

All Answers are to be written on the Question paper itself

Name of Student ----- Enrolment No. -----

Department / School -----

**BENNETT UNIVERSITY, GREATER NOIDA**

**Mid Term Examination, Even SEMESTER 2019-20**

COURSE CODE: EPHY108L

MAX. DURATION: 1 Hr

COURSE NAME: **Mechanics**

MAX. MARKS: 25

- **Notes :**
- Answers are to be written on the Question paper itself
- Answers must be written only in the space provided for each answer
- Answers written elsewhere will not be given marks
- No additional sheets can be attached to the question paper
- All questions are mandatory. There are 6 questions, Q.1 has four subparts.
- Rough work must be carried out in the space provided at the back of the question paper

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Q.1 (i) Angular momentum of a body is  $\mathbf{L} = 5\hat{i} + 6\hat{j} + 78\hat{k}$ , two external torques act on the body. One torque is  $\boldsymbol{\tau}_1 = 7\hat{i} + 10\hat{j} + 3\hat{k}$ , what is the other torque? Give justification (1 Mark)

Q. 1 (ii) A particle moves in a circle of radius 1 m under the influence of a force. Each time it completes a turn, its kinetic energy increases by 1 J. Is the force conservative/non-conservative. Give reason. (1 Mark)



**Q.1 (iii)** Does value of angular momentum depend on the choice of origin? Answer in yes/No.  
(0.5 Marks)

**Q.1 (iv)** If potential energy in a region is given by  $V = 5x$ , what is the y-component of force  $F$ , in that region? Justify your answer. (1 Mark)

**Q.2** An object is moving such that it has a constant acceleration  $a$  and its mass is increasing at a constant rate  $b$ . The object starts from rest. What is the force acting on it at an instant  $t$  when its mass is  $m$ ? (2 Marks)

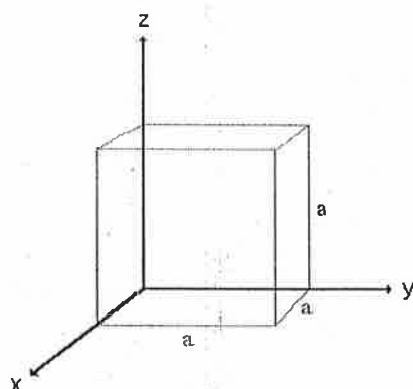


Q.3 A particle is moving in a circle of radius  $a$  with angular velocity  $\omega = \alpha t + \beta t^2$ , where  $\alpha$  and  $\beta$  are constants and  $t$  is time. Find the tangential component of acceleration. Assume origin is at the centre of the circle. (2 Marks)

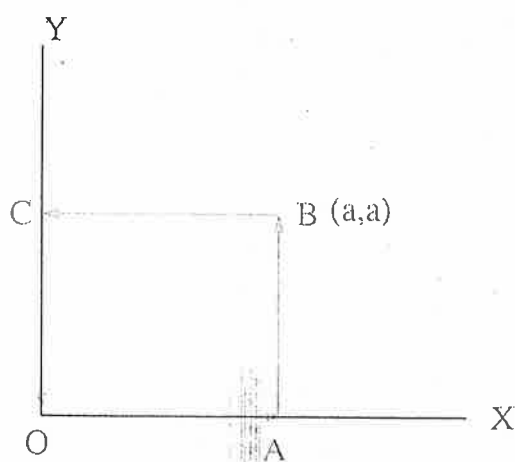
Q.4 Suppose an object has moment of inertia tensor  $I = \begin{pmatrix} I_1 & 0 \\ 0 & I_1 \end{pmatrix}$  about x and y axes. It is rotating with angular velocity  $\omega = \omega_1 \hat{j}$ . What is the direction of its axis of rotation? Find the angular momentum  $L$  in matrix and vector forms. (1.5 Marks)



Q.5 Find the moment of inertia tensor of a solid cube of side  $a$  about  $x$ ,  $y$  and  $z$  axes coinciding with three intersecting edges of the cube as shown in figure below. It has a uniformly distributed mass  $M$ . Write the final answer in matrix form. Show all steps. (8 Marks)



**Q. 6** Consider a force  $\mathbf{F} = y\hat{i} + 2x\hat{j}$ . Calculate work done by this force in going around a closed path which is a square of side  $a$  in the  $xy$  plane (shown below). The motion is in anti-clockwise direction. Calculate curl of  $\mathbf{F}$  and verify Stokes' theorem. Show all steps. (8 Marks)





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### Useful relations (symbols have their usual meanings):

Vector multiplication:

$$\mathbf{A} \cdot \mathbf{B} = AB \cos \theta, \quad |\mathbf{A} \times \mathbf{B}| = AB \sin \theta$$

$$\mathbf{A} \cdot \mathbf{B} = A_x B_x + A_y B_y + A_z B_z$$

$$\mathbf{A} \times \mathbf{B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

Plane polar coordinates:

$$x = r \cos \theta, \quad y = r \sin \theta, \quad \hat{r} = \cos \theta \hat{i} + \sin \theta \hat{j}, \quad \hat{\theta} = -\sin \theta \hat{i} + \cos \theta \hat{j}$$

Kinematics in polar coordinates:

$$\mathbf{r} = r \hat{r}, \quad \mathbf{v} = \dot{r} \hat{r} + r \dot{\theta} \hat{\theta}, \quad \mathbf{a} = (\ddot{r} - r \dot{\theta}^2) \hat{r} + (2\dot{r} \dot{\theta} + r \ddot{\theta}) \hat{\theta}$$

$$\text{Gradient of a scalar function: } \nabla V = \hat{i} \frac{\partial V}{\partial x} + \hat{j} \frac{\partial V}{\partial y} + \hat{k} \frac{\partial V}{\partial z}$$

$$\text{Conservative Force: } \mathbf{F} = -\nabla V$$

$$\text{Curl of a vector: } \nabla \times \mathbf{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix}$$

$$\text{Stokes' Theorem: } \oint_C \mathbf{F} \cdot d\mathbf{l} = \int_S (\nabla \times \mathbf{F}) \cdot d\mathbf{S}$$

Moment of Inertia tensor:

$$I = \begin{pmatrix} I_{xx} & I_{xy} & I_{xz} \\ I_{yx} & I_{yy} & I_{yz} \\ I_{zx} & I_{zy} & I_{zz} \end{pmatrix}$$

$$I_{xx} = \int (y^2 + z^2) dm, \quad I_{yy} = \int (x^2 + z^2) dm, \quad I_{zz} = \int (x^2 + y^2) dm$$

$$I_{xy} = -\int xy dm, \quad I_{xz} = -\int xz dm, \quad I_{yz} = -\int yz dm, \quad I_{yx} = I_{xy}, \quad I_{zx} = I_{xz}, \quad I_{zy} = I_{yz}$$

Rotational motion:

$$\mathbf{L} = \mathbf{r} \times \mathbf{P} = I \boldsymbol{\omega}$$

$$\boldsymbol{\tau} = \mathbf{r} \times \mathbf{F} = \frac{d\mathbf{L}}{dt}$$



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Space for Rough Work