

Classifying Colon Cancer Colonoscopy Images Using Edge Histograms

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15. Januar 2017

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Task - Overview

What?

- Colon cancer colonoscopy images
- Edge histograms
- KNN: K Nearest Neighbors - Classification

Task - Overview

How?

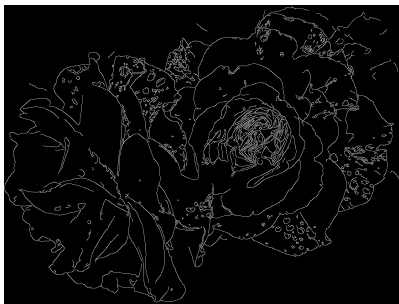
- 1 Preprocess images
- 2 Perform edge detection
- 3 Extract features (e.g. edge lengths)
- 4 Compute Edge Histogram
- 5 Classify with KNN
- 6 Analyze the results

Edges:

Edges are pixels, in which the image intensity function changes its magnitude



(a) Original Image



(b) Image after Edge Detection

Abbildung: Edge Detection using Canny

Edge Detection:

Almost every Edge Detector uses either the first derivative or the second derivative of the intensity function.

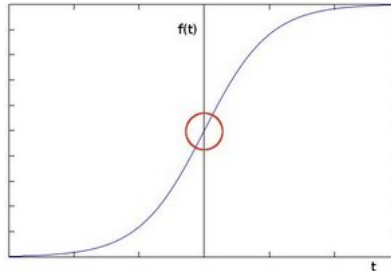


Abbildung: Intensity function

First Derivative:

Sobel-, Roberts-, Robinson-, Kirsch-Operator

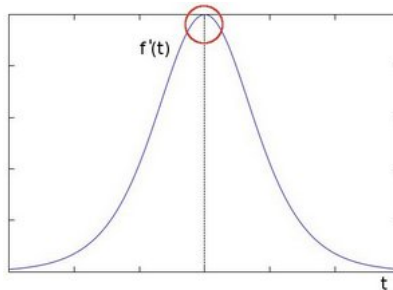


Abbildung: Intensity function - First derivative

Second Derivative:

Laplace-, Mexican-Hat-Operator

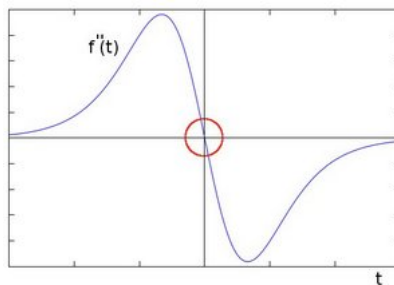


Abbildung: Intensity function - Second derivative

Canny Edge Detection:

- Low error rate
- Good localization
- Minimal response

Steps:

- 1 Filter out noise using Gaussian filter
- 2 Find the intensity gradient using Sobel-Operator

$$G = \sqrt{G_x^2 + G_y^2} \text{ or } G = |G_x| + |G_y|$$

- 3 Non-maximum suppression
- 4 Hysteresis

Overview

- Development and Frameworks
- Image Enhancement
- Edge Detection
- Edge Lengths
- Edge Orientation
- Histograms
- Image Classification

Development and Frameworks

Developed using:

- Java 8
- OpenCV for Java
- Eclipse Neon

Image Enhancement and Conversion

- Color Space Conversion
- Normalization
- CLAHE
- All part of OpenCV

Image Enhancement and Conversion

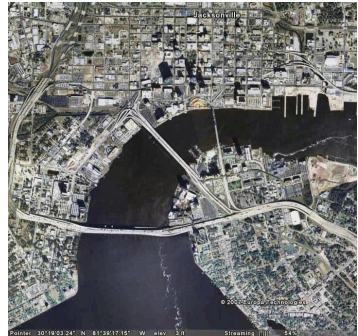


Image Enhancement and Conversion

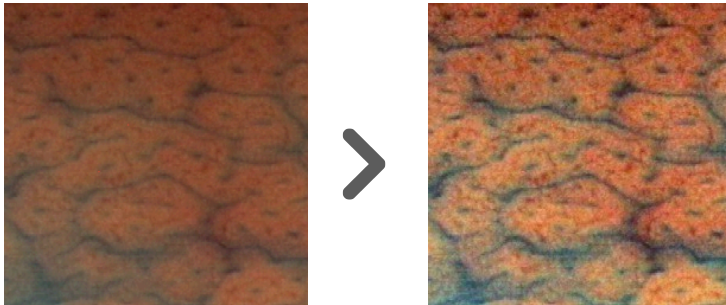
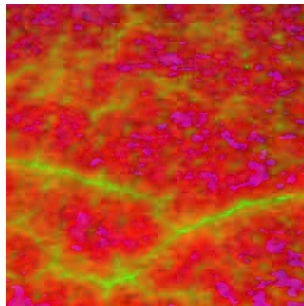
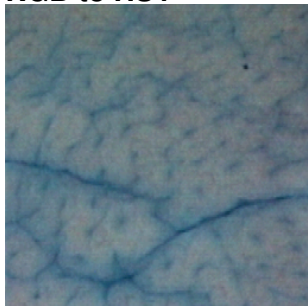


Image Enhancement and Conversion

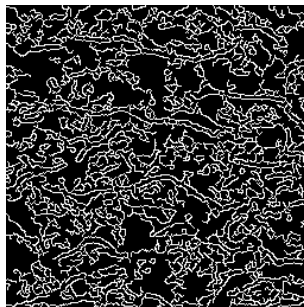
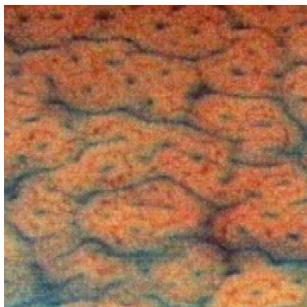
RGB to HSV



Edge Detection

- Grayscale Conversion
- Canny Edge Detector

Edge Detection



Edge Histograms

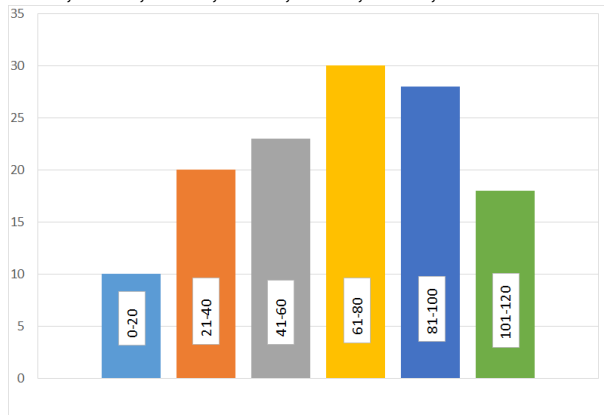
Definition

- Characteristics of an image e.g. edge lengths
- Partition characteristic attributes into bins
- In our case: Edge lengths & orientations
- Length: Image has
 - 5 edges of length 0 - 20 pixels
 - 20 edges of length 100 - 120 pixels

Edge Histograms

Simple Example:

10.0, 20.0, 23.0, 30.0, 28.0, 18.0, 1



Edge Histograms

- Histogram data for each example image collected in a hist-file.
- Specify Category. Here: Cancer stage
- Example:

```
210.0, 3.0, 170.0, 142.0, 126.0, 93.0, 32.0, 16.0, 1  
192.0, 2.0, 181.0, 139.0, 119.0, 87.0, 32.0, 17.0, 1  
143.0, 1.0, 172.0, 147.0, 128.0, 91.0, 30.0, 16.0, 1
```

Edge Lengths

Prerequisites

- Image with detected Edges
- Edges white
- Rest black
- Not entirely given → Threshold set at grayscale 200

Edge Lengths

Algorithm

Iterate over all pixels

- 1 Check if pixel is white → new edge found
- 2 Check immediate neighbours: if white → add pixel to edge
- 3 Follow white path until no more connected white pixels
- 4 Add all passes pixels to Collection of used pixels
- 5 Add one to category with detected length
- 6 Continue iterating and start at 1

Edge Lengths

Algorithm

```
function measureEdge(pixel) {  
    length = 1  
    for each surrounding pixel p:  
        if p == white  
            length += measureEdge(p)  
  
    return length  
}
```


Edge Orientation

- Requires edge detected image
- Use sobel operator to detect edges
- Extract edge orientations from image (OpenCV)
- Partition edges into bins
- Bin content: pixels part of edge with certain orientation
- Category: range of angles

Image Classification

- 1 Classify all example images → create file with histograms
- 2 Create List of Feature Vectors
- 3 Enhance image to classify
- 4 Create Feature Vector
- 5 KNN: Compare new vector all vectors in list
→ euclidean distance
- 6 Select K vectors with smallest distance
- 7 Classification: category found most often

Optimization of parameters

Difference between a perfectly working and barely functional program

- Selection of input images
- Thresholds for edge detection
- Edge Lengths: number of bins, range of lengths in bins
- Weights of features: all equally significant
 - Lengths: per edge
 - Orientation: per pixel

Problems

Encountered Problems



Results

Colormodels compared

Results

Edgelenh vs Edge Orientation vs both