

Data Structures & Algorithms

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Recap

- BFS
- DFS
- $O(|V| + |E|)$
- BSF and DFS Trees

Objectives

1. Optimization Problems
2. Greedy Algorithms
3. Minimum Spanning Tree
 - MST in Unweighted Graphs
 - MST in Weighted Graphs (Prim's Algorithm, and Krushkal's Algorithm)

Optimization Problems

Optimization Problems

- Many important problems that we deal in real-life are *optimization problems*
- Important thing to remember about such problems
 - *There exist many possible solutions*
 - *The goal is to find “an optimum” solution from amongst all possible solutions*

Optimization Problems

- If u and v are two vertices in a graph G , and I ask you to find a path between them – not an optimization problem
- But, if I ask you to find the/a shortest path between them – optimization problem
- Clues: “smallest”, “shortest” or “minimize” –
“largest”, “longest” or “maximize”

Optimization Problems

- Examples
 - Rod cutting problem
 - Knapsack problem
 - Travelling salesman problem
 - Vehicle routing problem

Greedy Algorithms

- Classic algorithmic paradigm for approaching optimization problems
- Basic structure:
 - Solve the problem as making a sequence of “moves”
 - The move that we take is the one that seems the best at the moment
 - Every time we make a move, we end up with a smaller version of the problem

Greedy Algorithms

- Finding solutions to problem **step-by-step**
- A partial solution is **incrementally expanded** towards a complete solution
- In each step, there are several ways to expand the partial solution
- The **best alternative for the moment is chosen**, the others are discarded.
- Thus, at each step the choice must be **locally optimal**
– this is the central point of this technique

Example: Activity Selection Problem

- **Problem:** Given a set $A = \{A_1, A_2, \dots, A_n\}$ of n activities with start and finish times (s_i, f_i) , $1 \leq i \leq n$, select maximal set S of “non-overlapping” activities.

Example: Activity Selection Problem

- Greedy solution:
 - Sort activity by finish time (let A_1, A_2, \dots, A_n be denote sorted sequence)
 - Pick first activity A_1
 - Remove all activities with start time before finish time of A_1
 - Recursively solve problem on remaining activities.

Example: Activity Selection Problem

- Greedy solution:

GREEDY-ACTIVITY-SELECTOR(s, f)

```
1   $n = s.length$ 
2   $A = \{a_1\}$ 
3   $k = 1$ 
4  for  $m = 2$  to  $n$ 
5      if  $s[m] \geq f[k]$ 
6           $A = A \cup \{a_m\}$ 
7           $k = m$ 
8  return  $A$ 
```

Example: Currency Counting

- For example, counting to a desired value using the least number of coins
- Let's say, we are given coins of value 1, 2, 5 and 10 of some currency. And the target value is 16 in that currency
- How will you proceed?

Example: Currency Counting II

- Does not always give the optimal solution
- Let's say, a monetary system consists of only coins of worth 1, 7 and 10.
- How would a greedy approach count out the value of 15?

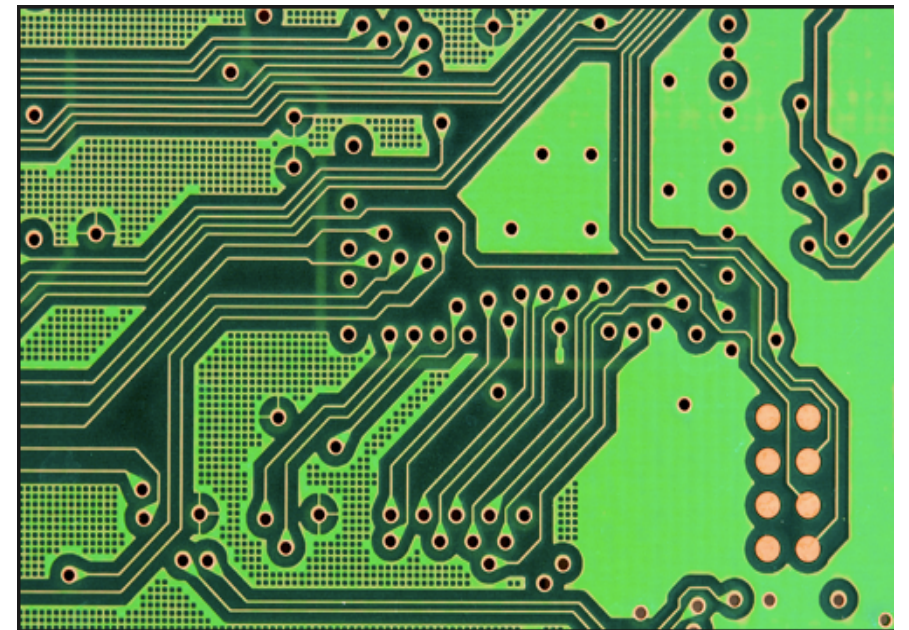
More Details

- For more details on Greedy Approaches
- Read Chapter 16, “*Introduction to Algorithms*”

Minimum Spanning Tree

Minimum Spanning Tree

- Suppose you have designed a printed circuit board
- You want to make sure that you have used the **minimum number of traces**
 - no extra connections between pins; would take up extra room
- How can you find these extra traces, if any?



Minimum Spanning Tree

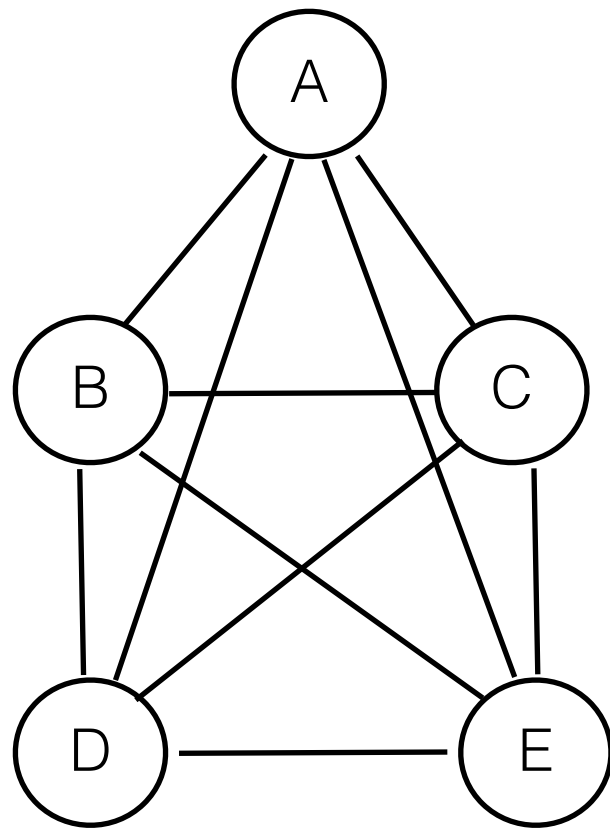
- Same question arises in many other situations:
 - ❖ Computer networks
 - ❖ Transportation networks
 - ❖ Water supply networks
 - ❖ Telecommunication networks

Minimum Spanning Tree

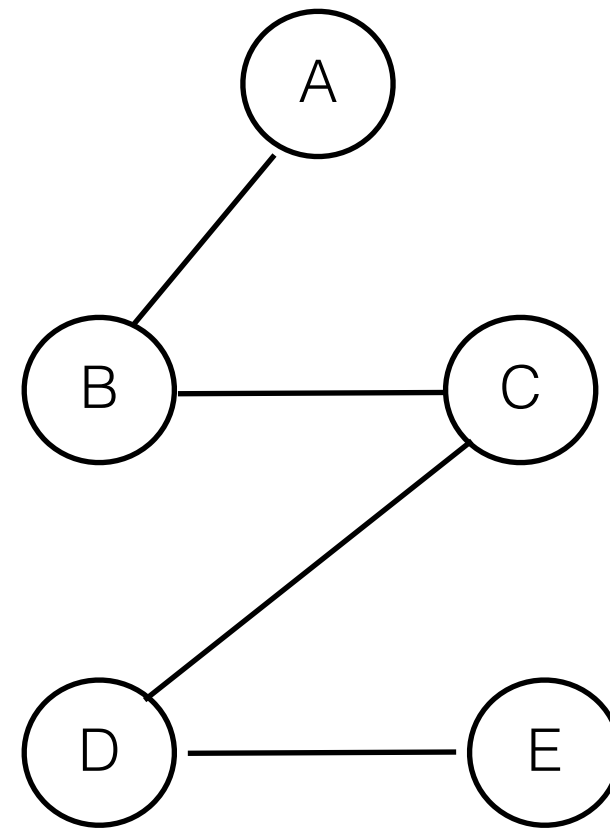
- The trick is to imagine such cases as a graph
 - Pins & Traces -> Vertices & Edges
- Then, **reduce** this graph such that it has the **same vertices** with the **minimum number of edges** to **connect** them

Minimum Spanning Tree

Minimum Spanning Tree



Extra Edges



Minimum Number of Edges

Remember: There are many possible minimum spanning trees for a given set of vertices
Notice that number of edges in MST is one less than the number of vertices!

Minimum Spanning Tree

- For **unweighted** graphs, **every spanning tree** is the **MST**
- DFS and BFS can be used
- Execute, and record the discovery edges

Minimum Spanning Tree

- We can find MST of a graph only if it is connected.
- Otherwise, we can find a union of MSTs for each of its connected component – *Minimum Spanning Forest*

Minimum Spanning Trees (MST) with Weighted Graphs

Weighted Graphs

- A graphs where each edge has a weight
- For example, in a weighted graph of cities, a weight could represent the
 - ❖ Distance between cities
 - ❖ Cost to fly between cities
 - ❖ Number of automobile trips made annually between them

MST with Weighted Graphs

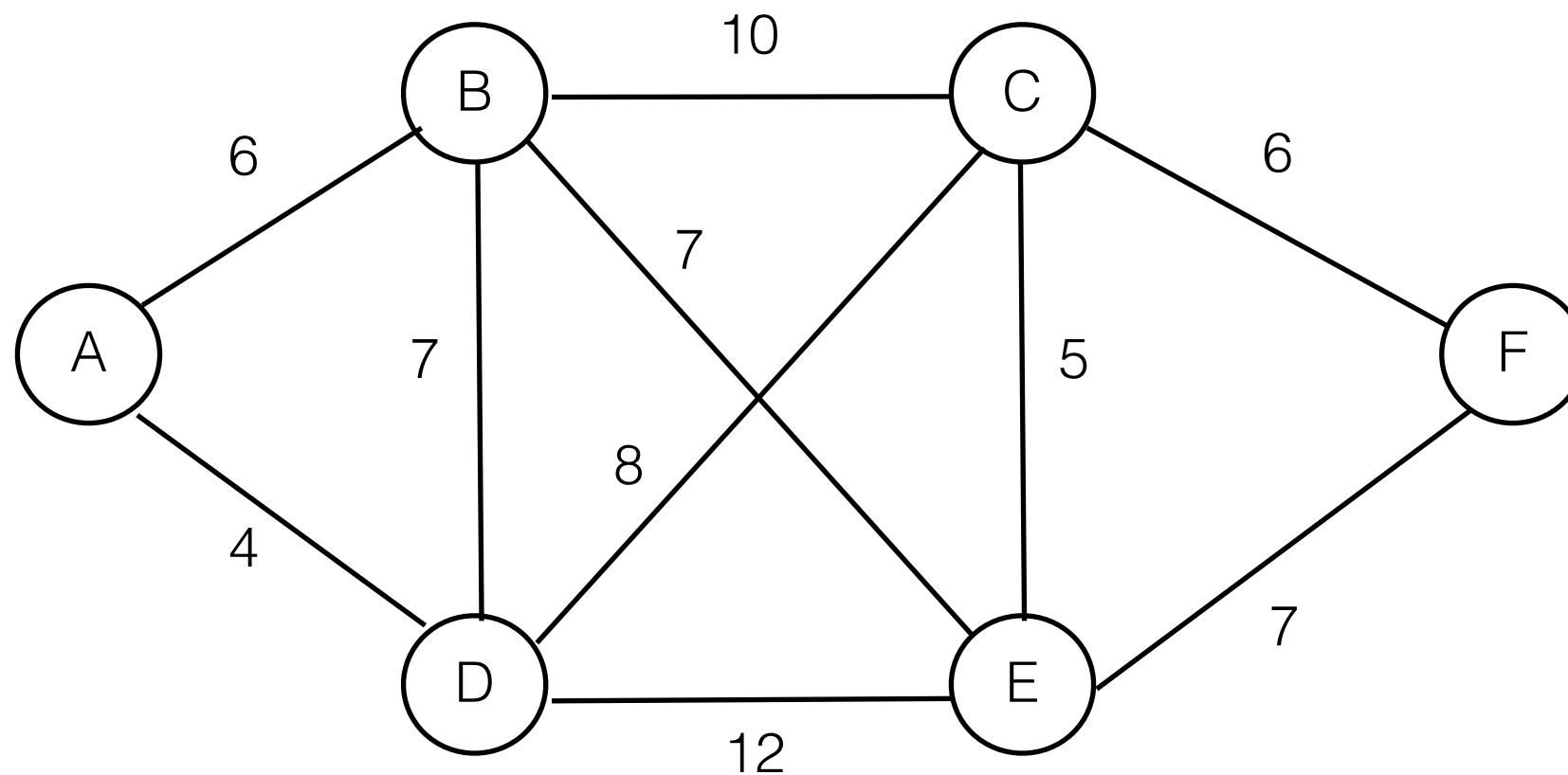
- Finding MST is a bit more difficult with weighted graphs
- Let's try to understand the process with the help of an example

MST with Weighted Graphs

- Example:
- We want to install a cable television line that connects **six cities**
 - Installing cable between any pair of cities has an associated cost
 - We want to achieve our goal with smallest cost

MST with Weighted Graphs

Let's say we are given the following information



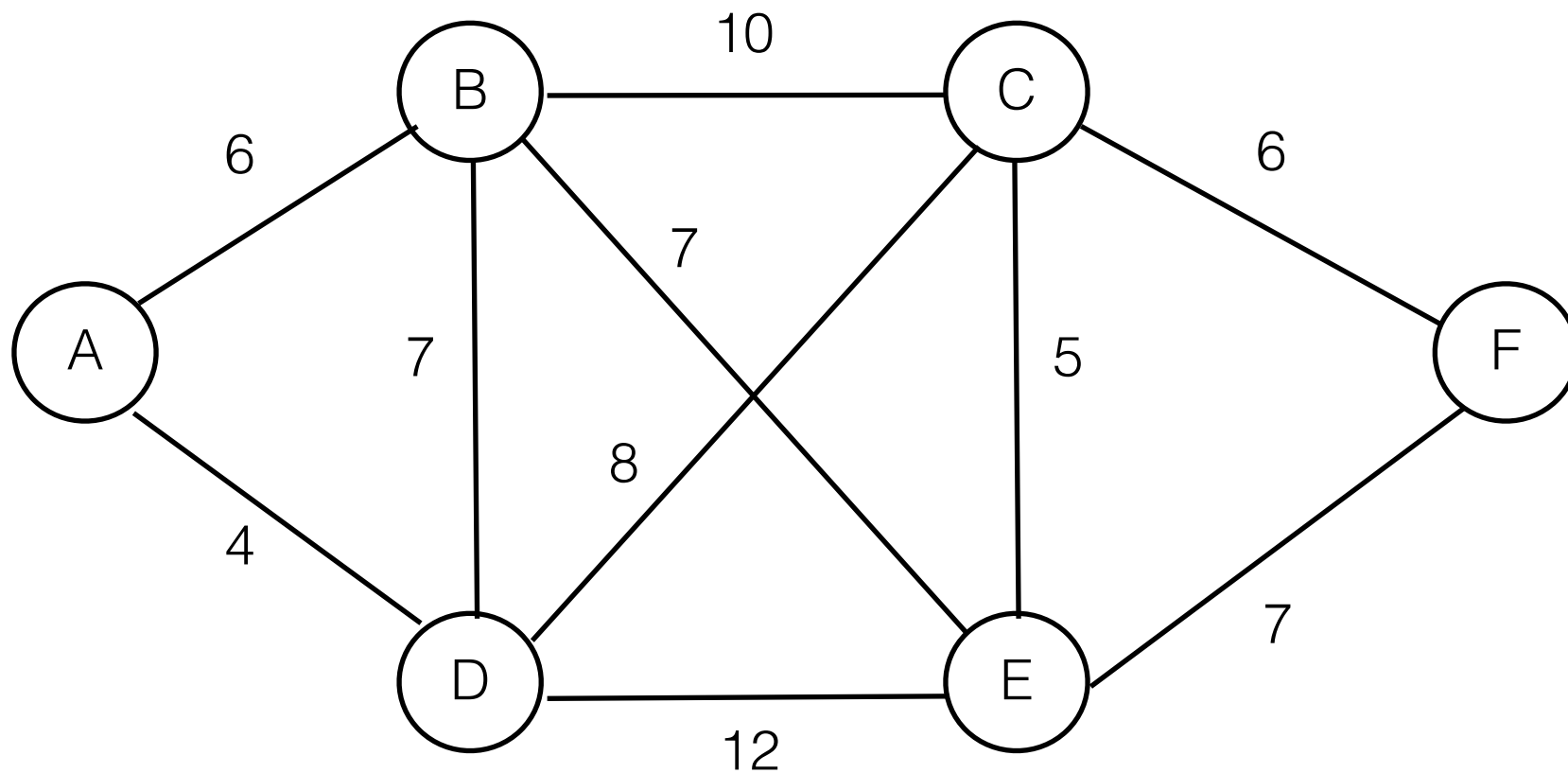
Weight: cost of installing cable, in million USD

Some links are missing; let's assume that they are just too expensive that there is no point in considering them
But the algorithm will work fine even if they were present.

MST with Weighted Graphs

- Given this information, we need to generate the minimum spanning tree for this graph
- Let's see how to do this.

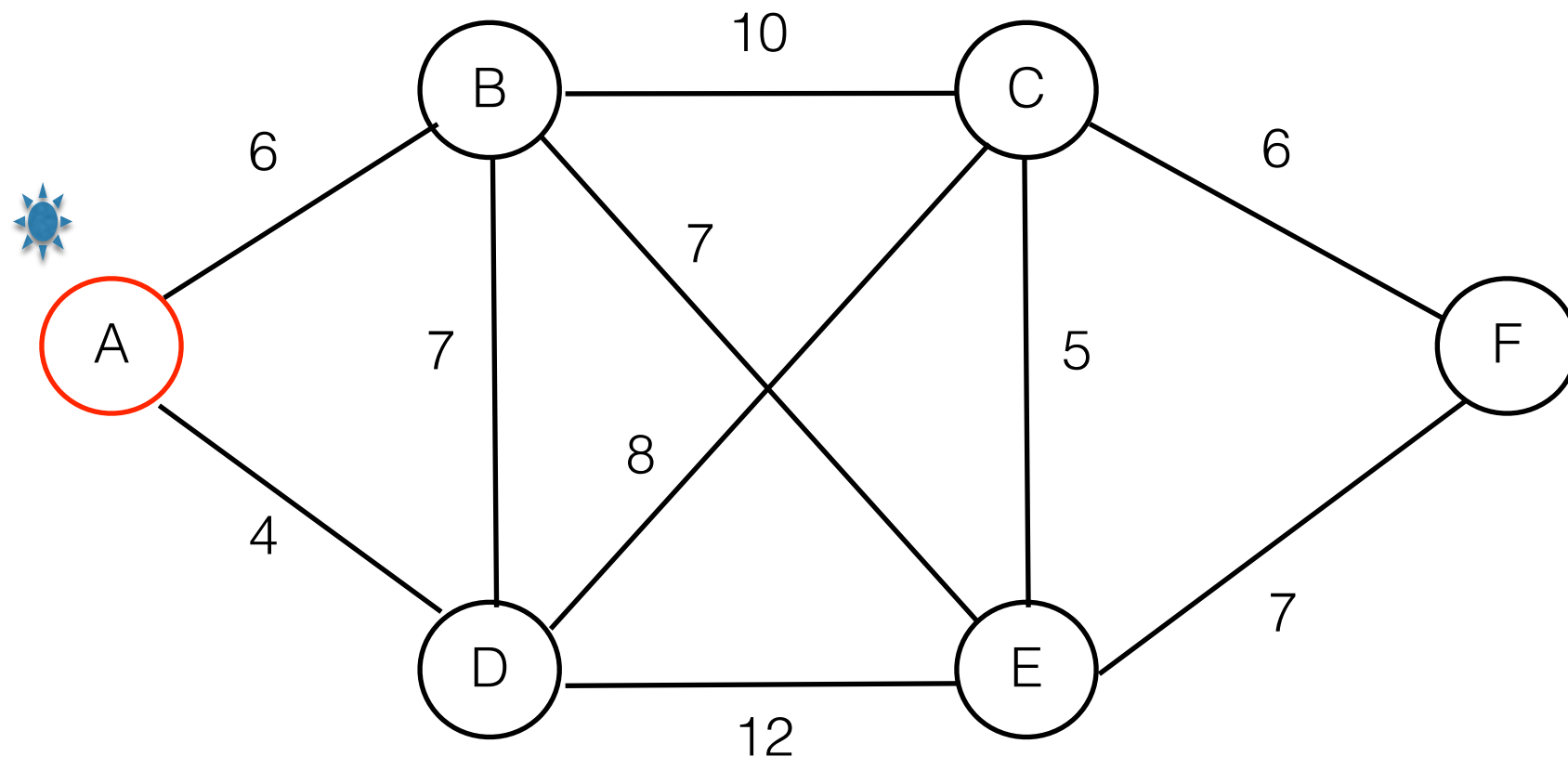
MST with Weighted Graphs



Edge	Weight

1. Start with any city; Let's pick A
2. Create an office in A
3. Measure the weight of the adjacent edges and insert them in the list on the right

MST with Weighted Graphs

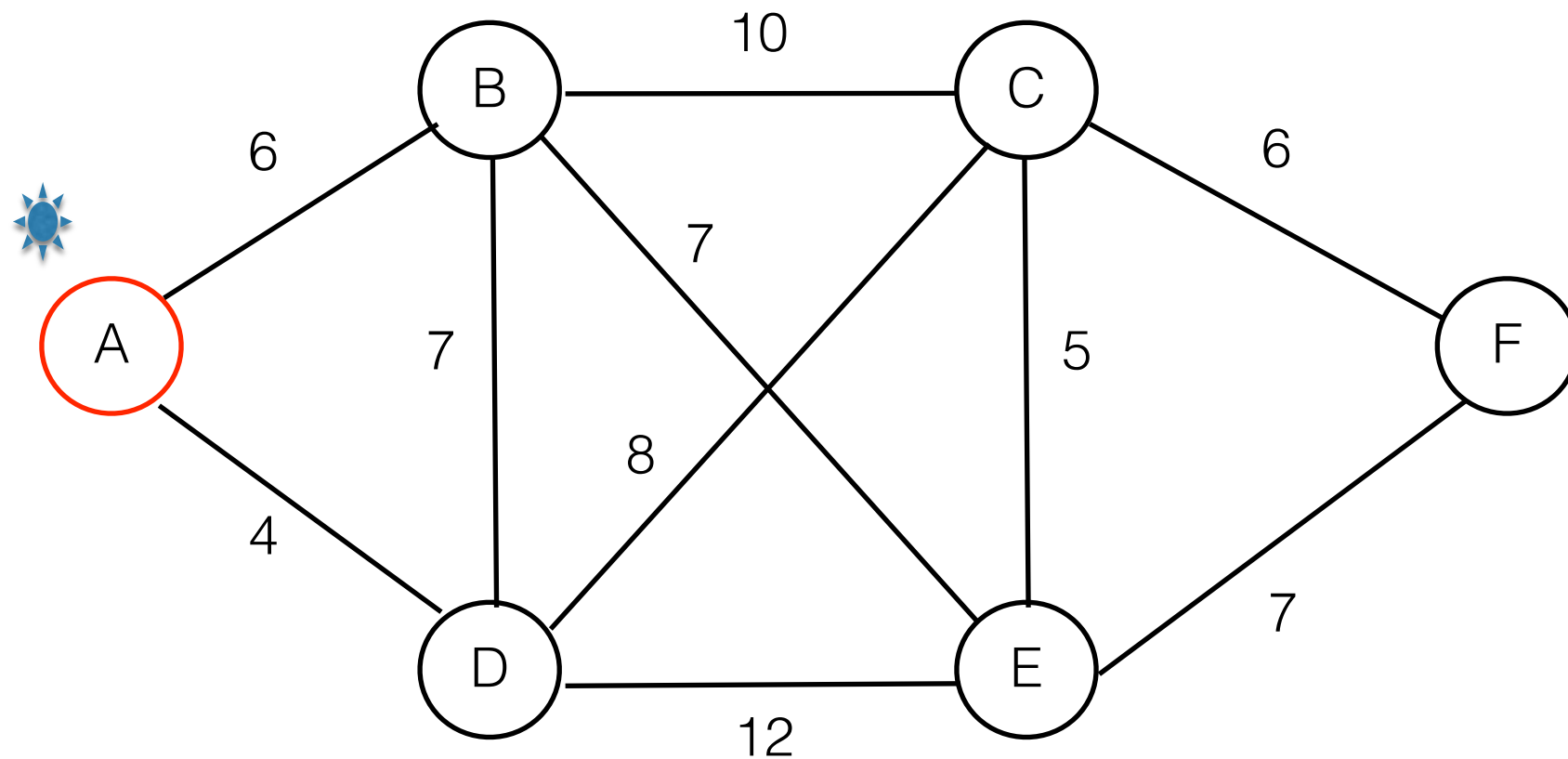


Edge	Weight
AB	6
AD	4



Indicates where a new office has just been built!

MST with Weighted Graphs



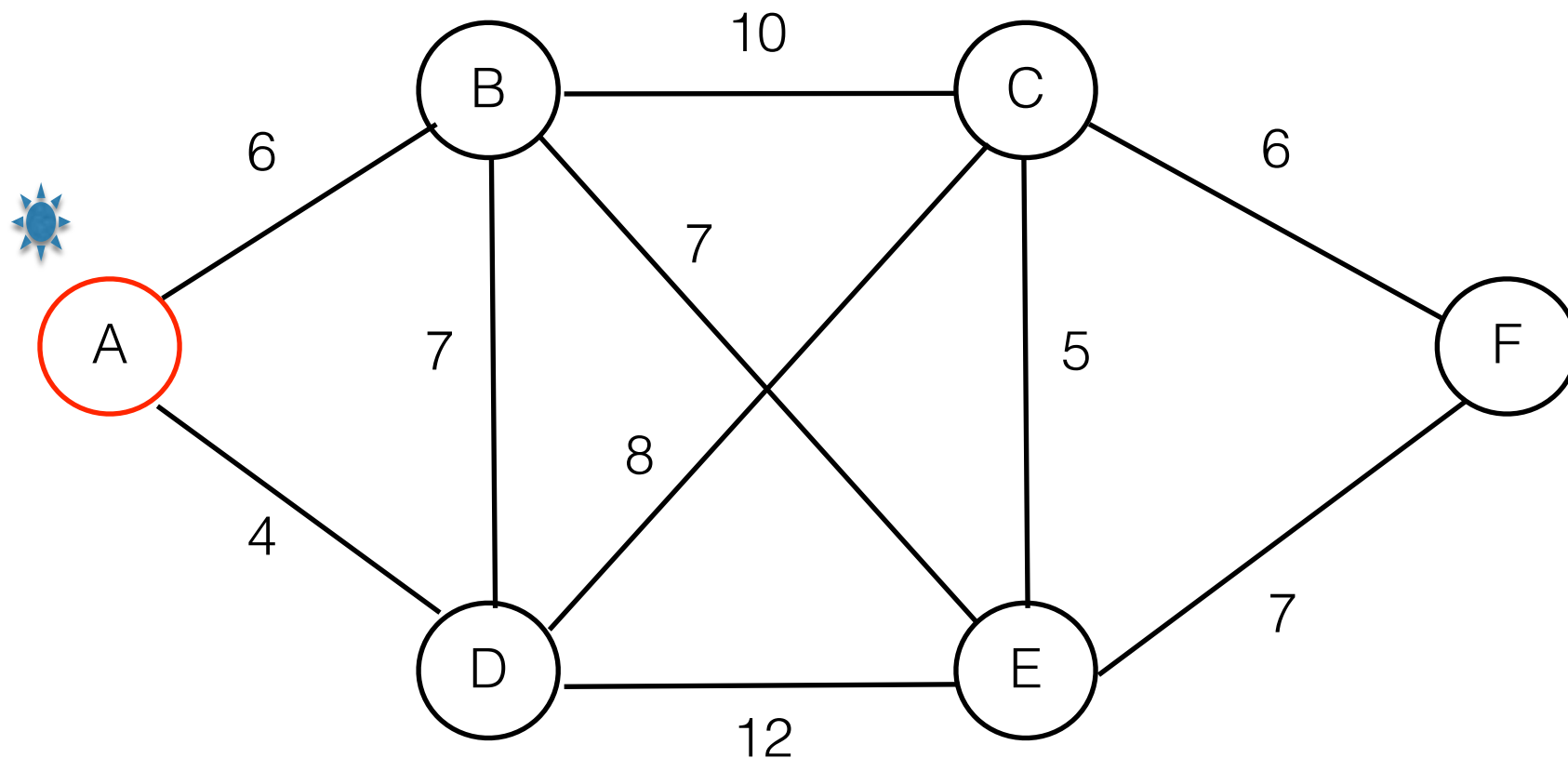
Edge	Weight
AB	6
AD	4

1. From the list, pick the cheapest link
2. Install it
3. Remove it from the list
4. Create an office in the new city.

Greedy Algorithms

- Try to find solutions to problems step-by-step
 - A partial solution is incrementally expanded towards complete solution
 - In each step, there are several ways to expand the partial solution:
 - The best alternative for the moment is chosen, the others are discarded
- At each step the choice must be **locally optimal** – this is the central point of this technique

MST with Weighted Graphs

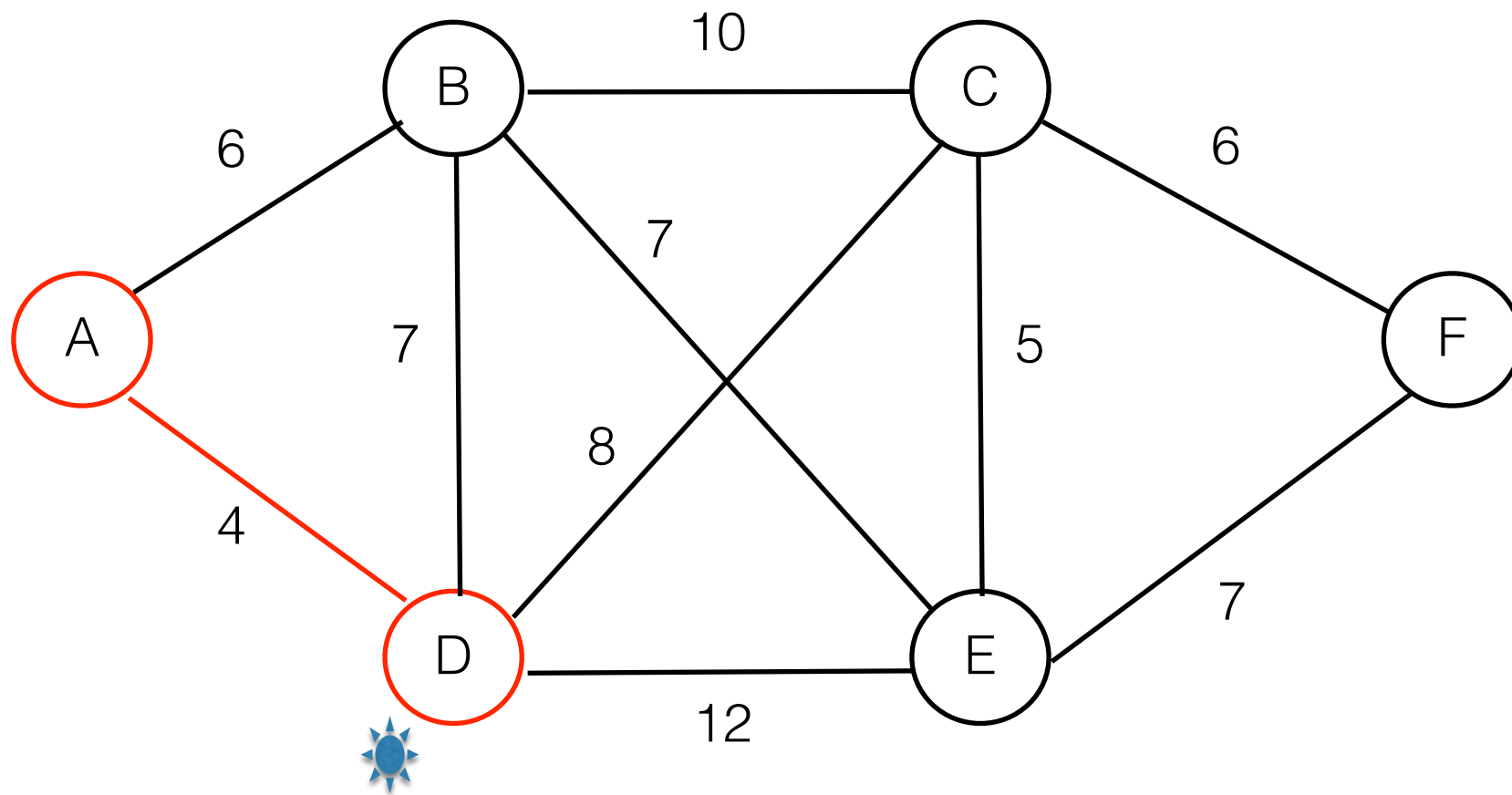


Edge	Weight
AB	6
AD	4

- From the list, pick the cheapest link
- Install it
- Remove it from the list
- Create an office in the new city.

Greedy Algorithm

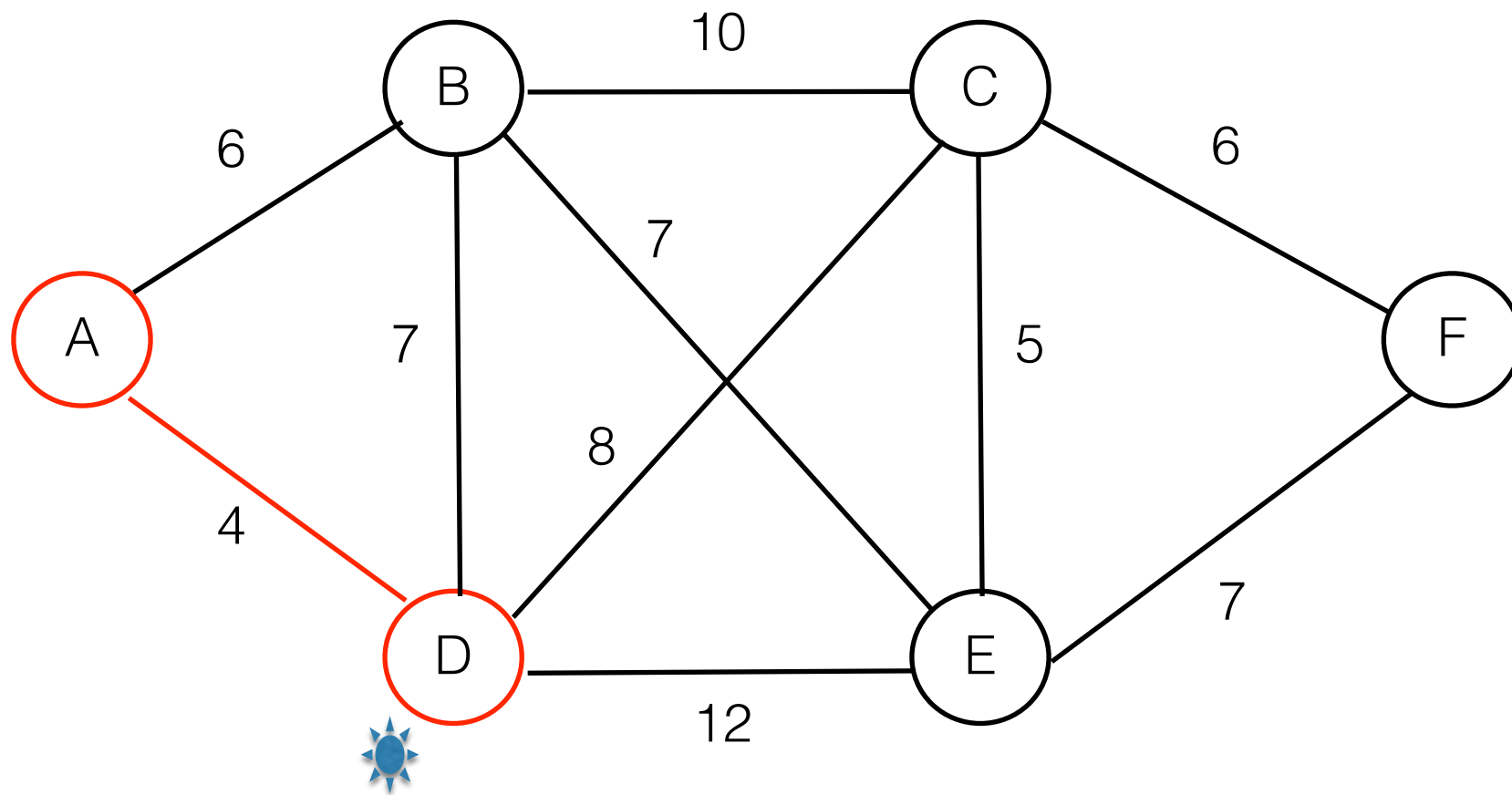
MST with Weighted Graphs



Edge	Weight
AB	6

- Now we have offices at A, and D
- And one link AD
- D is the newest office

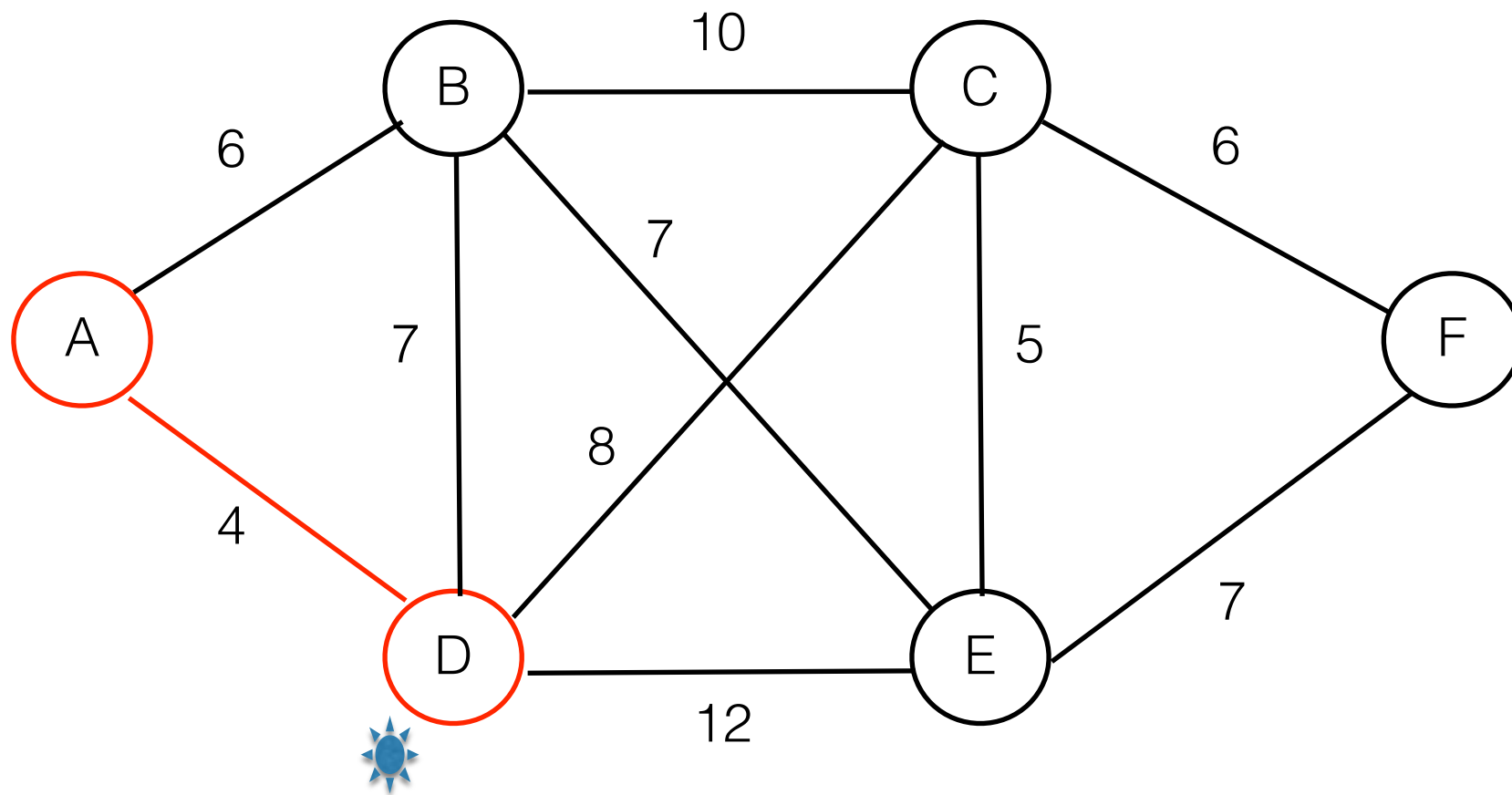
MST with Weighted Graphs



Edge	Weight
AB	6

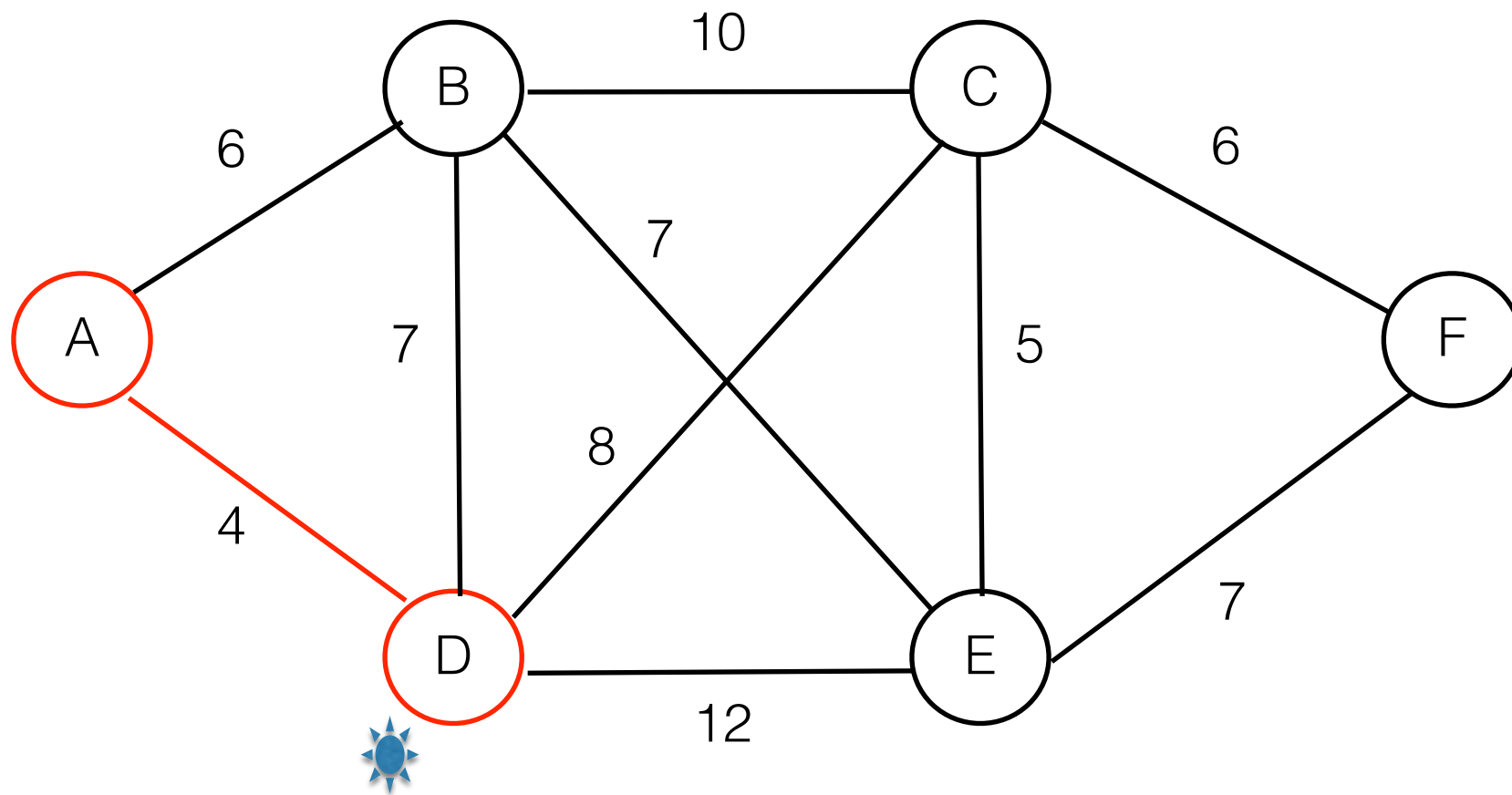
- Repeat the process for D.

MST with Weighted Graphs



Edge	Weight
AB	6
DB	7
DC	8
DE	12

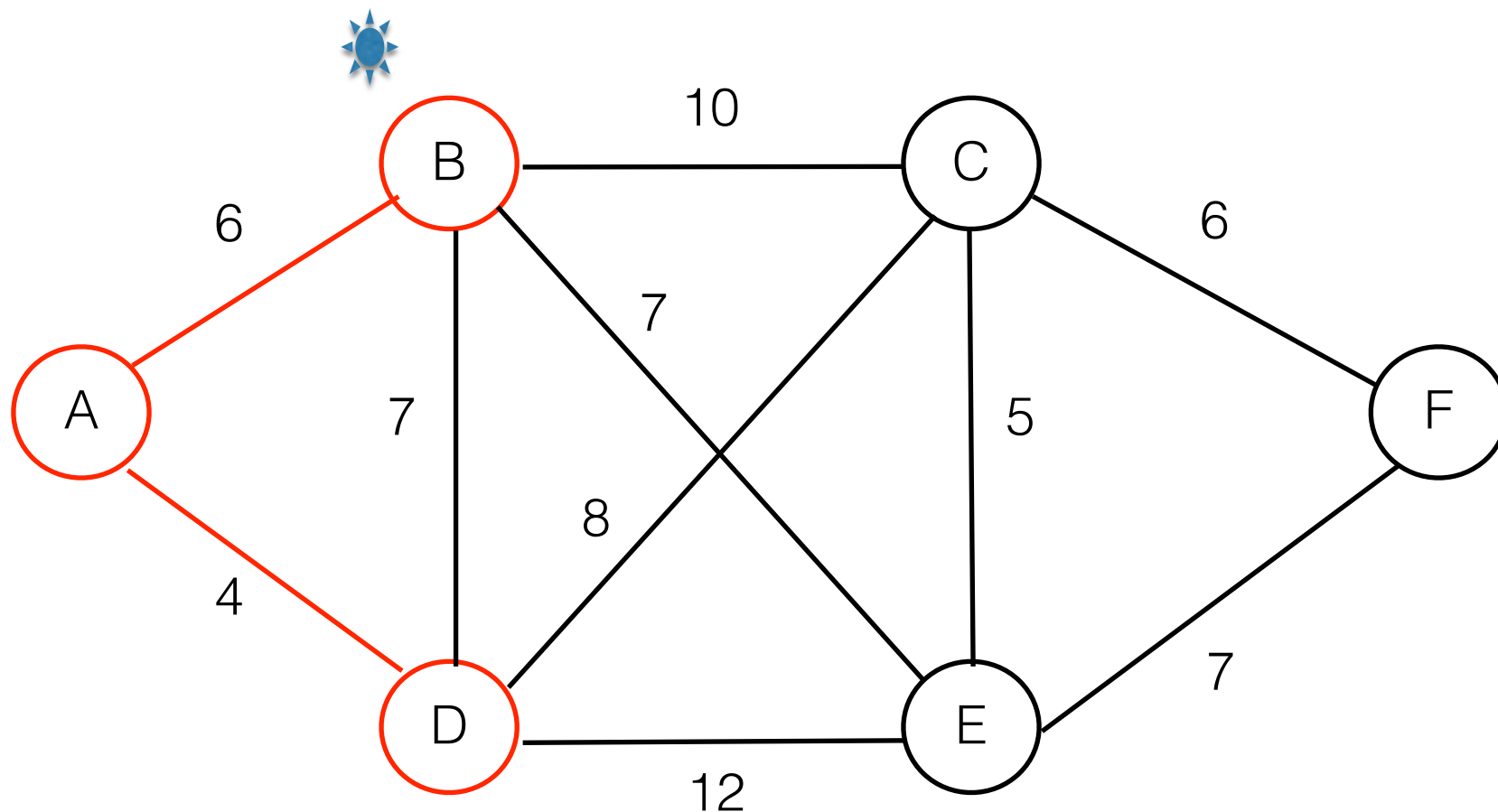
MST with Weighted Graphs



Edge	Weight
AB	6
DB	7
DC	8
DE	12

- Again, choose the cheapest from the list.
- Yeah, you got it, we always choose the cheapest from the list

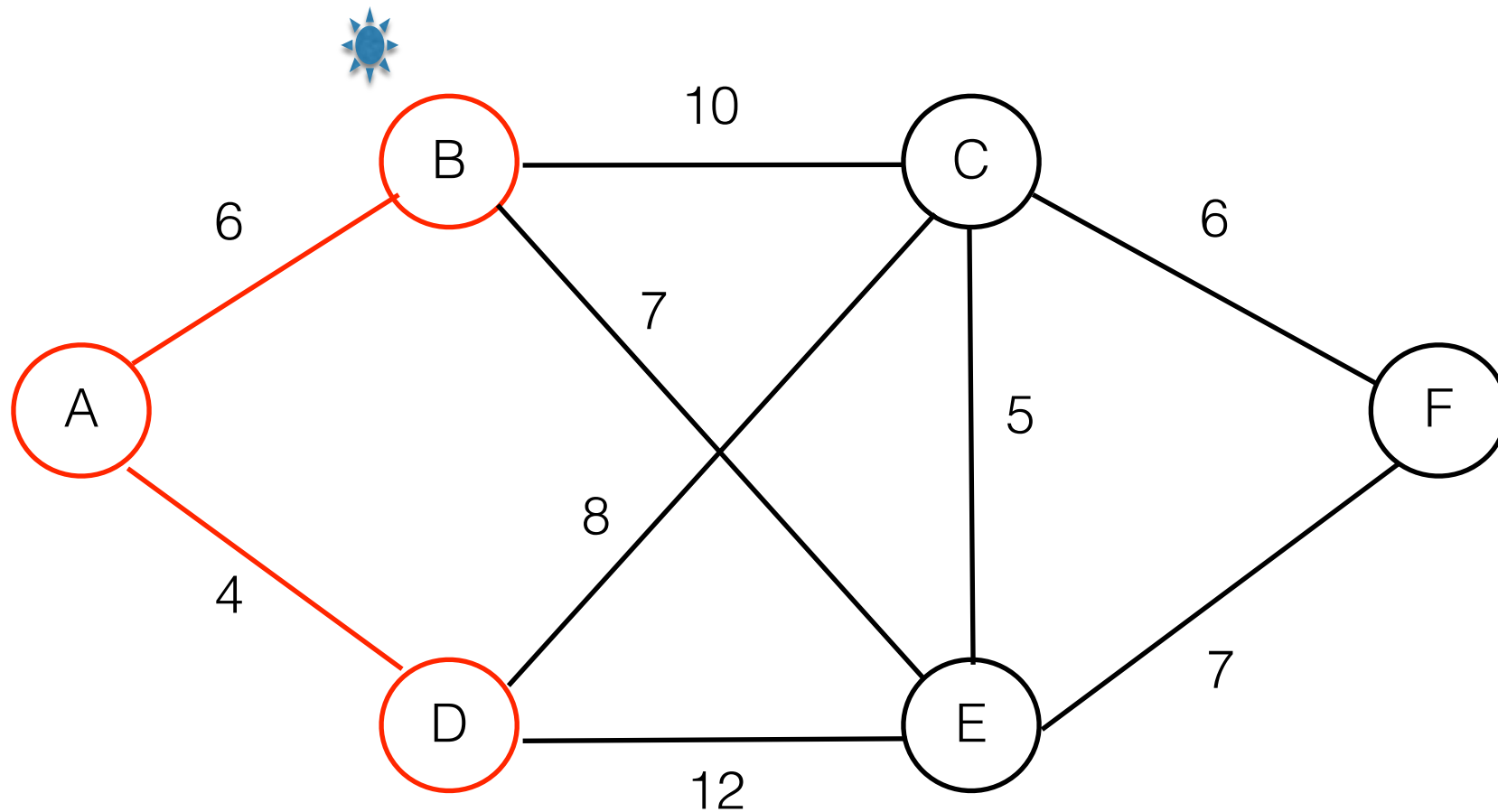
MST with Weighted Graphs



Edge	Weight
DB	7
DC	8
DE	12

- Note:
 - **DB** is redundant, that is, B already has an office
 - Thus we will remove it from the list, too!
 - ❖ **Remove from the list:**
 - The one that is the cheapest
 - And those that are redundant

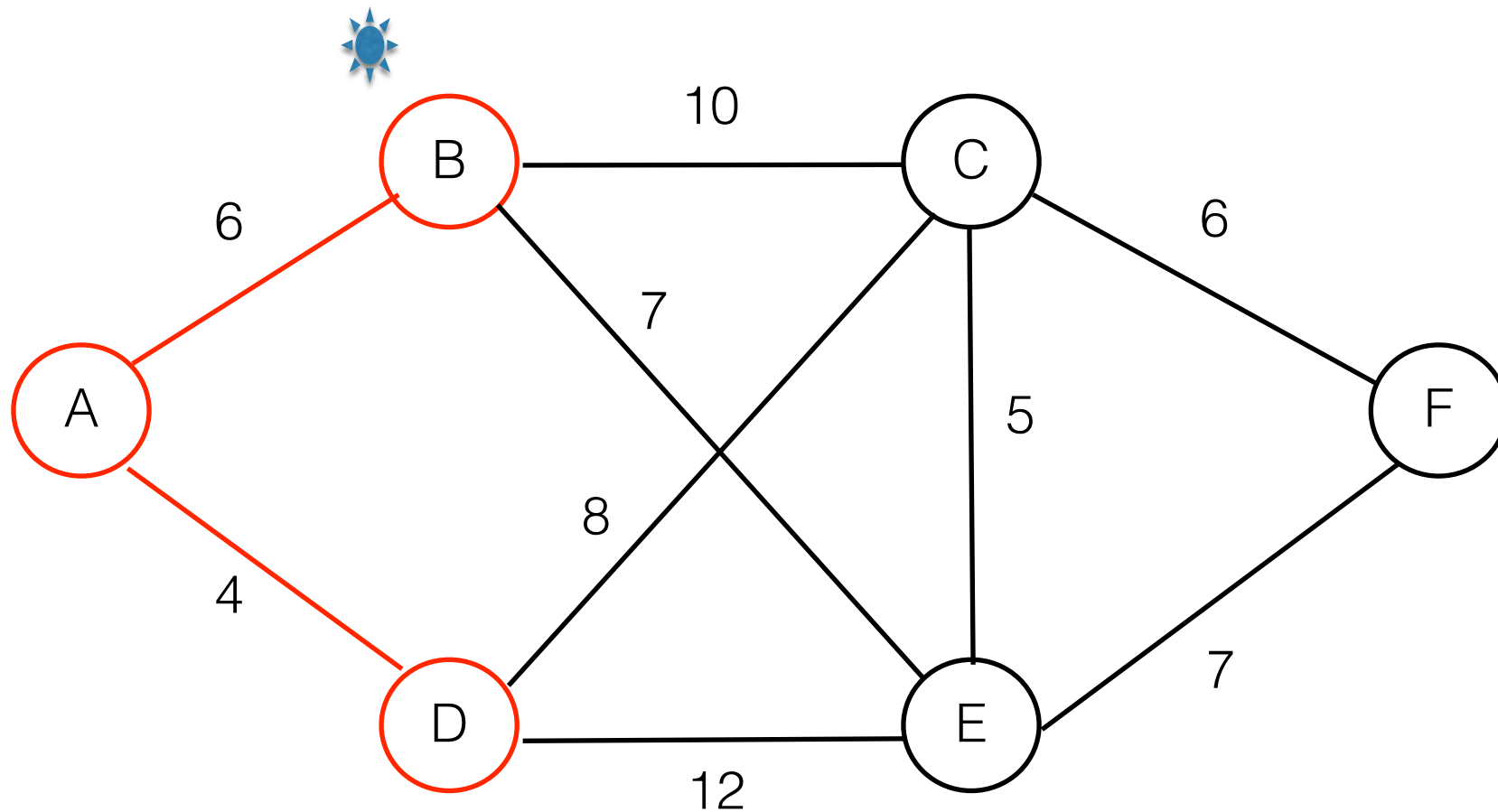
MST with Weighted Graphs



Edge	Weight
DC	8
DE	12

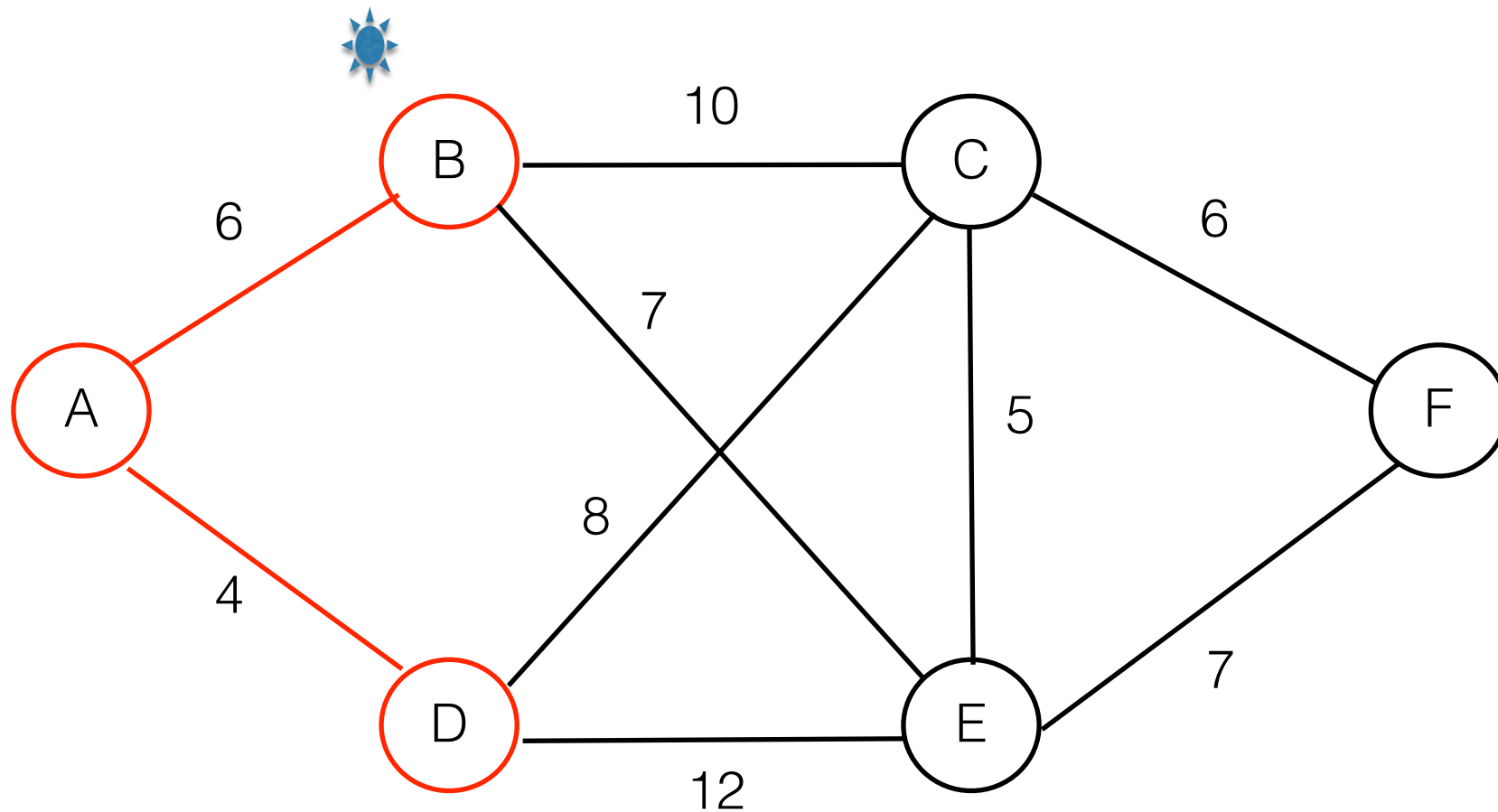
- Now B is the newest office
- Repeat the same for B

MST with Weighted Graphs



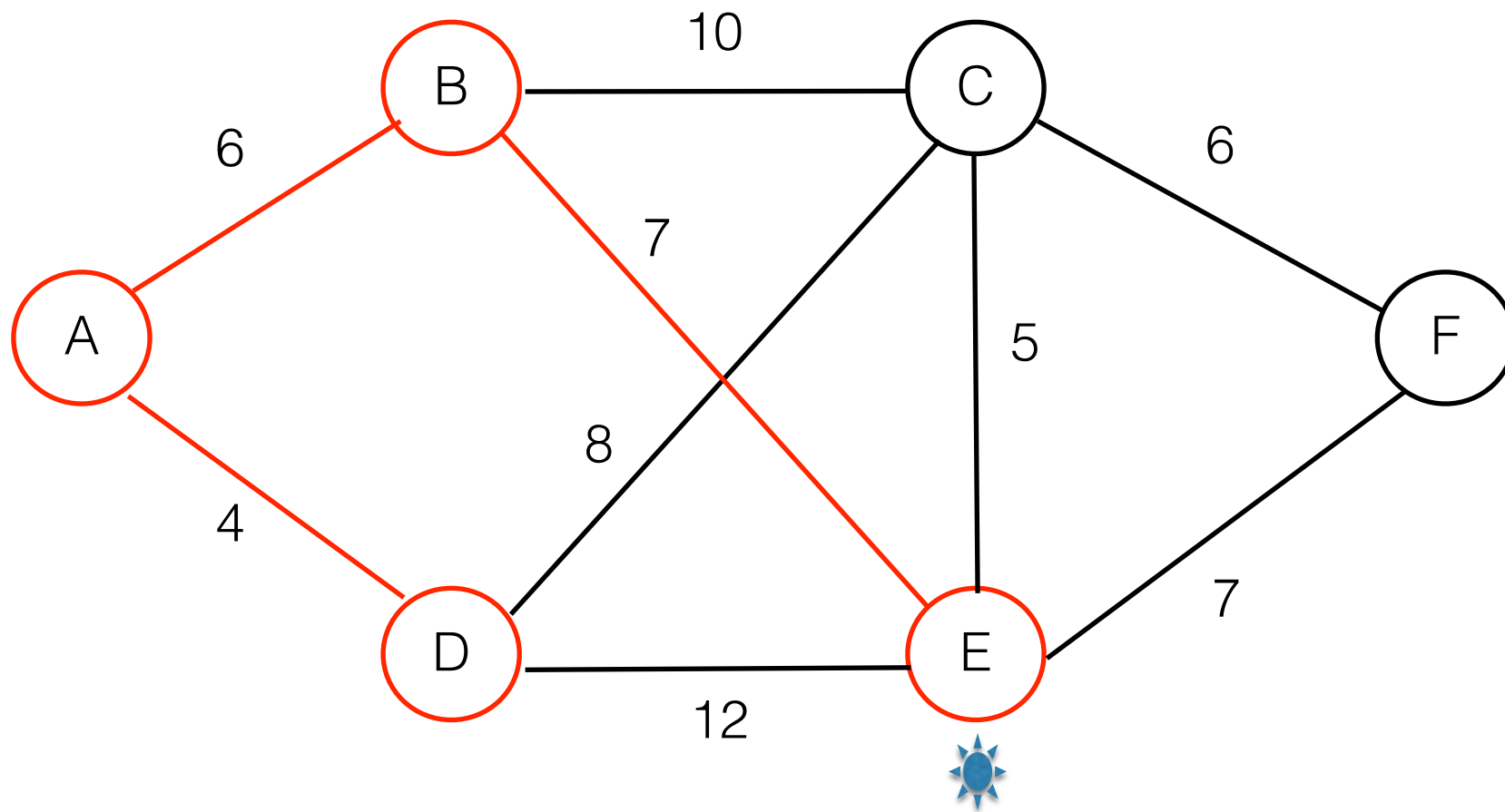
Edge	Weight
DC	8
DE	12
BC	10
BE	7

MST with Weighted Graphs



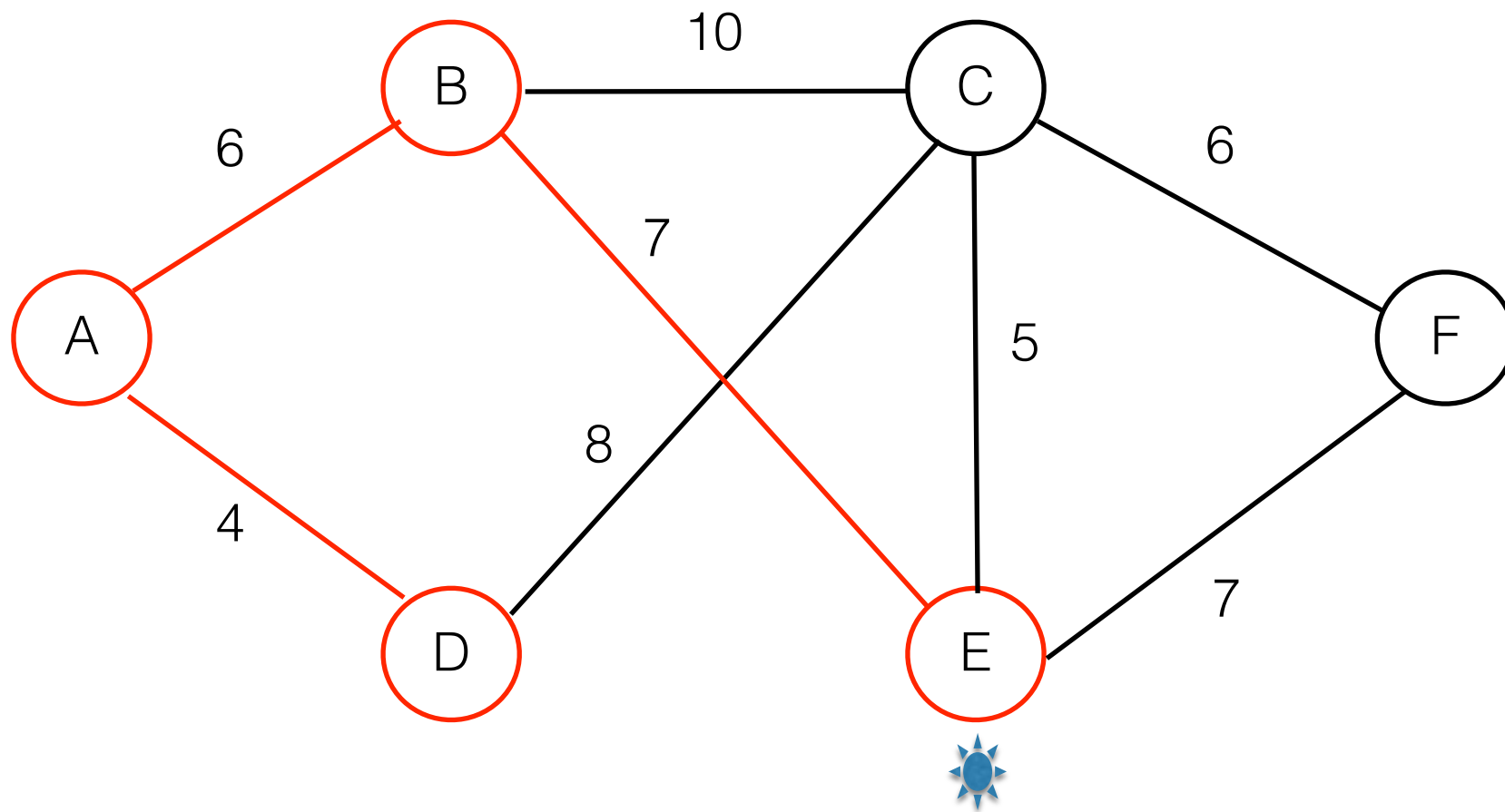
Edge	Weight
DC	8
DE	12
BC	10
BE	7

MST with Weighted Graphs



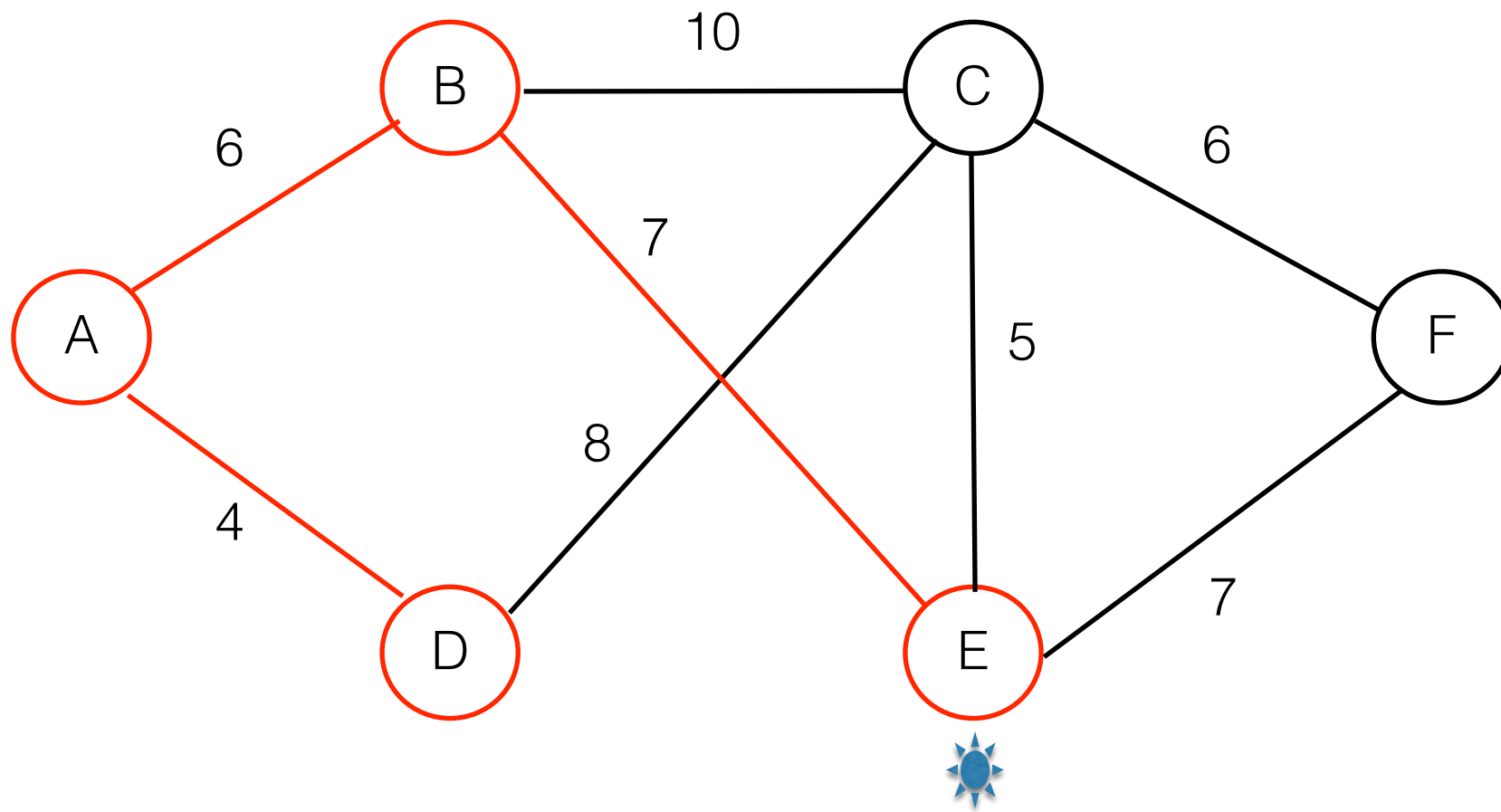
Edge	Weight
DC	8
DE	12
BC	10

MST with Weighted Graphs



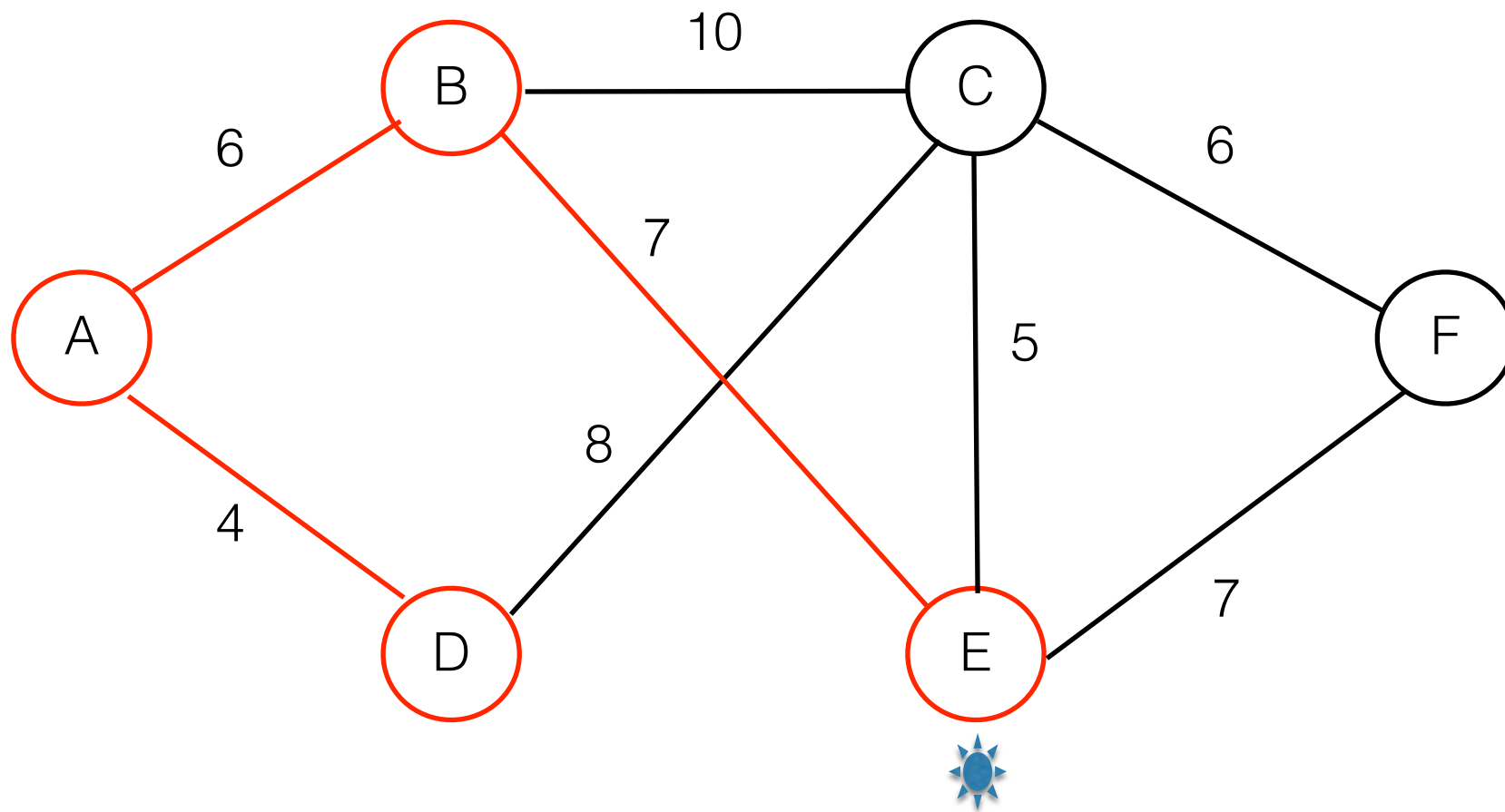
Edge	Weight
DC	8
BC	10

MST with Weighted Graphs



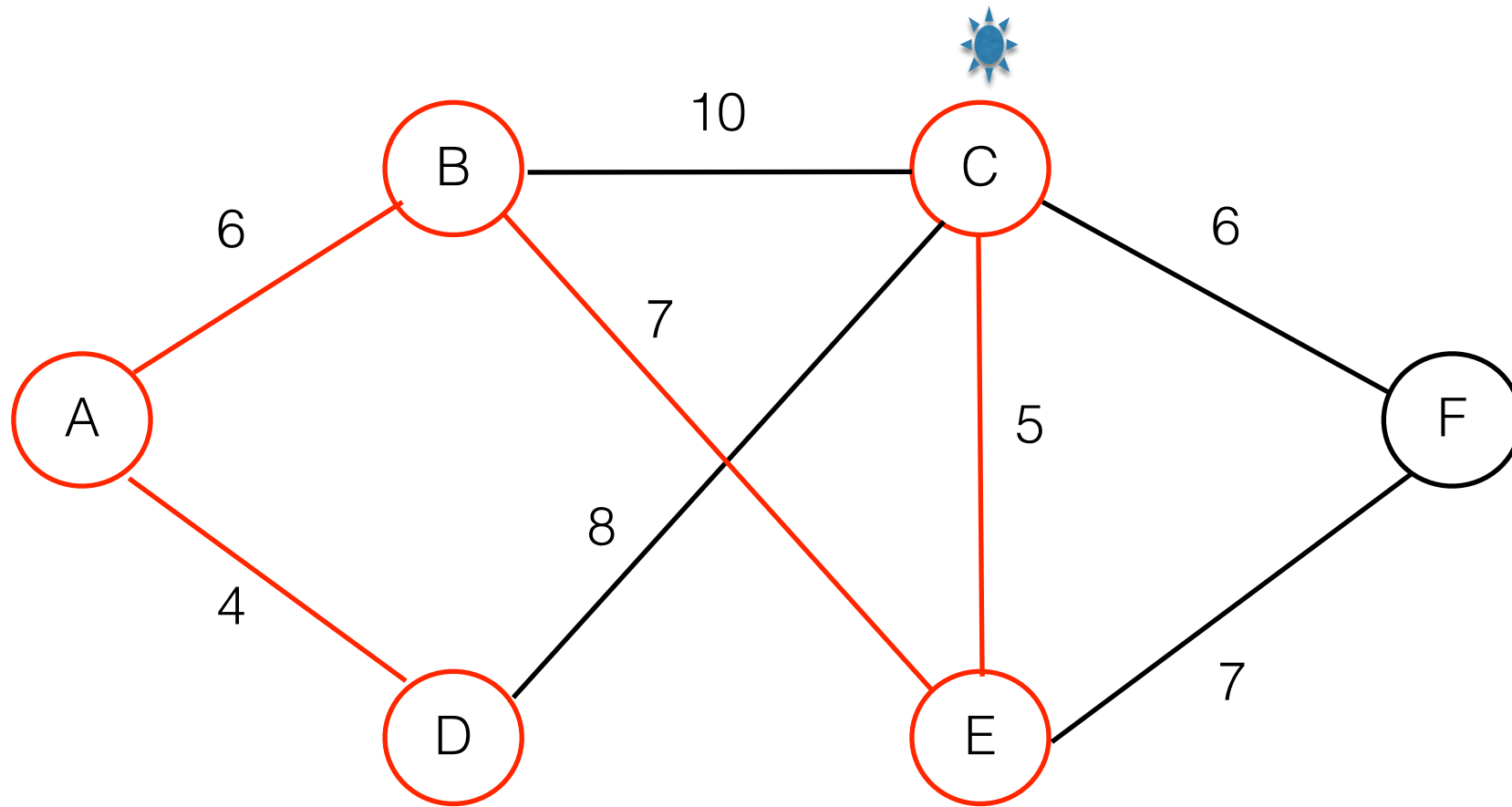
Edge	Weight
DC	8
BC	10
EC	5
EF	7

MST with Weighted Graphs



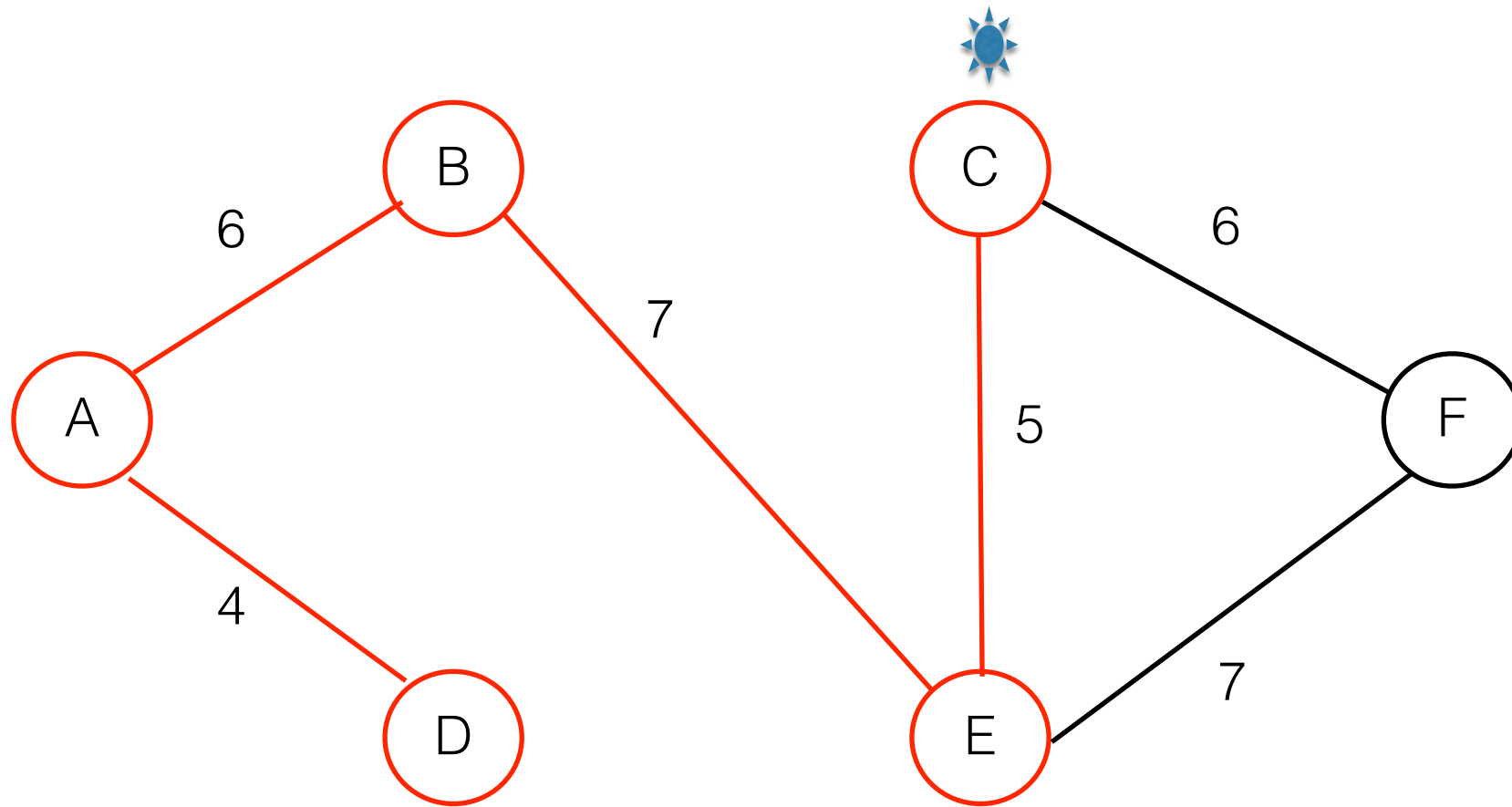
Edge	Weight
DC	8
BC	10
EC	5
EF	7

MST with Weighted Graphs



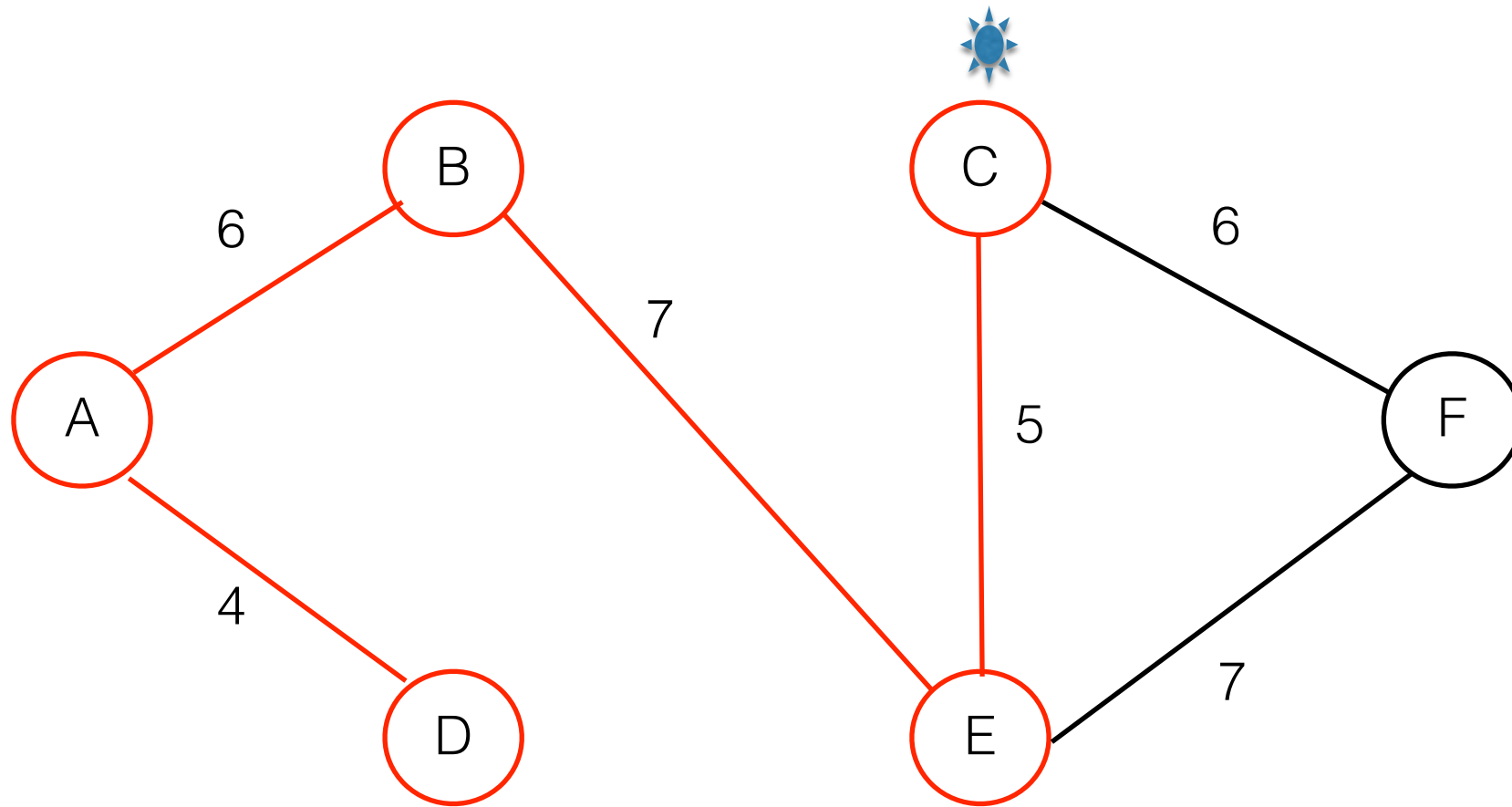
Edge	Weight
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BC	10
EF	7

MST with Weighted Graphs



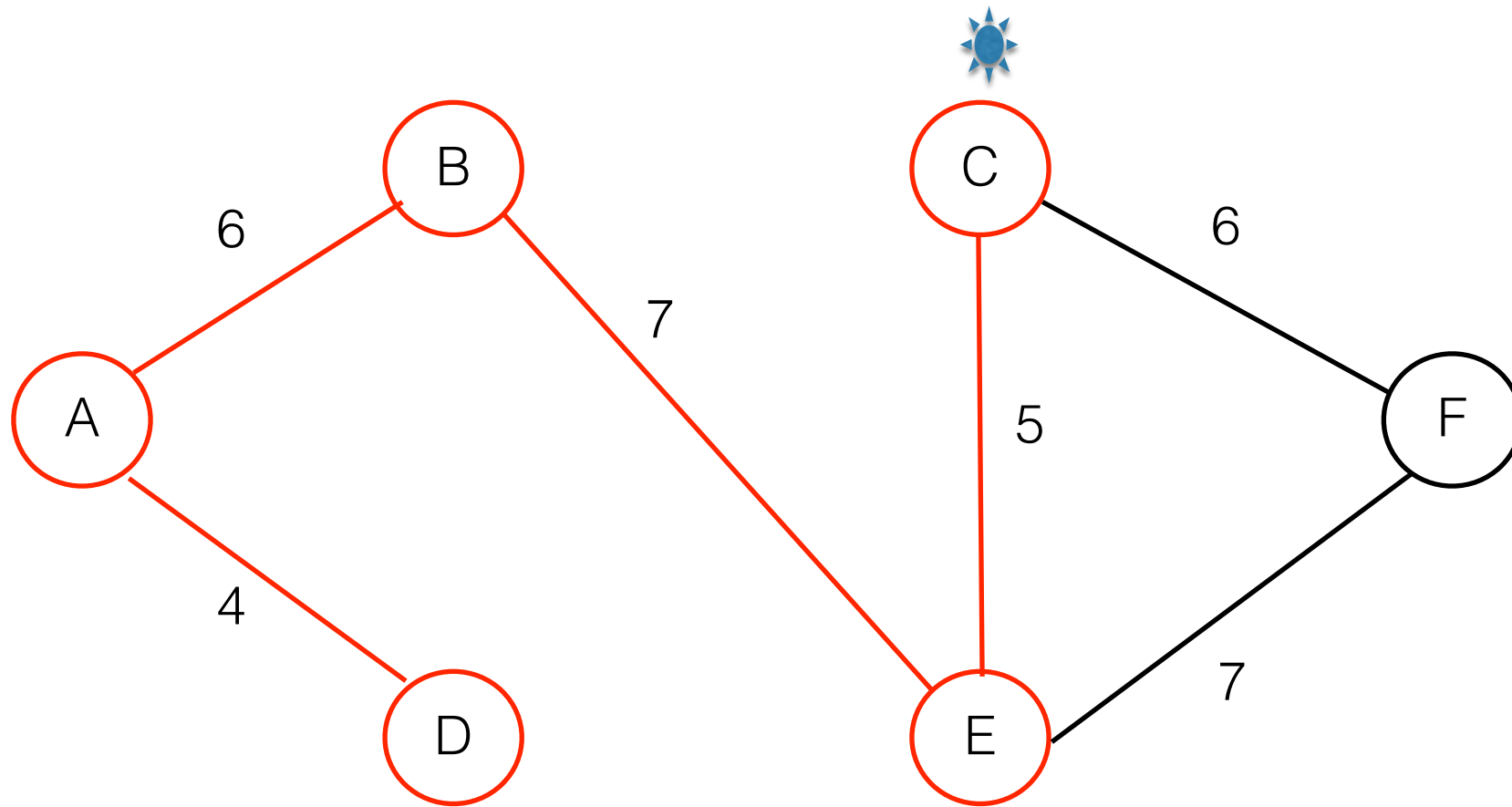
Edge	Weight
EF	7

MST with Weighted Graphs



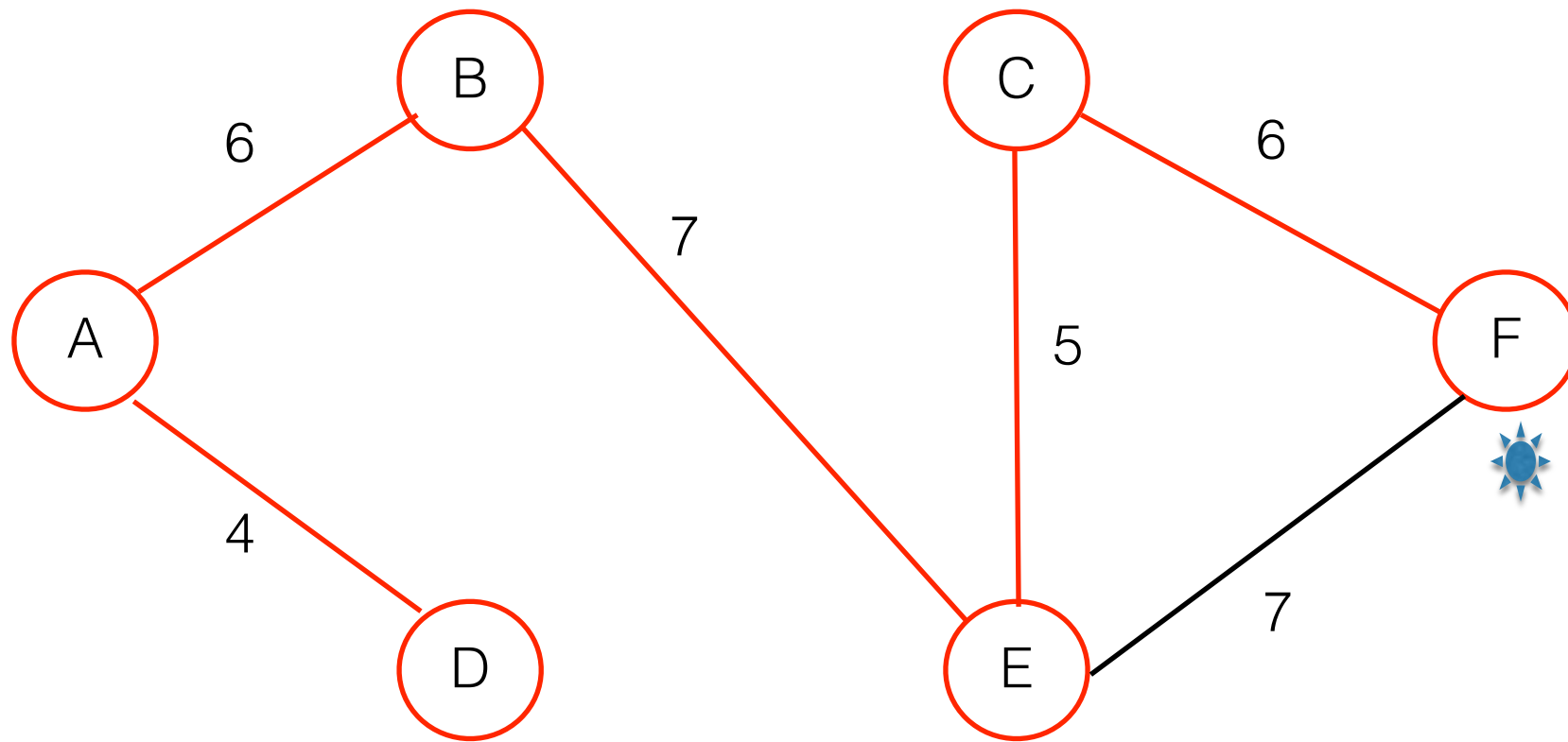
Edge	Weight
EF	7
CF	6

MST with Weighted Graphs



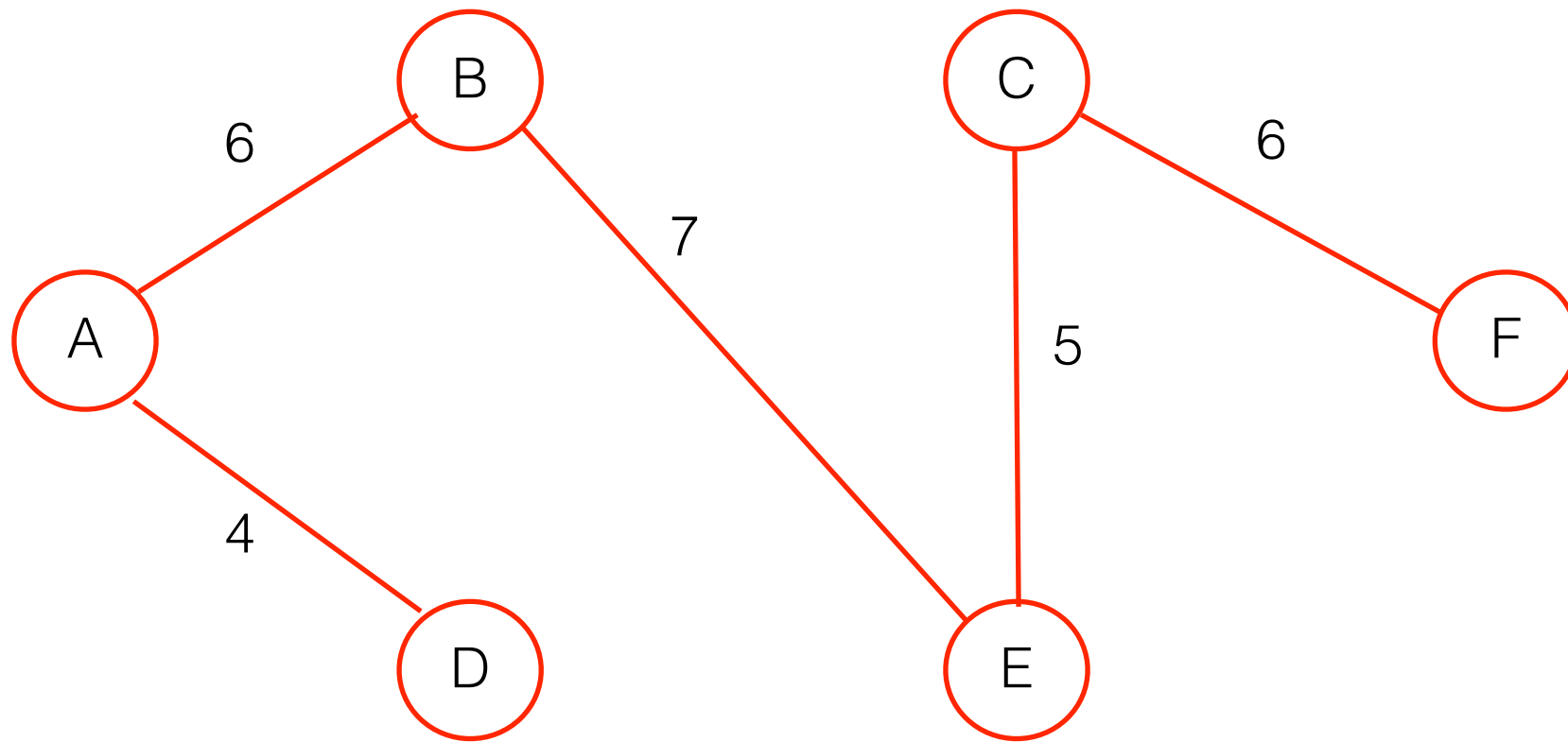
Edge	Weight
EF	7
CF	6

MST with Weighted Graphs



Edge	Weight
EF	7

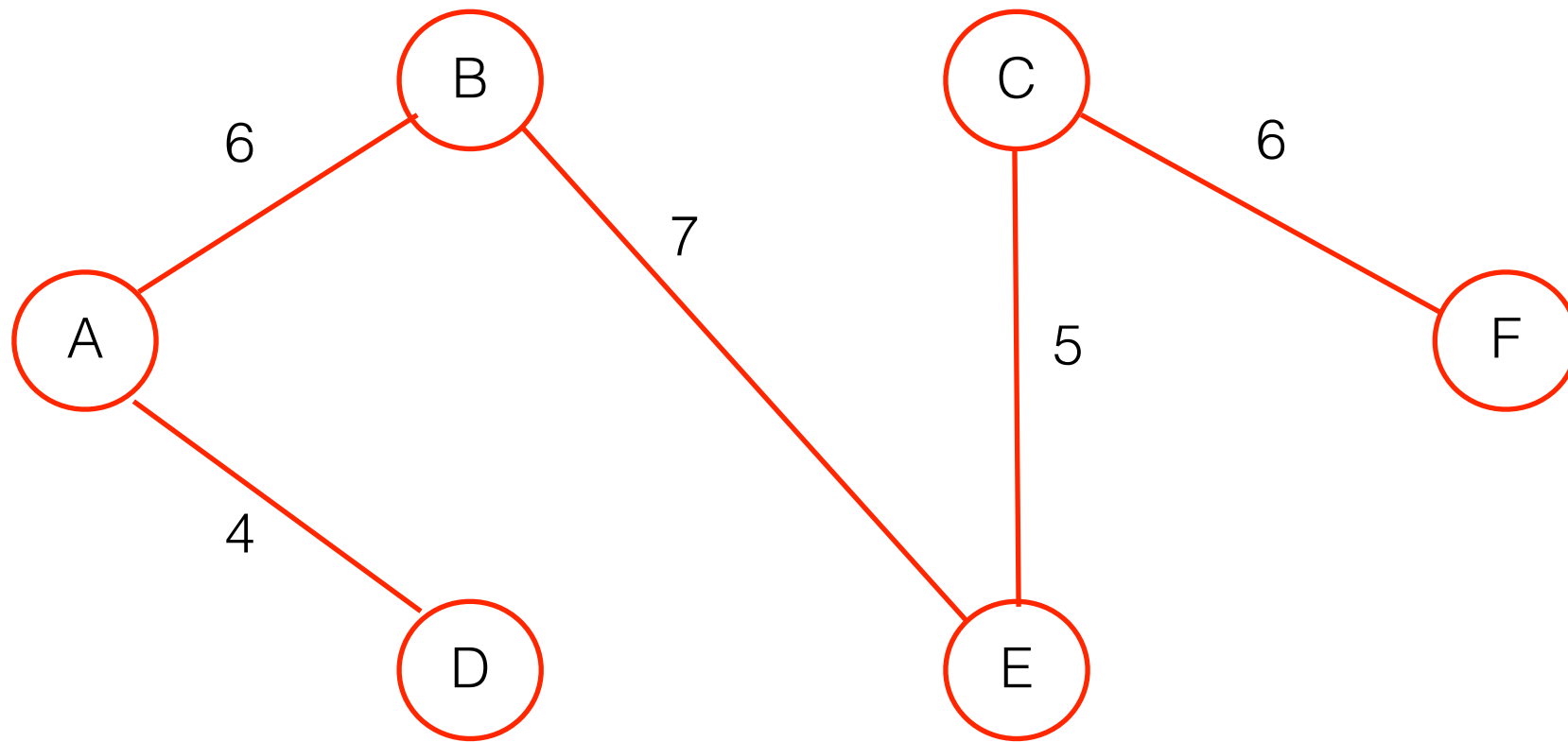
MST with Weighted Graphs



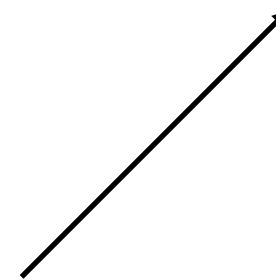
Edge	Weight

The Resultant Minimum Spanning Tree

MST with Weighted Graphs

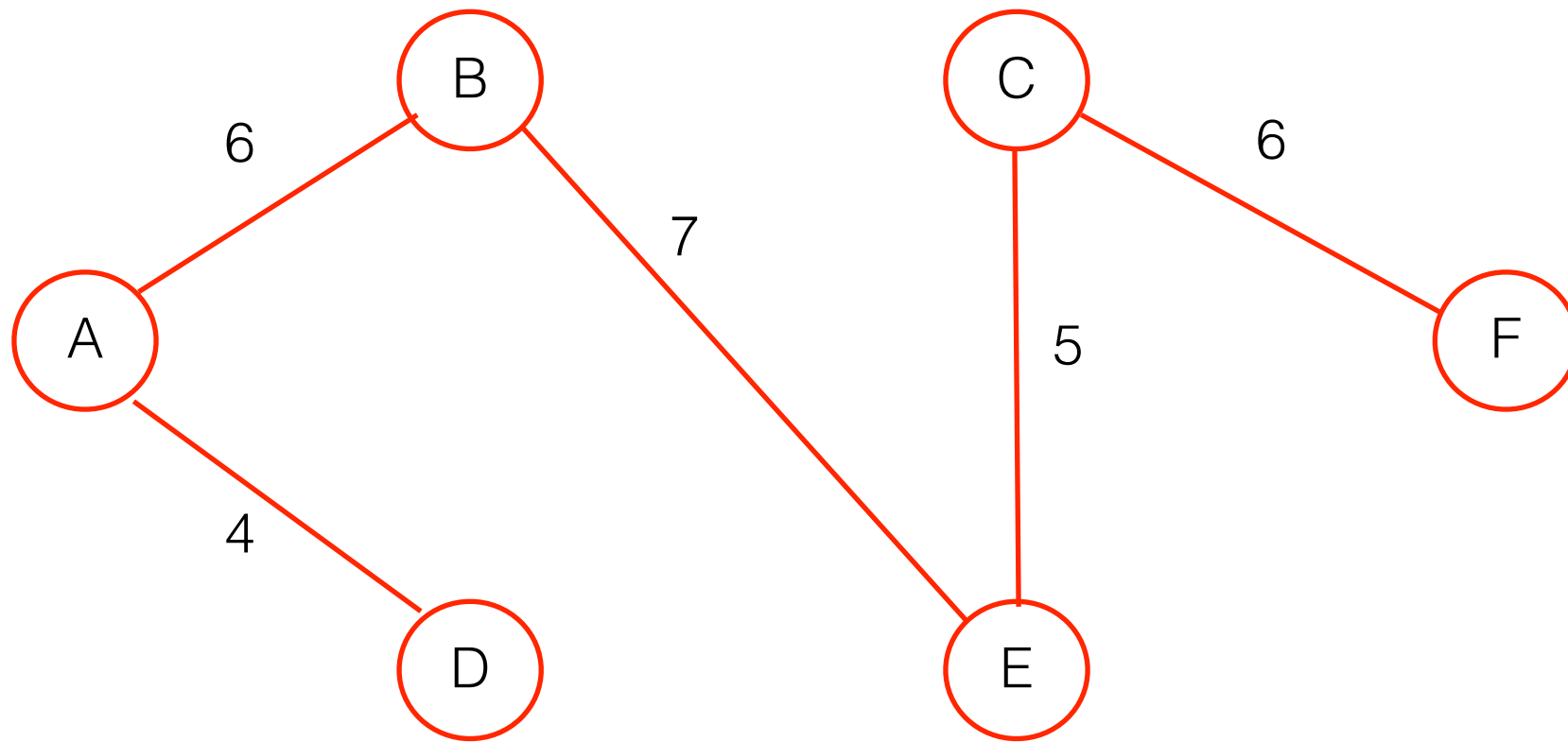


Edge	Weight



Which data structure would you choose to implement this list?

MST with Weighted Graphs

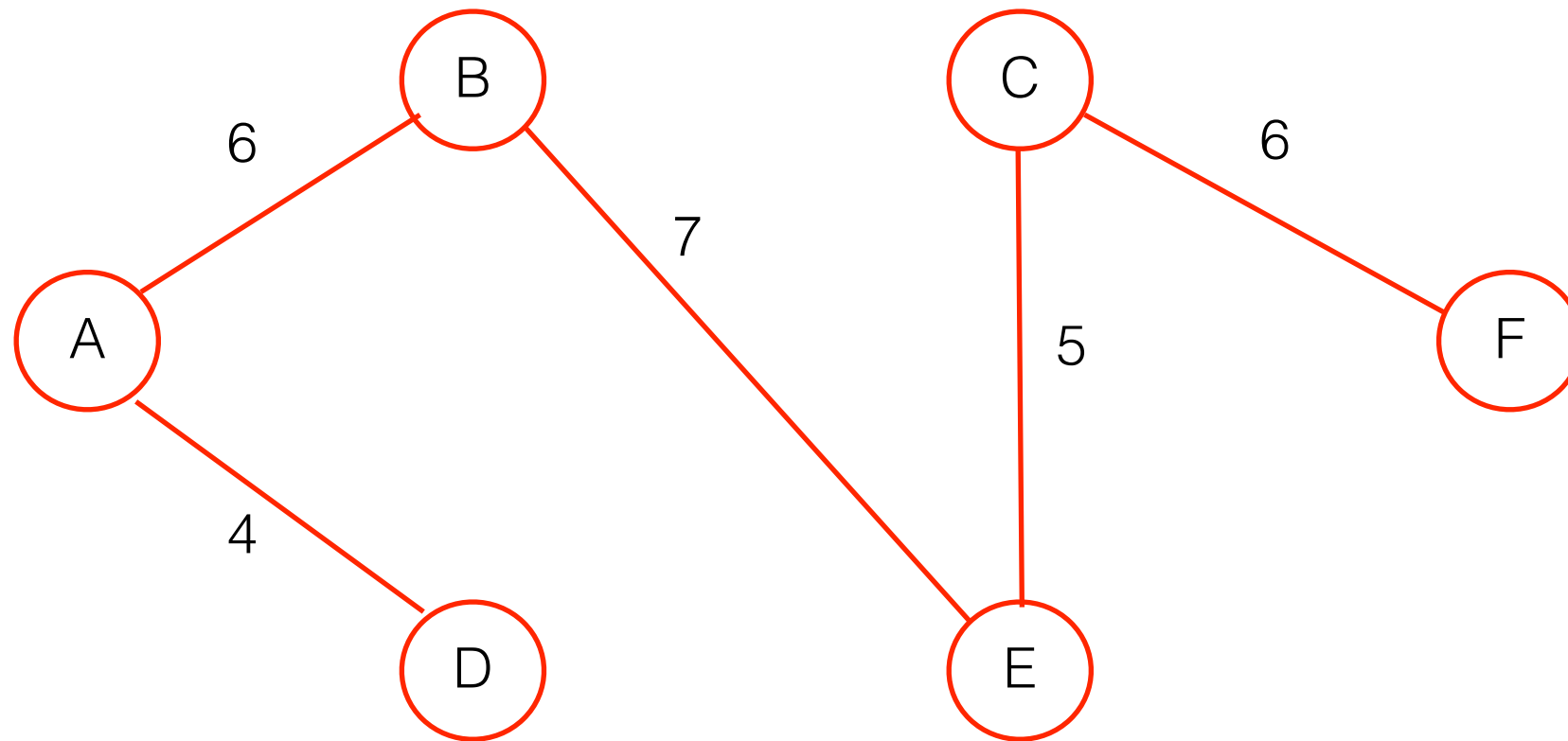


Edge	Weight

Which data structure would you choose to implement this list?

Priority Queue

Important Points



- ❖ We will need a **PQ**.
- ❖ At any point in time, let **A** be the set of vertices in **T**, and **V - A** be the set of vertices in **PQ**.
- ❖ Each step adds to **T** a “light edge” connecting it with a vertex **v** in **PQ** (moving **v** from **V - A** to **A**).

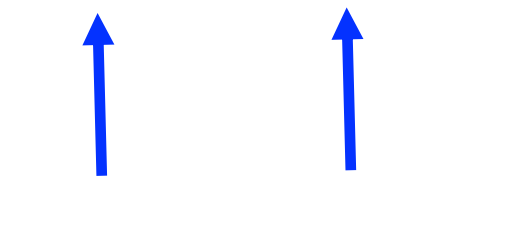
Prim-Jarnik's Algorithm

- This idea (which you just learned) of finding the MST is the basis of Prim's algorithm
- But, there is a slight modification regarding the PQ and its entries

PQ in Prim's Algorithm

- Each entry in the PQ is of the following type

- $\{D[v], (v, e)\}$

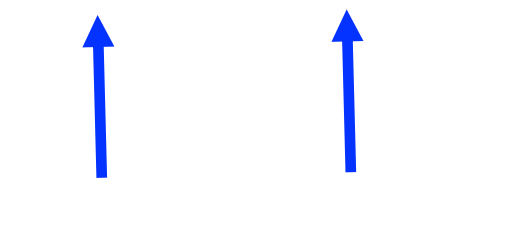

Key Value

- Where e is the incident edge with the minimum weight

PQ in Prim's Algorithm

- Each entry in the PQ is of the following type

- $\{D[v], (v, e)\}$


Key Value

- Where e is the incident edge with the minimum weight

Thus only one edge is stored for each vertex. It is the one that has the lowest weight.

Prim's Algorithm (1)

Algorithm PrimJarnik(G):

Input: An undirected, weighted, connected graph G with n vertices and m edges

Output: A minimum spanning tree T for G

Pick any vertex s of G

$D[s] = 0$

for each vertex $v \neq s$ **do**

$D[v] = \infty$

Initialize $T = \emptyset$.

Initialize a priority queue Q with an entry $(D[v], (v, \text{None}))$ for each vertex v , where $D[v]$ is the key in the priority queue, and (v, None) is the associated value.

while Q is not empty **do**

$(u, e) = \text{value returned by } Q.\text{remove_min}()$

 Connect vertex u to T using edge e .

for each edge $e' = (u, v)$ such that v is in Q **do**

 {check if edge (u, v) better connects v to T }

if $w(u, v) < D[v]$ **then**

$D[v] = w(u, v)$

 Change the key of vertex v in Q to $D[v]$.

 Change the value of vertex v in Q to (v, e') .

return the tree T

Prim's Algorithm (2)

Algorithm PrimJarnik(G):

Input: An undirected, weighted, connected graph G with n vertices and m edges

Output: A minimum spanning tree T for G

Pick any vertex s of G  Starting vertex

$D[s] = 0$

for each vertex $v \neq s$ **do**

$D[v] = \infty$

Initialize $T = \emptyset$.

Initialize a priority queue Q with an entry $(D[v], (v, \text{None}))$ for each vertex v , where $D[v]$ is the key in the priority queue, and (v, None) is the associated value.

while Q is not empty **do**

$(u, e) = \text{value returned by } Q.\text{remove_min}()$

 Connect vertex u to T using edge e .

for each edge $e' = (u, v)$ such that v is in Q **do**

 {check if edge (u, v) better connects v to T }

if $w(u, v) < D[v]$ **then**

$D[v] = w(u, v)$

 Change the key of vertex v in Q to $D[v]$.

 Change the value of vertex v in Q to (v, e') .

return the tree T

Prim's Algorithm (3)

Algorithm PrimJarnik(G):

Input: An undirected, weighted, connected graph G with n vertices and m edges

Output: A minimum spanning tree T for G

Pick any vertex s of G

$D[s] = 0$  Set its key to 0

for each vertex $v \neq s$ **do**

$D[v] = \infty$

Initialize $T = \emptyset$.

Initialize a priority queue Q with an entry $(D[v], (v, \text{None}))$ for each vertex v , where $D[v]$ is the key in the priority queue, and (v, None) is the associated value.

while Q is not empty **do**

$(u, e) = \text{value returned by } Q.\text{remove_min}()$

Connect vertex u to T using edge e .

for each edge $e' = (u, v)$ such that v is in Q **do**

{check if edge (u, v) better connects v to T }

if $w(u, v) < D[v]$ **then**

$D[v] = w(u, v)$

Change the key of vertex v in Q to $D[v]$.

Change the value of vertex v in Q to (v, e') .

return the tree T

Prim's Algorithm (4)

Algorithm PrimJarnik(G):

Input: An undirected, weighted, connected graph G with n vertices and m edges

Output: A minimum spanning tree T for G

Pick any vertex s of G

$D[s] = 0$

for each vertex $v \neq s$ **do**

$D[v] = \infty$

← For every other vertex, set its key to infinity

Initialize $T = \emptyset$.

Initialize a priority queue Q with an entry $(D[v], (v, \text{None}))$ for each vertex v , where $D[v]$ is the key in the priority queue, and (v, None) is the associated value.

while Q is not empty **do**

$(u, e) = \text{value returned by } Q.\text{remove_min}()$

Connect vertex u to T using edge e .

for each edge $e' = (u, v)$ such that v is in Q **do**

{check if edge (u, v) better connects v to T }

if $w(u, v) < D[v]$ **then**

$D[v] = w(u, v)$

Change the key of vertex v in Q to $D[v]$.

Change the value of vertex v in Q to (v, e') .

return the tree T

Prim's Algorithm (5)

Algorithm PrimJarnik(G):

Input: An undirected, weighted, connected graph G with n vertices and m edges

Output: A minimum spanning tree T for G

Pick any vertex s of G

$D[s] = 0$

for each vertex $v \neq s$ **do**

$D[v] = \infty$

Initialize $T = \emptyset$.

← Initial tree

Initialize a priority queue Q with an entry $(D[v], (v, \text{None}))$ for each vertex v , where $D[v]$ is the key in the priority queue, and (v, None) is the associated value.

while Q is not empty **do**

$(u, e) = \text{value returned by } Q.\text{remove_min}()$

 Connect vertex u to T using edge e .

for each edge $e' = (u, v)$ such that v is in Q **do**

 {check if edge (u, v) better connects v to T }

if $w(u, v) < D[v]$ **then**

$D[v] = w(u, v)$

 Change the key of vertex v in Q to $D[v]$.

 Change the value of vertex v in Q to (v, e') .

return the tree T

Prim's Algorithm (6)

Algorithm PrimJarnik(G):

Input: An undirected, weighted, connected graph G with n vertices and m edges

Output: A minimum spanning tree T for G

Pick any vertex s of G

$D[s] = 0$

for each vertex $v \neq s$ **do**

$D[v] = \infty$

Initialize $T = \emptyset$.

Initialize a priority queue Q with an entry $(D[v], (v, \text{None}))$ for each vertex v , where $D[v]$ is the key in the priority queue, and (v, None) is the associated value.

Create PQ.
Notice the "None"

while Q is not empty **do**

$(u, e) = \text{value returned by } Q.\text{remove_min}()$

 Connect vertex u to T using edge e .

for each edge $e' = (u, v)$ such that v is in Q **do**

 {check if edge (u, v) better connects v to T }

if $w(u, v) < D[v]$ **then**

$D[v] = w(u, v)$

 Change the key of vertex v in Q to $D[v]$.

 Change the value of vertex v in Q to (v, e') .

return the tree T

Prim's Algorithm (7)

Algorithm PrimJarnik(G):

Input: An undirected, weighted, connected graph G with n vertices and m edges

Output: A minimum spanning tree T for G

Pick any vertex s of G

$D[s] = 0$

for each vertex $v \neq s$ **do**

$D[v] = \infty$

Initialize $T = \emptyset$.

Initialize a priority queue Q with an entry $(D[v], (v, \text{None}))$ for each vertex v , where $D[v]$ is the key in the priority queue, and (v, None) is the associated value.

while Q is not empty **do**

$(u, e) = \text{value returned by } Q.\text{remove_min}()$

 Connect vertex u to T using edge e .

for each edge $e' = (u, v)$ such that v is in Q **do**

 {check if edge (u, v) better connects v to T }

if $w(u, v) < D[v]$ **then**

$D[v] = w(u, v)$

 Change the key of vertex v in Q to $D[v]$.

 Change the value of vertex v in Q to (v, e') .

return the tree T

← 1. While Q is not empty, remove the vertex u with the minimum key, and put it in T using e

Prim's Algorithm (8)

Algorithm PrimJarnik(G):

Input: An undirected, weighted, connected graph G with n vertices and m edges

Output: A minimum spanning tree T for G

Pick any vertex s of G

$D[s] = 0$

for each vertex $v \neq s$ **do**

$D[v] = \infty$

Initialize $T = \emptyset$.

Initialize a priority queue Q with an entry $(D[v], (v, \text{None}))$ for each vertex v , where $D[v]$ is the key in the priority queue, and (v, None) is the associated value.

while Q is not empty **do**

$(u, e) = \text{value returned by } Q.\text{remove_min}()$

 Connect vertex u to T using edge e .

for each edge $e' = (u, v)$ such that v is in Q **do**

 {check if edge (u, v) better connects v to T }

if $w(u, v) < D[v]$ **then**

$D[v] = w(u, v)$

 Change the key of vertex v in Q to $D[v]$.

 Change the value of vertex v in Q to (v, e') .

return the tree T

1. While Q is not empty, remove the vertex u with the minimum key, and put it in T using e

2. And, do the following

“Follow each outgoing edge to every adjacent vertex v of u , replace its key $D[v]$ with the weight $w(u, v)$, only if it is less than the key “

Prim's Algorithm Time Complexity

- Three main tasks
 1. Creation of PQ – $O(|V| \log |V|)$
 2. Emptying the PQ – $O(|V| \log |V|)$
 3. Updating the PQ – $O(|E| \log |V|)$
- Thus, T: $O(|E| \log |V|)$

Summary

1. Optimization Problems
2. Greedy Algorithms
3. Minimum Spanning Tree
 - MST in Unweighted Graphs
 - MST in Weighted Graphs (Prim's Algorithm, and [Krushkal's Algorithm](#))