

Neurocomputing

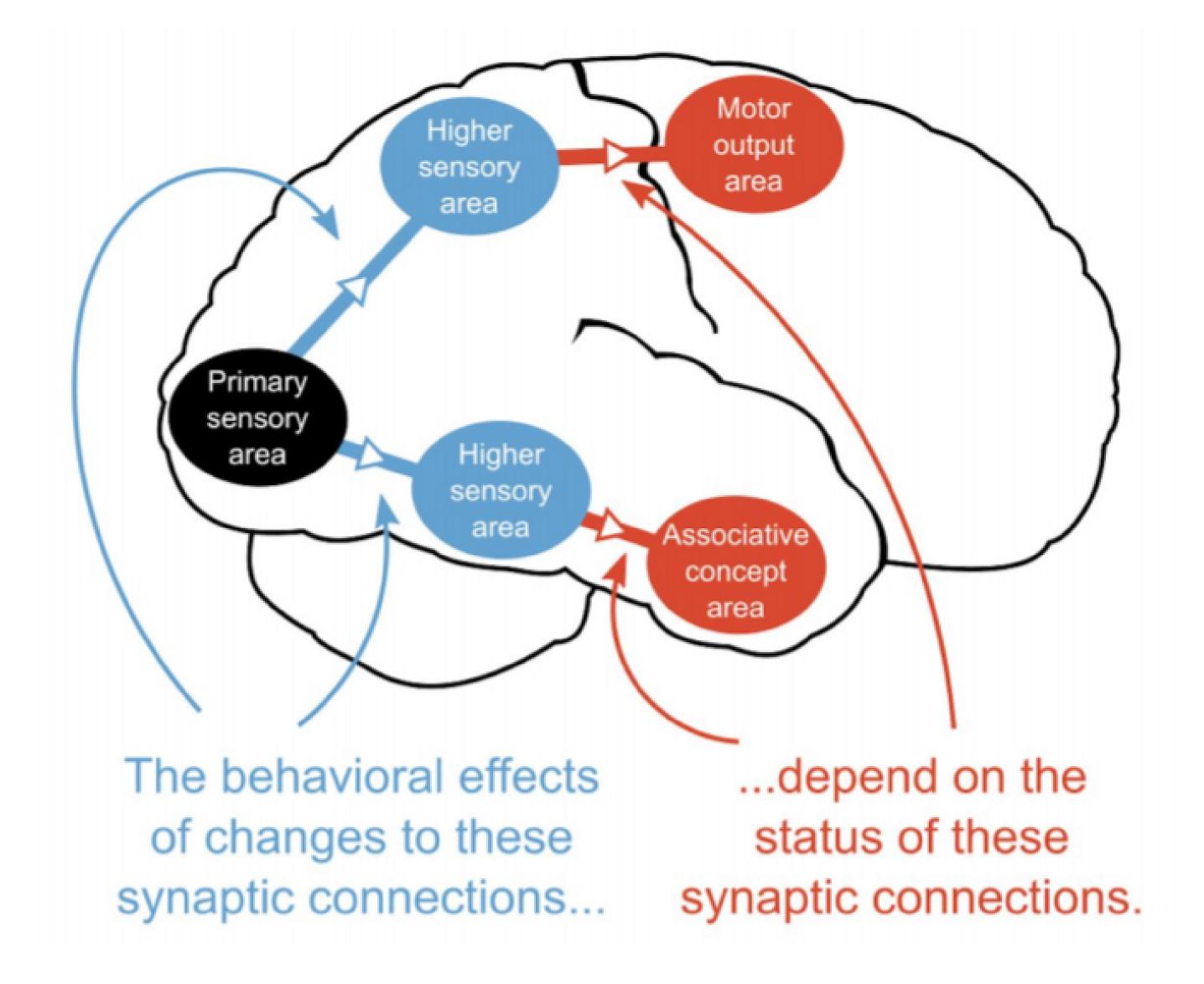
Beyond deep learning

Julien Vitay

Professur für Künstliche Intelligenz - Fakultät für Informatik

1 - Towards biological deep learning?

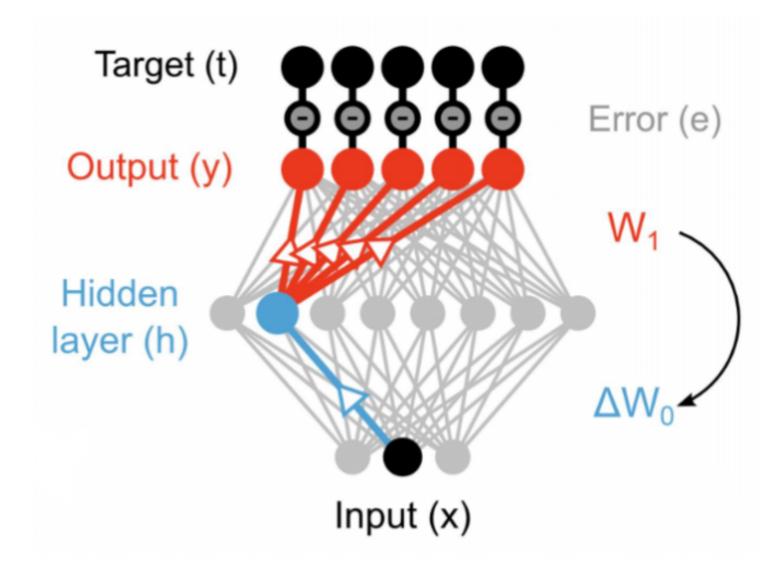
The credit assignment problem



Backpropagation is not biologically plausible

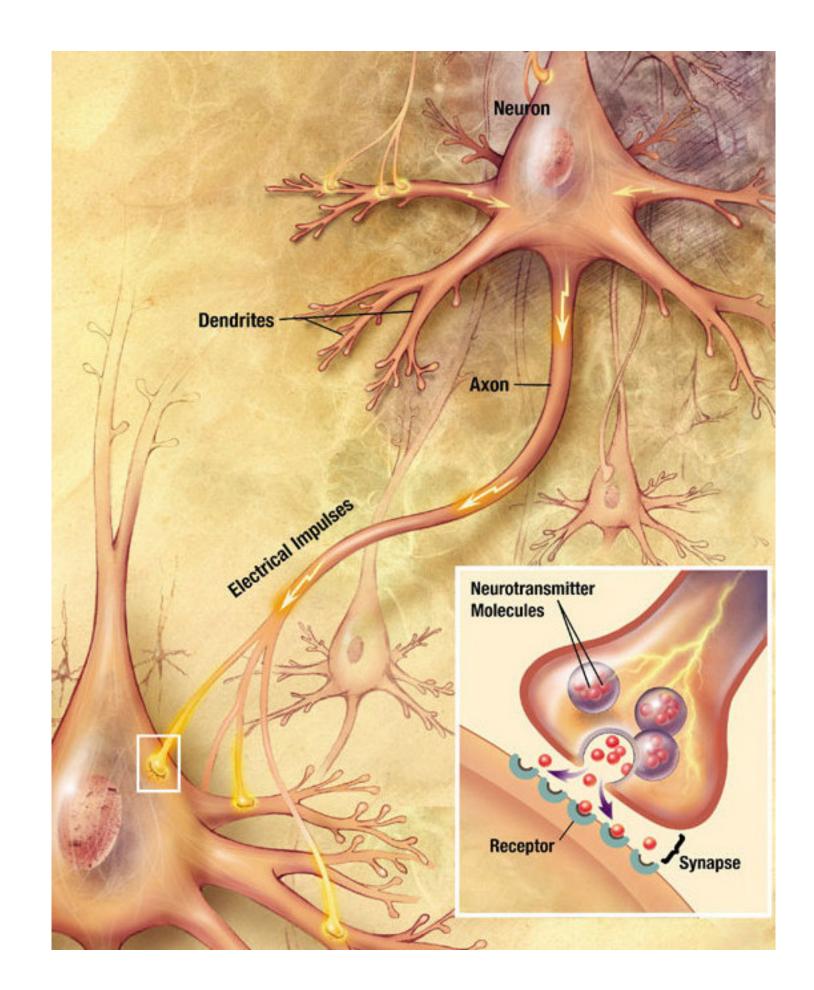
• Backpropagation solves the credit assignment problem by transmitting the error gradient backwards through the weights (\sim synapses).

$$\Delta W_0 = \eta \left(\mathbf{t} - \mathbf{y}
ight) imes W_1 imes \mathbf{x}^T$$

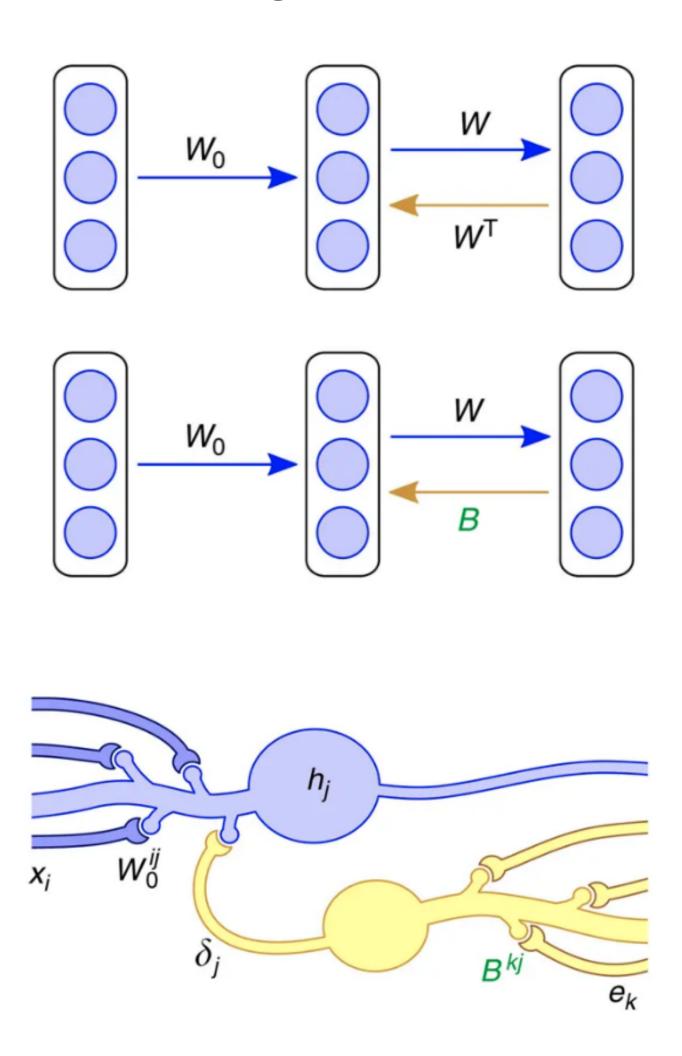


• But information only goes in one direction in the brain: from the presynaptic neuron to the postsynaptic one.

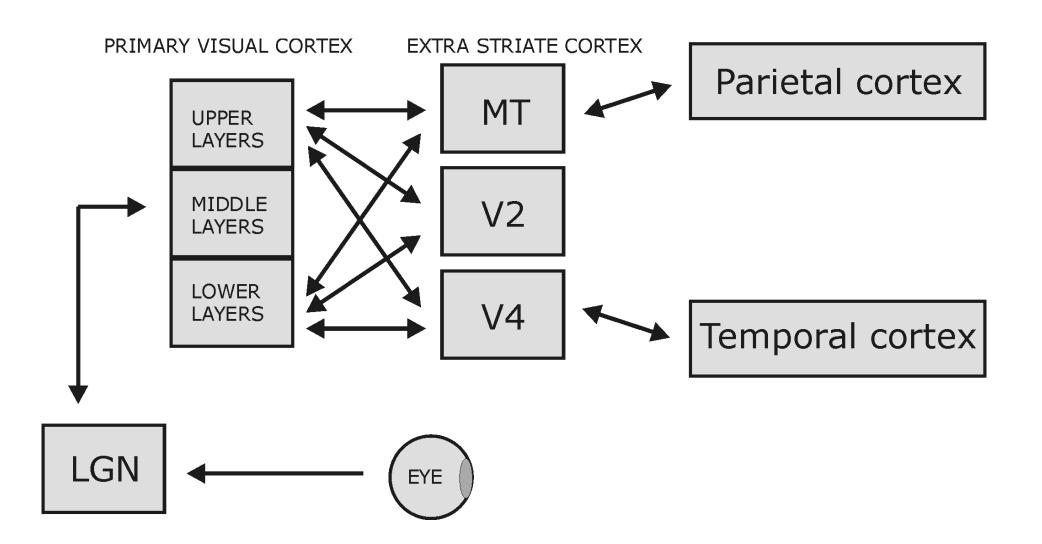
 A synapse does know not the weight of other synapses and cannot transmit anything backwards.



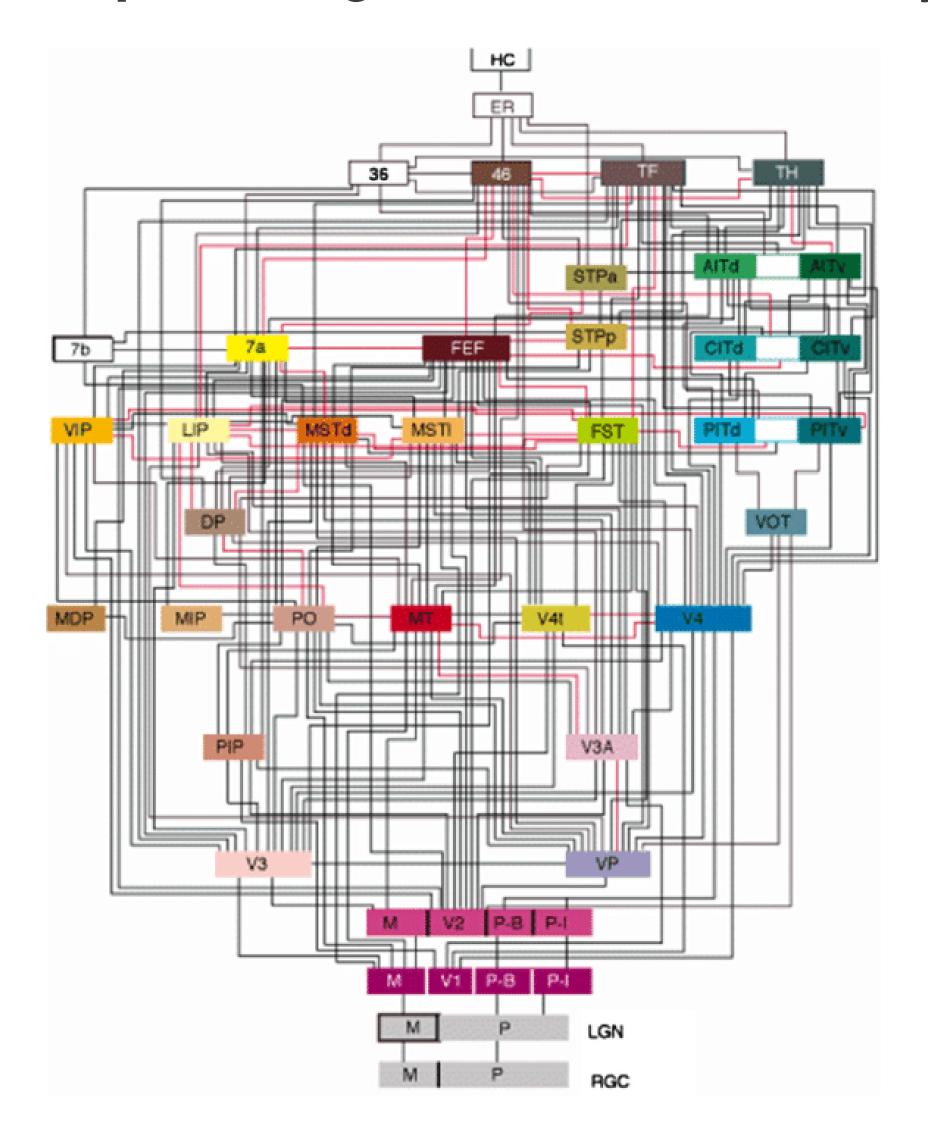
Feedback alignment



- An alternative mechanism consists of backpropagating the error through another set of **feedback weights**.
- Feedback connections are ubiquitous in the brain, especially in the neocortex.
- The feedback weights do not need to learn: they can stay random.
- The mechanism only works for small networks on MNIST until now.



Deep learning architectures are way too simple and unidirectional



- Deep learning architectures are mostly unidirectional, from the input to the output, without feedback connections.
- The brain is totally differently organized: a big "mess" of interconnected areas processing everything in parallel.
- The figure on the left is only for vision, and only for the cerebral cortex: the thalamus, basal ganglia, hippocampus, cerebellum, etc, create additional shortcuts.
- Is the complex structure of the brain just a side effect of evolution, or is it the only possible solution?
- Inductive bias: the choice of the architecture constrains the functions it can perform / learn.

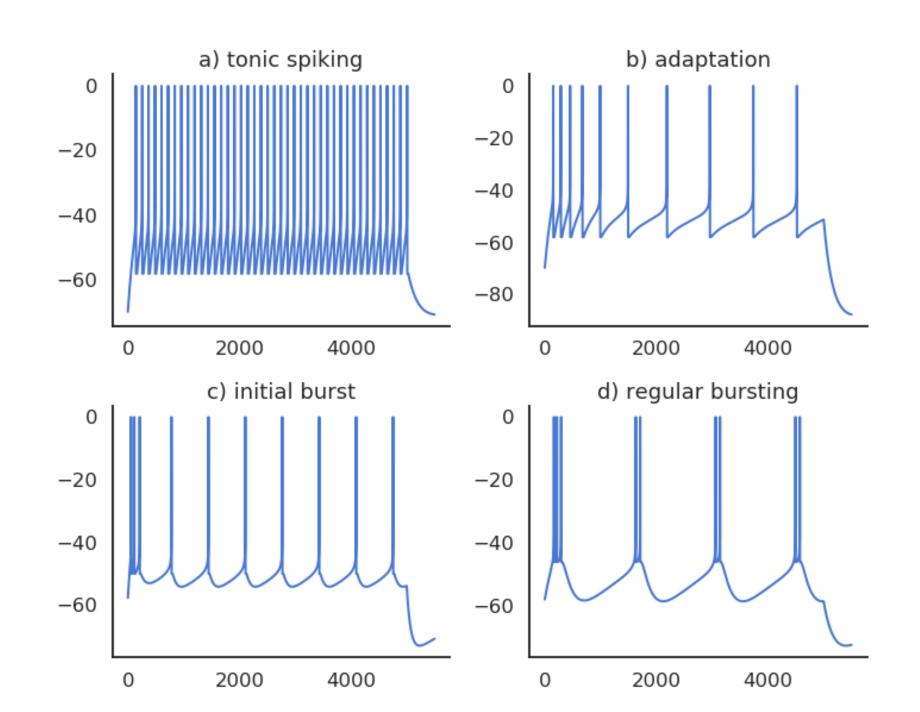
2 - Neural dynamics

Biological neurons have dynamics

• The artificial neuron has no dynamics, it is a simple mathematical function:

$$y=f(\sum_{i=1}^d w_i\,x_i+b)$$

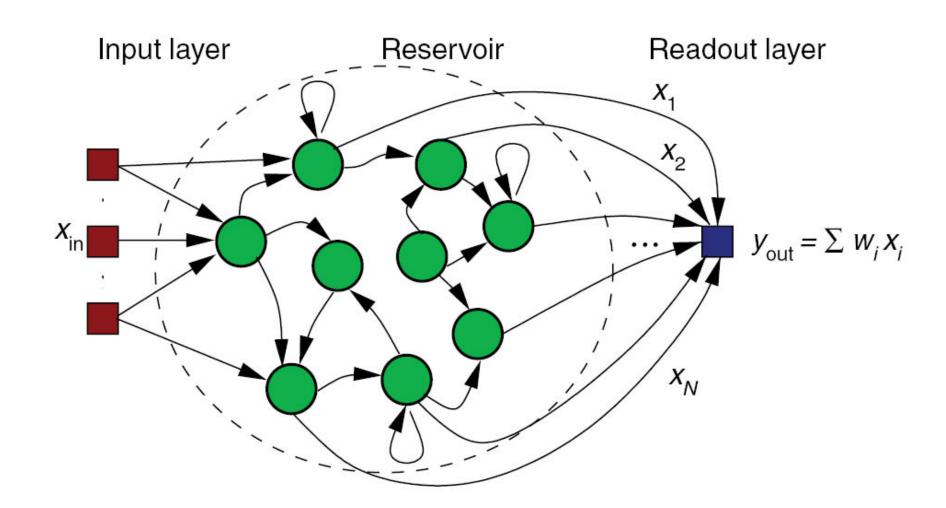
- If you do not change the inputs to an artificial neuron, its output won't change.
- Time does not exist, even in a LSTM: the only temporal variable is the frequency at which inputs are set.

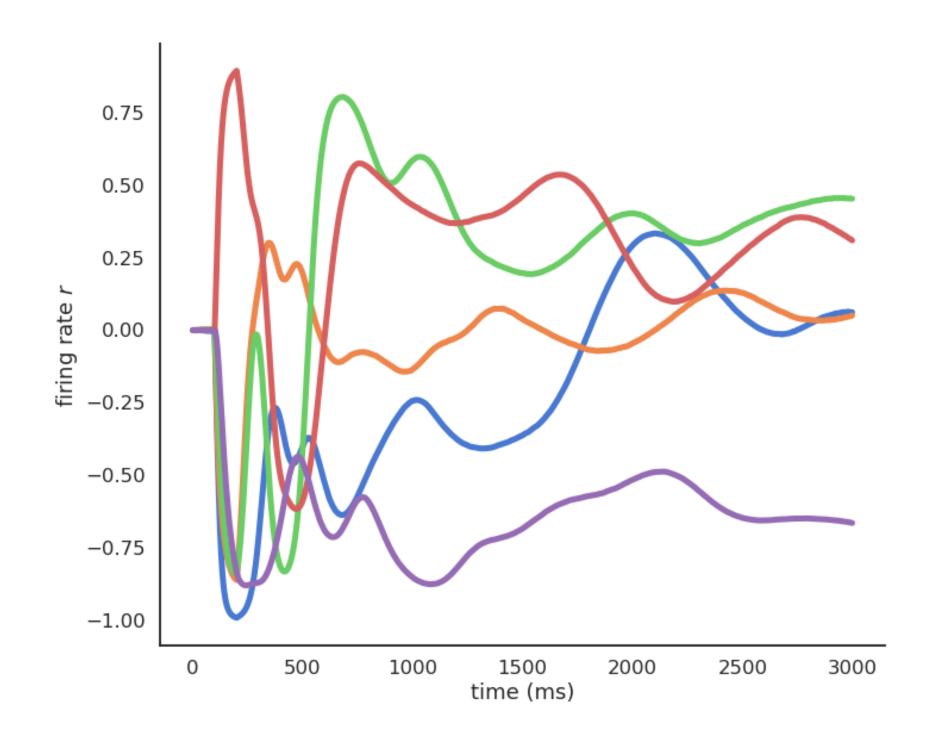


- Biological neurons have **dynamics**:
 - They adapt their firing rate to constant inputs.
 - they continue firing after an input disappears.
 - they fire even in the absence of inputs (tonic).
- These dynamics are essential to information processing in the brain.

Recurrent dynamics and emergence of functions

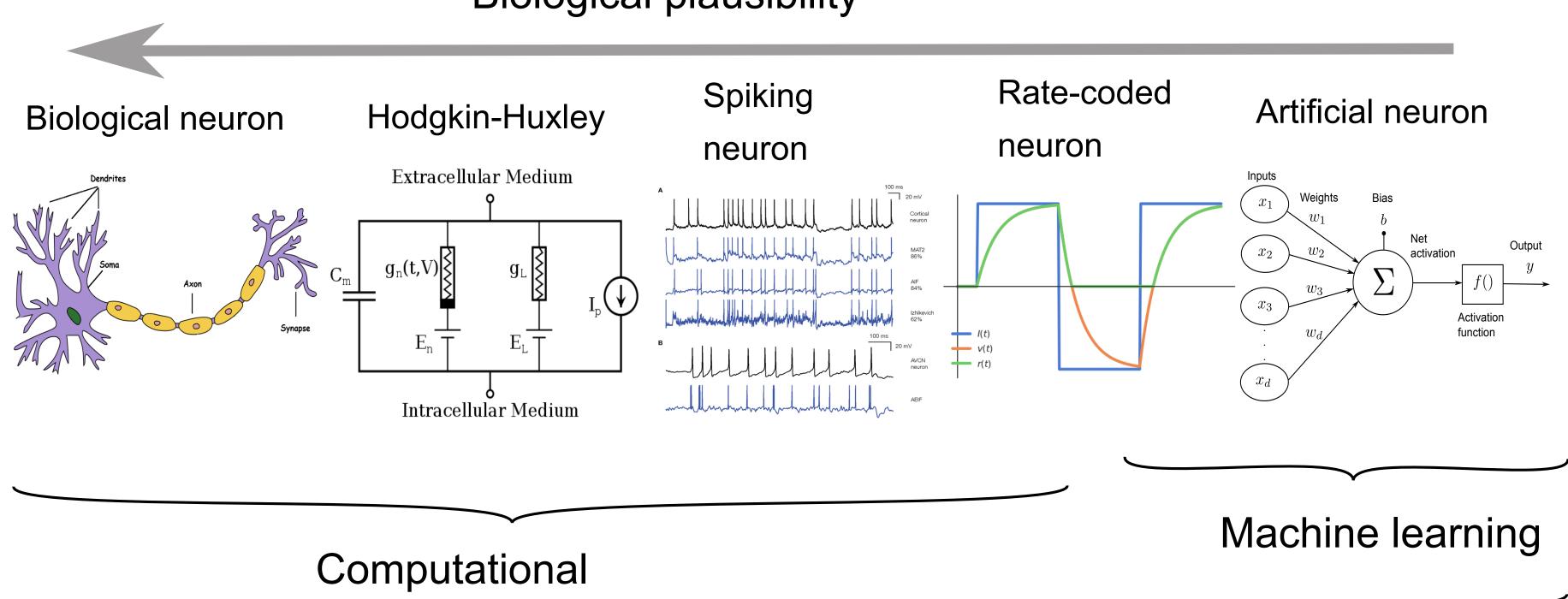
- Recurrent networks of dynamical neurons can exhibit very complex dynamics.
- Biological neural networks evolve at the **edge of chaos**, i.e. in a highly non-linear regime while still being deterministic.
- This allows the **emergence** of complex functions:
 - the whole is more than the sum of its parts.





Overview of neuron models

Biological plausibility



neuroscience

Neurocomputing

3 - Self-organization

Self-organization



- There are two complementary approaches to unsupervised learning:
 - the **statistical approach**, which tries to extract the most relevant information from the distribution of unlabeled data (autoencoders, etc).
 - **self-organization**, which tries to understand the principles of organization of natural systems and use them to create efficient algorithms.
- Self-organization is a generic process relying on four basic principles: locality of computations, learning, competition and cooperation.

Self-organization

- Self-organization is observed in a wide range of natural processes:
 - Physics: formation of crystals, star formation, chemical reactions...
 - Biology: folding of proteins, social insects, flocking behavior, brain functioning, Gaia hypothesis...
 - Social science: critical mass, group thinking, herd behavior...





Self-organization: locality of computations and learning

Not self-organized:

Self-organized:



- A self-organizing system is composed of elementary units (particles, cells, neurons, organs, individuals...)
 which all perform similar deterministic functions (rule of behavior) on a small part of the available information.
- There is **no central supervisor** or coordinator that knows everything and tells each unit what to do:
 - they have their own rule of behavior and apply it to the information they receive.
- The units are able to adapt their behavior to the available information: principle of localized learning.
- There is no **explicit loss function** specifying what the system should do: **emergence**.

Example: Conway's game of life.



- The rules of Conway's **Game of Life** (1970) are extremely simple:
 - A cell is either **dead** or **alive**.
 - A living cell with less than 1 neighbor dies.
 - A living cell with more than 4 neighbors dies.
 - A dead cell with 3 neighbors relives.

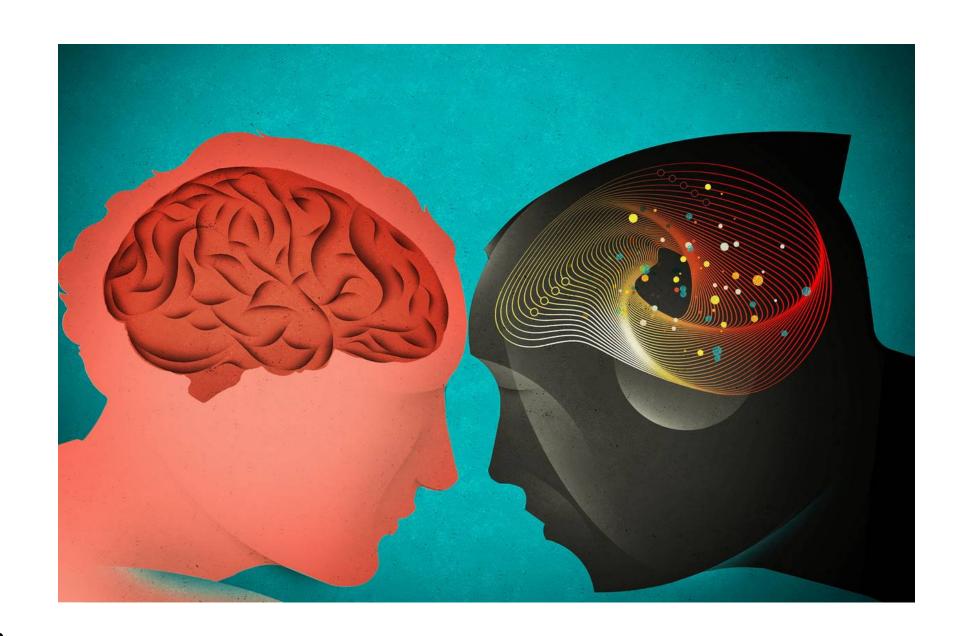
Source: https://www.jakubkonka.com/2015/03/15/game-of-life.html

- Despite this simplicity, GoL can exhibit very complex patterns (fractals, spaceships, pulsars).
- The GoL is an example of self-organizing cellular automata.

Key differences between deep networks and the brain

Bio-inspired AI has to tackle many challenges.

- No backpropagation in the brain, at least in its current form.
- Information processing is **local** to each neuron and synapse.
- Complex **recurrent** architecture (feedback connections).
- Neurons have non-linear dynamics, especially as populations (edge of chaos).
- **Emergence** of functions: the whole is more than the sum of its parts
- **Self-organization**. There is no explicit loss function to minimize: the only task of the brain is to ensure survival of the organism (homeostasis).
- **Embodiment**: the brain is part of a body.



Source: https://www.wsj.com/articles/should-artificial-intelligence-copy-the-human-brain-1533355265