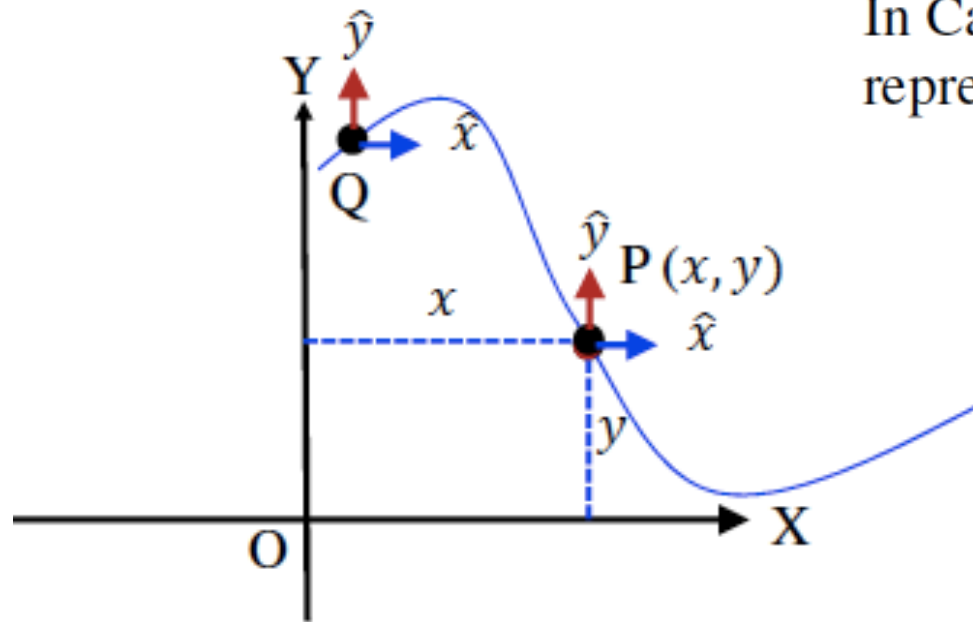


Lecture - 8

Coordinate Systems



In Cartesian coordinate position P is represented by (x, y) .

$$\overrightarrow{OP} = \vec{r} = x \hat{x} + y \hat{y}$$

Note:

- \hat{x} and \hat{y} are unit vectors **pointing the increasing direction** of x and y .

\hat{x} is the unit vector perpendicular to $x = \text{constant}$ line
 \hat{y} is the unit vector perpendicular to $y = \text{constant}$ line

Velocity $\vec{v} = \frac{d\vec{r}}{dt} = \frac{d}{dt} (x \hat{x} + y \hat{y})$

$$= \dot{x} \hat{x} + x \frac{d\hat{x}}{dt} + \dot{y} \hat{y} + y \frac{d\hat{y}}{dt}$$

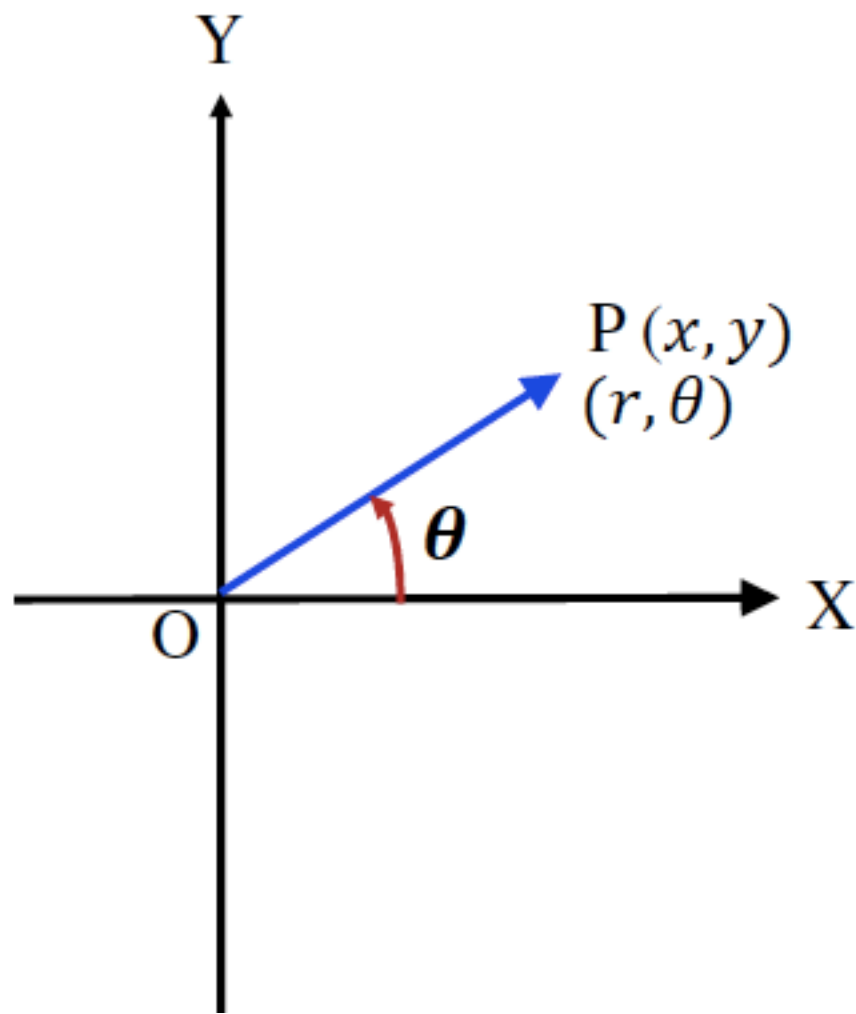
$$\vec{v} = \dot{x} \hat{x} + \dot{y} \hat{y}$$

$$\vec{a} = \frac{d\vec{v}}{dt} = \ddot{x} \hat{x} + \ddot{y} \hat{y}$$

Since,

$$\frac{d\hat{x}}{dt} = \frac{d\hat{y}}{dt} = 0$$

Plane-polar coordinate



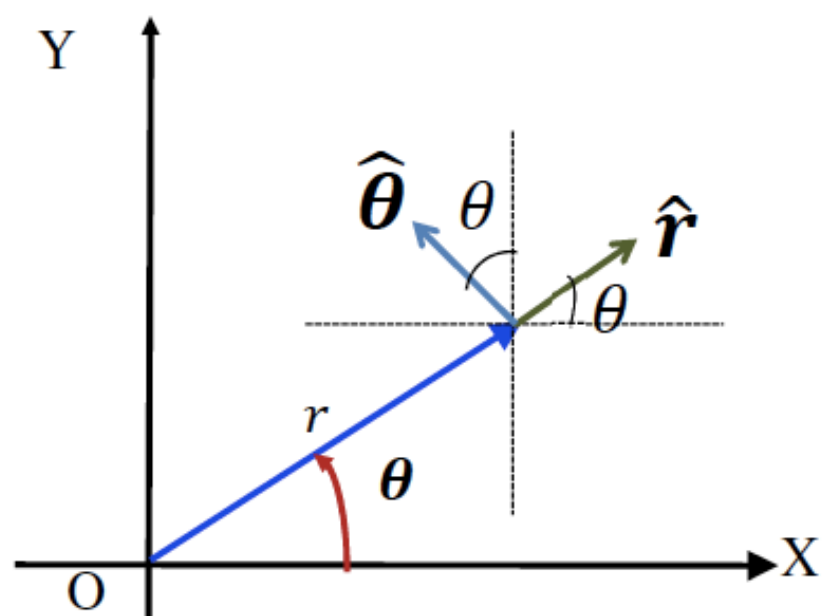
Each point $P(x, y)$ on the plane can also be represented by its distance (r) from the origin O and the angle (θ) OP makes with X -axis.

Relationship with Cartesian coordinates

$$x = r \cos \theta \quad \& \quad y = r \sin \theta$$

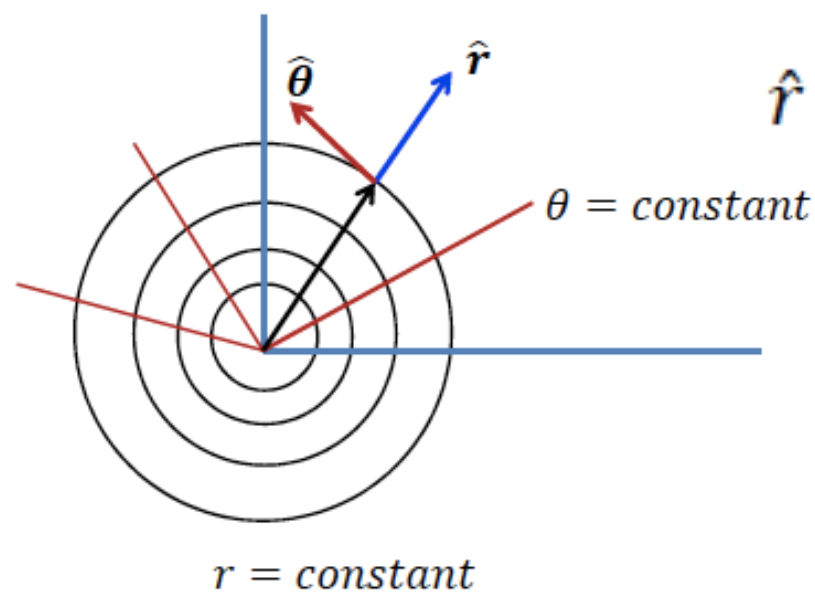
Thus ,
$$r = (x^2 + y^2)^{1/2}$$

$$\theta = \tan^{-1} \frac{y}{x}$$



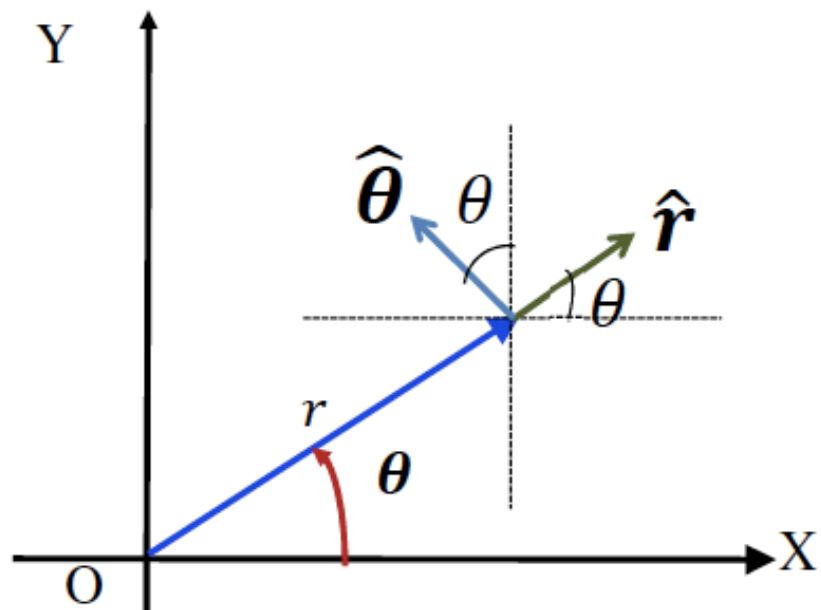
- \hat{r} and $\hat{\theta}$ are unit vector along increasing direction of coordinate r and θ .

\hat{r} and $\hat{\theta}$ are orthogonal: $\hat{r} \cdot \hat{\theta} = 0$



\hat{r} is the unit vector perpendicular to $r = \text{constant}$

$\hat{\theta}$ is the unit vector perpendicular to $\theta = \text{constant}$



$$\vec{r} = r \cos \theta \hat{x} + r \sin \theta \hat{y}$$

$$\hat{r} = \frac{\vec{r}}{|\vec{r}|}$$

$$\hat{r} = \frac{\partial \vec{r}}{\partial r}$$

$$\begin{aligned} \hat{r} &= \cos \theta \hat{x} + \sin \theta \hat{y} \\ \hat{\theta} &= -\sin \theta \hat{x} + \cos \theta \hat{y} \end{aligned}$$

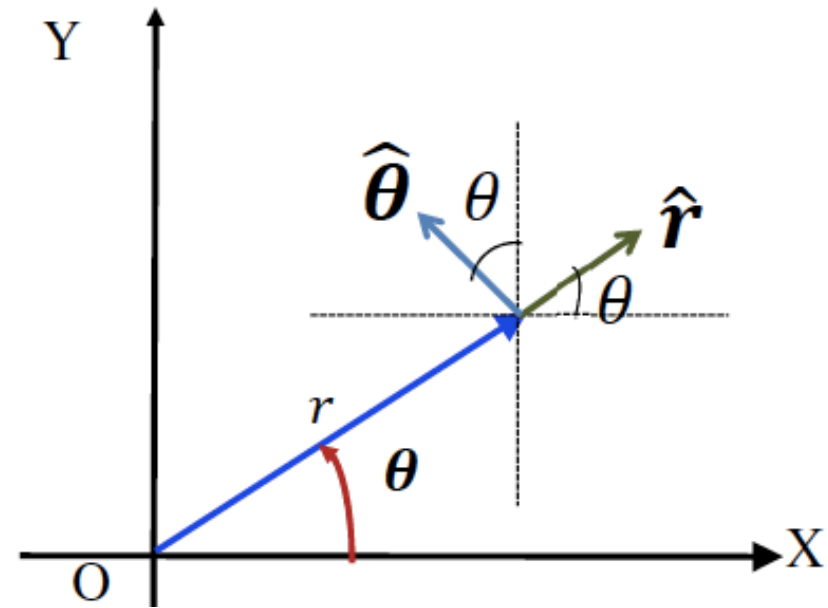
$$\hat{\theta} = \frac{\partial \hat{r}}{\partial \theta}$$

$$\vec{r} = r \hat{r}$$

$$\vec{v} = \frac{d\vec{r}}{dt} = \frac{d}{dt} (r \hat{r}) = \frac{dr}{dt} \hat{r} + r \frac{d\hat{r}}{dt} = \dot{r} \hat{r} + r \frac{\partial \hat{r}}{\partial \theta} \frac{d\theta}{dt}$$

$$\vec{v} = \dot{r} \hat{r} + r \dot{\theta} \hat{\theta}$$

Plane-polar coordinate



$$\vec{r} = r \cos \theta \hat{x} + r \sin \theta \hat{y}$$

$$\hat{r} = \frac{\vec{r}}{|\vec{r}|}$$

$$\hat{r} = \frac{\partial \vec{r}}{\partial r}$$

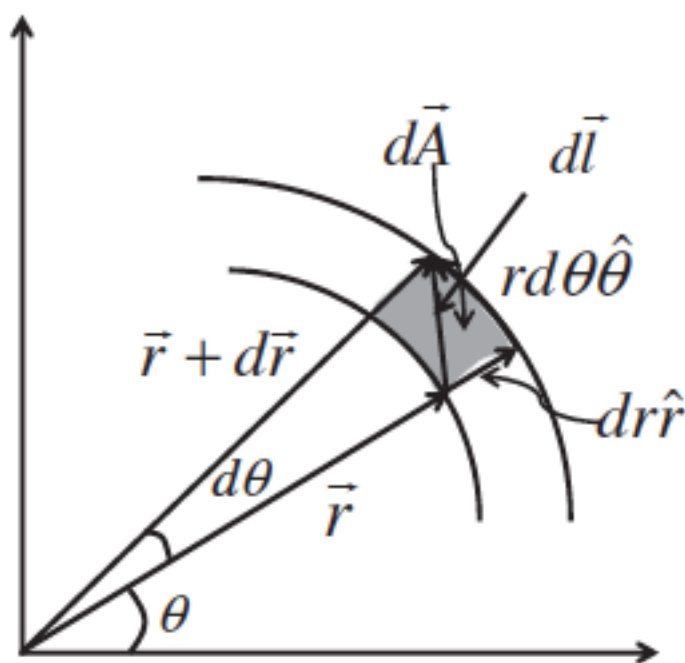
$$\begin{aligned} \hat{r} &= \cos \theta \hat{x} + \sin \theta \hat{y} \\ \hat{\theta} &= -\sin \theta \hat{x} + \cos \theta \hat{y} \end{aligned}$$

$$\hat{\theta} = \frac{\partial \hat{r}}{\partial \theta}$$

$$\vec{r} = r \hat{r}$$

$$\vec{v} = \frac{d\vec{r}}{dt} = \frac{d}{dt} (r \hat{r}) = \frac{dr}{dt} \hat{r} + r \frac{d\hat{r}}{dt} = \dot{r} \hat{r} + r \frac{\partial \hat{r}}{\partial \theta} \frac{d\theta}{dt}$$

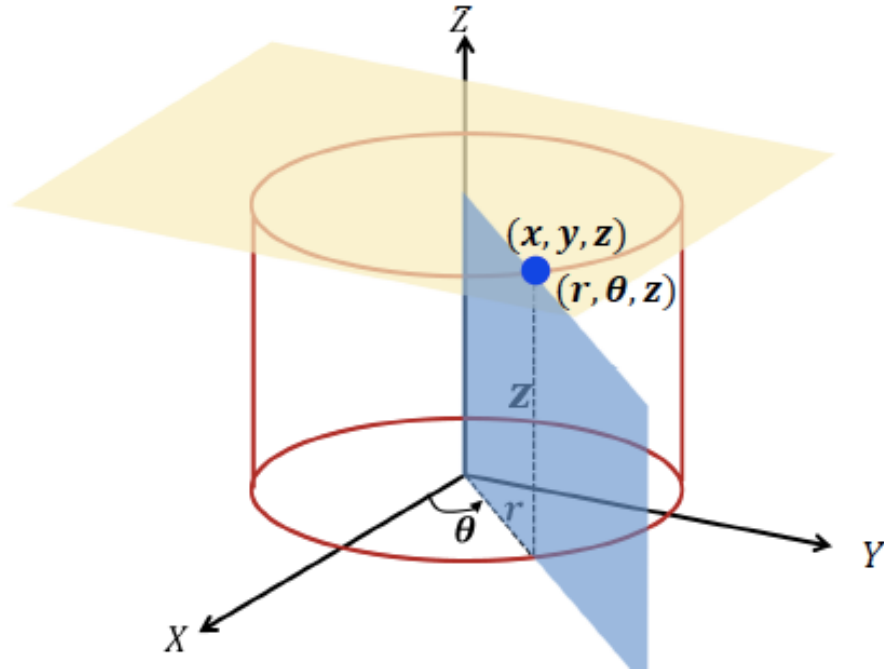
$$\vec{v} = \dot{r} \hat{r} + r \dot{\theta} \hat{\theta}$$



Line element: $d\vec{l} = dr\hat{r} + r d\theta\hat{\theta}$

Surface element: $d\vec{A} = dr\hat{r} \times r d\theta\hat{\theta} = r dr d\theta\hat{k}$

Cylindrical coordinate System



Polar coordinate unit vectors $(\hat{r}, \hat{\theta})$ + additional unit vector in the z –direction.

□ $\hat{r}, \hat{\theta}$ and \hat{z} are unit vectors along increasing direction of coordinates r, θ and z .

How to specify a point P in space?
 (r, θ, z)

- ✓ z is the Height from the XY -plane
- ✓ Coordinate of the foot of the point in XY plane.

$$\begin{aligned}x &= r \cos \theta \\y &= r \sin \theta \\z &= z\end{aligned}$$

Reverse transformation

$$\begin{aligned}r &= (x^2 + y^2)^{1/2} \\ \theta &= \tan^{-1} \frac{y}{x} \\ z &= z\end{aligned}$$

Line element:

$$d\vec{l} = dr\hat{r} + r d\theta\hat{\theta} + dz\hat{z}$$

Surface element with fix r :

$$d\vec{A} = r d\theta dz \hat{r}$$

Volume element: $dv = r dr d\theta dz$