CS 169 - HW 1

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1a)

I plan on creating my own Golden Section Search to find the minimum of a function. To better understand the algorithm I referenced the following articles and videos.

- https://www.youtube.com/watch?v=hLm8xfwWYPw
- https://en.wikipedia.org/wiki/Golden-section_search

As part of this algorithm I used the bracketing algorithm provided in the K&W book (p36) modified slightly to return the number of func_evals for data collection

```
In [ ]: function bracket_minimum(f, x=0; s=1e-2, k=2.0)
             a, ya = x, f(x)
             b, yb = a + s, f(a + s)
             if yb > ya
                 a, b = b, a
                 ya, yb = yb, ya
                 s = -s
             end
            func_evals = 2
            while true
                 c, yc = b + s, f(b + s)
                 func_evals += 1
                 if yc > yb
                     return a < c ? (a, c, func_evals) : (c, a, func_evals)</pre>
                 end
                 a, ya, b, yb = b, yb, c, yc
                 s *= k
             end
        end
```

bracket_minimum (generic function with 2 methods)

```
In [ ]: function optimizer1D(func, initial_point, initial_step_size=NaN)
            # optimization method used = Golden Section Search
            \# source(s) = custom made
            elapsed_time = @elapsed begin
                g = (sqrt(5) - 1) / 2 \# golden \ ratio
                ep = 1e-3 # epsilon s.t. if bracket size is smaller than epsilon we
                left, right, func_evals = bracket_minimum(func, initial_point)
                bracket_size = abs(right - left)
                # data
                convergence = func(initial_point)
                while bracket_size > ep
                    d = g * (right - left)
                    x1 = left + d
                    x2 = right - d
                    if func(x1) < func(x2)
                         left = x2
                    else
                         right = x1
                    end
                    bracket_size = abs(right - left)
                    mid = (left + right) / 2
                    if bracket_size > ep
                         convergence = func(mid)
                    end
                    func_evals += 3
                end
                min_point = (left + right) / 2
            end
            return convergence - func(min_point), func(min_point), func_evals, elaps
        end
```

optimizer1D (generic function with 2 methods)

1b)

This helper method generates a number according to the formula (LaTeX formatting generated by ChatGPT, equation by me):

```
k \cdot e^y, y \in [\text{lower, upper}], k \in \{-1, 1\}
```

```
In [ ]: function x(lower_bound, upper_bound)
             y = random_number = rand(lower_bound:upper_bound)
             sign = rand([-1, 1])
             return sign * exp(y)
        end
        x (generic function with 1 method)
In []: starting_points = [x(-10, 10) \text{ for } \_ \text{ in } 1:100]
        100-element Vector{Float64}:
         1096.6331584284585
         1096.6331584284585
           -0.049787068367863944
             0.00012340980408667956
           -0.0024787521766663585
             0.01831563888873418
           -0.00033546262790251185
           -0.01831563888873418
           -0.0009118819655545162
             1.0
             0.00012340980408667956
             0.006737946999085467
             0.36787944117144233
             0.0009118819655545162
             1.0
           -2.718281828459045
             0.00012340980408667956
           -1.0
             0.049787068367863944
        1c)
```

Below are the functions defined in part 1c using an a = 2

```
In [ ]: function f(a)
             function fa(x)
                 return 0.5 * (x-a)^2
             end
             return fa
        end
        function g(a)
             function ga(x)
                 return 0.25*x^4 - a*x
             end
             return ga
        end
        function h(a)
             function ha(x)
                 return exp(x) + exp(-x) - a*x
             end
             return ha
        end
```

h (generic function with 1 method)

Below are the minimum points of the functions above calculated by finding the derivative, using elementary derviative rules such as the *power rule* and *chain rule*, and finding when said derivative was equal to 0.

$$f'(x) = x - a$$

$$0 = x - a$$

$$x = a$$

$$g'(x) = x^{3} - a$$

$$0 = x^{3} - a$$

$$x = \sqrt[3]{a}$$

The step below was computed using symbolab

$$f'(x) = e^x - e^{-x} - a$$

 $0 = e^x - e^{-x} - a$
 $x = ln(1 + \sqrt{a})$

```
In [ ]: function min f(a)
            return a
        end
        function min_g(a)
            return cbrt(a)
        end
        function min_h(a)
            return log(1 + sqrt(a))
        end
        min_h (generic function with 1 method)
In [ ]: convergence_f, abs_err_f, func_evals_f, wall_time_f = 0, 0, 0, 0
        convergence_g, abs_err_g, func_evals_g, wall_time_g = 0, 0, 0, 0
        convergence_h, abs_err_h, func_evals_h, wall_time_h = 0, 0, 0, 0
        starting_points_h = [x(-2, 2) \text{ for } \_ \text{ in } 1:100]
        f 2 = f(a)
        g_2 = g(a)
        h_2 = h(a)
        min f calc = min f(a)
        min_g_calc = min_g(a)
        min_h_calc = min_h(a)
        for (index, x) in enumerate(starting_points)
            conv_f, est_min_f, iters_f, elapsed_f = optimizer1D(f_2, x, a)
            conv_g, est_min_g, iters_g, elapsed_g = optimizer1D(g_2, x, a)
            conv_h, est_min_h, iters_h, elapsed_h = optimizer1D(h_2, starting_points
            convergence_f += conv_f
            convergence_g += conv_g
            convergence_h += conv_h
            abs_err_f += abs(min_f_calc - est_min_f)
            abs_err_g += abs(min_g_calc - est_min_g)
            abs_err_h += abs(min_h_calc - est_min_h)
            func_evals_f += iters_f
            func_evals_g += iters_g
            func_evals_h += iters_h
            wall_time_f += elapsed_f
            wall_time_g += elapsed_g
            wall_time_h += elapsed_h
        end
```

In order to display the data I am using the package PrettyTables

```
In []: using PrettyTables

In []: colNames = ["", "f(x)", "g(x)", "h(x)"]
    rowNames = ["Convergence", "Absolute Error", "Func Evals", "Wall Time"]

    column1 = [convergence_f, abs_err_f, func_evals_f, wall_time_f] / 100
    column2 = [convergence_g, abs_err_g, func_evals_g, wall_time_g] / 100
    column3 = [convergence_h, abs_err_h, func_evals_h, wall_time_h] / 100

    data = hcat(rowNames, column1, column2, column3)
    pretty_table(data, header=colNames)
```

	f(x)	g(x)	h(x)
Convergence Absolute Error Func Evals	4.13864e-9 2.0 79.52	6.57339e-8 3.1498 75.24	3.75714e-8 0.184306 58.14
Wall Time	2.1876e-7	5.6295e-7	6.0581e-7

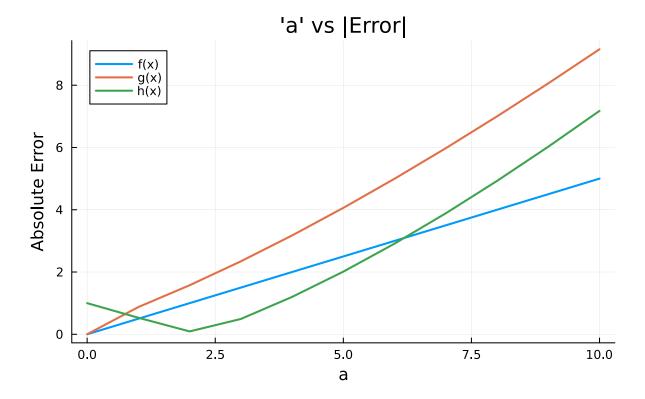
Looking at the data one thing I noticed was that the function evals for f(x) and g(x) where about the same. This makes sense since both use starting points from a larger range of starting values compared to h(x).

EXTRA CREDIT (1c)

I decieded to plot the difference in absolute error as I varied the a value for the provided functions.

```
In []: a_values = 0:10
        abs_err_f, abs_err_g, abs_err_h = [], [], []
        starting_points_ec = [x(-5, 5) \text{ for } \_ \text{ in } 1:50]
        for a in a_values
            temp_f, temp_g, temp_h = 0, 0, 0
            min_f_calc = min_f(a)
            min_g_calc = min_g(a)
            min_h_calc = min_h(a)
            f_a = f(a)
             g_a = g(a)
            h_a = h(a)
             for x in starting_points_ec
                 _, est_min_f, _, _ = optimizer1D(f_a, x)
                 _, est_min_g, _, _ = optimizer1D(g_a, x)
                 _, est_min_h, _, _ = optimizer1D(h_a, x)
                 temp_f += abs(min_f_calc - est_min_f)
                 temp_g += abs(min_g_calc - est_min_g)
                 temp_h += abs(min_h_calc - est_min_h)
             end
             append!(abs_err_f, temp_f / 100)
             append!(abs_err_g, temp_g / 100)
             append!(abs_err_h, temp_h / 100)
        end
```

I will use the Plots package to draw the multi-line graph



From this graph we can see that as * \mathbf{a} * incerases our error also increases. An exception to this when * \mathbf{a} * goes from 0 to/ ~2 for the function h(x), the error decreases for h(x).

NOTE: I'm an undergrad so the work below is merely for extracredit

2a)

```
In []:
    function optimizer2D(func, starting_x, starting_y, n=2)
        # optimization method used = Coordinate Descent
        # source(s) = custom made
        ep = 1e-3

        x = starting_x
        y = starting_y

        for _ in 1:n
             fx = func(x, y, fixed=:y)
             fy = func(x, y, fixed=:x)
             conv_x, x, iters_x, elapsed_x = optimizer1D(fx, x, a) # optimize x
             conv_y, y, iters_y, elapsed_y = optimizer1D(fy, x, a) # optimize y
             println("(", x, ",", y, ")")
        end

    return x, y
end
```

optimizer2D (generic function with 2 methods)

2b)

For this part I used the Rosenbrock function:

$$f(x,y)=(a-x)^2+b\cdot(y-x^2)^2,\quad a,b\in\mathbb{R}$$

more specifically where

$$a = 1 \text{ and } b = 100$$

The code below was generated by ChatGPT. It allows me to get the rosenbrock function fixed at a specific variable.

rosenbrock (generic function with 1 method)