

Submarine Recovery System User Manual

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1 Introduction

This system is used to recover the sunken submarine from the tank.

2 System description

Describe the system components.

3 Assembly

Describe how to assemble the thing

Required tools

- Screw drive
- ..

Put part A on B..

4 Needed software

Describe here how to install PUTTY and the camera software.

5 System control

how to establish the bluetooth connection, open putty and start driving.
Keys come here.

Table 1: Keys controlling the system.

Character	Action
'q'	Move the winch rope up
'a'	Move the winch rope down
'x'	Hold the winch
'z'	Release the winch
'w'	Move the claw servo 5° toward closing
's'	Move the claw servo 5° toward opening
'e'	Move the camera servo 5° to the left
'r'	Move the camera servo 5° to the right
'i'	Move the rover forward
'm'	Move the rover backward
'k' or space	Stop the rover
'l'	Turn the rover to the right
'j'	Turn the rover to the left