Recorded at time: 1677613972.5402777 world Broadcaster: /csc22939/deadreckoning node Broadcaster: /at 67 static Broadcaster: /at 8 static Broadcaster: /at 63 static | Broadcaster: /at 22 static` Average rate: $\overline{1}00\overline{0}0.0$ Average rate: 10.204 Average rate: $\overline{1}00\overline{0}0.0$ Average rate: $\overline{100000.0}$ Average rate: $1\overline{0}0\overline{0}0.0$ Buffer length: 4.9 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 1677613972.472 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 1677613967.571 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 at_fixed_22 at_fixed_8 at_fixed_67 odometry at_fixed_63 Broadcaster: /footprint to odomery Average rate: $10\overline{0}0\overline{0}.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 csc22939/footprint Broadcaster: /csc22939/robot state publisher Average rate: $100\overline{0}0.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 csc22939/base Broadcaster: /csc22939/robot state publisher Broadcaster: /csc22939/robot state publisher Broadcaster: /csc22939/robot state publisher Average rate: $100\overline{0}0.0$ Average rate: $100\overline{0}0.0$ Average rate: $100\overline{0}0.0$ Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 csc22939/right_motor csc22939/left_motor csc22939/bottom plate Broadcaster: /csc22939/robot state publisher Average rate: $100\overline{0}0.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 csc22939/left wheel axis csc22939/top_plate csc22939/right_wheel_axis csc22939/caster_wheel csc22939/side_plate_left csc22939/side_plate_right Broadcaster: /csc22939/right wheel encoder node | Broadcaster: /csc22939/left wheel encoder node Broadcaster: /csc22939/robot state publisher Average rate: $100\overline{0}0.0$ Average rate: $100\overline{0}0.0$ Average rate: $100\overline{0}0.0$ Average rate: $100\overline{0}0.0$ Average rate: 30.226 Average rate: 30.206Average rate: $100\overline{0}0.0$ Average rate: $100\overline{0}0.0$ Average rate: $100\overline{0}0.0$ Buffer length: 0.0 Buffer length: 0.0 Buffer length: 4.867 Buffer length: 0.0 Buffer length: 4.863 Most recent transform: 0.0 Most recent transform: 1677613972.495 Most recent transform: 0.0 Most recent transform: 1677613972.468 Most recent transform: 0.0 Oldest transform: 1677613967.605 Oldest transform: 1677613967.629 Oldest transform: 0.0 csc22939/interaction_plate csc22939/right_wheel csc22939/left_wheel csc22939/camera_mount csc22939/back_bumper csc22939/front_bumper csc22939/hat_support csc22939/side_cover_left csc22939/side_cover_right Broadcaster: /csc22939/robot_state_publisher Broadcaster: /csc22939/robot state publisher Average rate: $100\overline{0}0.0$ Average rate: $100\overline{0}0.0$ Buffer length: 0.0 Most recent transform: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 csc22939/tag_mount csc22939/camera_support Broadcaster: /csc22939/robot state publisher Average rate: $100\overline{0}0.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 csc22939/camera frame Broadcaster: /csc22939/robot state publisher Average rate: $100\overline{0}0.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 csc22939/camera_optical_frame

view frames Result