Weight Lifting Predictive Model

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Executive Summary

An experiement was designed where subjects wore sensors and did bicep curls in 5 different manners, one using correct form and the others being incorrect form. The idea was to see if the quality of the exercise could be assessed without the need for a live trainer to be present.

Data was taken from all of the sensors and other variables were derived from the direct sensor data. This report will attempt to determine a prediction model such that one could classify in which of the 5 manners the exercise was done from the sensor data and thereby provide feedback to the user about the quality of their exercising.

```
#Data URLs - for Reference
training.url <- 'http://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv'
test.cases.url <- 'http://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv'

#read downloaded data from working directory
train <- read.csv("./pml-training.csv", na.strings=c("NA","#DIV/0!",""))
test <- read.csv("./pml-testing.csv", na.strings=c("NA","#DIV/0!",""))</pre>
```

Preprocessing the data

The data first needed to be cleaned before a model could be buit on it. The steps below outline how this was accomplished: 1. Remove all the columns where the % of NA values is greater than 0.2. Remove the demographic fields like user name and the fields that give information about how the test was performed like window and time _stamps. These are columns 1:7.3. Do the same processing on the training and testing set 4. Partition the training set to get a validation set to test on for purposes of determining which model is the most accurate.

```
#Useful class forum discussion on cleaning/ pruning variables

na_count <- data.frame(x = colSums(is.na(train))/(nrow(train)))

na_remove <- which(na_count$x>0)

c.to.remove <- c(1:7, na_remove)

train <- train[_-c.to.remove] #with non-variable data removed

test <- test[_-c.to.remove]

#create validation set from training set

inTrain <- createDataPartition(y = train$classe, p=0.75, list=FALSE)

training <- train[inTrain,]

validation <- train[-inTrain,]
```

Model 1 - Random Forest

The first model tested will use the random forest technique.

```
set.seed(777)
#Configure parallel processing (per article: #https://github.com/lgreski/datasciencectacontent/blob/master/markdown/pml-rand
omForestPerformance.md)
cluster <- makeCluster(detectCores() - 1) # convention to leave 1 core for OS
registerDoParallel(cluster)
#create model
fitControlRF <- trainControl(method = "cv", number = 5, allowParallel = TRUE)
modFitRF <- train(classe ~ ., method="rf", data = training, trControl=fitControlRF)
#De-register parallel processing cluster
stopCluster(cluster)
registerDoSEQ()
#predict on validation set
predModRF <- predict(modFitRF, validation[,-53])
RF <- confusionMatrix(validation$classe, predModRF)</pre>
```

Model 2 - Boosting

The second model tested will use the boosting technique

```
set.seed(777)

#Configure parallel processing
cluster <- makeCluster(detectCores() - 1) # convention to leave 1 core for OS
registerDoParallel(cluster)

#create model
fitControlGBM <- trainControl(method = "cv", number = 5, allowParallel = TRUE)

modFitGBM <- train(classe ~ ., method="gbm", data = training, trControl=fitControlGBM, verbose = FALSE)

#De-register parallel processing cluster
stopCluster(cluster)
registerDoSEQ()

#predict on validation set
predModGBM <- predict(modFitGBM, validation[,-53])
GBM <- confusionMatrix(validation$classe, predModGBM)</pre>
```

Model 3 - Linear Discriminant Analysis

The third model tested will use the linear discriminant analysis technique.

```
set.seed(777)
#Configure parallel processing
cluster <- makeCluster(detectCores() - 1) # convention to leave 1 core for OS
registerDoParallel(cluster)
#Create model
fitControlLDA <- trainControl(method = "cv", number = 5, allowParallel = TRUE)

modFitLDA <- train(classe ~ ., method="lda", data = training, trControl=fitControlLDA)

#De-register parallel processing cluster
stopCluster(cluster)
registerDoSEQ()

#predict on validation set
predModLDA <- predict(modFitLDA, validation[,-53])
LDA <- confusionMatrix(validation$classe, predModLDA)</pre>
```

Results and Analysis

As seen in Table 1, which shows the accuracy and the out of sample error for the three modeling methods tried, random forest appears to have the best predictive results with the lowest out of sample error.

Out of sample error was calculated for the validation set as [1-accuracy].

```
Acc <- rbind("LDA" = LDA$overall["Accuracy"], "GBM" = GBM$overall["Accuracy"], "RF" = RF$overall["Accuracy"])

OutSamError <- 100*(1-Acc)
colnames(OutSamError) <- c("OutSampleError")

Results <- round(cbind(100*Acc, OutSamError), 2)

kable(Results, caption = "Table 1")
```

Tahla 1

AccuracyOutSampleError

LDA	70.35	29.65
GBM	95.96	4.04
RF	99.37	0.63

Data Exploration

It is interesting to note that the three different modeling methods each chose slightly different variables to be the most important, although each weighted magnet_dumbell_z and y and the pitch_forearm heavily.

```
varLDA <- as.matrix(varImp(modFitLDA)$importance)
varGBM <- as.matrix(varImp(modFitCBM)$importance)
varRF <- as.matrix(varImp(modFitRF)$importance)

varimp <- varimp <- merge(varRF, varGBM, by = "row.names", all = TRUE)

rownames(varimp) <- varimp[,1]
varimp <- varimp[,-1]
varimp <- merge(varimp, varLDA, by="row.names", all=TRUE)
colnames(varimp) <- c("variable", "RF", "GBM", "LDA-A", "LDA-B","LDA-C","LDA-D", "LDA-E")
varimp <- tbl_df(varimp)
varimp <- arrange(varimp, desc(RF), desc(GBM))

varimp[,2:8] <- round(varimp[,2:8], 1)
kable(varimp, caption = "Table 2")</pre>
```

Table 2

```
RF GBMLDA-ALDA-BLDA-CLDA-DLDA-E
variable
roll arm
                 9.5 4.7 34.1 34.1 34.1 34.1 24.4
yaw_dumbbell
                 8.8 1.9 20.5 20.5 20.5 40.0 11.8
accel forearm z
                 8.1 10.5
                          7.1
                               7.1
                                    7.1
gyros_dumbbell y
                 7.5 9.4 8.4 13.5
                                    8.9 12.1 13.5
magnet_forearm_y
                 6.7 2.1 18.6 36.6 27.6 24.6 36.6
accel_arm_x
                 6.6 3.4 49.8 73.5 61.2 49.8 73.5
magnet_forearm_x
                 5.9 4.8 37.5 69.5 32.2 32.2 69.5
magnet_arm_y
                 5.9 5.9 38.2 76.2 67.5 38.2 76.2
accel dumbbell x
                 5.7 6.9 57.4 57.4 57.4 57.4 48.1
                 5.7 0.9 9.3 12.8 10.7 21.8 12.8
yaw_forearm
magnet arm x
                 5.6 4.6 51.9 78.2 64.5 51.9 78.2
magnet_arm_z
                 5.3 8.9 51.9 51.9 51.9 51.9 39.9
pitch arm
                 4.8 1.5 27.1 43.0 49.2 27.1 43.0
                 3.9 4.0 7.4 7.4 8.2 7.4 7.2
gyros_arm_y
                 3.8 2.8 52.7 52.7 52.7 70.0 43.6
pitch dumbbell
accel_forearm_y
                 36 22 299 28 28 251 299
accel_arm_y
                 3.0 1.0 11.9 16.4 23.7 11.9 16.4
gyros_dumbbell_x
                 2.7 2.5 3.0 2.3 2.8
                                         7.5
                                              3.0
gyros_arm_x
                 2.5 1.7 6.9 4.8
                                    6.3 4.8
                 2.4 0.5 4.1
                               4.1
                                    4.1
gyros_forearm_y
                 2.3 1.5 31.0 28.6 11.9 25.6 31.0
accel arm z
total_accel belt
                19 12 64 87 203 87
                                              8.7
total_accel_arm
                1.8 0.9 31.7 38.8 31.3 18.3 38.8
gyros_belt_y
                 1.8 3.3 3.5 7.0 1.0 4.9
total_accel_forearm 1.7 2.3 23.4 26.2 31.8 23.4 26.2
gyros belt x
                 1.5 1.2 6.2 6.2 6.2 6.2 0.9
gyros dumbbell z
                 1.1 1.1
                          5.1 5.1
                                    5.1 5.1
                                               2.9
accel_belt_y
                 1.0 0.0 7.0 7.0 7.0 7.0
                                               5.6
gyros_forearm_z
                 1.0 1.3 7.2 7.2 7.2 7.2 3.9
accel_belt_x
                 0.8 0.6 11.1 10.7 15.4
                                          8.8 11.1
gyros forearm x
                 0.3 0.6 2.5
                              6.9 3.3
                                         6.2
gyros_arm_z
                 0.0 0.1
                          2.3
                               0.0
                                    3.4
```

Results of applying the model to the test data

The random forest model was applied to the test data. The results can be found in Table 3.

```
PredTestRF <- predict(modFitRF, test)
scenario <- c(1:20)
TestResults <- cbind(scenario, results = as.character(PredTestRF))
kable(TestResults, caption = "Table 3")</pre>
```

Table 3

scenarioresults