

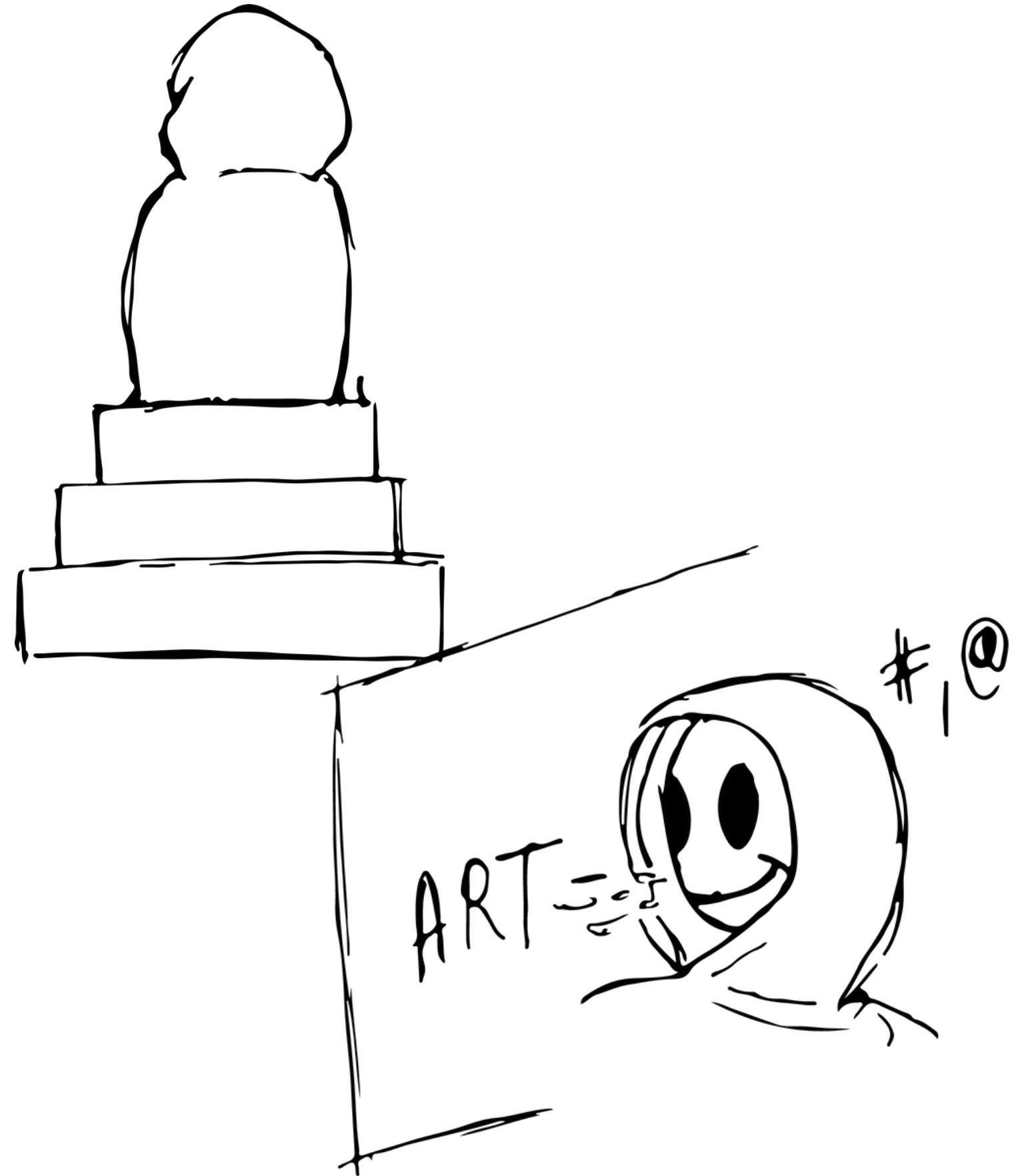
# GROUP 01 – WEEK 03

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DESIGN AND ROBOTICS  
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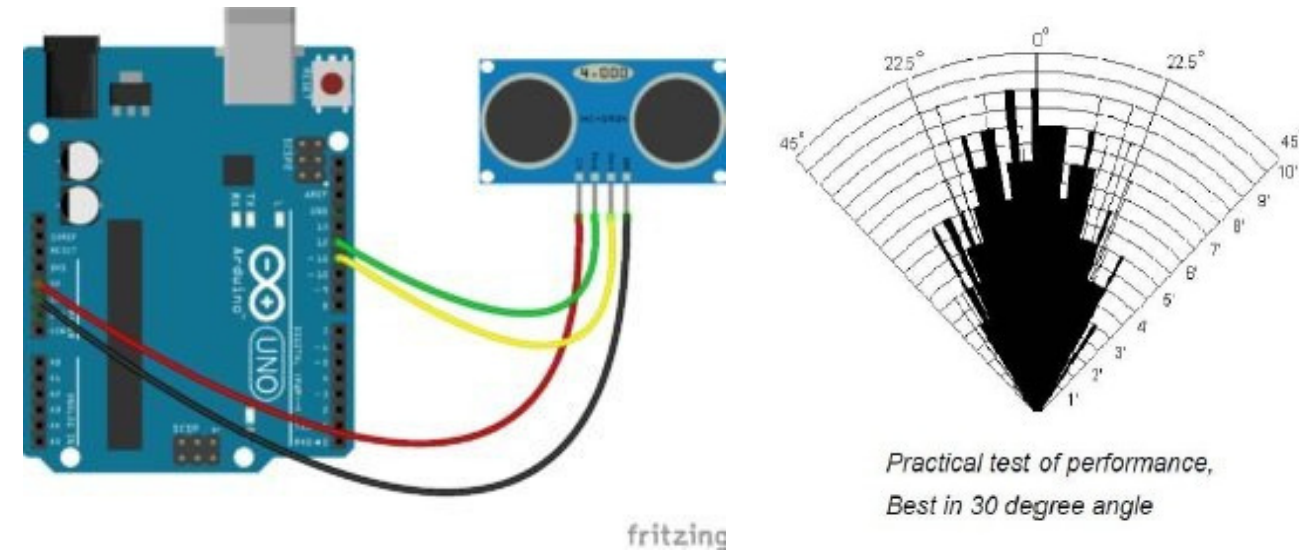
# Functions of our robot

1. Sensor of proximity when someone approaches the robot
2. Body rotation
3. Rotation of the neck upside
4. Action of sneezing
5. Loud sound of sneezing

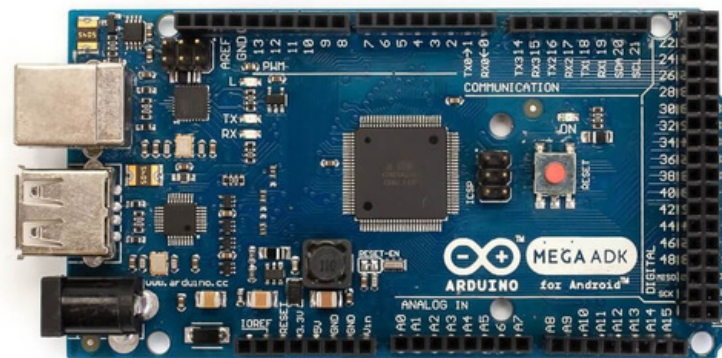


# Components

## Sonar sensor



## Arduino



## Motors

- for rotation
- for the neck movement
- for the sneeze



## Battery



# Components

Sound speakers



Sweater or textile component  
to cover the body



Dispenser - pump

