



Volumes of Generalized Unit Balls

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of Y. Either way,  $f(f(\pi)) = \pi$ , and f is a well-defined, sign-reversing involution, as desired.

In summary, we have shown combinatorially that for all values of n, there are almost as many even derangements as odd derangements of n elements. Or to put it another way, when randomly choosing a derangement with at least five elements, the *odds* of having an even derangement are nearly *even*.

**Acknowledgment.** We are indebted to Don Rawlings for bringing this problem to our attention and we thank Magnhild Lien, Will Murray, and the referees for many helpful ideas.

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# Volumes of Generalized Unit Balls

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Diamonds, cylinders, squares, stars, and balls. These geometric figures are familiar to undergraduate students, but what could they possibly have in common? One answer is: They are generalized balls. The standard Euclidean ball can be distorted into a variety of strange-shaped balls by linear and nonlinear transformations. The purpose of this note is to give a unified formula for computing the volumes of generalized unit balls in *n*-dimensional spaces.

A generalized unit ball in  $\mathbb{R}^n$  is described by the set

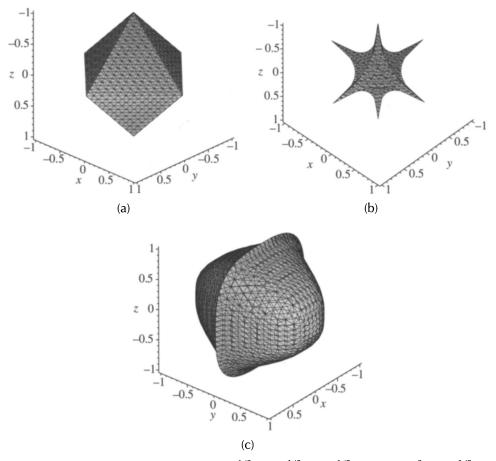
$$\mathbb{B}_{p_1, p_2, \dots, p_n} = \{ \mathbf{x} = (x_1, \dots, x_n) : |x_1|^{p_1} + \dots + |x_n|^{p_n} \le 1 \}, \tag{1}$$

where  $p_1 > 0$ ,  $p_2 > 0$ , ...,  $p_n > 0$ .

When the numbers  $p_1, \ldots, p_n$  are all greater than or equal to 1, the unit ball  $\mathbb{B}_{p_1 \ldots p_n}$  is convex. Since  $|x|^p$  is not concave on [-1,1] for  $0 , <math>\mathbb{B}_{p_1 \ldots p_n}$  is not necessarily convex anymore when n > 1. When  $p_1 = p_2 = \cdots = p_n = p \ge 1$ , we obtain the usual  $l_p$  ball. The  $l_2$  ball is denoted by  $\mathbb{B}$ . By choosing different numbers  $p_i$ , we can alter the appearance of the generalized balls greatly, as shown in FIGURE 1 with examples in  $\mathbb{R}^3$ .

Motivated by an article by Folland [5], I derived a unified formula for calculating the volume of these balls. Although the volume formulas for the standard Euclidean ball  $\mathbb B$  and simplex have been known for a long time [4, pp. 208, 220], the unified formula is (relatively) new. It is surprising that no matter how strange the balls look, the volume of any ball can be computed by a single formula, as follows:

THEOREM. Assume  $p_1, \ldots, p_n > 0$ . The volume of the unit ball  $\mathbb{B}_{p_1 p_2 \ldots p_n}$  in  $\mathbb{R}^n$  is equal to



**Figure 1** (a)  $|x_1| + |x_2| + |x_3| \le 1$ ; (b)  $|x_1|^{1/2} + |x_2|^{1/2} + |x_3|^{1/2} \le 1$ ; (c)  $|x_1|^3 + |x_2|^{1/2} + |x_3|^3 \le 1$ 

$$2^{n} \frac{\Gamma(1+1/p_{1})\cdots\Gamma(1+1/p_{n})}{\Gamma(1/p_{1}+1/p_{2}+\cdots+1/p_{n}+1)}.$$
 (2)

The volume of the positive orthant part, where all x-values are positive, may be obtained by removing the factor of  $2^n$  from the formula.

The formula involves the *gamma function*, which we review for readers who may be unfamiliar with it. For  $0 < t < \infty$ , we define

$$\Gamma(t) := \int_0^\infty s^{t-1} e^{-s} \, ds.$$

The integral converges for t > 0. The following facts will be needed: For u > 0 and v > 0, we have

$$\Gamma(u+1) = u\Gamma(u),\tag{3}$$

and

$$\int_0^1 s^{u-1} (1-s)^{v-1} ds = \frac{\Gamma(u)\Gamma(v)}{\Gamma(u+v)}.$$
 (4)

Although the integral in  $\Gamma(t)$  becomes infinite for  $t \le 0$ , (3) provides an analytic continuation formula to define  $\Gamma(t)$  for t < 0. The function  $\Gamma$  has discontinuities only at  $t = 0, -1, -2, \ldots$  More details can be found in Folland [6, pp. 344–346].

Proof.

Step 1. We begin with the fact that

$$V(\mathbb{B}_{p_1\dots p_n}) = \int_{\mathbb{B}_{p_1\dots p_n}} 1 \, d\mathbf{x}$$

and apply a change of variables that deforms the generalized ball into  $\mathbb{B}$ , the standard ball: Let  $y_1 = x_1^{p_1/2}, \ldots, y_n = x_n^{p_n/2}$ . For the function

$$\phi(\mathbf{y}) := (y_1^{2/p_1}, \dots, y_n^{2/p_n}),$$

the Jacobian determinant is

$$J\phi(\mathbf{y}) = \frac{2}{p_1} \cdots \frac{2}{p_n} y_1^{\frac{2}{p_1} - 1} \dots y_n^{\frac{2}{p_n} - 1}.$$

Readers may consult Folland [6, p. 432] for a detailed proof of the change of variables formula, which is our next ingredient. We use it to obtain

$$\int_{\mathbb{B}_{p_1 \dots p_n}} 1 \, d\mathbf{x} = \int_{\mathbb{B}} \left| J\phi(y) \right| d\mathbf{y} = \frac{2^n}{p_1 \dots p_n} \int_{\mathbb{B}} |y_1|^{2/p_1 - 1} \dots |y_n|^{2/p_n - 1} \, d\mathbf{y}.$$

Step 2. Assume  $\alpha_1, \ldots, \alpha_n > -1$ . We claim:

$$\int_{\mathbb{R}} |x_1|^{\alpha_1} \dots |x_n|^{\alpha_n} d\mathbf{x} = \frac{\Gamma(\beta_1) \dots \Gamma(\beta_n)}{\Gamma(\beta_1 + \dots + \beta_n + 1)},$$
(5)

where  $\beta_i := (\alpha_i + 1)/2$  for i = 1, ..., n.

To verify this claim, we develop a recursion formula. Let  $I(\alpha_1, \ldots, \alpha_n)$  denote the integral in (5). We then evaluate this as an iterated integral starting with  $x_1$  as outermost variable.

$$I(\alpha_1,\ldots,\alpha_n) = \int_{-1}^1 |x_1|^{\alpha_1} \int_{x_2^2+\cdots+x_n^2 \le 1-x_1^2} |x_2|^{\alpha_2} \cdots |x_n|^{\alpha_n} dx_2 \ldots dx_n dx_1$$

The inner integration takes place over a ball of radius  $r = \sqrt{1 - x_1^2}$ . Changing variables again, we set  $(x_2, \dots, x_n) = r(y_2, \dots, y_n)$  to get

$$\int_{x_2^2 + \dots + x_n^2 \le r^2} |x_2|^{\alpha_2} \cdots |x_n|^{\alpha_n} dx_2 \cdots dx_n$$

$$= \int_{y_2^2 + \dots + y_n^2 \le 1} r^{(n-1) + \alpha_2 + \dots + \alpha_n} |y_2|^{\alpha_2} \cdots |y_n|^{\alpha_n} dy_2 \cdots dy_n.$$

This gives  $I(\alpha_1, \ldots, \alpha_n) =$ 

$$\begin{split} &= \int_{-1}^{1} |x_{1}|^{\alpha_{1}} (1-x_{1}^{2})^{(n-1)/2+(\alpha_{2}+\cdots+\alpha_{n})/2} \int_{y_{2}^{2}+\cdots+y_{n}^{2}\leq 1} |y_{2}|^{\alpha_{2}} \cdots |y_{n}|^{\alpha_{n}} dy_{2} \dots dy_{n} dx_{1} \\ &= 2 \int_{0}^{1} x_{1}^{\alpha_{1}} (1-x_{1}^{2})^{(n-1)/2+(\alpha_{2}+\cdots+\alpha_{n})/2} dx_{1} \cdot \int_{y_{2}^{2}+\cdots+y_{n}^{2}\leq 1} |y_{2}|^{\alpha_{2}} \dots |y_{n}|^{\alpha_{n}} dy_{2} \dots dy_{n} \\ &= \int_{0}^{1} (x_{1}^{2})^{(\alpha_{1}-1)/2} (1-x_{1}^{2})^{(\alpha_{2}+\cdots+\alpha_{n}+n+1)/2-1} d(x_{1}^{2}) \int_{y_{2}^{2}+\cdots+y_{n}^{2}\leq 1} |y_{2}|^{\alpha_{2}} \cdots |y_{n}|^{\alpha_{n}} dy_{2} \dots dy_{n}. \end{split}$$

Hence by (4),

$$I(\alpha_1,\ldots,\alpha_n) = \frac{\Gamma((\alpha_1+1)/2)\Gamma((\alpha_2+\cdots+\alpha_n+n+1)/2)}{\Gamma((\alpha_1+\cdots+\alpha_n+n+2)/2)} \cdot I(\alpha_2,\ldots,\alpha_n).$$

This provides a recursion formula connecting  $I(\alpha_1, \alpha_2, ..., \alpha_n)$  and  $I(\alpha_2, ..., \alpha_n)$ . Applying the recursion formula (n-1) times, after cancellation, we obtain

$$I(\alpha_1, \dots, \alpha_n) = \frac{\Gamma(\frac{\alpha_1+1}{2}) \cdots \Gamma(\frac{\alpha_{n-1}+1}{2}) \frac{\alpha_n+1}{2} \Gamma(\frac{\alpha_n+1}{2})}{\Gamma(\frac{\alpha_1+\cdots+\alpha_n+n}{2}+1)} \cdot I(\alpha_n).$$
(6)

But

$$I(\alpha_n) = \int_{x^2 < 1} |x|^{\alpha_n} dx = 2 \int_0^1 x^{\alpha_n} dx = \frac{2}{\alpha_n + 1}.$$

Putting this into (6) yields (5).

Step 3. When  $\alpha_i = 2/p_i - 1$  for i = 1, ..., n, (5) gives

$$I(2/p_1 - 1, \dots, 2/p_n - 1) = \frac{\Gamma(1/p_1) \cdots \Gamma(1/p_n)}{\Gamma(1/p_1 + \dots + 1/p_n + 1)}.$$

Hence

$$V(\mathbb{B}_{p_1...p_n}) = 2^n \frac{1}{p_1} \cdots \frac{1}{p_n} I(2/p_1 - 1, \dots, 2/p_n - 1)$$
$$= 2^n \frac{\Gamma(1 + 1/p_1) \cdots \Gamma(1 + 1/p_n)}{\Gamma(1/p_1 + \dots + 1/p_n + 1)}.$$

The volume of positive orthant part follows from there being  $2^n$  orthants in  $\mathbb{R}^n$ .

In (1), you might argue that  $p_i$  cannot be infinite, but, my dear readers, we can consider a limiting case. Let us write

$$x^{\infty} = \begin{cases} 0 & \text{if } 0 \le x < 1, \\ 1 & \text{if } x = 1. \end{cases}$$

We proceed to single out a few special cases (calculus students' delights):

1. Some  $p_i = +\infty$ : as  $\Gamma$  is continuous on  $(0, +\infty)$ , we have  $V(\mathbb{B}_{p_1...p_n}) = 2 \cdot 2^{n-1} \frac{\Gamma(1+1/p_1) \cdots \Gamma(1+1/p_{i-1})\Gamma(1+1/p_{i+1}) \cdots \Gamma(1+1/p_n)}{\Gamma(1/p_1 + \cdots + 1/p_{i-1} + 1/p_i + \cdots + 1/p_{i-1} + 1)}$ .

In particular, when  $p_1 = p_2 = \cdots = p_n = +\infty$ , the volume of the ball is  $2^n$ , and the shape is an *n*-dimensional hypercube (excluding the portions of its boundary where two or more  $x_i$ s are simultaneously 1). When  $p_1 = p_2 = 2$ ,  $p_3 = \infty$ , the generalized ball is a circular cylinder in  $\mathbb{R}^3$ .

2. When  $p_1 = p_2 = \cdots = p_n = p > 0$ , we have  $V(\mathbb{B}_{p \dots p}) =$ 

$$2^{n} \frac{(\Gamma(1+1/p))^{n}}{\Gamma(n/p+1)} = \frac{(2/p)^{n} (\Gamma(1/p))^{n}}{(n/p)\Gamma(n/p)}.$$

Recall that  $\Gamma(1)=1$ ,  $\Gamma(1/2)=\pi^{1/2}$ , and  $\Gamma(n)=(n-1)!$ . For p=2, the generalized ball is the standard Euclidean ball with volume  $2\pi^{n/2}/(n\Gamma(n/2))$ . For p=1, the generalized ball

$$\{(x_1,\ldots,x_n): |x_1|+\cdots+|x_n|\leq 1\},\$$

is an *n*-dimensional diamond, and has volume  $2^n/n!$ . For p=1/2, the generalized ball has volume  $2^{2n}/(2n)!$ , and its shape is an *n*-dimensional star. These are two of the balls shown in FIGURE 1.

Surprisingly, for 0 we find the*n*-dimensional ball has smaller volume when*n*becomes larger, and that

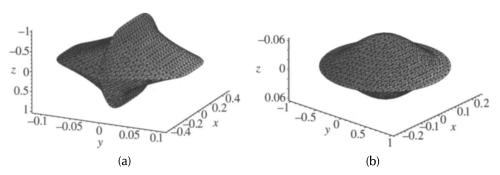
$$\lim_{n\to\infty} V(B_{\underline{p,p,\dots,p}}) = \lim_{n\to\infty} \frac{(2/p)^n (\Gamma(1/p))^n}{(n/p)\Gamma(n/p)} = 0.$$

Here we use Stirling's formula:  $\Gamma(x) \sim \sqrt{2\pi} x^{x-1/2} e^{-x}$ , where  $\sim$  means that the ratio of the quantity on the left and right approaches 1 as  $x \to \infty$  [6, p. 353].

3. For the ellipsoid  $\{(x_1, \ldots, x_n) : |x_1|^{p_1}/a_1^{p_1} + \cdots + |x_n|^{p_n}/a_n^{p_n} \leq 1\}$ , with  $a_i > 0$ , a simple linear transformation reduces it to the form in (1) and the theorem yields its volume as

$$a_1 \cdots a_n \cdot 2^n \frac{\Gamma(1+1/p_1) \cdots \Gamma(1+1/p_n)}{\Gamma(1/p_1+\cdots+1/p_n+1)}.$$

FIGURE 2 shows two ellipsoids in  $\mathbb{R}^3$  to give readers an idea of their appearance.



**Figure 2** (a)  $16|x_1|^4 + 3|x_2|^{1/2} + |x_3| \le 1$ ; (b)  $16|x_1|^2 + |x_2|^2 + 4|x_3|^{1/2} \le 1$ 

**Remark** After I obtained this result, Dr. J. M. Borwein, at Simon Fraser University, informed me that the 19th-century French mathematician Dirichlet had obtained a similar result using a different method [3, pp. 153–159]. An *induction-free* proof to the volume formula of the  $l_p$  ball, via the *Laplace transform*, has been given by Bor-

wein and Bailey in [2, pp. 195–197]. Similarly, one can derive an induction-free proof to the volume formula of generalized balls (2) using the Laplace transform. Finally, we remark that more properties on the gamma function and volume of Euclidean balls can be found in Stromberg [7, pp. 394–395].

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# Proof Without Words: A Triangular Sum

$$t(n) = 1 + 2 + \dots + n \to \sum_{k=0}^{n} t(2^{k}) = \frac{1}{3}t(2^{n+1} + 1) - 1$$

$$t(2^{n+1} + 1) - 3:$$

$$0 \to 0 \to 3t(1)$$

$$0 \to 0 \to 3t(2)$$

$$0 \to 0 \to 0 \to 3t(4)$$

$$0 \to 0 \to 0 \to 0 \to 0$$

$$0 \to 0 \to 0 \to 0 \to 0$$

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