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Signal Processing
Logistics of SP
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Tent books: 1) Lignal & Systems (OWN) → Oppenhei
2) 058: Principle Algo's & Application (PM) → By John G, Proakis & Dimitric Namolakis
  - tab sessions based on MATLAB.
  weightages
                                                                                                                                                     <u>Lab</u>

) Eubmissions → 15
      Q1 - 10
                                                                                                                                                    2) Mid Enam - 10
     Q2 --- 10
     Ass -> 20 -> 8 assignments
                                                                                                                                                    3) Final Enam / Project -> 15
   Mid Enam → 25
    end enam - 15
 → Total Harks: 140 [>130 → A ]
→ deuno & Viva after lab , Test Quizzes
   Pre-requisits for SP -> NESS: ) LTI
                                                                                                                                       2) FOUVIET Series & Transformation

3) Laplace Transform

4) Convolution - 200 c

5) Discrete signals [More focus]
Fourier thalysis:

Conview for periodic, aperiodic, continuous-time, discrete time \rightarrow FS: periodic E CT \rightarrow FF: aperiodic E CT \rightarrow FF: aperiodic E CT \rightarrow FF: aperiodic E
    - Discrete fourier Transform (DFT) → DT & finite langue signals
                                                                                                                                    algorithm ffr
                                                                                                                                                                                                                                      C periodic signal of length N
 Fourier Series:
    Synthesis: alt) - periodic (T)
     7(1) = bo + & ay cin (k wot) + & by cos (kupt), wo = 27
          tormula & Crejkust
\rightarrow a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) \sin(k\omega_{0}t) dt \qquad \forall \qquad b_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) \cos(k\omega_{0}t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k} = \frac{1}{T} \int_{\langle T \rangle} a(t) dt \qquad \partial a_{k
fs: an= 1 fact) e-jkwot
                                       = 1 [ Se-jkwt - Se-jkwt ]
                                           = \frac{1}{2} \left[ -\frac{1}{1\pi_{\text{low}}} \left[ 1 - e^{j\text{low}} \right] + \frac{1}{1\text{low}} \left[ e^{-j\text{low}} - 1 \right]
                                            = \frac{1}{2jkw} \left[ -x + e^{jkw} + e^{-jkw} + y \right] = \frac{1}{2jkw} (los (jkw) - 1)
      be=0 + k because it is a odd signal
    Partial Reconstruction / Synthesis:
        \chi(t) = a_0 + \sum_{k=1}^{k} a_k \sin(k \omega_0 t) + \sum_{k=1}^{k} b_k \cos(k \omega_0 t)
  Reconstruction error: el+) = x(+) - x(t)

As we keep adding more a more terms the osc. get

closes to point of disc. and some becomes more flat
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