



# Métriques extrinsèques pour l'évaluation de la compression 3D

# Existing Extrinsic Metrics

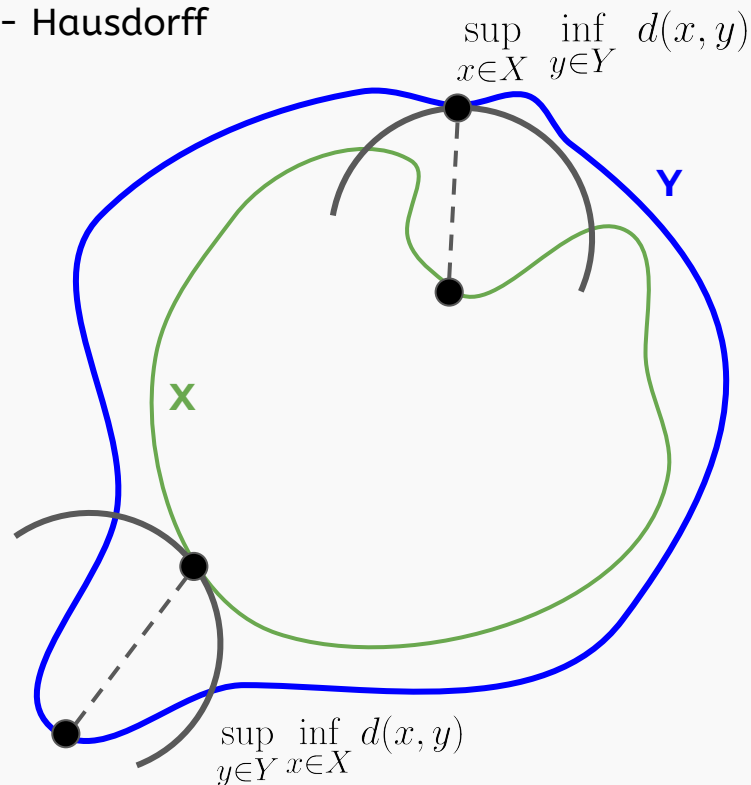
Metrics	Hausdorff [Cignoni 1998]	Completeness [Seitz 2006]	Accuracy [Seitz 2006]	DAME <sup>1</sup> [Váša 2012]	MSDM <sup>2</sup> [Lavoué 2006]	MSDM2 <sup>2</sup> [Lavoué 2011]
Computation method(s)	Euclidean distance			Dihedral Angles	Contrast, Structure, Curvature	
Type	Geometric	Geometric and Global for 3D Reconstruction		Perceptual		Perceptual Multiscale

<sup>1</sup>DAME : *Dihedral Angle Mesh Error*

<sup>2</sup>MSDM : *Multi-Scale Distortion Measure*

# Existing Extrinsic Metrics

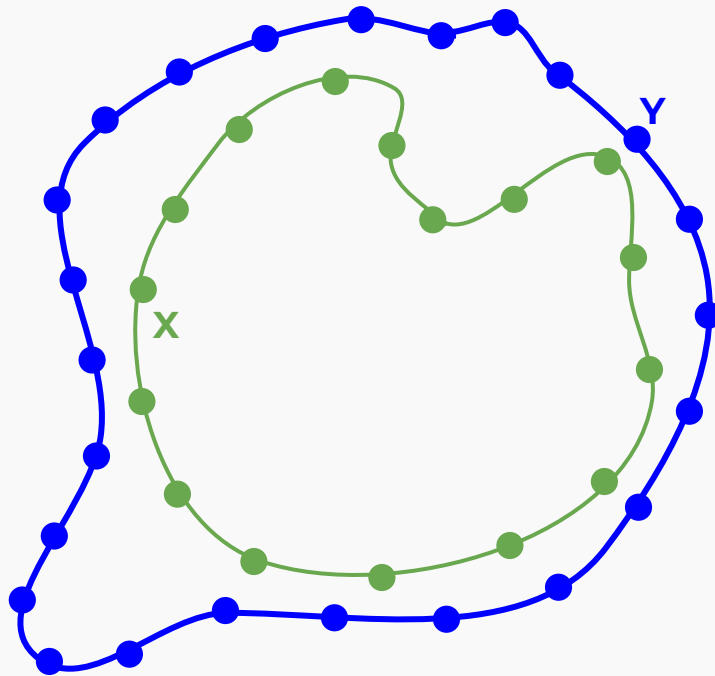
Geometric Metrics - Hausdorff  
[Hausdorff 1962]



**X - Reference 3D Model**  
**Y - Reconstructed 3D Model**

# Existing Extrinsic Metrics

Geometric Metrics



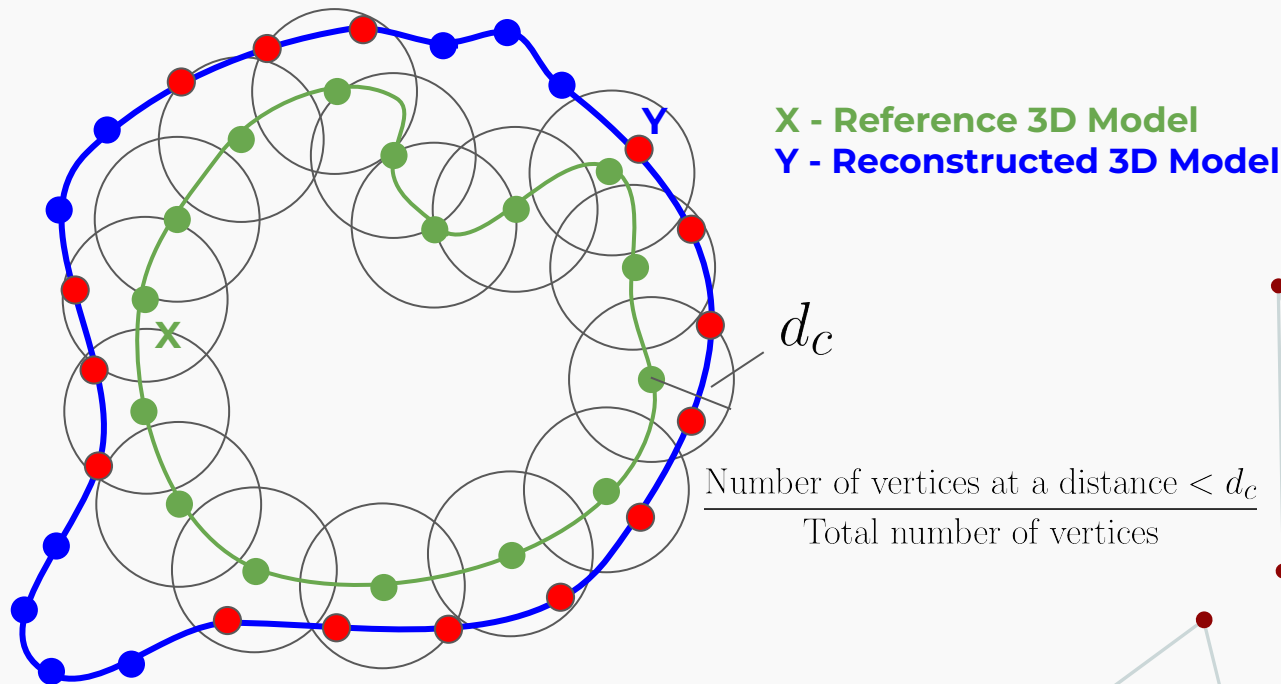
X - Reference 3D Model

Y - Reconstructed 3D Model

# Existing Extrinsic Metrics

Geometric Metrics - Completeness

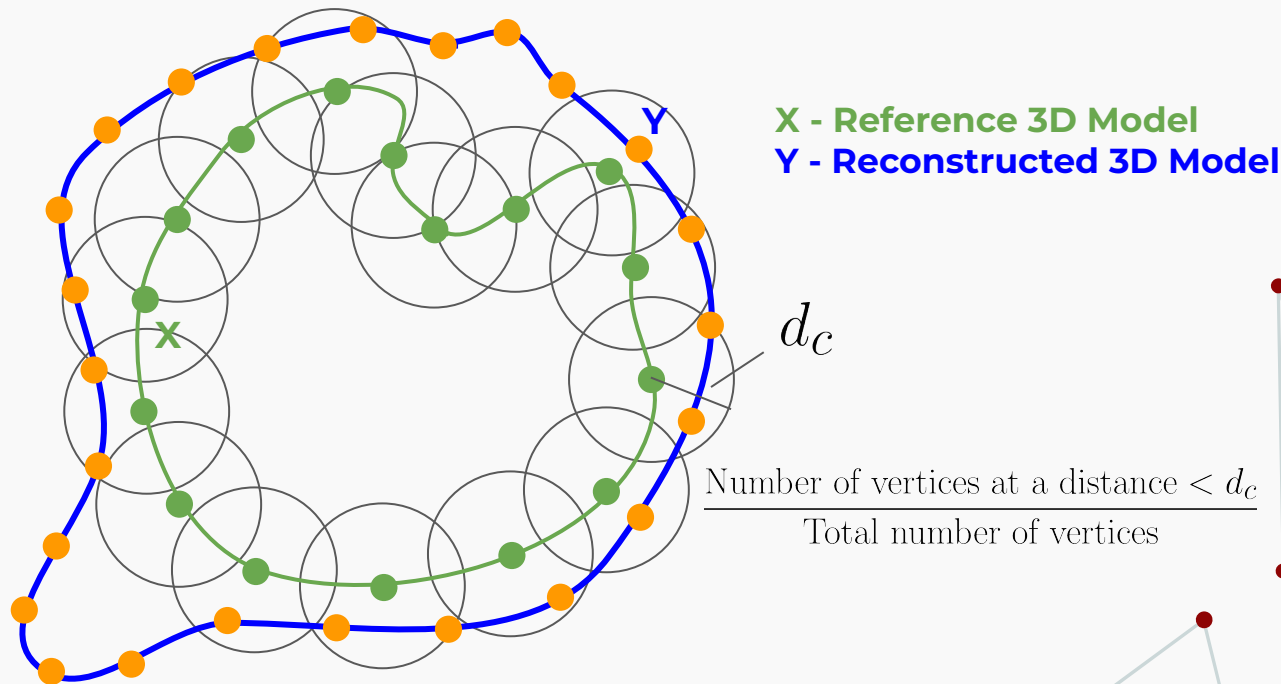
[Seitz 2006]



# Existing Extrinsic Metrics

## Geometric Metrics - Completeness

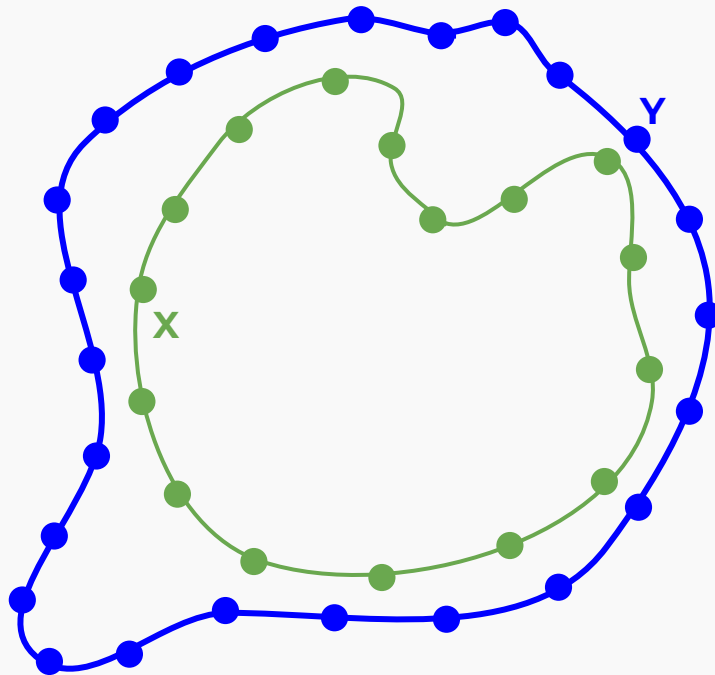
[Seitz 2006]



# Existing Extrinsic Metrics

Geometric Metrics - Accuracy

[Seitz 2006]



X - Reference 3D Model

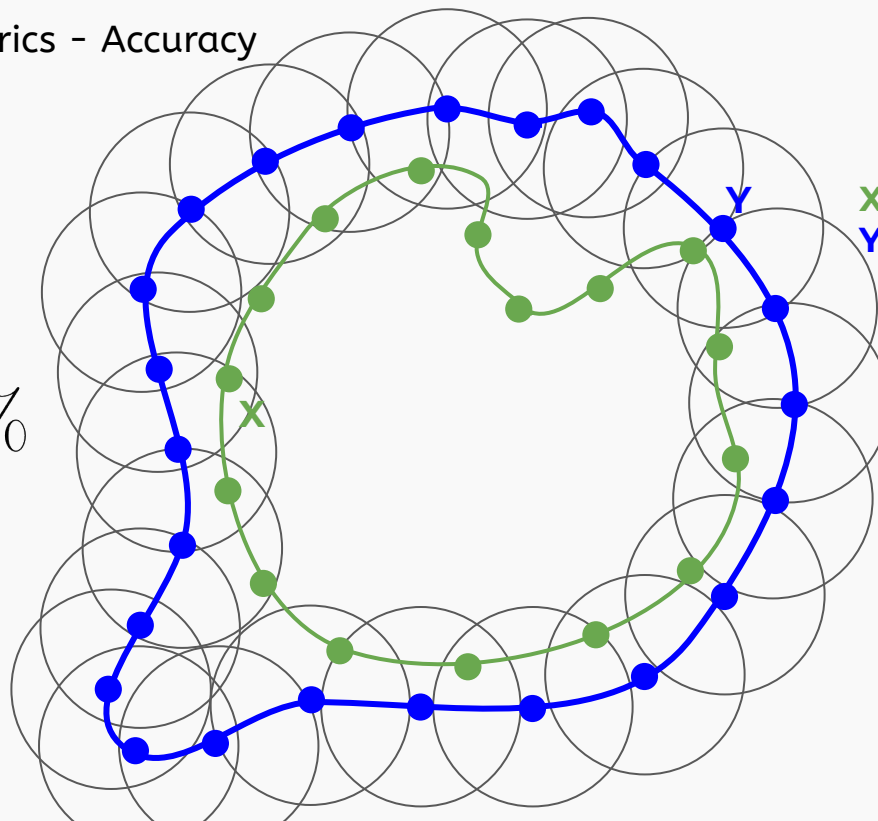
Y - Reconstructed 3D Model

# Existing Extrinsic Metrics

Geometric Metrics - Accuracy

[Seitz 2006]

$$T_a = 75\%$$



X - Reference 3D Model

Y - Reconstructed 3D Model

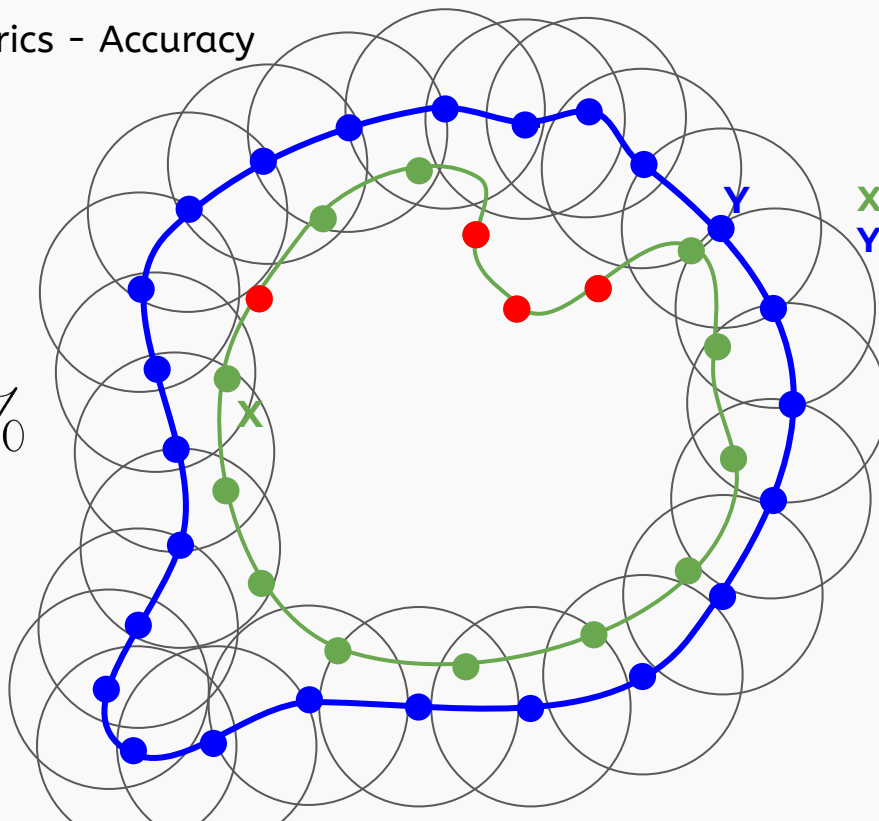


# Existing Extrinsic Metrics

Geometric Metrics - Accuracy

[Seitz 2006]

$$T_a = 75\%$$



X - Reference 3D Model

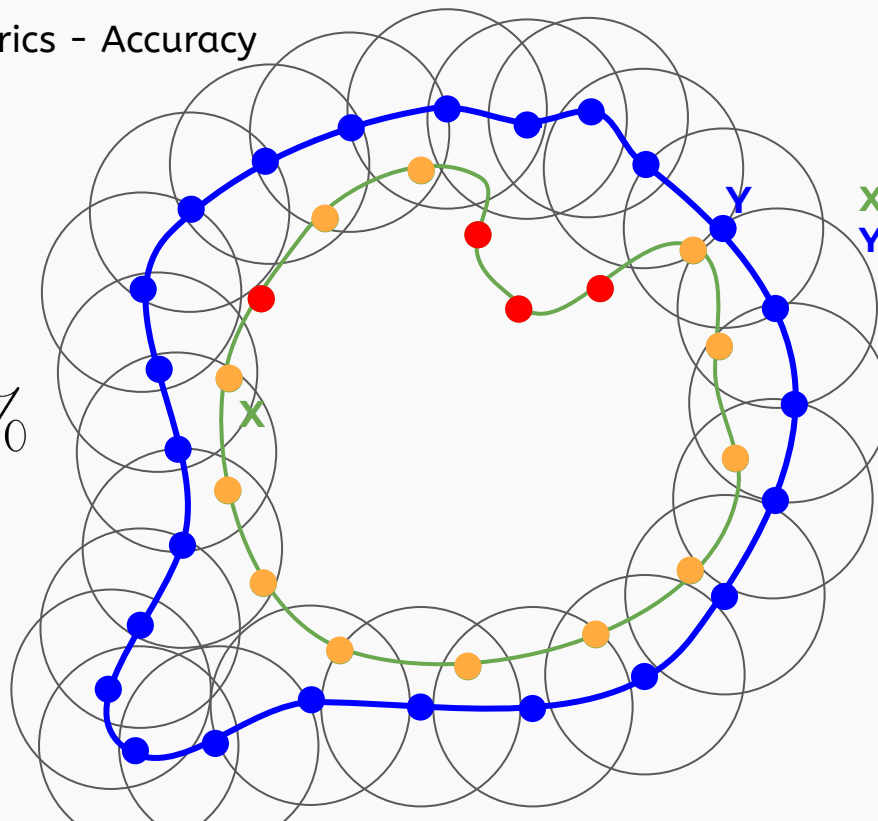
Y - Reconstructed 3D Model

# Existing Extrinsic Metrics

Geometric Metrics - Accuracy

[Seitz 2006]

$$T_a = 75\%$$



X - Reference 3D Model

Y - Reconstructed 3D Model

# Existing Extrinsic Metrics

Metrics	Hausdorff [Cignoni 1998]	Completeness [Seitz 2006]	Accuracy [Seitz 2006]	DAME <sup>1</sup> [Váša 2012]	MSDM <sup>2</sup> [Lavoué 2006]	MSDM2 <sup>2</sup> [Lavoué 2011]
Computation method(s)	Euclidean distance			Dihedral Angles	Contrast, Structure, Curvature	
Type	Geometric	Geometric and Global for 3D Reconstruction		Perceptual		Perceptual Multiscale

<sup>1</sup>DAME : *Dihedral Angle Mesh Error*

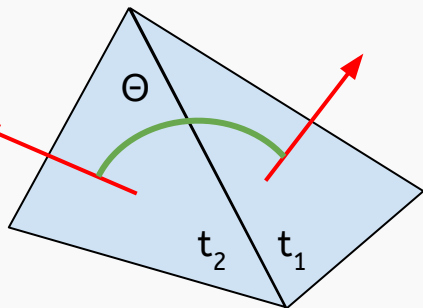
<sup>2</sup>MSDM : *Multi-Scale Distortion Measure*

# Existing Extrinsic Metrics

## Perceptual Metrics - DAME

[Váša 2012]

*Dihedral Angle Mesh Error*



$$\text{DAME} = \frac{1}{||\Omega||} \sum_{\{t_1, t_2\} \in \Omega} ||\theta_{t_1, t_2} - \overline{\theta_{t_1, t_2}}|| \cdot m_{t_1, t_2} \cdot (w_{t_1} + w_{t_2})$$

↓  
Set of Triangle  
Pairs

↓  
Dihedral angle  
difference between  
 $t_1$  and  $t_2$

↓  
Masking effect

↓  
Visibility

# Existing Extrinsic Metrics

## Perceptual Metrics - MSDM

[Lavoué 2006]

*Mesh Structural Distortion Measure*

$$C(\tilde{x}_{ref}, \tilde{x}_r) = \frac{\|\sigma_{\tilde{x}_{ref}} - \sigma_{\tilde{x}_r}\|}{\max(\sigma_{\tilde{x}_{ref}}, \sigma_{\tilde{x}_r})}$$

**Contrast**

$$L(\tilde{x}_{ref}, \tilde{x}_r) = \frac{\|\mu_{\tilde{x}_{ref}} - \mu_{\tilde{x}_r}\|}{\max(\mu_{\tilde{x}_{ref}}, \mu_{\tilde{x}_r})}$$

**Curvature**

$$S(\tilde{x}_{ref}, \tilde{x}_r) = \frac{\|\sigma_{\tilde{x}_{ref}} \sigma_{\tilde{x}_r} - \sigma_{\tilde{x}_{ref} \tilde{x}_r}\|}{\sigma_{\tilde{x}_{ref}} \sigma_{\tilde{x}_r}}$$

**Structure**

$\mu$  : mean of curvature on a given neighborhood

$\sigma$  : standard deviation of curvature on a given neighborhood

# Existing Extrinsic Metrics

## Perceptual Metrics - MSDM2

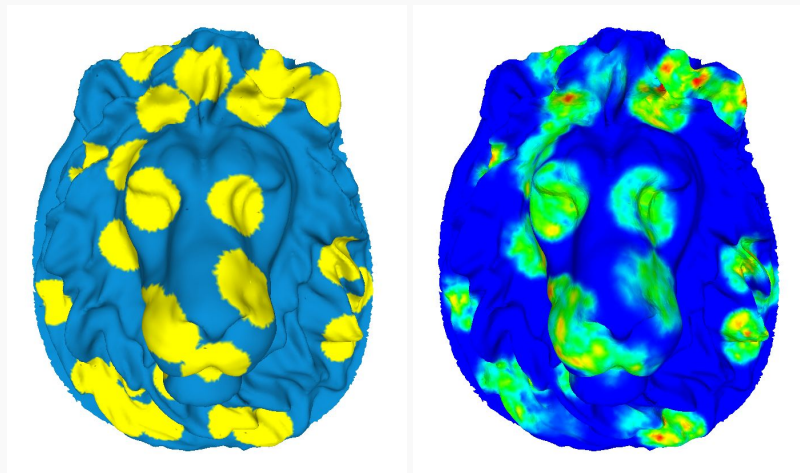
[Lavoué 2011]

*Mesh Structural Distortion Measure 2*

Perceptual

Contrast, Structure, Curvature

Multiscale



MSDM2 response on local noise