9/16

LEEL TITT

هــــ فــــ

فر

المسكنة

JA.

Free abelian groups & finitely generated abelian groups \$2.1, A (too) optimistic goal would be to classify all groups up to isomorphism. But for important classes of groups, this is possible we will do it for a subdass (finitely generated) of a belian groups.

First we need to falk about free abeltan groups.

Defin Let G be an abelian group. A subset BEG is called a basis (orbase) is every element gEG has a unique expression as $g = \sum_{i=1}^{n} m_i x_i$ with $m_i \in \mathbb{Z}$ and $x_i \in \mathbb{B}$.

(Here and throughout we we additive notation for a belian groups) G is called free if it posseses a basis.

Rmc. This is very similar to notion of basis in linear algebra Rmc (over a fixeld) except that the coefficient are in Z.

Then the cardinalithes of B1 and Bz are the same.

Defin The rank of a free abelian group Gis the caudinality of lary one of its | bases.

Inm Let G be a free abelian group of finite rank n. Then G = Zn

Romein fact even for & of infinite rank we we have G= Zwix this is interpreted suitebly (have to use direct sum rather than direct product).

Rmk: we have presentation Z' = (x,1x2,...,xx 1 x;x; = X; X;)

(makin, the generators commute makes all clements commute).

Just like every group is a quotient of a free group, every abelian group is a quotient of a free abelian group. We will restrict our attention to finitely generated abelian groups because these are more tractable.

The Let G be a finitely generated abelian group, generated by a elements x....x. Then G=2ⁿ/H for some subgroup H SG.

All of the previous theorems are relatively straightforward.

Of course, we can have r=0 (if G is finite) or k>0 (if G is free). Def'n An element $x \in G$ of a Got necessarily abelian) group Gis called torsion if $x^n = 1$ for some $n \ge 1$.

In an abelian group G, the set Tor(G) of torsion elements (which in abbitue notation have nx=0 first ne n=1) forms a subgroup, called the torsion subgroup (or torsion part) to G.

G is called torsion-free if Tor(G) = {0} and in general G/Tor(G) is called the torsion free part of G.

So the classification says that for an abelian gr. G.

the torsion part is 21/m, 20.00 \$21/mx 21 and the torsion-free

part is Z?

شة) كست

E

Ļ

(_

<u>(</u>_

<u>_</u>

(or For Gafin.gen. abelian gp., also can worke Guntavely as G~ Z/ @ Z/P, Z & Z/P, Z D ... B Z/P2 Z where the P. Pz,..., Pe ove a prime numbers (allowed to repeat). Pfot corollary from thm: If nand more coprime then Z/nm Z ~ Z/nZOZ/mZ/ (exercise for you!) Thus if M= Pa Paz ... Pak is the prime factor. Zation of m, tren V/m2/ = Z/Pa, I O Z/Pa= I & .. O Z/Pa Z. B Remark The integers m, Imz 1... Imx from then are the inversion of G. The prime powers Pi,..., Pe from cor, are the elementary divisors of G. E.g. G= Z/6Z DZ/12Z is the invariant factor representation, equiv. to G = Z/2Z D Z/4Z DZ/3Z DZ/3Z, elementary division rep. So how to prove classification of fin. gen. abelian groups? We know G = Z /H for some subgroup H = Z n Normally thatal we've been quotienting by kernels of homomomphisms, but since we're dealing with abelian grs, we can quotient by images. The cokernel (coker(4) of a homomorphism 4: Zm > Zn is Zm/im(4), the codomain mad the image. We can represent 4 by a matrix: \$1,..., &n are gen's of 2th 4 represents of Minister coeff? *11.... In one gen's of 2th [301][\frac{y_1}{y_2}] = [\frac{3y_1 + y_3}{y_3}, \frac{2y_1 + y_2 - 4y_3}{x_2}] \frac{4y_3}{x_2} \frac{1}{x_2} Small exercise: We can take in finite, i.e., we only need to impose finitely many relations.

-0

-0

-0

_

C: >o any fin. gen, ab. gp. G is of form G=cocerte) for some liZ=Zn. Œ: So we need to undorstand structure of covernels of Z-matrices. Œ E Thm (Smith Normal Form) Let e: 2 be a homo. شنك represented by a nxm matrix M with weff's in Z. E E Then M = SDT where Taxa matrix, Smxm matrix are invertible over I and D = (dij) is a matrix whose off-diagonal (i+i) e E entries are zero and whose diagonal entries M; = Cli, i Satisfy milmelmal ... Imk. E.g. A matrix in SNF looks 1. Ye D= [02000]. The Colourer will be coker(b) = 2/12 @ 2/12 @ 2/62 @ 2/0. 2 € = 4 @ V/2X & V/6V in the form we want! £ Since multiply my on left and right by inventible over Z £ matrices does not change the Z-image, this proves the classification! E L To prove the Smith Normal Form theorem, we need an algorithm that tells us now to convert M to SNF via a serves of Z-chuestile & vow and column operations: **(** [04] = D P.G. M= [21] Sub. 2nd St. [-Z2] Sub. (st w) from 2nd ے Think: RREF and faussian elimination. But I skin 4 the full description of the SNF algorithm, Remark: Infact SNF works for modules over any PID (Principal Ideal Domain), we may retorn to this later 4 ھے In the semester... / C