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INTRODUCTION TO SEGMENT TREES (RANGE MINIMUM QUERY)

12 Mar 2014 · by MGhareeb · in Algorithms, Data Structure · Leave a comment

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Range Minimum Query

Given an array A of length N, answer getMin(i,j) quuries. getMin(i,j) should return the index m, where $A[m] = min_{i < k < j} \{A[k]\}$.

There are many ways to do this. In the case where A's element values are allowed to change, and yet we have to maintain getMin(i,j) to work correctly, a segment tree is our best option. Follows is a brief explanation of segment trees for this specific example. I'll put a more generalized explanation in another post.

Segment Trees

The idea behind a segment tree is to build a **binary tree** where each node represents a segment of A. For Range Minimum Query, each tree node will contain the value of getMin(segment) (the index of the minimum value in the node's segment of the array).

Now, how are nodes and segments assigned? For simplicity, let's assume that A's length is a power of two:

- Starting at the lowest level of the tree, we'll have N leaf nodes each representing an element of A. As shown in the following figure, if we label leaf nodes from 0 to N-1 from left to right, each node i will contain the value i.
- For each internal node node starting from the bottom, we compute node.value as follows: $node.value = m, A[m] = min\{A[node.left.value], A[node.right.value]\}$

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- . Meaning, a parent node node will g children such that A[node.value] is
- Since this is a binary tree with the last tree will have the height of log(N) \dashv node, the root, which holds getMin(each node on a level L will represent $2^{log(N)+1-L}$.

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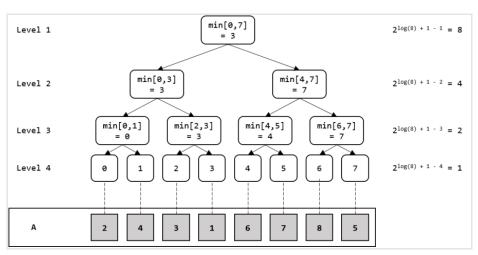
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The implementation is going to be straight forward from here on. We'll represent the tree as an array tree of length 2 << ceil(log2(N + 1)). Node i has a left child 2 * i and a right child 2 * i + 1. On an update(i), we'll traverse the tree from top to bottom, change array value at when we reach the leaf i, and update the tree as we go back up. On a getMin(range), we'll recurse from root until we visit all maximal sub-segments of the range and return the required value. Here's an implementation in C++ with this tutorial as a reference:

```
#include <iostream>
 1
 2
     #include <vector>
 3
     #include <cstring>
 4
     #include <cmath>
 5
     using namespace std;
 6
 7
     class segTree {
         // O(n)
 8
         int *array, *tree;
 9
10
         int arrayLen, treeLen;
11
12
         // 0(n)
         void initialize(int node, int b, int e) {
13
14
              if (b == e)
15
                  tree[node] = b;
              else {
16
                  // recurse
17
                  initialize(2 * node, b, (b + e) / 2);
18
                  initialize(2 * node + 1, (b + \acute{e}) / 2
19
                  // update value
20
                  if (array[tree[2 * node]] <= array[tr</pre>
21
                       tree[node] = tree[2 * node];
22
23
                       tree[node] = tree[2 * node + 1];
24
              }
25
```

```
26
27
      public:
28
          segTree(int *array, int arrayLen) {
29
               this->arrayLen = arrayLen;
30
               this->array = array;
               this->treeLen = 2 << (int)ceil(log2(array
cout << "treeLen=" << treeLen << endl;</pre>
31
32
               33
               memset(tree, -1, sizeof(int)*
initialize(1, 0, arrayLen - 1);
34
35
          }
36
37
          // O(\log n)
38
39
          void update(int i, int v, int node = 1, int b
40
               e = arrayLen - 1 - e;
41
               if (b == e) {
42
                    array[i] = v;
               } else {
43
44
                    int mid = (b + e) / 2;
                   if (i <= mid)
45
                        update(i, v, 2 * node, b, arrayLe
46
47
                    update(i, v, 2 * node + 1, mid +
if (array[tree[2 * node]] <= array[tr
    tree[node] = tree[2 * node];</pre>
48
49
50
51
                    else
52
                        tree[node] = tree[2 * node + 1];
53
               }
54
          }
55
56
          // O(\log n)
57
          int query(int i, int j, int node = 1, int b =
58
               e = arrayLen - 1 - e;
               // bad interval
59
60
               if (i > e || j < b)
61
                    return -1;
               // good interval
62
63
               if (b >= i && e <= j)
64
                    return tree[node];
65
               // partial interval
               int left = query(i, j, 2 * node, b, array
66
               int right = query(i, j, 2 * node + 1, (b
67
               if (left == -1)
68
69
                    return tree[node] = right;
70
               if (right == -1)
71
                    return tree[node] = left;
72
               if (array[left] <= array[right])</pre>
73
                    return tree[node] = left;
74
               return tree[node] = right;
75
          }
76
     };
77
78
     int main() {
79
          int A[10] = { 2, 4, 3, 1, 6, 7, 8, 9, 1, 7 };
80
          segTree t(A, 10);
          cout << "getMin(0, 4) = " << t.query(0, 4) <<
81
          t.update(1, 0);
cout << "getMin(0, 4) = " << t.query(0, 4) <<
82
83
          t.update(0, -1);
cout << "getMin(0, 4) = " << t.query(0, 4) <<
84
85
86
          return 0;
87
     }
```

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std::cout <<

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