```c
/*
servo_init() initialize the servo control
*/
void servo_init(void);

/*
move_servo1() moves servo 1 to the input argument position angle (in degree)
*/
void move_servo1(uint16_t angle);

/*
move_servo1() moves servo 2 to the input argument position angle (in degree)
*/
void move_servo2(uint16_t angle);
```