

## Partial Differential Equations

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# Chapter 1

## Basics

A PDE is an equation relating the partial derivatives of some unknown function

<https://www.youtube.com/watch?v=atvw5iseoGQ&list=PLF6061160B55B0203&index=3>

## Chapter 2

# Partial Differential Equations

### 2.1 Notation

First order differential of  $u$  w.r.t  $t$

$$\frac{du}{dx} \tag{2.1}$$

$$\dot{u} \tag{2.2}$$

Second order differential of  $u$  w.r.t  $t$

$$\frac{d^2u}{dx^2} \tag{2.3}$$

$$\ddot{u} \tag{2.4}$$

Laplace function

$$\Delta u(x) = \sum_{i=0}^n \frac{d^2u}{dx_i^2}(x) = 0 \tag{2.5}$$

### 2.2 Definitions

### 2.3 Equations

#### 2.3.1 Heat Equation

The Heat Equation was originally developed to model how heat diffuses across a region

$$\frac{du}{dt} = \frac{d^2u}{dx^2} \tag{2.6}$$

$$\dot{u} = \Delta u \tag{2.7}$$

In this specific instance of the Heat Equation we are working in a single dimension

### Example

Is the following equation a solution to the heat equation

$$u = \frac{1}{2}x^2 + t$$

Check

$$\frac{d}{dt}u = \frac{d}{dt}\frac{1}{2}x^2 + \frac{d}{dt}t$$

$$\frac{d}{dt}u = 1$$

$$\frac{d^2}{dx^2}u = \frac{d^2}{dx^2}\frac{1}{2}x^2 + \frac{d^2}{dx^2}t$$

$$\frac{d^2}{dx^2}u = 1$$

$$\therefore \frac{d}{dt}u = \frac{d^2}{dx^2}u$$

### Family of Solutions

The following equation can generate an infinite number of solutions to the heat equation.

$$u = e^{ax+bt}$$

We can determine what a and b can represent as follows

$$\begin{aligned}\frac{d}{dt}u &= e^{ax+bt} \frac{d}{dt}(ax + bt) \\ &= e^{ax+bt} \cdot b\end{aligned}$$

$$\begin{aligned}\frac{d}{dx}u &= e^{ax+bt} \frac{d}{dx}(ax + bt) \\ &= e^{ax+bt} \cdot a\end{aligned}$$

$$\frac{d^2}{dx^2}u = e^{ax+bt} \cdot a^2$$

$$e^{ax+bt} \cdot b = e^{ax+bt} \cdot a^2$$

$$\therefore b = a^2$$

### 2.3.2 Wave Equation

$$\frac{d^2u}{dt^2} = t^2 \frac{d^2u}{dx^2} \quad (2.8)$$

## Derivation

Model a string being moved up and down in a flat plane. Due to the nature of the string the force acting upon it to return to the  $y=0$  axis is proportional to the "concavity".

$$\text{Force} = F = ma$$

Since acceleration is the 2nd derivative to position

$$F = m \cdot \frac{d^2 u}{dt^2}$$

Concavity can be modelled as the 2nd derivative of the shape of the string, since we are describing the degree of the curve the string is creating

$$\therefore \frac{d^2 u}{dx^2}$$

Since we now have both sides of the equation but we are missing  $c^2$ . We can compare the units each side so far.

where  $c^2$  is the velocity of the string

### 2.3.3 Laplace Equation

### 2.3.4 Transport Equation

## 2.4 Basics

? Does a solution exist?

? Is the solution unique?

? Does the solution depend continuously on the data?

? How regular is the solution? Is it continuously differentiable? Or even smooth?