (Complex Pendulum *
Used Amplitude))
Used Acc = 1 - (Eccentric Velocity / Gravitational Velocity)
Concentric = Mass Kg * Radius * ROM sine * 9.81 * Concentric Velocity
print('Concentric')
print(Concentric)
Eccentric = Mass Kg * Radius * ROM sine * 9.81 * Used Acc
print('Eccentric')
print(Eccentric)
p1 = plt.plot(ROM_in_angle, Concentric, 'b', label='Concentric')
p2 = plt.plot(ROM_in_angle, Eccentric, 'g', label='Eccentric')
plt.legend(loc='upper left')
plt.xlabel('Angle (°)')
plt.ylabel('Power (W)')
plt.title(f'Resistance profile of a {exercise}')
plt.show()
```