Broadband noise for rotating blades: analysis of acceleration effects in the time and frequency domains

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Outline

- Open rotor broadband noise
 - Motivation
 - Amiet's theory for rotating blades
 - Review of acceleration effects
- Time domain formulation
 - Review of time domain formulations
 - FW-H formulation 1C
 - Blade loading
- Results
 - Rotor parameters
 - Stationary blade element
 - Rotating blade element
- 4 Conclusions

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Motivation

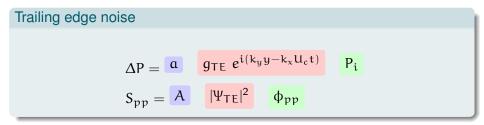




- Broadband noise for Open Rotors or CRORS
- Need fast semi-analytical models for design

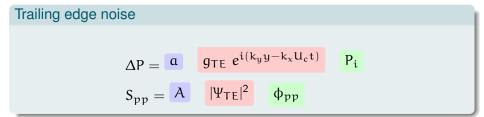
Amiet's theory for stationary aerofoils

Amiet 1974, 1975, 1976



Amiet's theory for stationary aerofoils

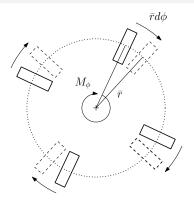
Amiet 1974, 1975, 1976



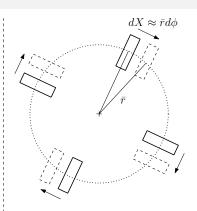
Leading edge noise

$$\Delta P = b$$
 $g_{LE} e^{i(k_y y - k_x Ut)}$
 W_i
 $S_{pp} = B$
 $|\Psi_{LE}|^2$
 ϕ_{ww}

Translations instead of rotations



 ${\bf Exact~FW\text{-}H~based~model:} \\ {\bf Predicts~noise~from~rotating~airfoils} \\$



Approximate model (Amiet):

Predicts noise from translating airfoil + correction for Doppler shift

+ correction for Doppler shift + average over all angles ϕ

Courtesy of Vincent Blandeau (2011)

Lowson's theory

Lowson (1965)

$$p \sim \dot{F} + \alpha F \, \dot{M}$$

Lowson's theory

Lowson (1965)

$$p \sim \dot{F} + \alpha F \dot{M}$$

Amiet's idea

$$\dot{F} \sim \omega_S F$$

$$\dot{M}\sim\Omega M$$

If
$$\omega_s \gg \Omega$$
,

$$p \sim \dot{F}$$

→ Source in rectilinear motion.

Lowson's theory

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Amiet's idea

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 $\dot{M} \sim \Omega M$

If $\omega_s \gg \Omega$,

 $p\sim \dot{F}$

 \rightarrow Source in rectilinear motion.

Question

Is $\omega_S\gg\Omega$ always necessary? Is Amiet's approach more widely applicable?

Frequency domain formulation



- S. Sinayoko, M. Kingan, A. Agarwal. Trailing edge noise for rotating blades. *Proceedings of the Royal Society A*, 2014.
- Frequency Domain formulation including acceleration effects
- Reviewed and validated Amiet's theory for rotating blades.

Acceleration effects on TEN



S. Sinayoko, M. Kingan, A. Agarwal.

On the effect of acceleration on trailing edge noise radiation from rotating blades.

AIAA-2013-2287, 2013.

Findings

- Amiet's method found to work for $\omega \gtrsim \Omega/10$.
- Reason: error on instant PSD is averaged out over one cycle.

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Issues

- Source frequency becomes very low at certain azimuthal angles
- 4 Hard to distinguish acceleration effect in exact formulation

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Issues

- Source frequency becomes very low at certain azimuthal angles
- 4 Hard to distinguish acceleration effect in exact formulation
- → Use Leading Edge Noise instead of Trailing Edge Noise
- → Use Time Domain formulation instead

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Broadband noise formulations in the time domain

Casper and Farassat (IJA 2002, JSV 2004)

First trailing edge noise prediction for *stationary* blade in the time domain using FW-H.

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Trailing edge noise prediction for *rotating* blade in the time domain using FW-H.

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Trailing edge noise prediction for *rotating* blade in the time domain using FW-H.

Glegg, Devenport and Alexander (JSV 2015)

- Broadband rotor noise predictions using a time domain approach
- Predicts PSD rather than pressure field.

FW-H equations in uniform flow: formulation 1C

Far field formulation

Najafi-Yazdi, Bres, Mongeau (PRS A 2010)

$$\begin{split} 4\pi c_0 p \approx \boxed{\int_{f=0} \left[\frac{\Delta \dot{p} n_i \tilde{R}_i}{R^* (1-M_R)^2} \right] d\eta} + \\ \\ \int_{f=0} \left[\frac{\Delta p \dot{n}_i \tilde{R}_i}{R^* (1-M_R)^2} \right] d\eta - \int_{f=0} \left[\frac{\dot{M}_R \Delta p n_i \tilde{R}_i}{R^* (1-M_R)^3} \right] d\eta \end{split}$$

FW-H equations in uniform flow: formulation 1C

Far field formulation

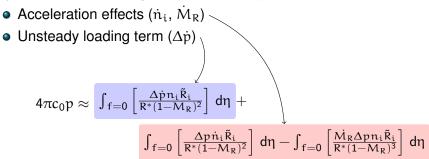
Najafi-Yazdi, Bres, Mongeau (PRS A 2010)

• Unsteady loading term (
$$\Delta\dot{p}$$
)
$$4\pi c_0 p \approx \left[\int_{f=0}^{\Delta\dot{p}n_i\tilde{R}_i} \left[\frac{\Delta\dot{p}n_i\tilde{R}_i}{R^*(1-M_R)^2}\right] d\eta + \int_{f=0}^{4} \left[\frac{\Delta\dot{p}n_i\tilde{R}_i}{R^*(1-M_R)^2}\right] d\eta - \int_{f=0}^{4} \left[\frac{\dot{M}_R\Delta\dot{p}n_i\tilde{R}_i}{R^*(1-M_R)^3}\right] d\eta$$

FW-H equations in uniform flow: formulation 1C

Far field formulation

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Stationary blade element

Time domain fluctuations from wavenumber spectrum

$$\begin{split} & \Delta p(x,y,t) = Re \left\{ \frac{W_0(k_x,k_y)g_{LE}(x,k_x,k_y)e^{i[k_x(x-Ut)+k_yy+\varphi]}}{8\Phi_{ww}(k_x,k_y)\Delta k_x\Delta k_y}. \end{split} \right. \end{split}$$

$$k_x = \omega_s/U$$
, $\Delta k_x = 2\pi/U$, $\Delta k_y = 2\pi/\text{span}$

Stationary blade element

Time domain fluctuations from wavenumber spectrum

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$$k_x = \omega_s/U, \hspace{1cm} \Delta k_x = 2\pi/U, \hspace{1cm} \Delta k_y = 2\pi/\text{span}$$

 \rightarrow New factor $\sqrt{8}$ compared to π in Casper and Farassat (2004). Proof:

$$\label{eq:local_power} \text{Incident Power} = \frac{1}{2} W_0(k_x,k_y)^2 = 4 \Phi_{ww}(k_x,k_y) \Delta k_x \Delta k_y.$$

Rotating blade element

Objective: avoid calculating the instantaneous spectrum

PSD computation for rotating blade element

- Select observer position and frequency.
- **2** Compute source frequency $\omega_S(\tau)$ from Doppler shift.
- **3** Compute pressure jump $\Delta p(x, y, \tau)$ over 4 periods.
- **①** Compute far field pressure p(t) using FW-H.
- **5** Compute power by time averaging $p^2(t)$.

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Note on period:

- Period is $T_{\Omega} = 2\pi/\Omega$ for $\omega > \Omega$
- Period is $T_{\omega} = 2\pi/\omega$ for $\omega < \Omega$

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Open propeller blade element

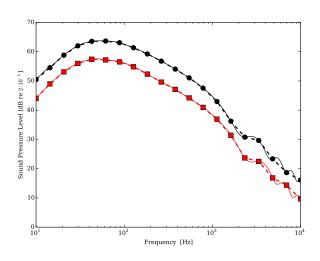
Blade parameters

```
radius
                 chord
                                 Pitch
                          M_{BO}
                                         M_{FO}
                                                 M_{FB}
Take-off
          1.80
                 0.31 m
                         0.748
                                 38 deg
                                         0.228
                                                0.782
Cruise
          1.80
                 0.31 m
                         0.748
                                 13 deg
                                         0.584
                                                0.949
```

- Turbulence intensity: 5% of inflow velocity
- Turbulence length scale: r/2 = 0.9
- Observer location: distance 100λ , elevation angle $\pi/4$.

Stationary blade element

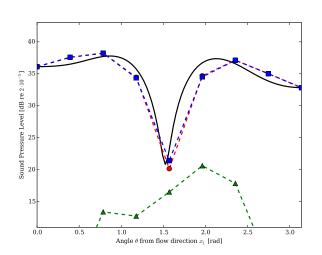
take-off cruise



Rotating blade element: high frequency directivity

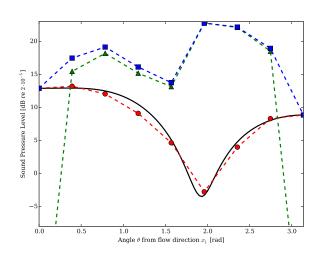
SPL directivity for take-off blade element

 $\begin{array}{ccc} & \text{High frequency: } \omega = 10\Omega \\ & \text{Amiet} & \textbf{Unsteady loading} & \text{Acceleration effects} & \textbf{Total} \end{array}$



Rotating blade element: low frequency directivity

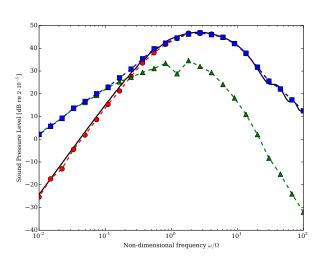
SPL directivity for take-off blade element



Rotating blade element

SPL spectrum for take-off blade element

Amiet Unsteady loading Acceleration effects Total



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Achievements

- Predicted leading edge noise in the time domain with FW-H
- Acceleration term can be switched on and off
- Compared predictions to Amiet's formulation for model propeller blade elements

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- Acceleration effects can be neglected for time averaged PSD for $\omega \geqslant 0.5\Omega$.
- Much better than $\omega \gg \Omega$.
- Amiet's formulation can be used even at low frequencies.

Acknowledgements



Southampton Institute of Sound and Vibration Research

Acknowledgements





Vibration Research

Further information



http://www.sinayoko.com



http://bitbucket.org/sinayoko



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Thank you!