

## Xrelab - Non-Maxima Suppression on Detected Images

### Issues seen while using the current scripts present (while using the windows OS)

- Below is a list of changes, you can take the list as a reference, but I am sure you will need something different to make it work on your own windows machine because each environment is different. Make these changes and make sure the path names are correct

1. in myfrcnn\demo.py,  
#from model.nms\_wrapper import nms  
from nms.py\_cpu\_nms import py\_cpu\_nms as nms

2. in myfrcnn\layer\_utils\proposal\_target\_layer.py  
#from utils.cython\_bbox import bbox\_overlaps

3. in myfrcnn\layer\_utils\proposal\_layer.py  
#from model.nms\_wrapper import nms

4. in myfrcnn\layer\_utils\anchor\_target\_layer.py  
#from utils.cython\_bbox import bbox\_overlaps

5. in \myfrcnn\model\test.py  
#from model.nms\_wrapper import nms

The Definition parse\_args() , has been changed as below to make the model work on resnet 101

```
def parse_args():  
    """Parse input arguments."""  
    parser = argparse.ArgumentParser(description='Tensorflow Faster R-CNN demo')  
    parser.add_argument('--net', dest='demo_net', help='Network to use [vgg16 res101]', choices=NETS.keys(), default='res101')  
    parser.add_argument('--dataset', dest='dataset', help='Trained dataset [pascal_voc pascal_voc_0712]', choices=DATASETS.keys(), default='pascal_voc')  
    args = parser.parse_args()  
    return args
```

- The Below three files are always required for a complete model, which is not there for vgg16 , hence it does not work and throws out an “path error”. I figured that out from a lot of searches and this link help me understand where the error was :

<https://stackoverflow.com/questions/41265035/tensorflow-why-there-are-3-files-after-saving-the-model>

vgg16\_faster\_rcnn\_iter\_70000.ckpt.meta

vgg16\_faster\_rcnn\_iter\_70000.ckpt.index

vgg16\_faster\_rcnn\_iter\_70000.ckpt.data-00000-of-00001

- Give only absolute path for better clarity, the below has been changed in the demo.py function:

```
path=os.getcwd()
print(path, "---",NETS[demonet][0])
tfmodel = os.path.join('C:/Public/xrelab/Week7_detection1/data/voc_2007_trainval_voc_2012_trainval/',
NETS[demonet][0])
#tfmodel = os.path.join('../data/voc_2007_trainval+voc_2012_trainval',NETS[demonet][0])
#tfmodel=path
print("checking the model here", tfmodel)
```

- Go through the TF link here to understand what the code does , and understand how to debug:  
[https://www.tensorflow.org/guide/saved\\_model](https://www.tensorflow.org/guide/saved_model)
- My Current Anaconda has the config as such below which is functional

boost	1.67.0	py36hf75dd32_0	conda-forge
boost-cpp	1.67.0	hea38baa_0	conda-forge
bs4	0.0.1	<pip>	
bz2file	0.98	<pip>	
bzip2	1.0.6	hfa6e2cd_5	anaconda
ca-certificates	2018.4.16	0	conda-forge
certifi	2018.4.16	py36_0	conda-forge
cffi	1.11.5	py36h945400d_0	
chardet	3.0.4	py36h420ce6e_1	
click	6.7	<pip>	
colorama	0.3.9	py36h029ae33_0	
configparser	3.5.0	<pip>	
cryptography	2.2.1	py36hfa6e2cd_0	
cycler	0.10.0	py36h009560c_0	
Cython	0.28.4	<pip>	
decorator	4.2.1	py36_0	
dlib	19.9	np111py36_0	conda-forge
docutils	0.14	py36h6012d8f_0	
easydict	1.7	<pip>	
entrypoints	0.2.3	py36hfd66bb0_2	
face-recognition-models	0.3.0	<pip>	
freetype	2.8.1	ha63716d_1	conda-forge
future	0.16.0	<pip>	
gym	0.10.5	<pip>	
h5py	2.7.1	py36he54a1c3_0	
hdf5	1.10.1	h98b8871_1	
html5lib	0.9999999	py36_0	
icc_rt	2017.0.4	h97af966_0	
icu	58.2	ha66f8fd_1	
idna	2.6	py36h148d497_1	
imagesize	1.0.0	py36_0	
intel-openmp	2018.0.0	8	
ipykernel	4.8.2	py36_0	
ipython	6.2.1	py36h9cf0123_1	
ipython_genutils	0.2.0	py36h3c5d0ee_0	
ipywidgets	7.1.2	py36_0	
jedi	0.11.1	py36_1	
jinja2	2.10	py36h292fed1_0	
jpeg	9c	hfa6e2cd_0	conda-forge
jsonschema	2.6.0	py36h7636477_0	
jupyter	1.0.0	py36_4	
jupyter_client	5.2.3	py36_0	
jupyter_console	5.2.0	py36h6d89b47_1	
jupyter_core	4.4.0	py36h56e9d50_0	
kaggle	1.4.2	<pip>	
keras	2.1.5	py36_0	
kiwisolver	1.0.1	py36h12c3424_0	

libpng	1.6.34	h7602738_1	conda-forge
libprotobuf	3.5.2	he51fdeb_1	conda-forge
m2w64-gcc-libgfortran	5.3.0	6	
m2w64-gcc-libs	5.3.0	7	
m2w64-gcc-libs-core	5.3.0	7	
m2w64-gmp	6.1.0	2	
m2w64-libwinpthread-git	5.0.0.4634.697f757	2	
markdown	2.6.11	py36_0	
markupsafe	1.0	py36h0e26971_1	
matplotlib	2.2.2	py36h153e9ff_0	
mistune	0.8.3	py36_0	
mkl	2018.0.2	1	
mkl_fft	1.0.1	py36h452e1ab_0	
mkl_random	1.0.1	py36h9258bd6_0	
msys2-conda-epoch	20160418	1	
nbconvert	5.3.1	py36h8dc0fde_0	
nbformat	4.4.0	py36h3a5bc1b_0	
networkx	2.1	<pip>	
notebook	5.4.1	py36_0	
numpy	1.11.3	py36h4a99626_4	
numpydoc	0.7.0	py36ha25429e_0	
opencv-python	3.4.0.12	<pip>	
openssl	1.0.2o	hfa6e2cd_1	conda-forge
packaging	17.1	py36_0	
pandas	0.22.0	py36h6538335_0	
pandoc	1.19.2.1	hb2460c7_1	
pandocfilters	1.4.2	py36h3ef6317_1	
parso	0.1.1	py36hae3edee_0	
patsy	0.5.0	py36_0	
pickleshare	0.7.4	py36h9de030f_0	
Pillow	5.0.0	<pip>	
pip	9.0.3	py36_0	
pip	18.0	<pip>	
plotly	2.5.1	py36_0	
prompt_toolkit	1.0.15	py36h60b8f86_0	
protobuf	3.5.2	py36he51fdeb_0	conda-forge
py4j	0.10.6	py36_0	
pycparser	2.18	py36hd053e01_1	
pyglet	1.2.4	<pip>	
pygments	2.2.0	py36hb010967_0	
pyopenssl	17.5.0	py36h5b7d817_0	
pyarsing	2.2.0	py36h785a196_1	
pyqt	5.6.0	py36hb5ed885_5	
pysocks	1.6.8	py36_0	
pyspark	2.3.0	py36_0	
python	3.6.5	h0c2934d_0	
python-dateutil	2.7.2	py36_0	
pytz	2018.3	py36_0	
PyWavelets	0.5.2	<pip>	
pywinpty	0.5.1	py36_0	
pyyaml	3.12	py36h1d1928f_1	
pyzmq	17.0.0	py36hfa6e2cd_0	
qt	5.6.2	h2639256_8	conda-forge
qtconsole	4.3.1	py36h99a29a9_0	
requests	2.18.4	py36h4371aae_1	
scikit-image	0.13.1	<pip>	
scikit-learn	0.19.1	py36h53aea1b_0	
scipy	1.0.1	py36hce232c7_0	
seaborn	0.8.1	py36h9b69545_0	
send2trash	1.5.0	py36_0	
setuptools	39.0.1	py36_0	
simplegeneric	0.8.1	py36_2	
sip	4.18.1	py36h9c25514_2	
six	1.11.0	py36h4db2310_1	
snowballstemmer	1.2.1	py36h763602f_0	
sphinx	1.7.2	py36_0	

sphinxcontrib	1.0	py36hbbac3d2_1
sphinxcontrib-websupport	1.0.1	py36hb5e5916_1
sqlite	3.24.0	hb652765_0 conda-forge
statsmodels	0.8.0	py36h6189b4c_0
tensorflow	1.2.1	py36_0
terminado	0.8.1	py36_1
testpath	0.3.1	py36h2698cfe_0
tornado	5.0.1	py36_1
tqdm	4.19.8	py36_0
traitlets	4.3.2	py36h096827d_0
typing	3.6.4	py36_0
urllib3	1.22	py36h276f60a_0
vc	14.1	h0510ff6_3
vs2015_runtime	15.5.2	3
wcwidth	0.1.7	py36h3d5aa90_0
werkzeug	0.14.1	py36_0
wheel	0.30.0	py36h6c3ec14_1

## Output

```

Namespace(dataset='pascal_voc', demo_net='res101')
C:\Public\xrelab\Week7_detection1 --- res101_faster_rcnn_iter_110000.ckpt
checking the model here
C:/Public/xrelab/Week7_detection1/data/voc_2007_trainval_voc_2012_trainval/res101_faster_rcnn_iter_110000.ckpt
<nets.resnet_v1.resnetv1 object at 0x000002A4584A7400>
C:/Public/xrelab/Week7_detection1/data/voc_2007_trainval_voc_2012_trainval/res101_faster_rcnn_iter_110000.ckpt
Model restored !!!
Loaded network
C:/Public/xrelab/Week7_detection1/data/voc_2007_trainval_voc_2012_trainval/res101_faster_rcnn_iter_110000.ckpt
~~~~~
Demo for data/demo/000001.jpg
Entering into the Demo function
Detection took 33.073s for 300 object proposals

```

---

## Code

```
'''
Custom implementation of nms (Non-Maxima Suppression)
```

```
-Using Felzenszwalb et al.
```

```
'''
```

```
import numpy as np
```

```
def non_max_suppress_slow(boxes, overlapThresh):
    if len(boxes)==0:
        return []
```

```
    #initialize a list of picked indices
    pick=[]
```

```
    #grab the coordinates of the bounding boxes
    x1=boxes[:,0]
    y1=boxes[:,1]
    x2=boxes[:,2]
    y2=boxes[:,3]
```

```

#compute the area of the bounding boxes and sort the bounding boxes by the bottom-right y-
coordinate
area=(x2-x1+1)*(y2-y1+1)
idxs=np.argsort(y2) #very important

while len(idxs)>0:
    last=len(idxs)-1
    i=idxs[last]
    pick.append(i)
    suppress=[last]

# Time of compute the overlap ratios to ignore some of the bounding boxes
for pos in range(0, last):
    j=idxs[pos]

    #find the largest (x,y) coordinates for the start of the bounding box and the smallest (x,y)
coordinates for the end of the bbox
    xx1=max(x1[i], x1[j])
    yy1=max(y1[i], y1[j])
    xx2=min(x2[i], x2[j])
    yy2=min(y2[i], y2[j])

    #Width and height of the bounding box
    w=max(0,xx2-xx1+1)
    h=max(0,yy2-yy1+1)

    #Compute the ratio of overlap between the computed Bounding box and the bounding
box on the area list
    overlap=float(w*h)/area[j]

    # if there is sufficient overlap, suppress the current bounding box
    if overlap>overlapThresh:suppress.append(pos)

    #delete all indexes from the index list that are in the suppression list
    idxs=np.delete(idxs, suppress)
# return only the bounding boxes that were picked
return pick

```

## Output

- Per class Output

```
[[ 0.00000000e+00  7.53882446e+01  8.59855042e+01  1.82000000e+02
  1.76660717e-04]
 [ 5.27669067e+01  1.75738159e+02  2.73335266e+02  1.82000000e+02
  4.03766791e-07]
 [ 2.66698227e+01  1.44555435e+02  2.28405914e+02  1.80168167e+02
  4.84814382e-06]
 [ 1.87606674e+02  1.11119522e+02  2.74000000e+02  1.72879929e+02
  6.45169820e-08]
 [ 0.00000000e+00  1.67456818e+01  1.90810150e+02  1.70641388e+02
  7.72375643e-06]
 [ 1.63595428e+02  2.85271263e+01  2.69738220e+02  1.52213379e+02
  1.38052462e-06]
 [ 1.34481239e+00  2.11989021e+00  1.70276108e+01  1.68099728e+01
  1.64946002e-07]
 [ 5.39297256e+01  3.95479679e+00  7.01377792e+01  1.50176420e+01
  3.97014844e-07]
 [ 2.69408752e+02  1.49826717e+00  2.74000000e+02  1.47632170e+01
  1.25326991e-07]
 [ 1.68714249e+02  2.41870022e+00  1.82132401e+02  1.07102919e+01
  5.55073825e-07]]
```

- Detections Visualized :

car detections with  $p(\text{car} \mid \text{box}) \geq 0.7$



person 0.772 on 0.976

person detections with  $p(\text{person} | \text{box}) \geq 0.7$

