

### Neurocomputing

Linear classification

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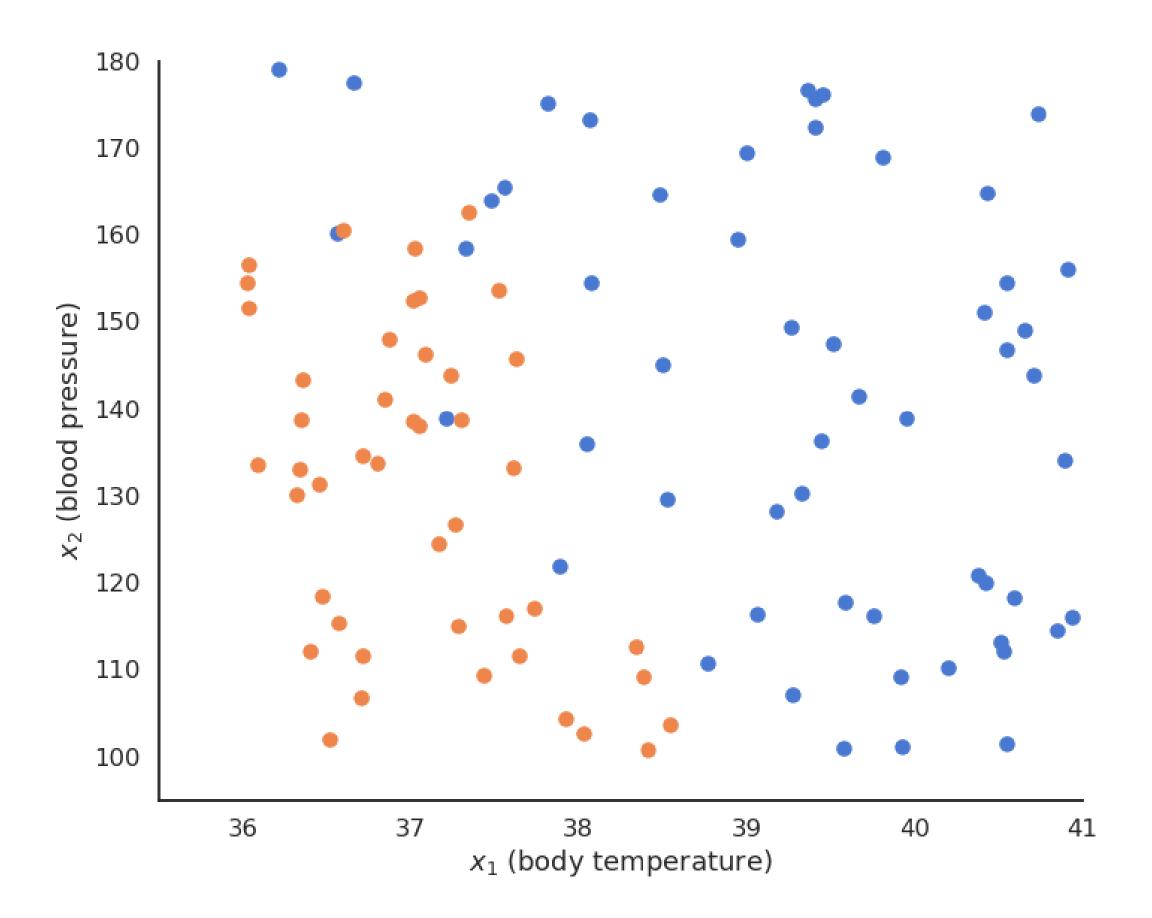
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https://tu-chemnitz.de/informatik/KI/edu/neurocomputing

1 - Hard linear classification

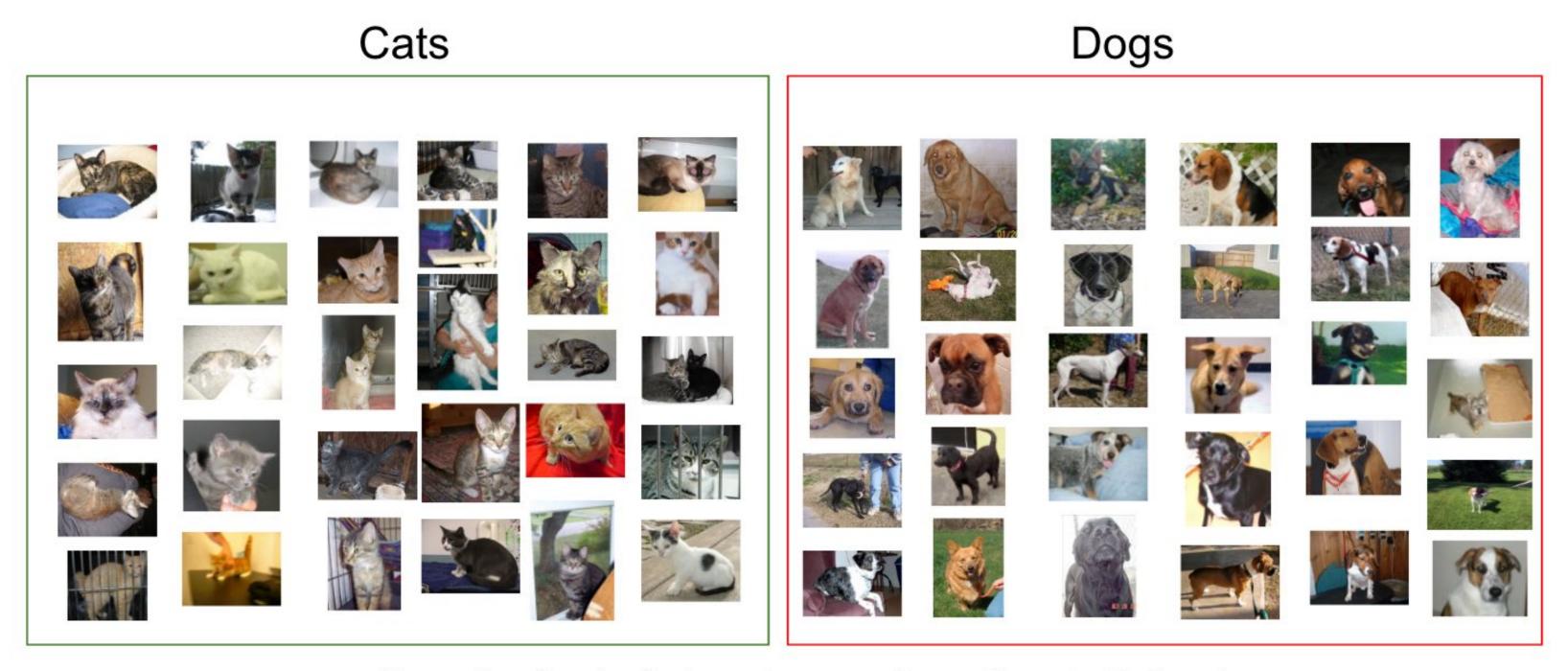
#### **Binary classification**

- The training data  $\mathcal D$  is composed of N examples  $(\mathbf x_i,t_i)_{i=1..N}$  , with a d-dimensional input vector  $\mathbf x_i\in\Re^d$  and a binary output  $t_i\in\{-1,+1\}$
- ullet The data points where t=+1 are called the **positive class**, the other the **negative class**.



#### **Binary classification**

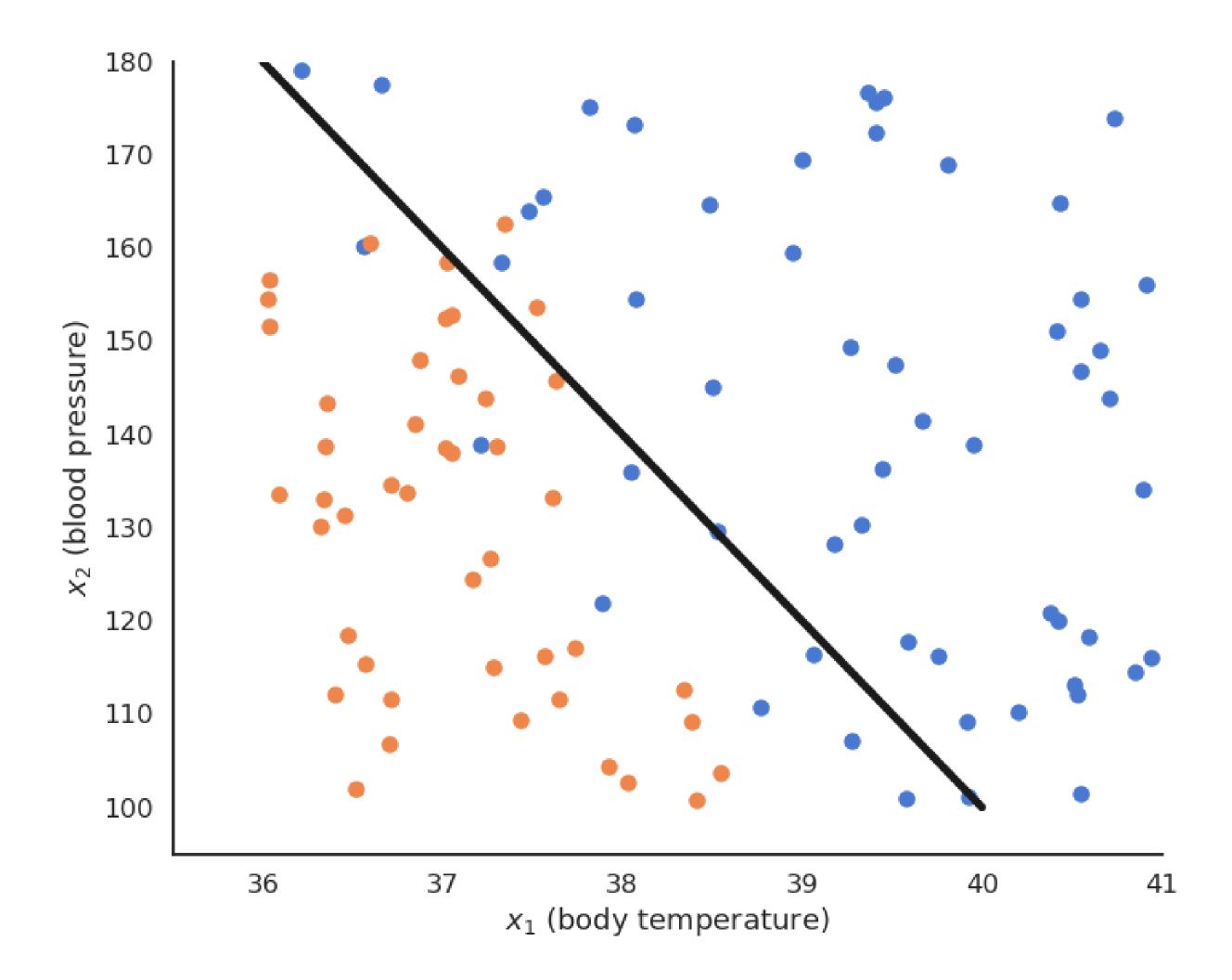
• For example, the inputs  $\mathbf{x}_i$  can be images (one dimension per pixel) and the positive class corresponds to cats  $(t_i=+1)$ , the negative class to dogs  $(t_i=-1)$ .



Sample of cats & dogs images from Kaggle Dataset

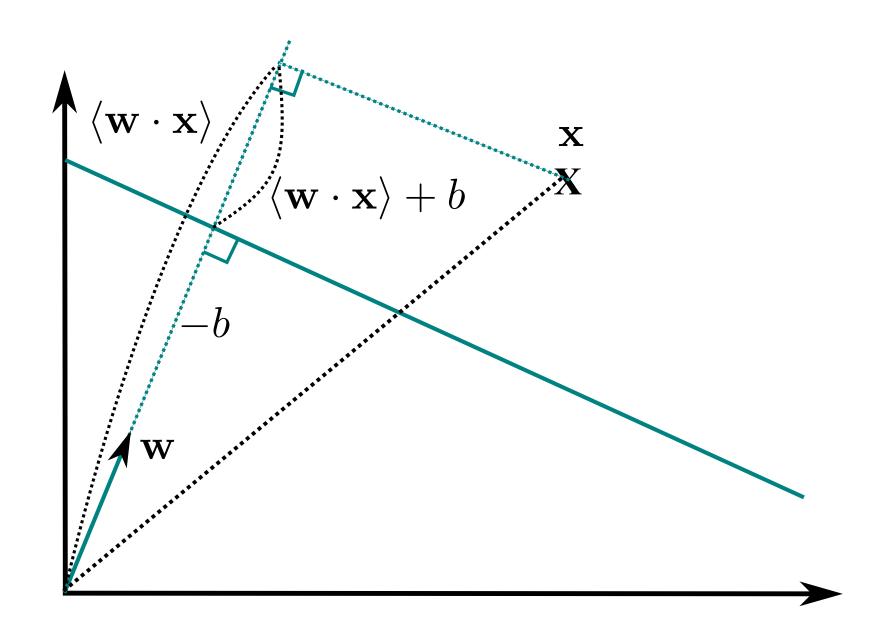
## **Binary linear classification**

ullet We want to find the hyperplane  $(\mathbf{w},b)$  of  $\Re^d$  that correctly separates the two classes.



### **Binary linear classification**

- For a point  $\mathbf{x} \in \mathcal{D}$ ,  $\langle \mathbf{w} \cdot \mathbf{x} \rangle + b$  is the projection of  $\mathbf{x}$  onto the hyperplane  $(\mathbf{w},b)$ .
  - If  $\langle \mathbf{w} \cdot \mathbf{x} \rangle + b > 0$ , the point is above the hyperplane.
  - If  $\langle {\bf w} \cdot {\bf x} \rangle + b < 0$ , the point is below the hyperplane.
  - If  $\langle \mathbf{w} \cdot \mathbf{x} \rangle + b = 0$ , the point is on the hyperplane.
- By looking at the **sign** of  $\langle {f w}\cdot {f x} \rangle + b$ , we can predict the class of the input:

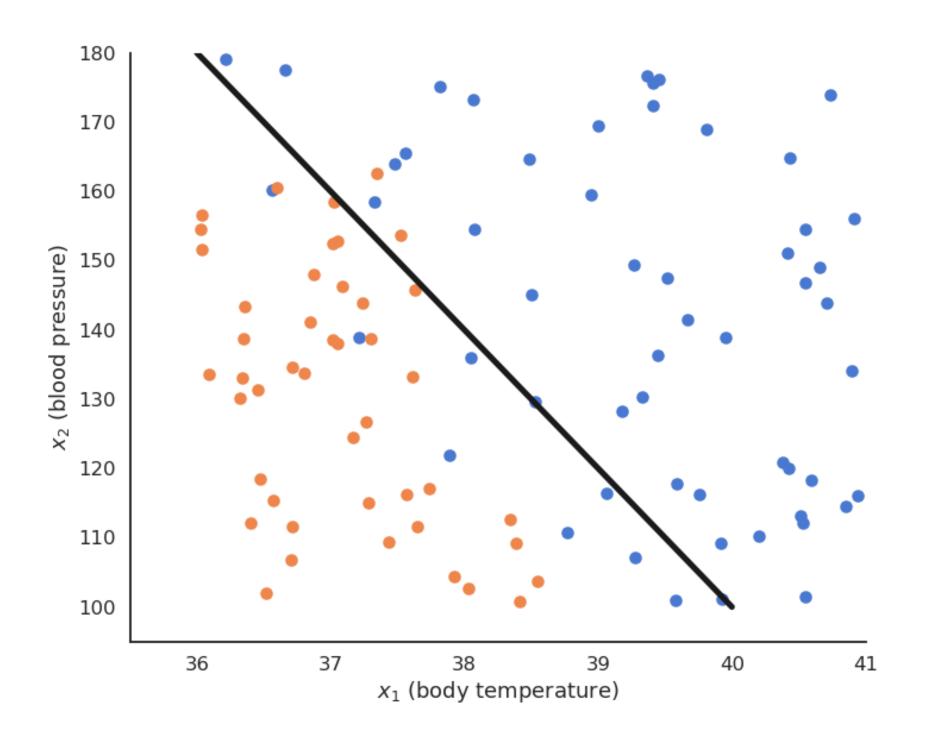


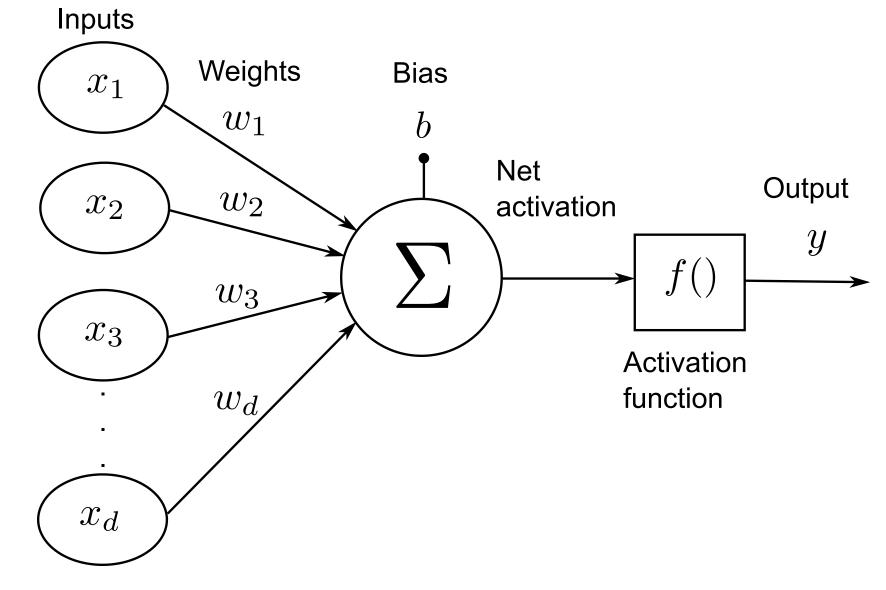
$$ext{sign}(\langle \mathbf{w} \cdot \mathbf{x} \rangle + b) = egin{cases} +1 & ext{if } \langle \mathbf{w} \cdot \mathbf{x} \rangle + b \geq 0 \ -1 & ext{if } \langle \mathbf{w} \cdot \mathbf{x} \rangle + b < 0 \end{cases}$$

#### **Binary linear classification**

• Binary linear classification can be made by a single artificial neuron using the sign transfer function.

$$y = f_{\mathbf{w},b}(\mathbf{x}) = ext{sign}(\langle \mathbf{w} \cdot \mathbf{x} 
angle + b) = ext{sign}(\sum_{j=1}^a w_j \, x_j + b)$$

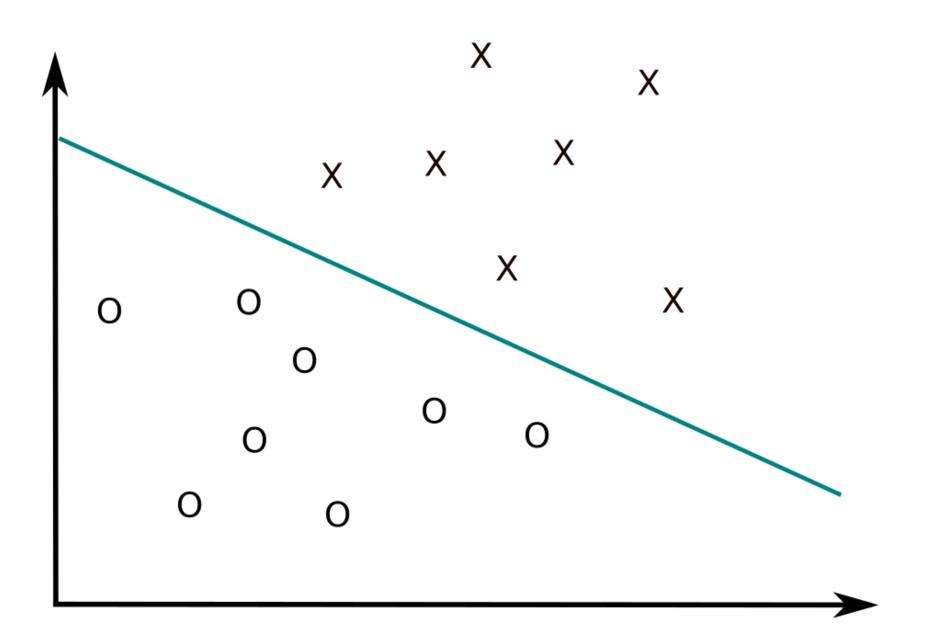




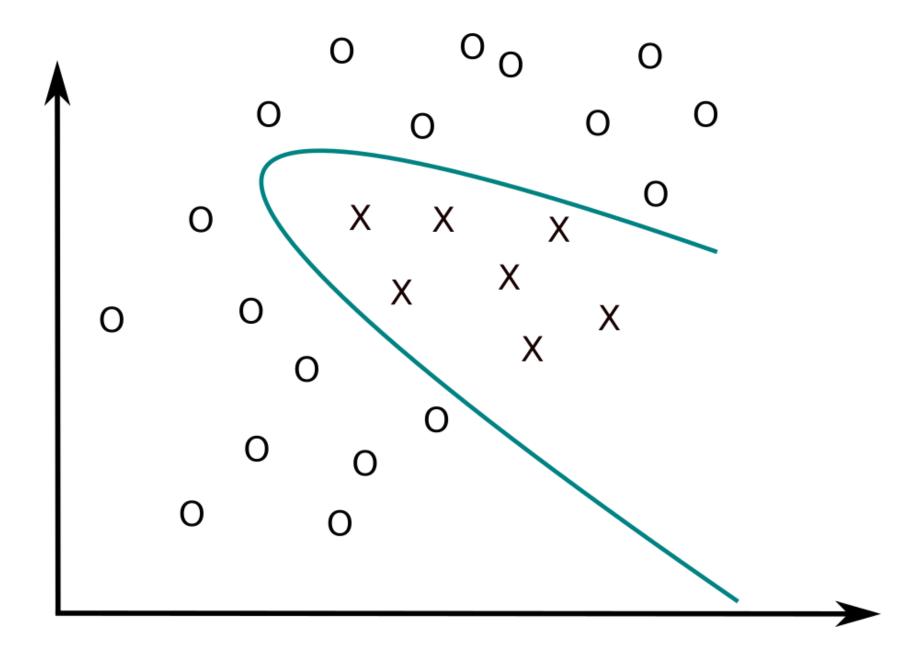
ullet w is the weight vector and b is the bias.

### Linearly separable datasets

#### **Linearly separable**



#### **Non-linearly separable**



- Linear classification is the process of finding an hyperplane  $(\mathbf{w},b)$  that correctly separates the two classes.
- If such an hyperplane can be found, the training set is said linearly separable.
- Otherwise, the problem is **non-linearly separable** and other methods have to be applied (MLP, SVM...).

#### Linear classification as an optimization problem

• The Perceptron algorithm tries to find the weights and biases minimizing the **mean square error** (*mse*) or **quadratic loss**:

$$\mathcal{L}(\mathbf{w},b) = \mathbb{E}_{\mathcal{D}}[(t_i-y_i)^2] pprox rac{1}{N} \sum_{i=1}^N (t_i-y_i)^2$$

- When the prediction  $y_i$  is the same as the data  $t_i$  for all examples in the training set (perfect classification), the mse is minimal and equal to 0.
- We can apply gradient descent to find this minimum.

$$egin{cases} \Delta \mathbf{w} = -\eta \, 
abla_{\mathbf{w}} \, \mathcal{L}(\mathbf{w}, b) \ \ \Delta b = -\eta \, 
abla_b \, \mathcal{L}(\mathbf{w}, b) \end{cases}$$

### Linear classification as an optimization problem

• Let's search for the partial derivative of the quadratic error function with respect to the weight vector:

$$abla_{\mathbf{w}} \, \mathcal{L}(\mathbf{w}, b) = 
abla_{\mathbf{w}} \, rac{1}{N} \, \sum_{i=1}^N (t_i - y_i)^2 = rac{1}{N} \, \sum_{i=1}^N 
abla_{\mathbf{w}} \, (t_i - y_i)^2 = rac{1}{N} \, \sum_{i=1}^N 
abla_{\mathbf{w}} \, l_i(\mathbf{w}, b)$$

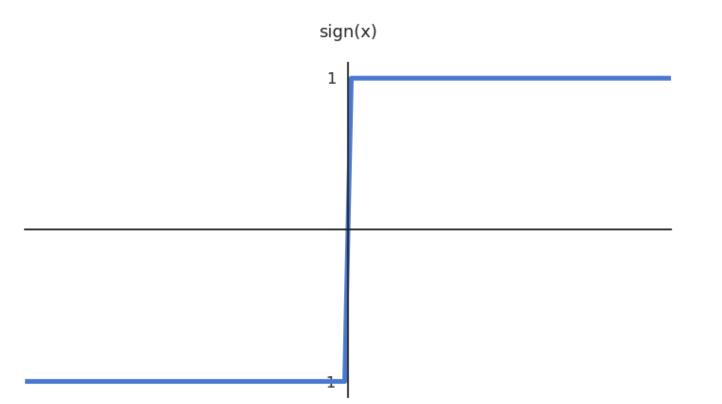
• Everything is similar to linear regression until we get:

$$abla_{\mathbf{w}} l_i(\mathbf{w}, b) = -2 \left( t_i - y_i \right) 
abla_{\mathbf{w}} \operatorname{sign}(\langle \mathbf{w} \cdot \mathbf{x}_i \rangle + b)$$

• In order to continue with the chain rule, we would need to differentiate  $\operatorname{sign}(x)$ .

$$abla_{\mathbf{w}} l_i(\mathbf{w}, b) = -2 (t_i - y_i) \operatorname{sign}'(\langle \mathbf{w} \cdot \mathbf{x}_i \rangle + b) \mathbf{x}_i$$

• But the sign function is **not** differentiable...



#### Linear classification as an optimization problem

• We will simply pretend that the sign() function is linear, with a derivative of 1:

$$abla_{\mathbf{w}} \, l_i(\mathbf{w}, b) = -2 \left( t_i - y_i 
ight) \mathbf{x}_i$$

ullet The update rule for the weight vector  ${f w}$  and the bias b is therefore the same as in linear regression:

$$egin{cases} \Delta \mathbf{w} = \eta \, rac{1}{N} \, \sum_{i=1}^N (t_i - y_i) \, \mathbf{x}_i \ \Delta b = \eta \, rac{1}{N} \, \sum_{i=1}^N (t_i - y_i) \end{cases}$$

#### Batch version of linear classification

• By applying gradient descent on the quadratic error function, one obtains the following algorithm:



#### **Batch linear classification**

ullet for M epochs:

• 
$$\mathbf{dw} = 0$$
  $db = 0$ 

• for each sample  $(\mathbf{x}_i, t_i)$ :

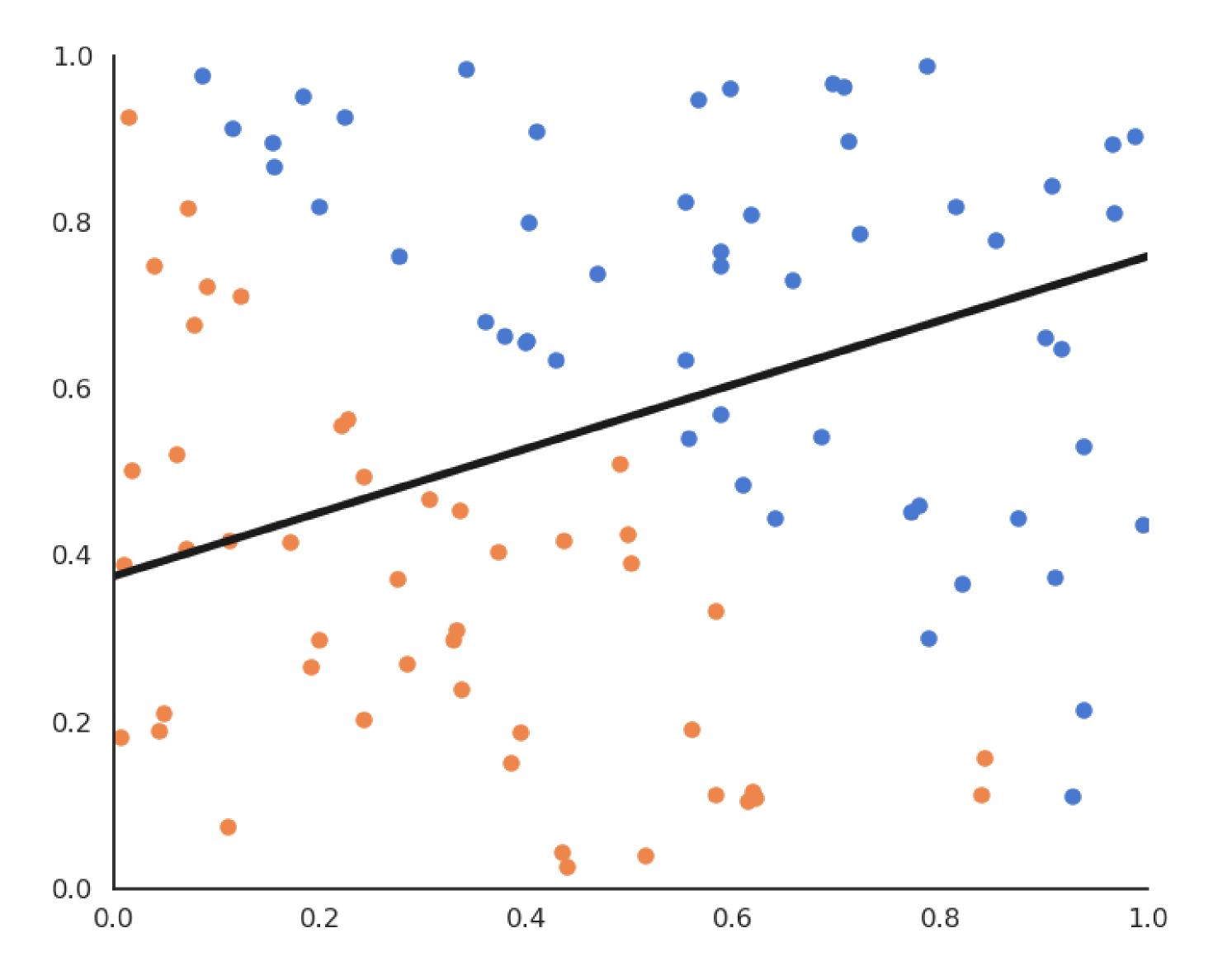
$$egin{aligned} \circ \ y_i = \mathrm{sign}(\langle \mathbf{w} \cdot \mathbf{x}_i 
angle + b) \end{aligned}$$

$$\mathbf{w} \cdot \mathbf{dw} = \mathbf{dw} + (t_i - y_i) \, \mathbf{x}_i \,$$

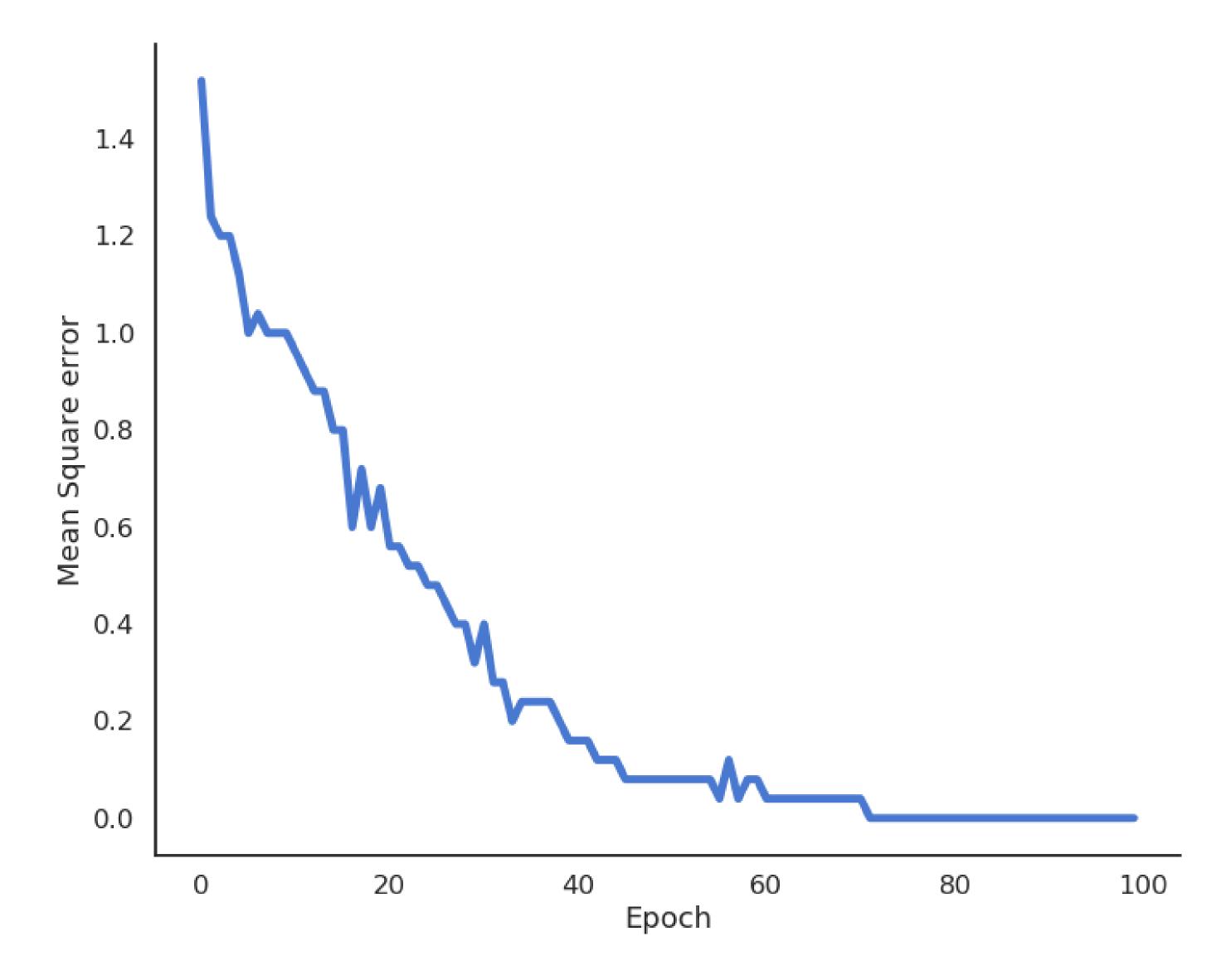
$$\circ \ db = db + (t_i - y_i)$$

- $\Delta \mathbf{w} = \eta \, rac{1}{N} \, \mathbf{dw}$
- $\Delta b = \eta \, rac{1}{N} \, db$
- This is called the batch version of the Perceptron algorithm.
- ullet If the data is linearly separable and  $\eta$  is well chosen, it converges to the minimum of the mean square error.

## Linear classification: batch version



#### Linear classification: batch version



### Online version of linear classification: the Perceptron algorithm

• The **Perceptron algorithm** was invented by the psychologist Frank Rosenblatt in 1958. It was the first algorithmic neural network able to learn linear classification.



#### **Perceptron algorithm**

- ullet for M epochs:
  - for each sample  $(\mathbf{x}_i, t_i)$ :

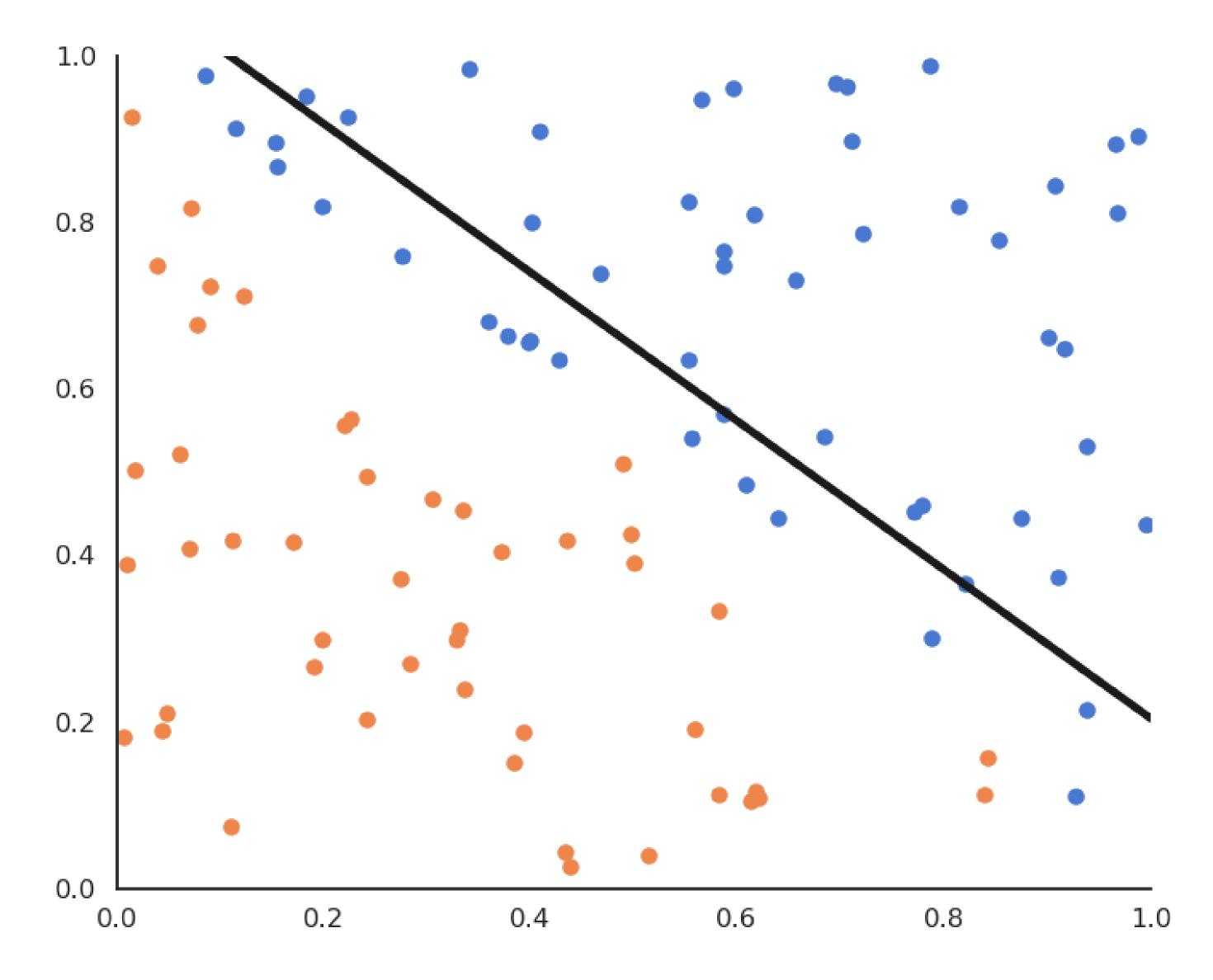
$$y_i = \operatorname{sign}(\langle \mathbf{w} \cdot \mathbf{x}_i \rangle + b)$$

$$\circ \ \Delta \mathbf{w} = \eta \left( t_i - y_i 
ight) \mathbf{x}_i$$

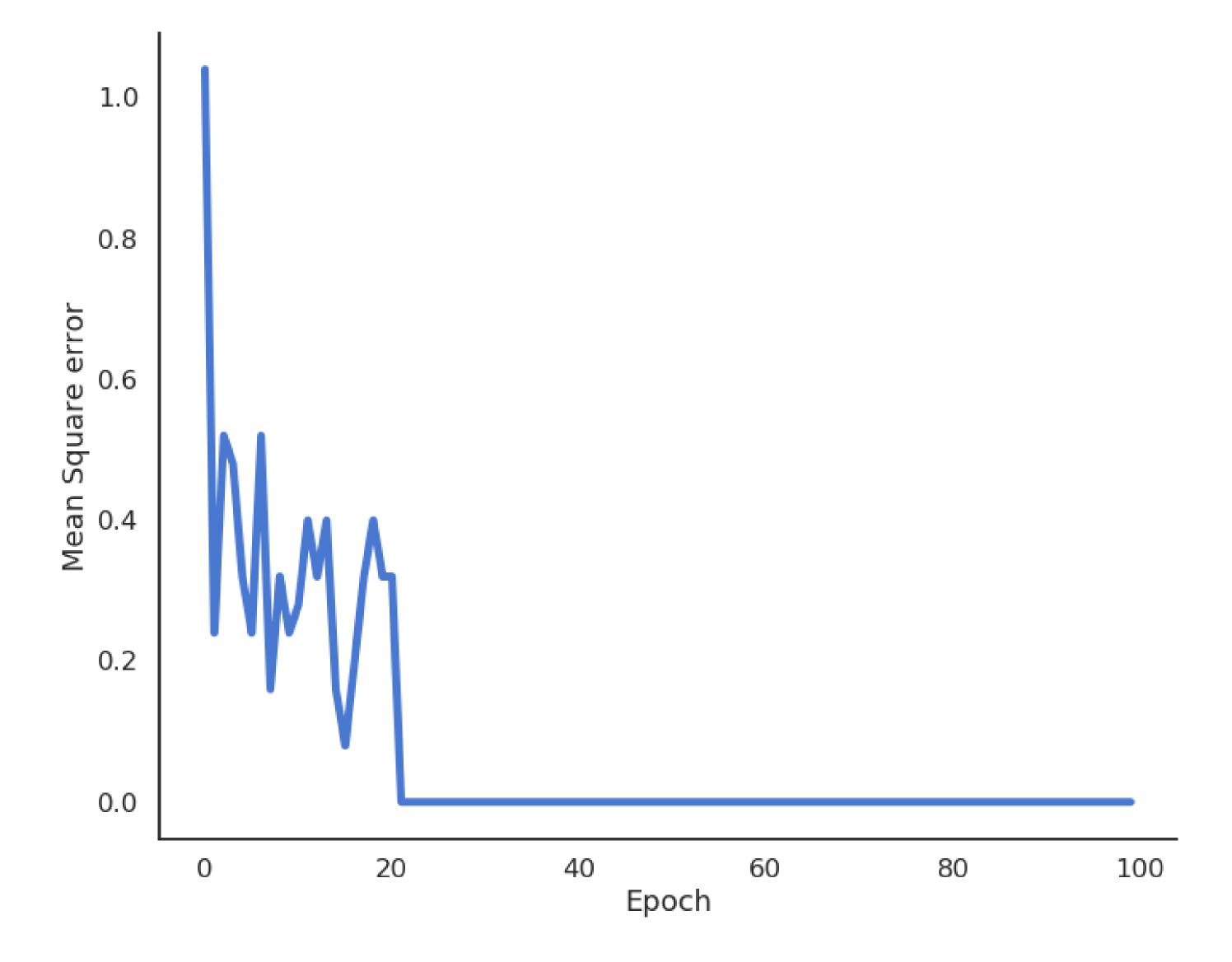
$$\circ \ \Delta b = \eta \left( t_i - y_i 
ight)$$

- This algorithm iterates over all examples of the training set and applies the **delta learning rule** to each of them immediately, not at the end on the whole training set.
- One could check whether there are still classification errors on the training set at the end of each epoch and stop the algorithm.
- The delta learning rule depends on the learning rate  $\eta$ , the error made by the prediction  $(t_i y_i)$  and the input  $\mathbf{x}_i$ .

## Linear classification: online version



#### Linear classification: online version



### Batch vs. Online learning

The mean square error is defined as the expectation over the data:

$$\mathcal{L}(\mathbf{w},b) = \mathbb{E}_{\mathcal{D}}[(t_i-y_i)^2]$$

- Batch learning uses the whole training set as samples to estimate the mse:
- Online learning uses a single sample to estimate the mse:

$$\mathcal{L}(\mathbf{w},b)pprox rac{1}{N} \sum_{i=1}^{N} (t_i-y_i)^2$$

$$\Delta \mathbf{w} = \eta \, rac{1}{N} \sum_{i=1}^N (t_i - y_i) \, \mathbf{x_i}$$

 $egin{aligned} \mathcal{L}(\mathbf{w},b) &pprox (t_i-y_i)^2 \ \Delta \mathbf{w} &= \eta \left(t_i-y_i
ight) \mathbf{x_i} \end{aligned}$ 

$$\Delta \mathbf{w} = \eta \left( t_i - y_i 
ight) \mathbf{x_i}$$

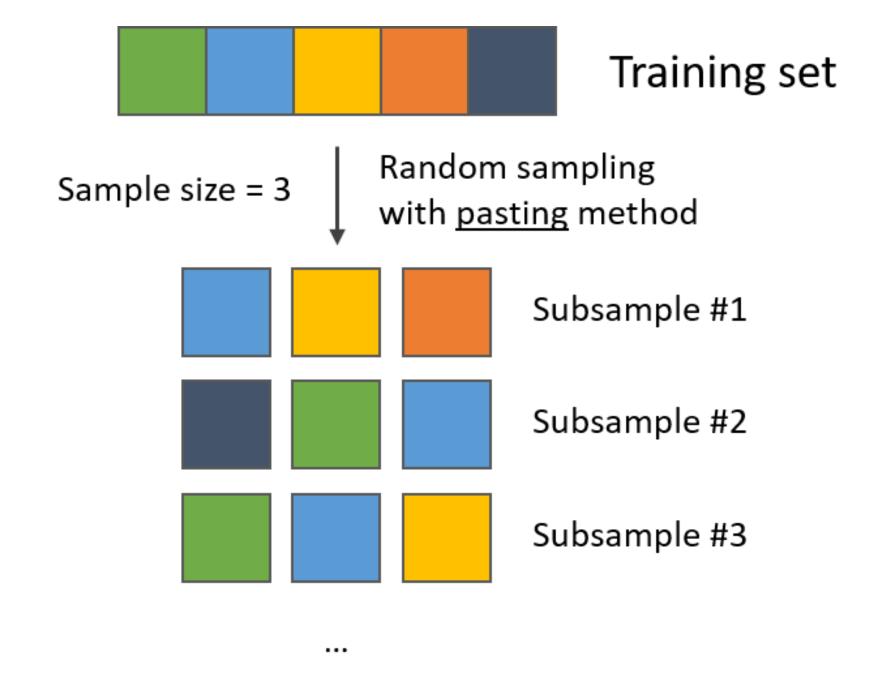
- Batch learning has less bias (central limit theorem) and is less sensible to noise in the data, but is very slow.
- Online learning converges faster, but can be instable and overfits (high variance).

#### **Stochastic Gradient Descent - SGD**

- In practice, we use a trade-off between batch and online learning called Stochastic Gradient Descent
  (SGD) or Minibatch Gradient Descent.
- The training set is randomly split at each epoch into small chunks of data (a **minibatch**, usually 32 or 64 examples) and the batch learning rule is applied on each chunk.

$$\Delta \mathbf{w} = \eta \, rac{1}{K} \sum_{i=1}^K (t_i - y_i) \, \mathbf{x_i}$$

- If the **batch size** is well chosen, SGD is as stable as batch learning and as fast as online learning.
- The minibatches are randomly selected at each epoch (i.i.d).

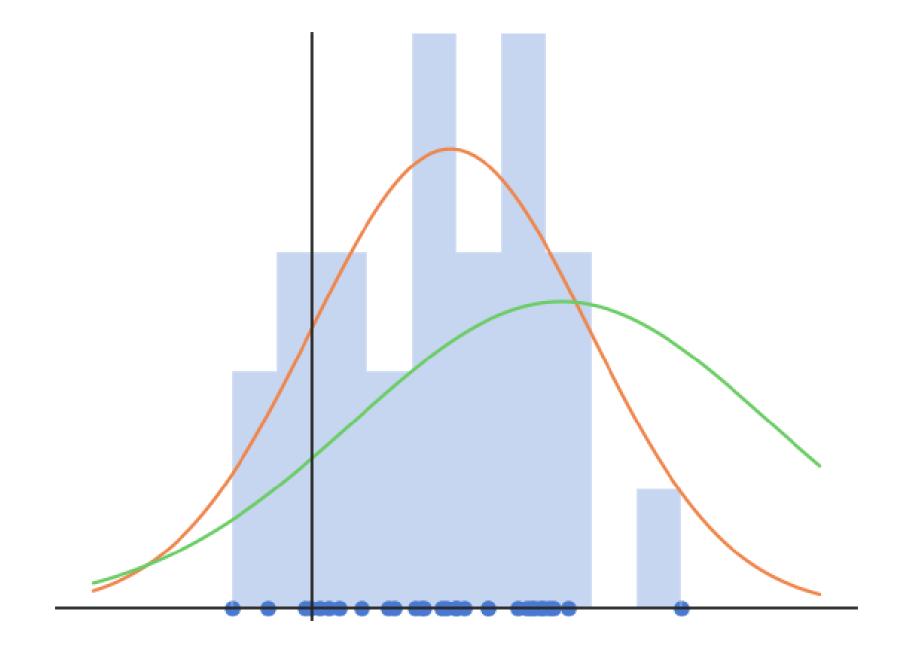


Online learning is a stochastic gradient descent with a batch size of 1.

- Let's consider N samples  $\{x_i\}_{i=1}^N$  independently taken from a normal distribution X.
- The probability density function (pdf) of a normal distribution is:

$$f(x;\mu,\sigma) = rac{1}{\sqrt{2\pi\sigma^2}} \, \exp{-rac{(x-\mu)^2}{2\sigma^2}}$$

where  $\mu$  is the mean of the distribution and  $\sigma$  its standard deviation.

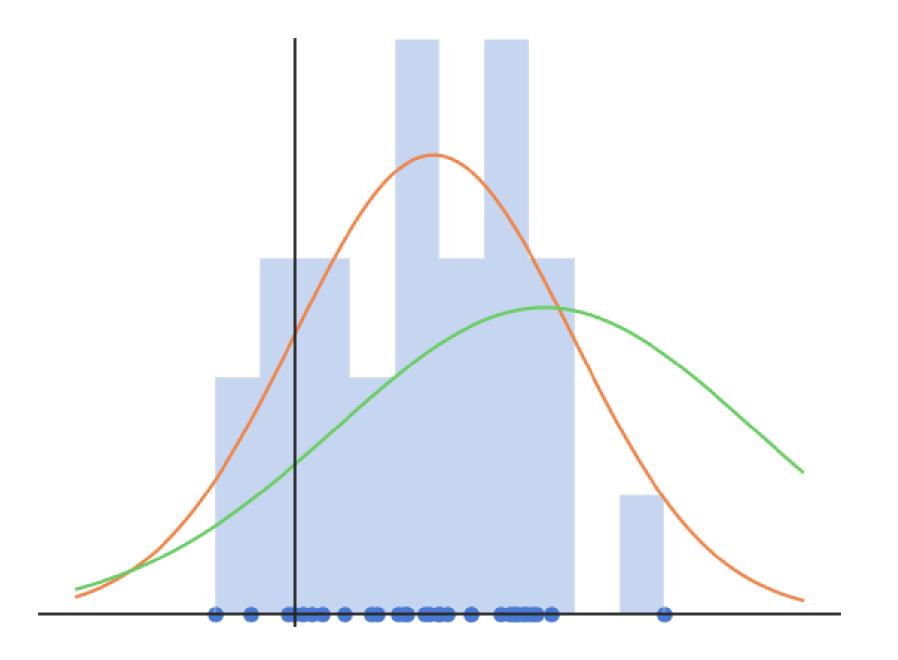


ullet The problem is to find the values of  $\mu$  and  $\sigma$  which explain best the observations  $\{x_i\}_{i=1}^N$  .

• The idea of MLE is to maximize the joint density function for all observations. This function is expressed by the **likelihood function**:

$$L(\mu,\sigma) = P(\mathbf{x};\mu,\sigma) = \prod_{i=1}^N f(x_i;\mu,\sigma)$$

 When the pdf takes high values for all samples, it is quite likely that the samples come from this particular distribution.



- ullet The likelihood function reflects how well the parameters  $\mu$  and  $\sigma$  explain the observations  $\{x_i\}_{i=1}^N$  .
- Note: the samples must be i.i.d. so that the likelihood is a product.

ullet We therefore search for the values  $\mu$  and  $\sigma$  which **maximize** the likelihood function.

$$\max_{\mu,\sigma} \ \ L(\mu,\sigma) = \prod_{i=1}^N f(x_i;\mu,\sigma)$$

For the normal distribution, the likelihood function is:

$$egin{aligned} L(\mu,\sigma) &= \prod_{i=1}^N f(x_i;\mu,\sigma) \ &= \prod_{i=1}^N rac{1}{\sqrt{2\pi\sigma^2}} \, \exp{-rac{(x_i-\mu)^2}{2\sigma^2}} \ &= (rac{1}{\sqrt{2\pi\sigma^2}})^N \, \prod_{i=1}^N \exp{-rac{(x_i-\mu)^2}{2\sigma^2}} \ &= (rac{1}{\sqrt{2\pi\sigma^2}})^N \, \exp{-rac{\sum_{i=1}^N (x_i-\mu)^2}{2\sigma^2}} \end{aligned}$$

ullet To find the maximum of  $L(\mu,\sigma)$ , we need to search where the gradient is equal to zero:

$$egin{cases} rac{\partial L(\mu,\sigma)}{\partial \mu} = 0 \ rac{\partial L(\mu,\sigma)}{\partial \sigma} = 0 \end{cases}$$

• The likelihood function is complex to differentiate, so we consider its logarithm  $l(\mu,\sigma)=\log(L(\mu,\sigma))$  which has a maximum for the same value of  $(\mu,\sigma)$  as the log function is monotonic.

$$egin{align} l(\mu,\sigma) &= \log(L(\mu,\sigma)) \ &= \log\left((rac{1}{\sqrt{2\pi\sigma^2}})^N\,\exp{-rac{\sum_{i=1}^N(x_i-\mu)^2}{2\sigma^2}}
ight) \ &= -rac{N}{2}\log(2\pi\sigma^2) - rac{\sum_{i=1}^N(x_i-\mu)^2}{2\sigma^2} \ \end{gathered}$$

•  $l(\mu, \sigma)$  is called the **log-likelihood** function.

$$l(\mu,\sigma) = -rac{N}{2}\log(2\pi\sigma^2) - rac{\sum_{i=1}^N(x_i-\mu)^2}{2\sigma^2}$$

• The maximum of the log-likelihood function respects:

$$egin{aligned} rac{\partial l(\mu,\sigma)}{\partial \mu} &= rac{\sum_{i=1}^{N}(x_i-\mu)}{\sigma^2} = 0 \ rac{\partial l(\mu,\sigma)}{\partial \sigma} &= -rac{N}{2}rac{4\pi\sigma}{2\pi\sigma^2} + rac{\sum_{i=1}^{N}(x_i-\mu)^2}{\sigma^3} \ &= -rac{N}{\sigma} + rac{\sum_{i=1}^{N}(x_i-\mu)^2}{\sigma^3} = 0 \end{aligned}$$

• We obtain:

$$\mu = rac{1}{N} \sum_{i=1}^N x_i \qquad \qquad \sigma^2 = rac{1}{N} \sum_{i=1}^N (x_i - \mu)^2$$

 Unsurprisingly, the mean and variance of the normal distribution which best explains the data are the mean and variance of the data...

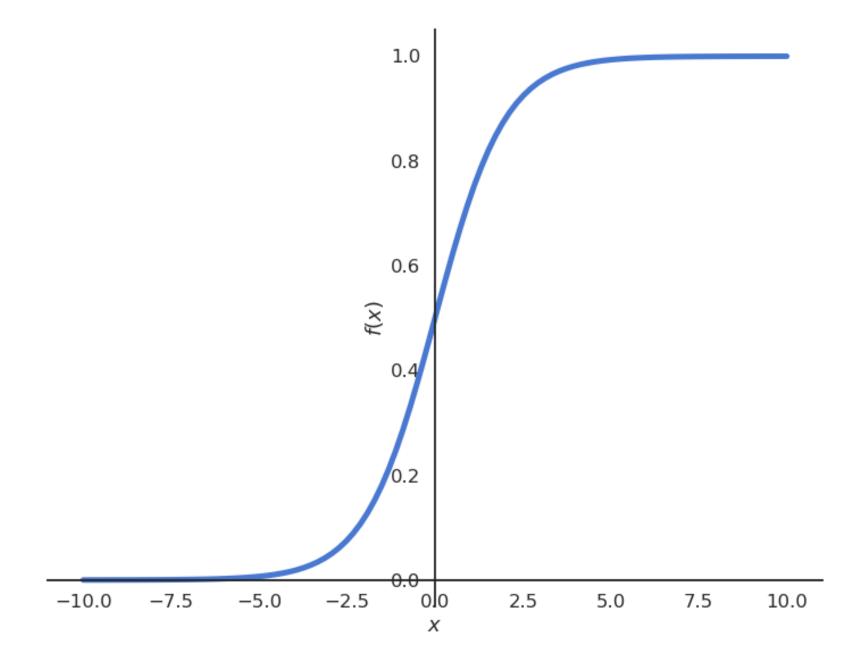
$$\mu = rac{1}{N} \sum_{i=1}^N x_i \qquad \qquad \sigma^2 = rac{1}{N} \sum_{i=1}^N (x_i - \mu)^2$$

- The same principle can be applied to estimate the parameters of any distribution: normal, exponential, Bernouilli, Poisson, etc...
- When a machine learning method has an probabilistic interpretation (i.e. it outputs probabilities), MLE can be used to find its parameters.
- One can use global optimization like here, or gradient descent to estimate the parameters iteratively.

3 - Soft linear classification : Logistic regression

#### Reminder: Logistic regression

ullet We want to perform a regression, but where the targets  $t_i$  are bounded betwen 0 and 1.



• We can use a logistic function instead of a linear function in order to transform the net activation into an output:

$$y=\sigma(w\,x+b)=rac{1}{1+\exp(-w\,x-b)}$$

#### Use of logistic regression for soft classification

• Logistic regression can be used in binary classification if we consider  $y = \sigma(w \, x + b)$  as the probability that the example belongs to the positive class (t = 1).

$$P(t = 1|x; w, b) = y;$$
  $P(t = 0|x; w, b) = 1 - y$ 

• The output t therefore comes from a Bernouilli distribution  $\mathcal{B}$  of parameter  $p=y=f_{w,b}(x)$ . The probability mass function (pmf) is:

$$f(t|x;w,b) = y^t \, (1-y)^{1-t}$$

- ullet If we consider our training samples  $(x_i,t_i)$  as independently taken from this distribution, our task is:
  - to find the parameterized distribution that best explains the data, which means:
  - to find the parameters w and b maximizing the **likelihood** that the samples t come from a Bernouilli distribution when x, w and b are given.
- We only need to apply **Maximum Likelihood Estimation** (MLE) on this Bernouilli distribution!

#### MLE for logistic regression

• The likelihood function for logistic regression is:

$$egin{aligned} L(w,b) &= P(t|x;w,b) = \prod_{i=1}^N f(t_i|x_i;w,b) \ &= \prod_{i=1}^N y_i^{t_i} \ (1-y_i)^{1-t_i} \end{aligned}$$

• The likelihood function is quite hard to differentiate, so we take the log-likelihood function:

$$egin{aligned} l(w,b) &= \log L(w,b) \ &= \sum_{i=1}^N [t_i \, \log y_i + (1-t_i) \, \log (1-y_i)] \end{aligned}$$

• or even better: the **negative log-likelihood** which will be minimized using gradient descent:

$$\mathcal{L}(w,b) = -\sum_{i=1}^{N} [t_i \, \log y_i + (1-t_i) \, \log (1-y_i)]$$

### MLE for logistic regression

 We then search for the minimum of the negative log-likelihood function by computing its gradient (here for a single sample):

$$egin{aligned} rac{\partial l_i(w,b)}{\partial w} &= -rac{\partial}{\partial w}[t_i\,\log y_i + (1-t_i)\,\log(1-y_i)] \ &= -t_i\,rac{\partial}{\partial w}\log y_i - (1-t_i)\,rac{\partial}{\partial w}\log(1-y_i) \ &= -t_i\,rac{rac{\partial}{\partial w}y_i}{y_i} - (1-t_i)\,rac{rac{\partial}{\partial w}(1-y_i)}{1-y_i} \ &= -t_i\,rac{y_i\,(1-y_i)\,x_i}{y_i} + (1-t_i)\,rac{y_i\,(1-y_i)\,x_i}{1-y_i} \ &= -(t_i-y_i)\,x_i \end{aligned}$$

Same gradient as the linear perceptron, but with a non-linear output function!

#### Logistic regression for soft classification

• Logistic regression is a regression method used for classification. It uses a non-linear transfer function  $\sigma(x)=rac{1}{1+\exp(-x)}$  applied on the net activation:

$$y_i = \sigma(\langle \mathbf{w} \cdot \mathbf{x}_i 
angle + b)$$

ullet The continuous output y is interpreted as the probability of belonging to the positive class.

$$P(t_i = 1|\mathbf{x}_i; \mathbf{w}, b) = y_i; \qquad P(t_i = 0|\mathbf{x}_i; \mathbf{w}, b) = 1 - y_i$$

• We minimize the negative log-likelihood loss function using gradient descent:

$$\mathcal{L}(\mathbf{w}, b) = -\sum_{i=1}^{N} [t_i \, \log y_i + (1 - t_i) \, \log (1 - y_i)]$$

• We obtain the delta learning rule, using the class as a target and the probability as a prediction:

$$egin{cases} \Delta \mathbf{w} = \eta \left( t_i - y_i 
ight) \mathbf{x}_i \ \Delta b = \eta \left( t_i - y_i 
ight) \end{cases}$$

### Logistic regression



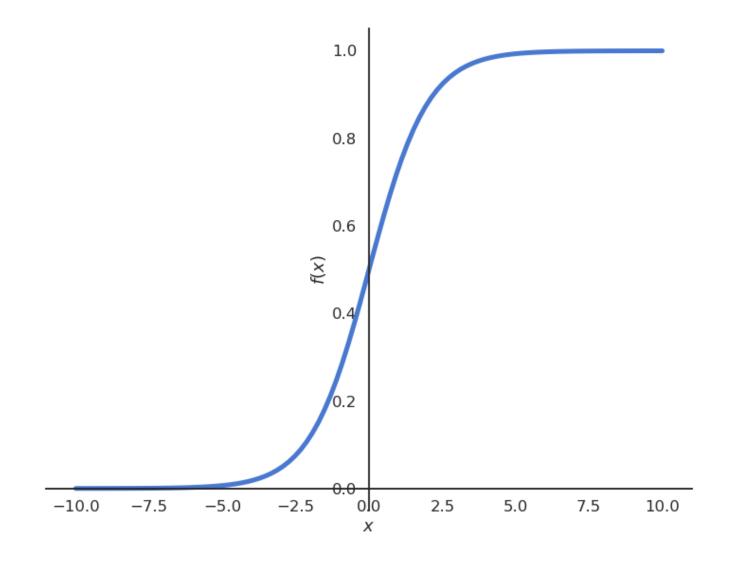
#### **Logistic regression**

- $\mathbf{w} = 0$  b = 0
- ullet for M epochs:
  - for each sample  $(\mathbf{x}_i, t_i)$ :

$$egin{aligned} egin{aligned} & egin{aligned} & y_i = \sigma(\langle \mathbf{w} \cdot \mathbf{x}_i 
angle + b) \end{aligned}$$

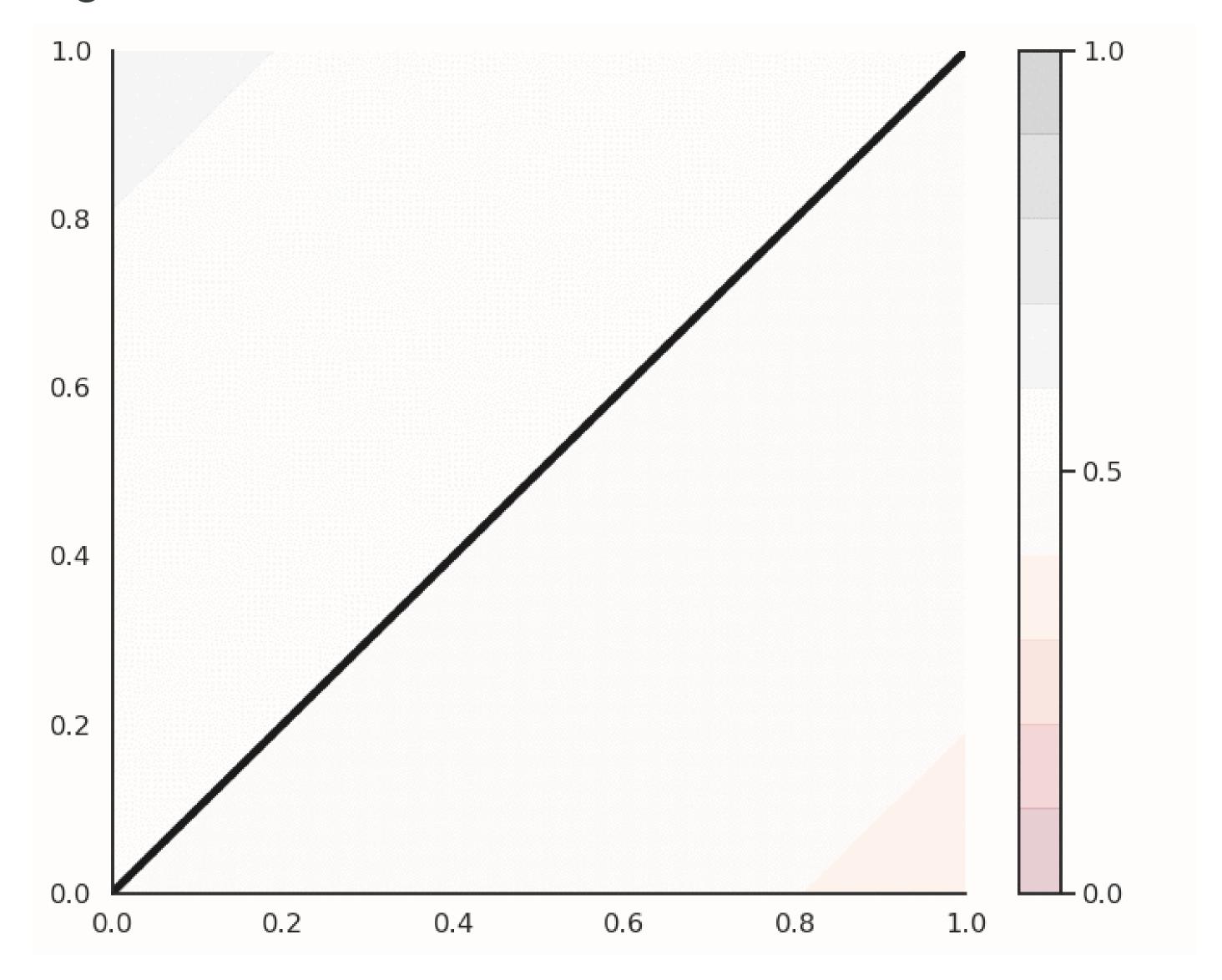
$$\circ \ \Delta \mathbf{w} = \eta \left( t_i - y_i 
ight) \mathbf{x}_i$$

$$\circ \ \Delta b = \eta \left( t_i - y_i 
ight)$$

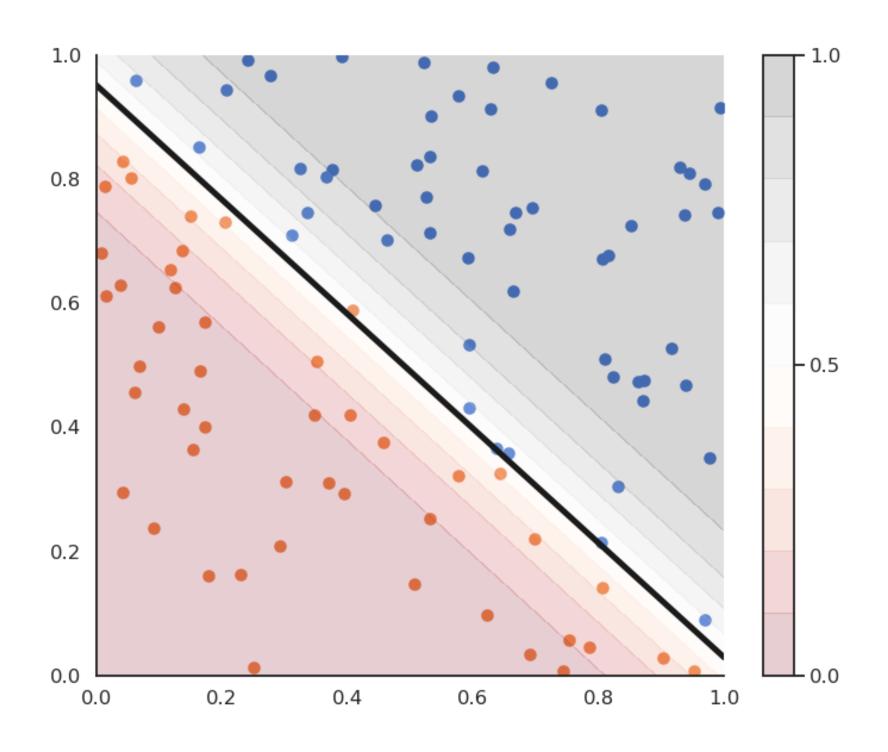


- Logistic regression works just like linear classification, except in the way the prediction is done.
- To know to which class  $\mathbf{x}_i$  belongs, simply draw a random number between 0 and 1:
  - if it is smaller than  $y_i$  (probability  $y_i$ ), it belongs to the positive class.
  - if it is bigger than  $y_i$  (probability  $1-y_i$ ), it belongs to the negative class.
- Alternatively, you can put a hard limit at 0.5:
  - ullet if  $y_i>0.5$  then the class is positive.
  - ullet if  $y_i < 0.5$  then the class is negative.

# Logistic regression



### Logistic regression and confidence score

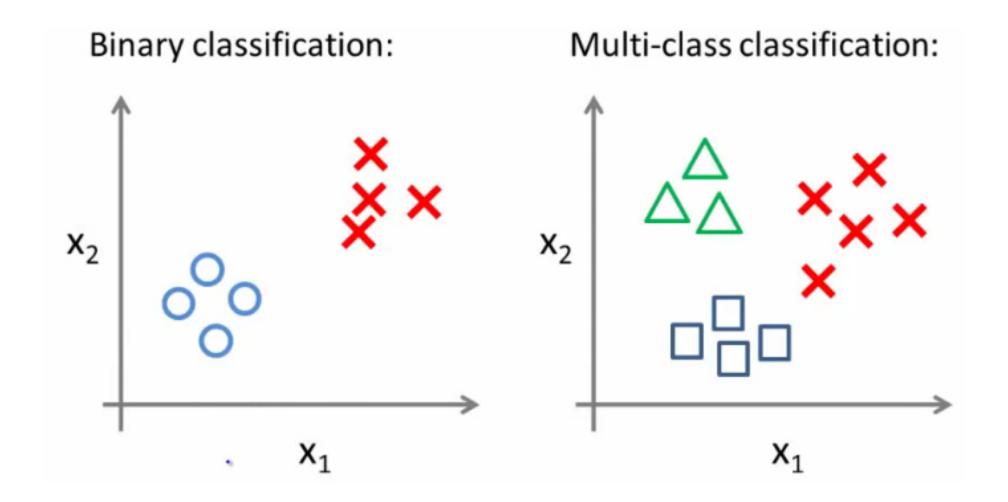


- Logistic regression also provides a confidence score:
  - the closer y is from 0 or 1, the more confident we can be that the classification is correct.
- This is particularly important in **safety critical** applications:
  - If you detect the positive class but with a confidence of 0.51, you should perhaps not trust the prediction.
  - If the confidence score is 0.99, you can probably trust the prediction.

4 - Multi-class classification

#### **Multi-class classification**

ullet Can we perform multi-class classification using the previous methods when  $t\in\{A,B,C\}$  instead of t=+1 or -1?



#### Multi-class classification

Two main solutions:

- One-vs-All (or One-vs-the-rest): one trains simultaneously a binary (linear) classifier for each class. The examples belonging to this class form the positive class, all others are the negative class:
  - A vs. B and C
  - B vs. A and C
  - C vs. A and B

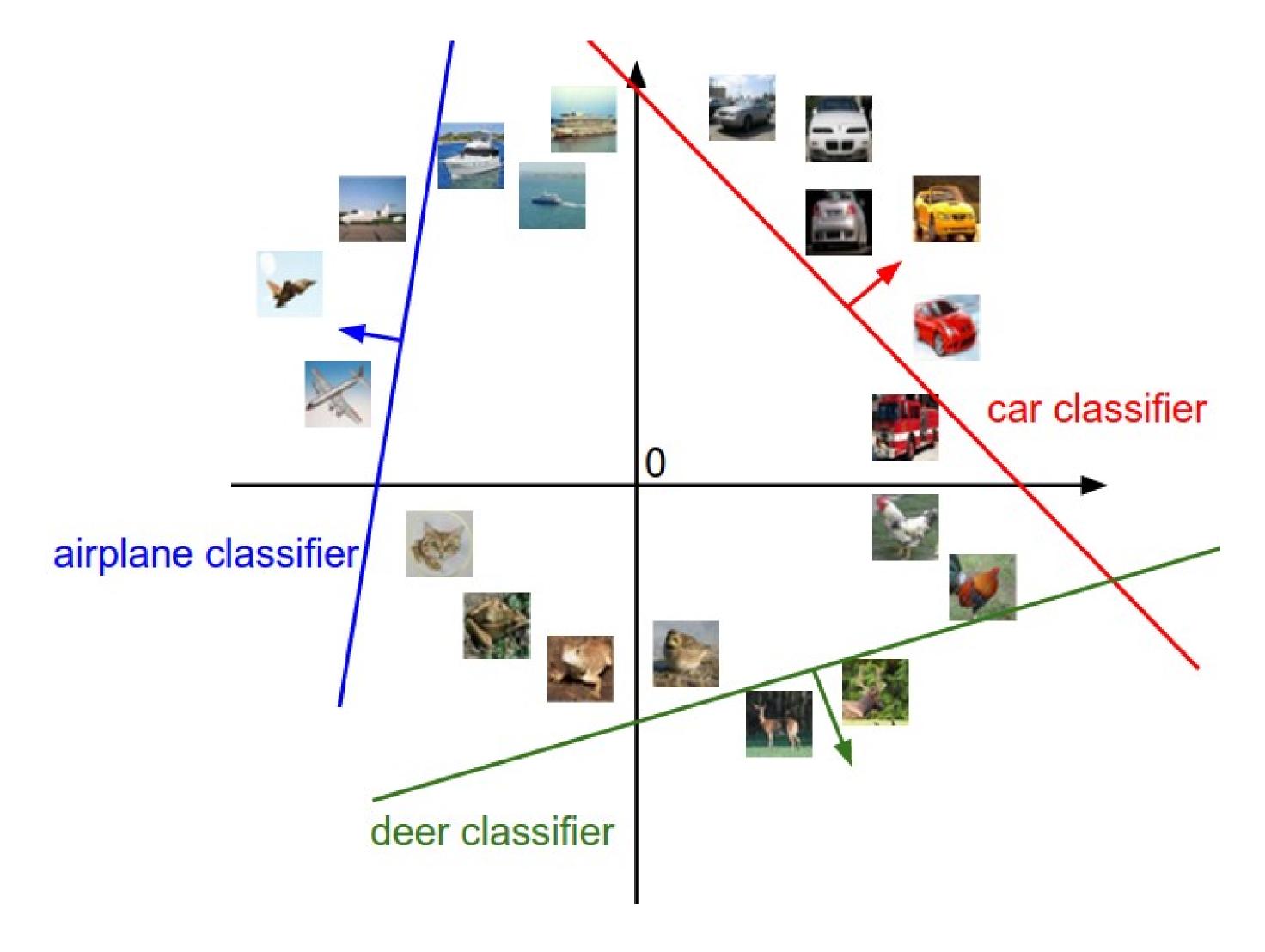
If multiple classes are predicted for a single example, ones needs a confidence level for each classifier saying how sure it is of its prediction.

- One-vs-One: one trains a classifier for each pair of class:
  - A vs. B
  - B vs. C
  - C vs. A

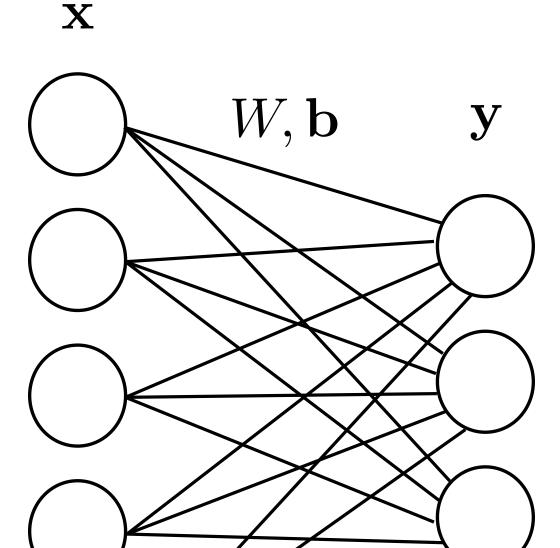
A majority vote is then performed to find the correct class.

#### **Multi-class classification**

• Example of One-vs-All classification: one binary classifier per class.



#### Softmax linear classifier



- ullet Suppose we have C classes (dog vs. cat vs. ship vs...).
- The One-vs-All scheme involves C binary classifiers  $(\mathbf{w}_i, b_i)$ , each with a weight vector and a bias, working on the same input  $\mathbf{x}$ .

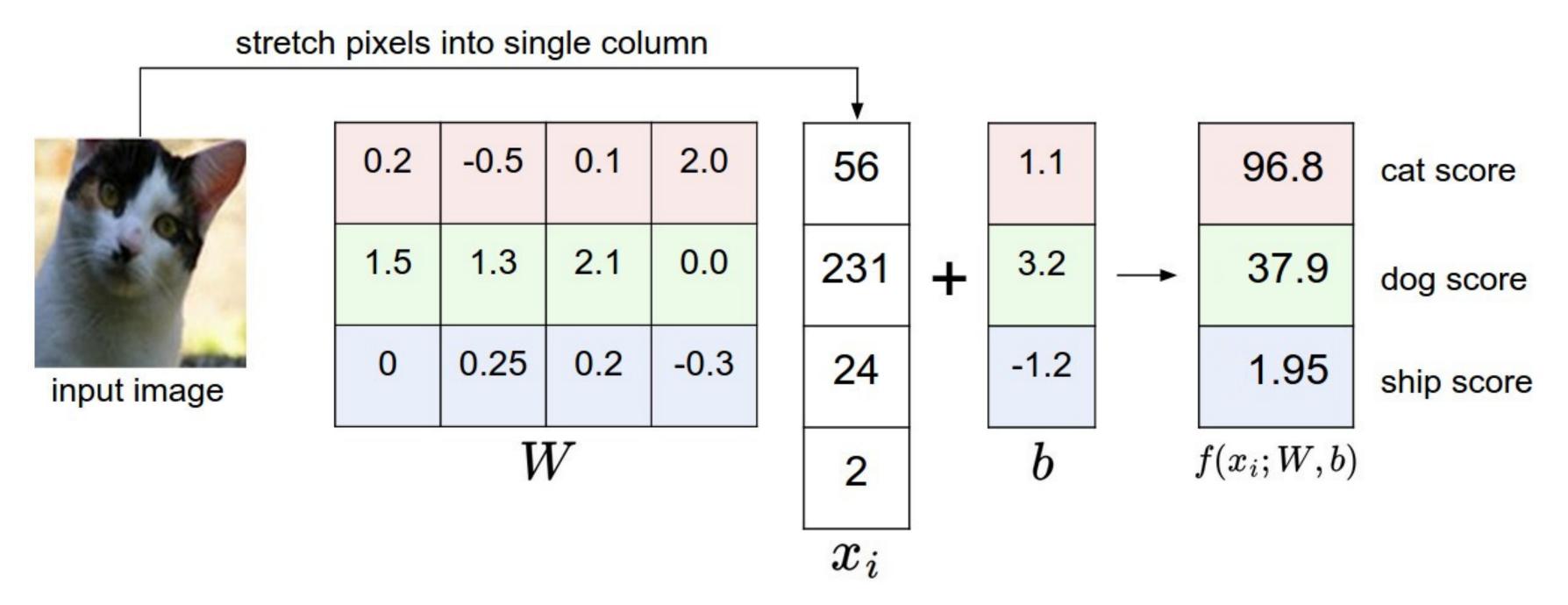
$$y_i = f(\langle \mathbf{w}_i \cdot \mathbf{x} 
angle + b_i)$$

• Putting all neurons together, we obtain a **linear perceptron** similar to multiple linear regression:

$$\mathbf{y} = f(W imes \mathbf{x} + \mathbf{b})$$

• The C weight vectors form a  $C \times d$  weight matrix W, the biases form a vector  ${\bf b}$ .

#### Softmax linear classifier



• The net activations form a vector **z**:

$$\mathbf{z} = f_{W,\mathbf{b}}(\mathbf{x}) = W imes \mathbf{x} + \mathbf{b}$$

- Each element  $z_j$  of the vector  ${\bf z}$  is called the **logit score** of the class:
  - the higher the score, the more likely the input belongs to this class.
- The logit scores are not probabilities, as they can be negative and do not sum to 1.

## One-hot encoding

- ullet How do we represent the ground truth  ${f t}$  for each neuron?
- The target vector **t** is represented using **one-hot encoding**.



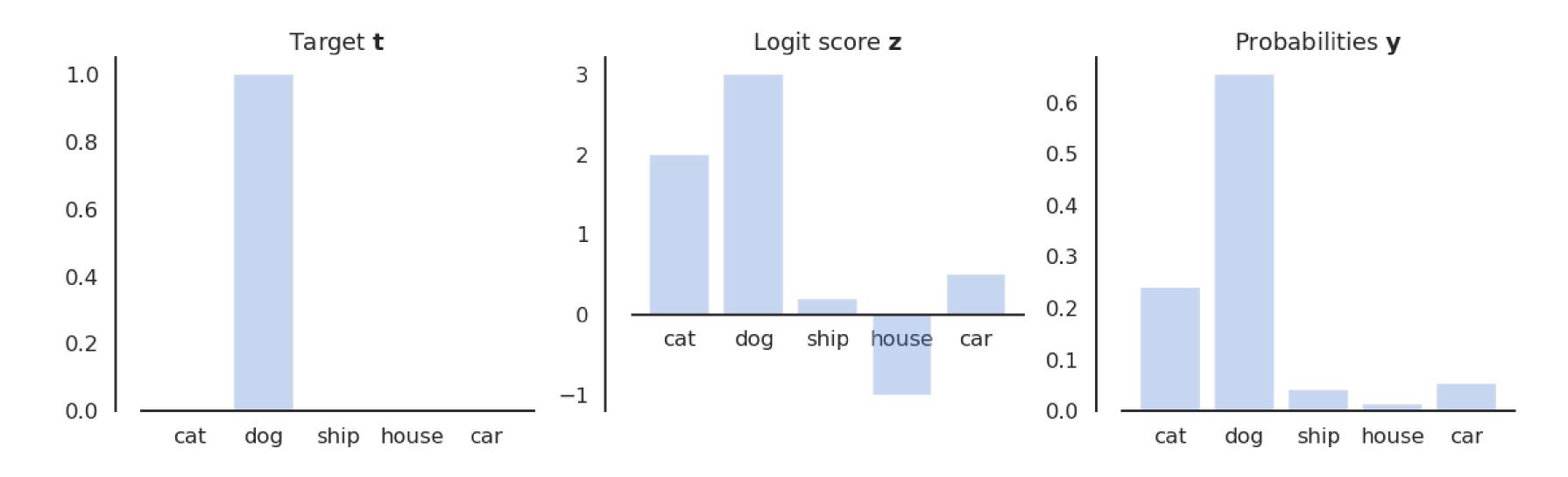
- The binary vector has one element per class: only one element is 1, the others are 0.
- Example:

$$\mathbf{t} = [\mathrm{cat}, \mathrm{dog}, \mathrm{ship}, \mathrm{house}, \mathrm{car}] = [0, 1, 0, 0, 0]$$

## One-hot encoding

- The labels can be seen as a **probability distribution** over the training set, in this case a **multinomial** distribution (a dice with C sides).
- f t:

$$P(\mathbf{t}|\mathbf{x}) = [P(\text{cat}|\mathbf{x}), P(\text{dog}|\mathbf{x}), P(\text{ship}|\mathbf{x}), P(\text{house}|\mathbf{x}), P(\text{car}|\mathbf{x})] = [0, 1, 0, 0, 0]$$



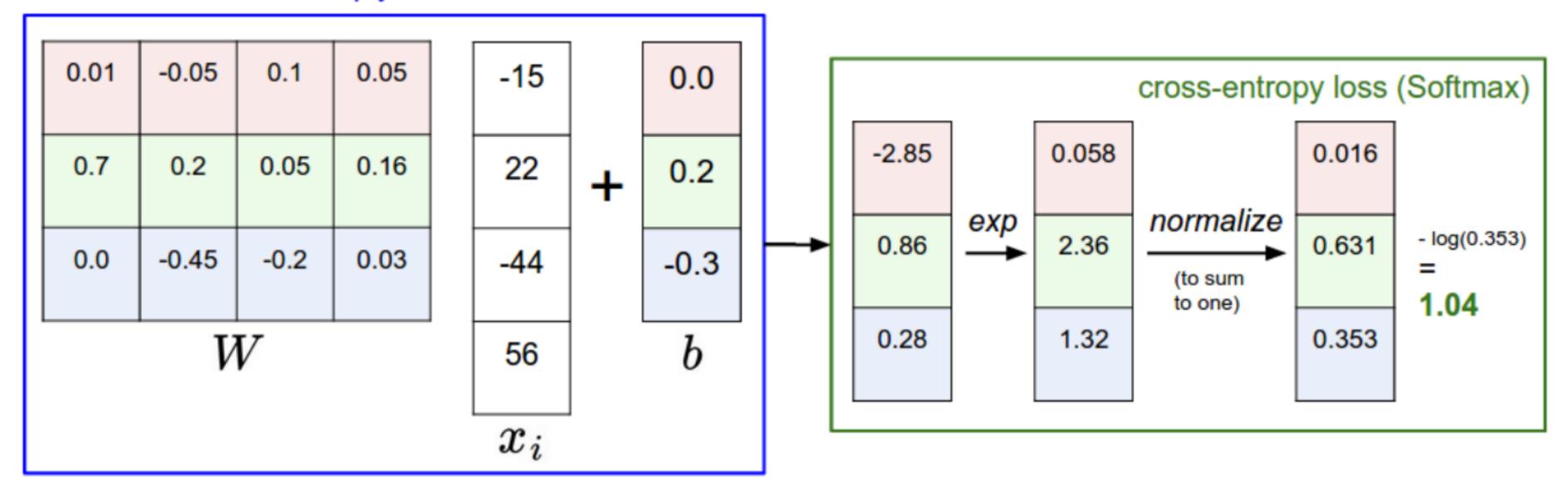
• We need to transform the logit score  $\mathbf{z}$  into a **probability distribution**  $P(\mathbf{y}|\mathbf{x})$  that should be as close as possible from  $P(\mathbf{t}|\mathbf{x})$ .

#### Softmax linear classifier

ullet The **softmax** operator makes sure that the sum of the outputs  $\mathbf{y}=\{y_i\}$  over all classes is 1.

$$y_j = P( ext{class} = ext{j}| extbf{x}) = \mathcal{S}(z_j) = rac{\exp(z_j)}{\sum_k \exp(z_k)}$$

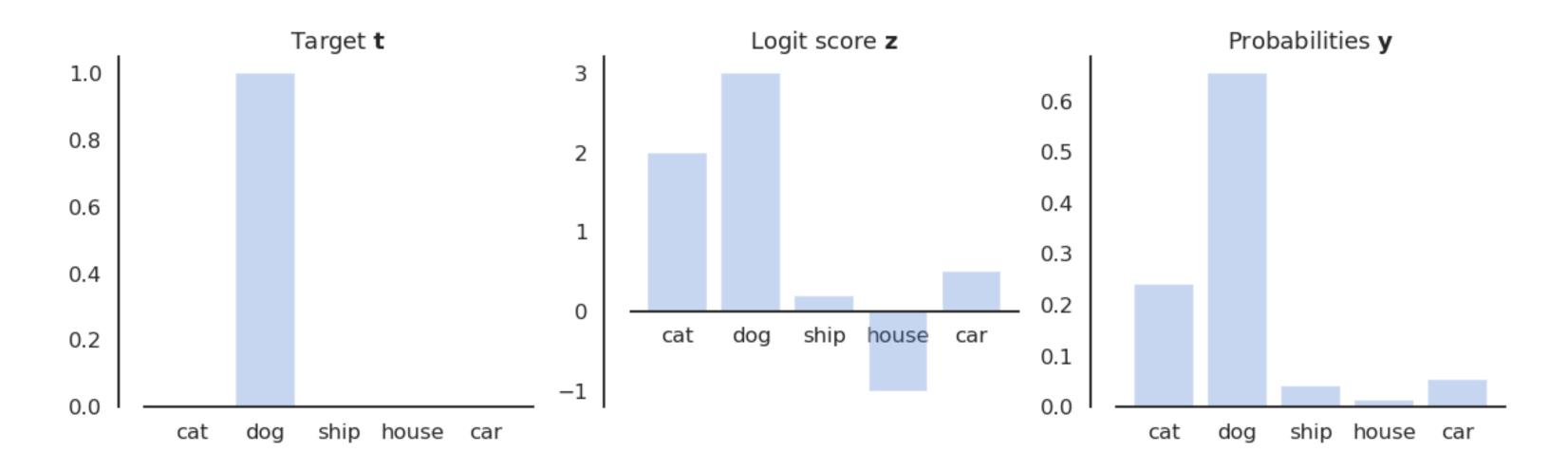
#### matrix multiply + bias offset



- The higher  $z_i$ , the higher the probability that the example belongs to class j.
- This is very similar to logistic regression for soft classification, except that we have multiple classes.

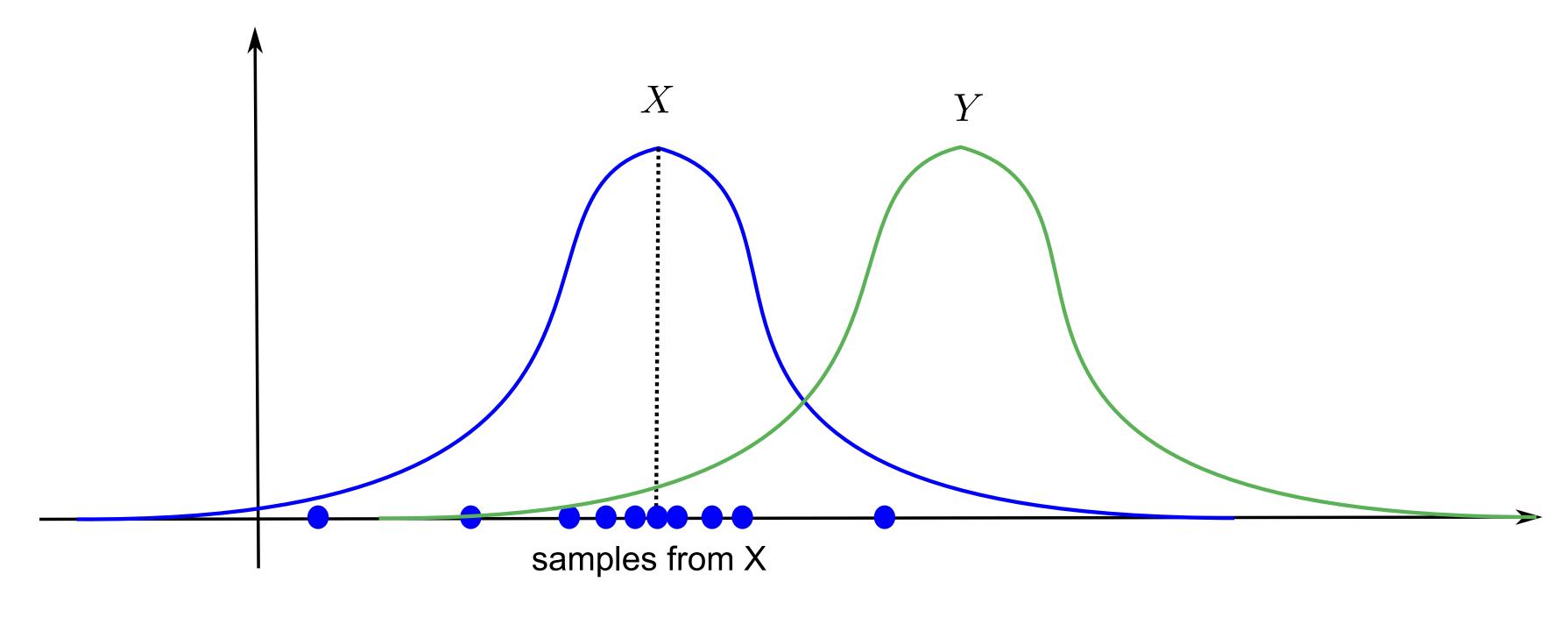
• We cannot use the mse as a loss function, as the softmax function would be hard to differentiate:

$$\mathrm{mse}(W,\mathbf{b}) = \sum_j (t_j - rac{\exp(z_j)}{\sum_k \exp(z_k)})^2$$



- We actually want to minimize the statistical distance netween two distributions:
  - The model outputs a multinomial probability distribution  ${f y}$  for an input  ${f x}$ :  $P({f y}|{f x};W,{f b})$ .
  - ullet The one-hot encoded classes also come from a multinomial probability distribution  $P(\mathbf{t}|\mathbf{x})$ .
- ullet We search which parameters  $(W,\mathbf{b})$  make the two distributions  $P(\mathbf{y}|\mathbf{x};W,\mathbf{b})$  and  $P(\mathbf{t}|\mathbf{x})$  close.

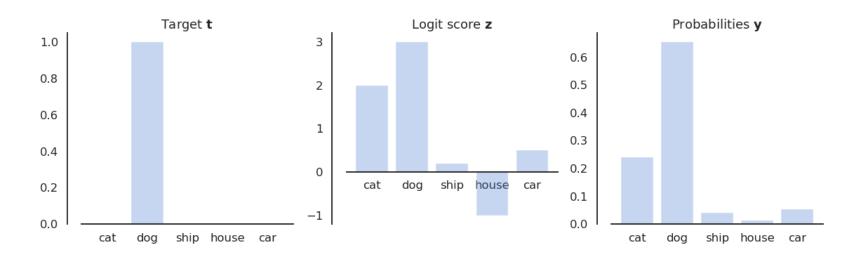
- The training data  $\{\mathbf{x}_i, \mathbf{t}_i\}$  represents samples from  $P(\mathbf{t}|\mathbf{x})$ .
- $P(\mathbf{y}|\mathbf{x};W,\mathbf{b})$  is a good model of the data when the two distributions are close, i.e. when the **negative** log-likelihood of each sample under the model is small.



ullet For an input  ${f x}$ , we minimize the **cross-entropy** between the target distribution and the predicted outputs:

$$l(W, \mathbf{b}) = \mathcal{H}(\mathbf{t}|\mathbf{x}, \mathbf{y}|\mathbf{x}) = \mathbb{E}_{t \sim P(\mathbf{t}|\mathbf{x})}[-\log P(\mathbf{y} = t|\mathbf{x})]$$

## Cross-entropy and negative log-likelihood



• The cross-entropy samples from  $\mathbf{t}|\mathbf{x}$ :

$$l(W, \mathbf{b}) = \mathcal{H}(\mathbf{t}|\mathbf{x}, \mathbf{y}|\mathbf{x}) = \mathbb{E}_{t \sim P(\mathbf{t}|\mathbf{x})}[-\log P(\mathbf{y} = t|\mathbf{x})] = -\sum_{j=1}^C P(t_j|\mathbf{x})\,\log P(y_j = t_j|\mathbf{x})$$

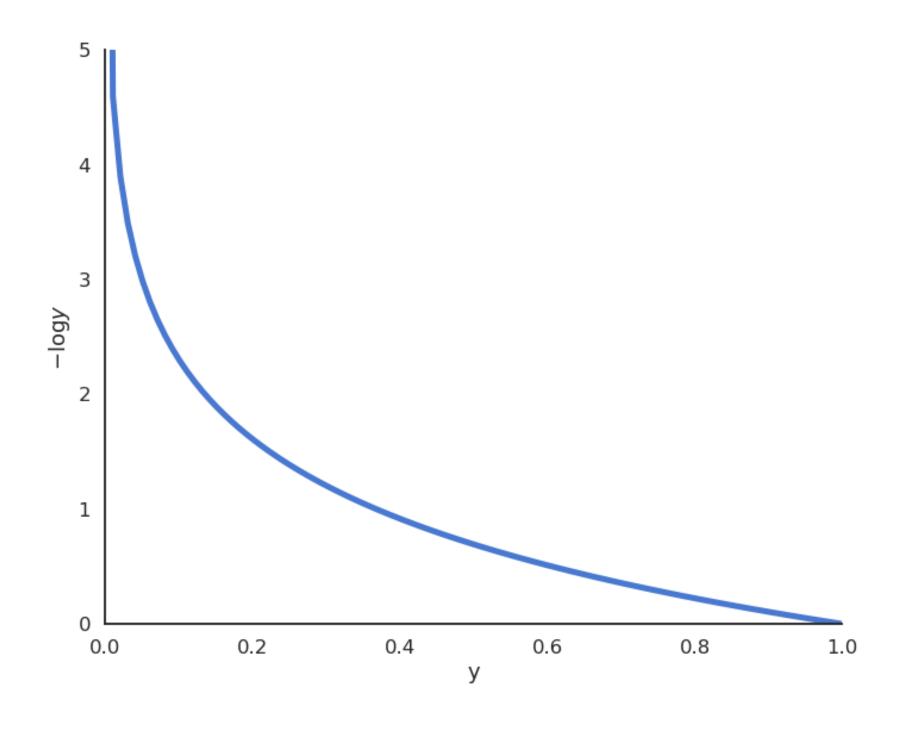
• For a given input  ${f x}$ ,  ${f t}$  is non-zero only for the correct class  $t^*$ , as  ${f t}$  is a one-hot encoded vector [0,1,0,0,0]:

$$l(W, \mathbf{b}) = -\log P(\mathbf{y} = t^* | \mathbf{x})$$

ullet If we note  $j^st$  the index of the correct class  $t^st$ , the cross entropy is simply:

$$l(W,\mathbf{b}) = -\log y_{j^*}$$

## Cross-entropy and negative log-likelihood



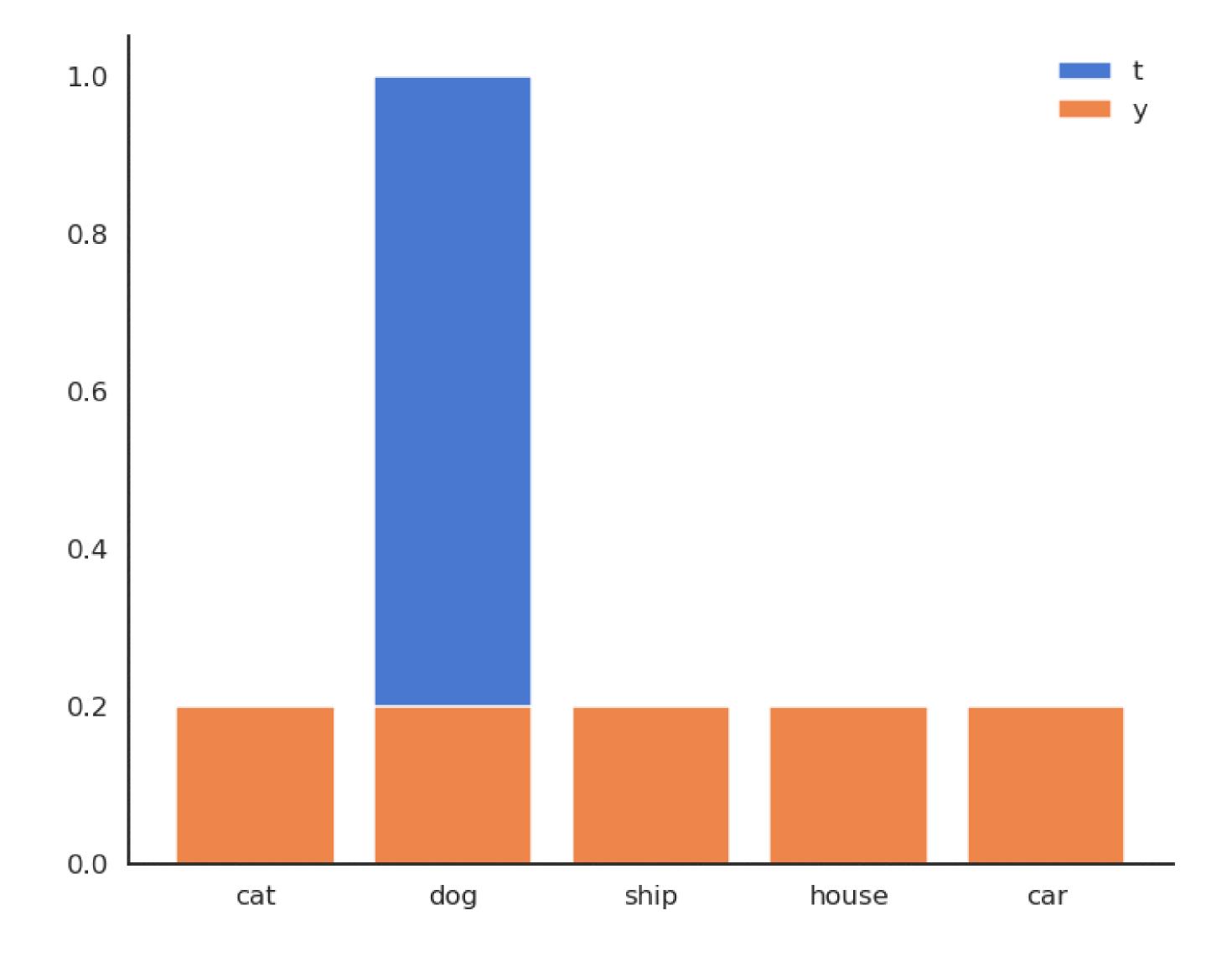
 As only one element of t is non-zero, the crossentropy is the same as the negative log-likelihood of the prediction for the true label:

$$l(W,\mathbf{b}) = -\log y_{j^*}$$

- The minimum of  $-\log y$  is obtained when y=1:
  - We want to classifier to output a probability 1 for the true label.
- Because of the softmax activation function, the probability for the other classes should become closer from 0.

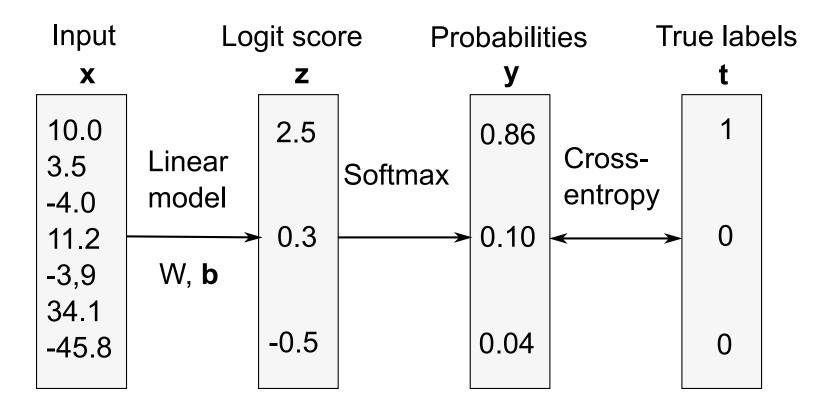
$$y_j = P( ext{class} = ext{j}) = rac{\exp(z_j)}{\sum_k \exp(z_k)}$$

• Minimizing the cross-entropy / negative log-likelihood pushes the output distribution  $\mathbf{y}|\mathbf{x}$  to be as close as possible to the target distribution  $\mathbf{t}|\mathbf{x}$ .



• As  $\mathbf{t}$  is a binary vector [0, 1, 0, 0, 0], the cross-entropy / negative log-likelihood can also be noted as the dot product between  $\mathbf{t}$  and  $\log \mathbf{y}$ :

$$l(W, \mathbf{b}) = - \langle \mathbf{t} \cdot \log \mathbf{y} 
angle = - \sum_{j=1}^C t_j \, \log y_j = - \log y_{j^*}$$



• The **cross-entropy loss function** is then the expectation over the training set of the individual cross-entropies:

$$\mathcal{L}(W, \mathbf{b}) = \mathbb{E}_{\mathbf{x}, \mathbf{t} \sim \mathcal{D}}[-\langle \mathbf{t} \cdot \log \mathbf{y} 
angle] pprox rac{1}{N} \sum_{i=1}^{N} -\langle \mathbf{t}_i \cdot \log \mathbf{y}_i 
angle$$

• The nice thing with the **cross-entropy** loss function, when used on a softmax activation function, is that the partial derivative w.r.t the logit score **z** is simple:

$$egin{aligned} rac{\partial l(W,\mathbf{b})}{\partial z_i} &= -\sum_j rac{\partial}{\partial z_i} t_j \log(y_j) = -\sum_j t_j rac{\partial \log(y_j)}{\partial z_i} = -\sum_j t_j rac{1}{y_j} rac{\partial y_j}{\partial z_i} \ &= -rac{t_i}{y_i} rac{\partial y_i}{\partial z_i} - \sum_{j 
eq i}^C rac{t_j}{y_j} rac{\partial y_j}{\partial z_i} = -rac{t_i}{y_i} y_i (1 - y_i) - \sum_{j 
eq i}^C rac{t_j}{y_i} (-y_j y_i) \ &= -t_i + t_i y_i + \sum_{j 
eq i}^C t_j y_i = -t_i + \sum_{j 
eq i}^C t_j y_i = -t_i + y_i \sum_{j 
eq i}^C t_j \ &= -(t_i - y_i) \end{aligned}$$

i.e. the same as with the mse in linear regression!

Vector notation:

$$rac{\partial l(W,\mathbf{b})}{\partial \mathbf{z}} = -(\mathbf{t}-\mathbf{y})$$

• As:

$$z = W \times x + b$$

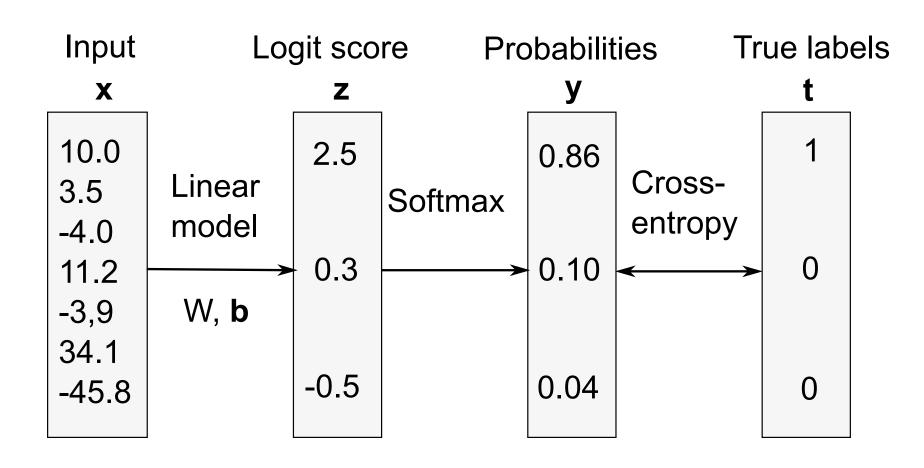
we can obtain the partial derivatives:

$$egin{aligned} rac{\partial l(W, \mathbf{b})}{\partial W} &= rac{\partial l(W, \mathbf{b})}{\partial \mathbf{z}} imes rac{\partial \mathbf{z}}{\partial W} = -(\mathbf{t} - \mathbf{y}) imes \mathbf{x}^T \ rac{\partial l(W, \mathbf{b})}{\partial \mathbf{b}} &= rac{\partial l(W, \mathbf{b})}{\partial \mathbf{z}} imes rac{\partial \mathbf{z}}{\partial \mathbf{b}} = -(\mathbf{t} - \mathbf{y}) \end{aligned}$$

• So gradient descent leads to the **delta learning rule**:

$$egin{cases} \Delta W = \eta \left( \mathbf{t} - \mathbf{y} 
ight) imes \mathbf{x}^T \ \Delta \mathbf{b} = \eta \left( \mathbf{t} - \mathbf{y} 
ight) \end{cases}$$

#### Softmax linear classifier



• We first compute the **logit scores z** using a linear layer:

$$\mathbf{z} = W \times \mathbf{x} + \mathbf{b}$$

• We turn them into probabilities **y** using the **softmax** activation function:

$$y_j = rac{\exp(z_j)}{\sum_k \exp(z_k)}$$

• We minimize the cross-entropy / negative log-likelihood on the training set:

$$\mathcal{L}(W, \mathbf{b}) = \mathbb{E}_{\mathbf{x}, \mathbf{t} \sim \mathcal{D}}[-\langle \mathbf{t} \cdot \log \mathbf{y} 
angle]$$

which simplifies into the delta learning rule:

$$egin{cases} \Delta W = \eta \left( \mathbf{t} - \mathbf{y} 
ight) imes \mathbf{x}^T \ \Delta \mathbf{b} = \eta \left( \mathbf{t} - \mathbf{y} 
ight) \end{cases}$$

## Comparison of linear classification and regression

- Classification and regression differ in the nature of their outputs: in classification they are discrete, in regression they are continuous values.
- However, when trying to minimize the mismatch between a model  ${f y}$  and the real data  ${f t}$ , we have found the same **delta learning rule**:

$$egin{cases} \Delta W = \eta \left( \mathbf{t} - \mathbf{y} 
ight) imes \mathbf{x}^T \ \Delta \mathbf{b} = \eta \left( \mathbf{t} - \mathbf{y} 
ight) \end{cases}$$

- Regression and classification are in the end the same problem for us. The only things that needs to be adapted is the activation function of the output and the **loss function**:
  - For regression, we use regular activation functions and the mean square error (mse):

$$\mathcal{L}(W, \mathbf{b}) = \mathbb{E}_{\mathbf{x}, \mathbf{t} \in \mathcal{D}}[||\mathbf{t} - \mathbf{y}||^2]$$

For classification, we use the softmax activation function and the cross-entropy (negative log-likelihood) loss function:

$$\mathcal{L}(W, \mathbf{b}) = \mathbb{E}_{\mathbf{x}, \mathbf{t} \sim \mathcal{D}}[-\langle \mathbf{t} \cdot \log \mathbf{y} 
angle]$$

## 5 - Multi-label classification

#### Multi-label classification



GK Hart/Vikki Hart/Getty Images

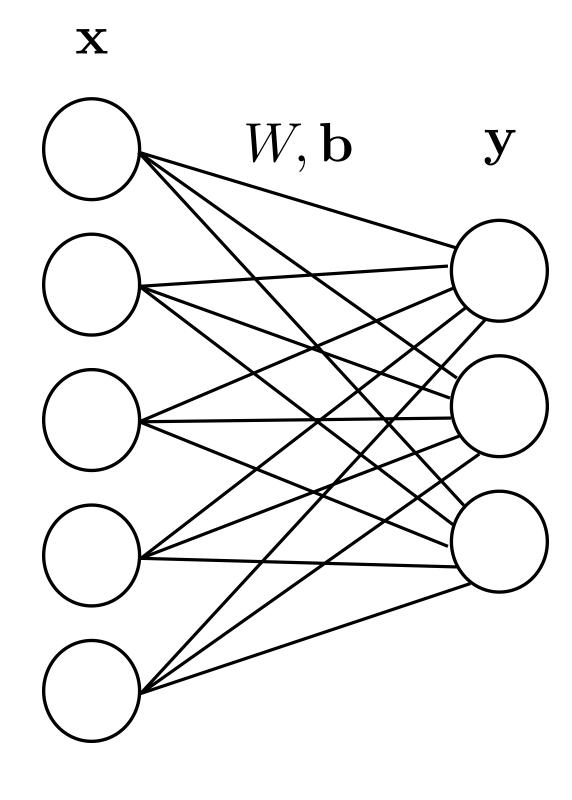
- What if there is more than one label on the image?
- The target vector **t** does not represent a probability distribution anymore:

$$\mathbf{t} = [\mathrm{cat}, \mathrm{dog}, \mathrm{ship}, \mathrm{house}, \mathrm{car}] = [1, 1, 0, 0, 0]$$

• Normalizing the vector does not help: it is not a dog **or** a cat, it is a dog **and** a cat.

$$\mathbf{t} = [\mathrm{cat}, \mathrm{dog}, \mathrm{ship}, \mathrm{house}, \mathrm{car}] = [0.5, 0.5, 0, 0, 0]$$

#### Multi-label classification



• For multi-label classification, we can simply use the **logistic** activation function for the output neurons:

$$\mathbf{y} = \sigma(W imes \mathbf{x} + \mathbf{b})$$

• The outputs are between 0 and 1, but they do not sum to one. Each output neuron performs **logistic regression for soft classification** on their class:

$$y_j = P({
m class} = j | {f x})$$

• Each output neuron  $y_j$  has a binary target  $t_j$  (one-vs-the-rest) and has to minimize the negative log-likelihood:

$$l_j(W,\mathbf{b}) = -t_j\,\log y_j + (1-t_j)\,\log(1-y_j)$$

• The **binary cross-entropy** loss is the sum of the negative log-likelihood for each class:

$$\mathcal{L}(W, \mathbf{b}) = \mathbb{E}_{\mathcal{D}}[-\sum_{j=1}^C t_j \, \log y_j + (1-t_j) \, \log(1-y_j)]$$