Dynamic programming is both a mathematical optimization method and a computer programming method.

The method was developed by Richard Bellman in the 1950s and has found applications in numerous fields, from aerospace engineering to economics.

## Computer programming

There are two key attributes that a problem must have in order for dynamic programming to be applicable: optimal substructure and overlapping sub-problems. If a problem can be solved by combining optimal solutions to non-overlapping sub-problems, the strategy is called "divide and conquer" instead.[1] This is why merge sort and quick sort are not classified as dynamic programming problems.

## Top-down approach

This is the direct fall-out of the recursive formulation of any problem. If the solution to any problem can be formulated recursively using the solution to its sub-problems, and if its sub-problems are overlapping, then one can easily memoize or store the solutions to the sub-problems in a table. Whenever we attempt to solve a new sub-problem, we first check the table to see if it is already solved. If a solution has been recorded, we can use it directly, otherwise we solve the sub-problem and add its solution to the table.

## Bottom-up approach

Once we formulate the solution to a problem recursively as in terms of its sub-problems, we can try reformulating the problem in a bottom-up fashion: try solving the sub-problems first and use their solutions to build-on and arrive at solutions to bigger sub-problems. This is also usually done in a tabular form by iteratively generating solutions to bigger and bigger sub-problems by using the solutions to small sub-problems.