

VISVESVARAYA TECHNOLOGICAL UNIVERSITY

“JnanaSangama”, Belgaum -590014, Karnataka.



LAB REPORT on

Artificial Intelligence

Submitted by:

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Under the Guidance of
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Associate Professor, BMSCE

in partial fulfillment for the award of the degree of
BACHELOR OF ENGINEERING
in
COMPUTER SCIENCE AND ENGINEERING



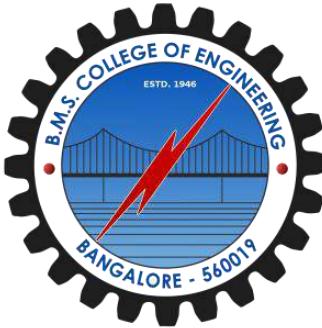
B.M.S. COLLEGE OF ENGINEERING

(Autonomous Institution under VTU)

BENGALURU-560019

Nov 2023 - Feb 2024

**B. M. S. College of Engineering,
Bull Temple Road, Bangalore 560019**
(Affiliated To Visvesvaraya Technological University, Belgaum)
Department of Computer Science and Engineering



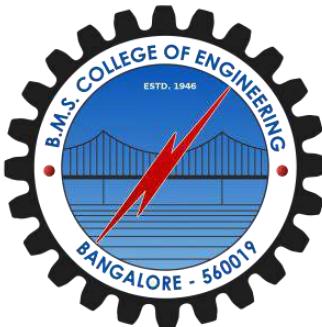
CERTIFICATE

This is to certify that the Lab work entitled “**Artificial Intelligence**” carried out by **Sanchay Agrawal (1BM21CS186)**, who is bonafide student of **B. M. S. College of Engineering**. It is in partial fulfillment for the award of **Bachelor of Engineering in Computer Science and Engineering** of the Visvesvaraya Technological University, Belgaum during the year 2022-23. The Lab report has been approved as it satisfies the academic requirements in respect of **Artificial Intelligence - (22CS5PCAIN)** work prescribed for the said degree.

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DECLARATION

I, Sanchay Agrawal (1BM21CS186), student of 5th Semester, B.E, Department of Computer Science and Engineering, B. M. S. College of Engineering, Bangalore, here by declare that, this lab report entitled " Artificial Intelligence " has been carried out by me under the guidance of Dr. Madhavi R.P., Associate Professor, Department of CSE, B. M. S. College of Engineering, Bangalore during the academic semester November - 2023-February-2024.

I also declare that to the best of my knowledge and belief, the development reported here is not from part of any other report by any other students.

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1. Course Outcomes

CO1: Apply knowledge of agent architecture, searching and reasoning techniques for different applications.

CO2: Analyse Searching and Inferencing Techniques.

CO3: Design a reasoning system for a given requirement

CO4: Conduct practical experiments for demonstrating agents, searching and inferencing.

2. Experiments

2.1 Experiment - 1

2.1.1 Question:

Implement Vacuum cleaner agent.

2.1.2 Code:

```
def vacuum_world():
    goal_state = {'A': 0, 'B': 0}
    cost = 0

    location_input = input("Enter Location of Vacuum")
    status_input = int(input("Enter status of " + location_input))
    status_input_complement = int(input("Enter status of the other room"))
    print("Initial Location Condition" + str(goal_state))

    if location_input == 'A':
        # Location A is Dirty.
        print("Vacuum is placed in Location A")
        if status_input == 1:
            print("Location A is Dirty.")
            # Suck the dirt and mark it as clean
            goal_state['A'] = 0
            cost += 1 # Cost for suck
            print("Cost for CLEANING A " + str(cost))
            print("Location A has been Cleaned.")

        if status_input_complement == 1:
            # If B is Dirty
            print("Location B is Dirty.")
            print("Moving right to Location B. ")
            cost += 1 # Cost for moving right
            print("COST for moving RIGHT " + str(cost))
            # Suck the dirt and mark it as clean
```

```

goal_state['B'] = 0
cost += 1 # Cost for suck
print("COST for SUCK " + str(cost))
print("Location B has been Cleaned. ")
else:
    print("No action " + str(cost))
    # Suck and mark clean
    print("Location B is already clean.")

if status_input == 0:
    print("Location A is already clean ")
    if status_input_complement == 1: # If B is Dirty
        print("Location B is Dirty.")
        print("Moving RIGHT to Location B. ")
        cost += 1 # Cost for moving right
        print("COST for moving RIGHT " + str(cost))
        # Suck the dirt and mark it as clean
        goal_state['B'] = 0
        cost += 1 # Cost for suck
        print("Cost for SUCK " + str(cost))
        print("Location B has been Cleaned. ")
    else:
        print("No action " + str(cost))
        print(cost)
        # Suck and mark clean
        print("Location B is already clean.")

else:
    print("Vacuum is placed in Location B")
    # Location B is Dirty.
    if status_input == 1:
        print("Location B is Dirty.")
        # Suck the dirt and mark it as clean
        goal_state['B'] = 0
        cost += 1 # Cost for suck
        print("COST for CLEANING " + str(cost))
        print("Location B has been Cleaned.")

    if status_input_complement == 1:
        # If A is Dirty
        print("Location A is Dirty.")
        print("Moving LEFT to Location A. ")
        cost += 1 # Cost for moving right
        print("COST for moving LEFT " + str(cost))
        # Suck the dirt and mark it as clean
        goal_state['A'] = 0

```

```

cost += 1 # Cost for suck
print("COST for SUCK " + str(cost))
print("Location A has been Cleaned.")

else:
    print(cost)
    # Suck and mark clean
    print("Location B is already clean.")

if status_input_complement == 1: # If A is Dirty
    print("Location A is Dirty.")
    print("Moving LEFT to Location A. ")
    cost += 1 # Cost for moving right
    print("COST for moving LEFT " + str(cost))
    # Suck the dirt and mark it as clean
    goal_state['A'] = 0
    cost += 1 # Cost for suck
    print("Cost for SUCK " + str(cost))
    print("Location A has been Cleaned. ")
else:
    print("No action " + str(cost))
    # Suck and mark clean
    print("Location A is already clean.")

# Done cleaning
print("GOAL STATE: ")
print(goal_state)
print("Performance Measurement: " + str(cost))

```

vacuum_world()

2.1.3 Output:

```

Enter Location of Vacuum: A
Enter status of A1
Enter status of the other room: 1
Initial Location Condition{'A': 0, 'B': 0}
Vacuum is placed in Location A
Location A is Dirty.
Cost for CLEANING A 1
Location A has been Cleaned.
Location B is Dirty.
Moving right to Location B.
COST for moving RIGHT 2
COST for SUCK 3
Location B has been Cleaned.
GOAL STATE:
{'A': 0, 'B': 0}
Performance Measurement: 3

```

2.1.4 Observation Book Pictures:

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Experiment - 1

Aim:

Implement Vacuum cleaner agent.

Code:

```
def vacuum_world():
    goal_state = {'A': '0', 'B': '0'}
    cost = 0

    location_input = input("Enter location of vacuum: ")
    status_input = input("Enter status of " + location_input)
    status_input_complement = input("Enter status of other room")

    init_state = {location_input: status_input, 'B': status_input_complement}

    print("Initial location condition: " + str(init_state))

    if location_input == 'A':
        print("Vacuum is placed in location A")
        if status_input == '1':
            print("location A is dirty")
            goal_state['A'] = '0'
            cost += 1
            print("Cost for cleaning A " + str(cost))
            print("location A has been cleaned")

    if status_input_complement == '1':
        print("location B is dirty")
        print("Moving right to the location B")
        cost += 1
```

print ("Cost for Moving Right" + str(cost))

goal-state ['B'] = '0'

cost += 1

print ("Cost for Suck" + str(cost))

print ("Location B has been cleaned")

else :

print ("No action" + str(cost))

print ("Location B is already clean")

If status-input = '0' :

print ("Location A is already clean")

If status-input-complement = '1' :

print ("Location B is dirty")

print ("Moving Right to Location B")

cost += 1

print ("Cost for moving right" + str(cost))

goal-state ['B'] = '0'

cost += 1

print ("Cost for Suck" + str(cost))

print ("Location B has been cleaned")

else :

print ("No action" + str(cost))

print (cost)

print ("Location B is already clean").

else :

print ("Vacuum is placed in location B")

If status-input = '1' :

print ("Location B is Dirty")

goal-state ['B'] = '0'

cost += 1

print ("Cost for Cleaning" + str(cost))

print ("Location B has been cleaned")

```

if status - input - complement == '1' :
    print ("location A is Dirty")
    print ("Moving LEFT to the location A")
    cost += 1
    print ("Cost for Moving Left" + str(cost))
    goal_state ['A'] = '0'
    cost += 1
    print ("Cost for Suck" + str(cost))
    print ("location A has been cleaned")

```

else :

```

print (cost)
print ("location B is already clean")

```

if status - input - complement == '1' :

```

    print ("location A is Dirty")
    print ("Moving Left to Location A")
    cost += 1

```

```

    print ("Cost for Moving Left" + str(cost))
    goal_state ['A'] = '0'

```

```

    cost += 1

```

```

    print ("Cost for Suck" + str(cost))

```

```

    print ("location A has been cleaned")

```

else :

```

    print ("No action" + str(cost))

```

```

    print ("location A is already clean")

```

```

print ("GOAL STATE")

```

```

print (goal state)

```

```

print ("Performance Measurement :" + str(cost))

```

Vacuum-world()

Output:

Enter location of Vacuum : A

Enter status of A : 1

Enter status of other room : 1

Initial location condition : { 'A' : '1', 'B' : '1' }

Vacuum is placed in location A

Location A is Dirty

Cost of cleaning A : 1

Location A has been cleaned

Location B is Dirty.

Moving Right to location B.

Cost for Moving Right : 2

Cost for Suck : 3

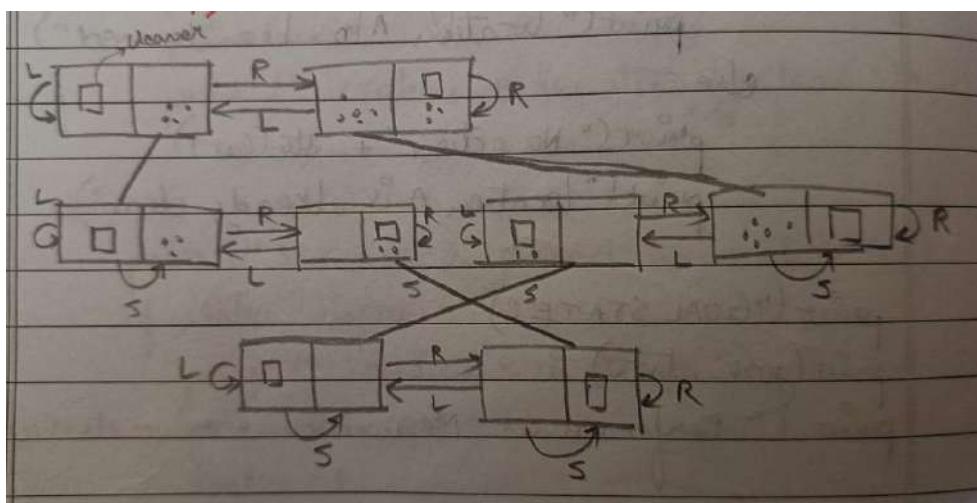
Location B has been cleaned.

Goal State:

{ 'A' : '0', 'B' : '0' }

~~Performance Measurement : 3~~

~~8
20 Jul 23~~



2.2 Experiment - 2

2.2.1 Question:

Implement 8 puzzle using Breadth First Search Algorithm.

2.2.2 Code:

```
import sys  
import numpy as np
```

```
class Node:  
    def __init__(self, state, parent, action):  
        self.state = state  
        self.parent = parent  
        self.action = action
```

```
class StackFrontier:  
    def __init__(self):  
        self.frontier = []
```

```
    def add(self, node):  
        self.frontier.append(node)
```

```
    def contains_state(self, state):  
        return any((node.state[0] == state[0]).all() for node in self.frontier)
```

```
    def empty(self):  
        return len(self.frontier) == 0
```

```
    def remove(self):  
        if self.empty():  
            raise Exception("Empty Frontier")  
        else:  
            node = self.frontier[-1]  
            self.frontier = self.frontier[:-1]  
            return node
```

```
class QueueFrontier(StackFrontier):  
    def remove(self):  
        if self.empty():  
            raise Exception("Empty Frontier")  
        else:  
            node = self.frontier[0]  
            self.frontier = self.frontier[1:]  
            return node
```

```

class Puzzle:
    def __init__(self, start, startIndex, goal, goalIndex):
        self.start = [start, startIndex]
        self.goal = [goal, goalIndex]
        self.solution = None

    def neighbors(self, state):
        mat, (row, col) = state
        results = []

        if row > 0:
            mat1 = np.copy(mat)
            mat1[row][col] = mat1[row - 1][col]
            mat1[row - 1][col] = 0
            results.append(('up', [mat1, (row - 1, col)]))
        if col > 0:
            mat1 = np.copy(mat)
            mat1[row][col] = mat1[row][col - 1]
            mat1[row][col - 1] = 0
            results.append(('left', [mat1, (row, col - 1)]))
        if row < 2:
            mat1 = np.copy(mat)
            mat1[row][col] = mat1[row + 1][col]
            mat1[row + 1][col] = 0
            results.append(('down', [mat1, (row + 1, col)]))
        if col < 2:
            mat1 = np.copy(mat)
            mat1[row][col] = mat1[row][col + 1]
            mat1[row][col + 1] = 0
            results.append(('right', [mat1, (row, col + 1)]))

        return results

    def print(self):
        solution = self.solution if self.solution is not None else None
        print("Start State:\n", self.start[0], "\n")
        print("Goal State:\n", self.goal[0], "\n")
        print("\nStates Explored: ", self.num_explored, "\n")
        print("Solution:\n ")
        for action, cell in zip(solution[0], solution[1]):
            print("action: ", action, "\n", cell[0], "\n")
        print("Goal Reached!!")

    def does_not_contain_state(self, state):
        for st in self.explored:

```

```

if (st[0] == state[0]).all():
    return False
    return True

def solve(self):
    self.num_explored = 0

    start = Node(state=self.start, parent=None, action=None)
    frontier = QueueFrontier()
    frontier.add(start)

    self.explored = []

    while True:
        if frontier.empty():
            raise Exception("No solution")

        node = frontier.remove()
        self.num_explored += 1

        if (node.state[0] == self.goal[0]).all():
            actions = []
            cells = []
            while node.parent is not None:
                actions.append(node.action)
                cells.append(node.state)
                node = node.parent
            actions.reverse()
            cells.reverse()
            self.solution = (actions, cells)
            return

        self.explored.append(node.state)

        for action, state in self.neighbors(node.state):
            if not frontier.contains_state(state) and self.does_not_contain_state(state):
                child = Node(state=state, parent=node, action=action)
                frontier.add(child)

start = np.array([[1, 2, 3], [8, 0, 4], [7, 6, 5]])
goal = np.array([[2, 8, 1], [0, 4, 3], [7, 6, 5]])

startIndex = (1, 1)
goalIndex = (1, 0)

```

```
p = Puzzle(start, startIndex, goal, goalIndex)
p.solve()
p.print()
```

2.2.3 Output:

```
Start State:
[[1 2 3]
 [8 0 4]
 [7 6 5]]

Goal State:
[[2 8 1]
 [0 4 3]
 [7 6 5]]

States Explored: 358

Solution:

action: up
[[1 0 3]
 [8 2 4]
 [7 6 5]]

action: left
[[0 1 3]
 [8 2 4]
 [7 6 5]]

action: down
[[8 1 3]
 [0 2 4]
 [7 6 5]]

action: right
[[8 1 3]
 [2 0 4]
 [7 6 5]]

action: right
[[8 1 3]
 [2 4 0]
 [7 6 5]]

action: up
[[8 1 0]
 [2 4 3]
 [7 6 5]]

action: left
[[8 0 1]
 [2 4 3]
 [7 6 5]]

action: left
[[0 8 1]
 [2 4 3]
 [7 6 5]]

action: down
[[2 8 1]
 [0 4 3]
 [7 6 5]]

Goal Reached!!
```

2.2.4 Observation Book Pictures:

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Experiment - 2

Aim:

Implement 8-puzzle using Breadth First Search Algorithm.

Code:

```
import sys
import numpy as np
```

class Node:

```
def __init__(self, state, parent, action):
    self.state = state
    self.parent = parent
    self.action = action
```

class StackFrontier:

```
def __init__(self):
    self.frontier = []

def add(self, node):
    self.frontier.append(node)

def contains_state(self, state):
    return any((node.state[0] == state[0]).all() for
               node in self.frontier)

def empty(self):
    return len(self.frontier) == 0

def remove(self):
    if self.empty():
        raise Exception("Empty Frontier")
```

else :

```
node = self.frontier[-1]
self.frontier = self.frontier[:-1]
return node.
```

class QueueFrontier(StackFrontier):

```
def remove(self):
    if self.empty():
        raise Exception("Empty Frontier")
```

else :

```
node = self.frontier[0]
self.frontier = self.frontier[1:]
return node.
```

class Puzzle:

```
def __init__(self, start, startIndex, goal, goalIndex):
    self.start = [start, startIndex]
    self.goal = [goal, goalIndex]
    self.solution = None
```

def neighbours(self, state):

```
mat, (row, col) = state
results []
```

if row > 0:

```
mat1 = np.copy(mat)
```

```
mat1[row][col] = mat1[row-1][col]
```

```
mat1[row-1][col] = 0
```

```
results.append(("up", mat1, (row-1, col)))
```

if $col > 0$:

$mat1 = np.copy(mat)$

$mat1[row][col] = mat1[row][col - 1]$

$mat1[row][col - 1] = 0$

$results.append((\text{'left'}, [mat1, (row, col - 1)]))$

if $row < 2$:

$mat1 = np.copy(mat)$

$mat1[row][col] = mat1[row + 1][col]$

$mat1[row + 1][col] = 0$

$results.append((\text{'down'}, [mat1, (row + 1, col)]))$

if $col < 2$:

$mat1 = np.copy(mat)$

$mat1[row][col] = mat1[row][col + 1]$

$mat1[row][col + 1] = 0$

$results.append((\text{'right'}, [mat1, (row, col + 1)]))$

return results

def print(self):

solutions = self.solutions if self.solution is not None
else None

print("Start State:\n", self.start[0], "\n")

print("Goal State:\n", self.goal[0], "\n")

print("No States Explored:", self.num_explored, "\n")

print("Solutions:\n")

for action, cell in zip(solutions[0], solutions[1]):

print("action:", action, "\n", cell[0], "\n")

print("Goal Reached")

```
def does-not-contain-state(self, state):
    for st in self.explored:
        if (st[0] == state[0]).all():
            return False
    return True
```

```
def solve(self):
    self.num_explored = 0
```

```
start = Node(state=self.start, parent=None,
             action=None)
```

```
frontier = QueueFrontier()
frontier.add(start)
```

```
self.explored[]
```

```
while True:
```

```
if frontier.empty():
    raise Exception("No solution")
```

```
node = frontier.remove()
self.num_explored += 1
```

```
if (node.state[0] == self.goal[0]).all():
    actions = []
```

```
cells = []
```

```
while node.parent is not None:
```

```
actions.append(node.action)
```

```
cells.append(node.state)
```

```
self
```

```
actions.append(node.action)
```

```
cells.append(node.state)
```

```
node = node.parent
```

actions.reverse()

cells.reverse()

self.solution = (actions, cells)

return

self.explored.append(node.state)

for action, state in self.neighbors(node.state):

if not frontier.contains(state) and

self.does_not_contain_state(state):

child = Node(state=state, parent=node,
action=action)

frontier.add(child)

start = np.array([[1, 2, 3], [8, 0, 4], [7, 6, 5]])

goal = np.array([[2, 8, 1], [0, 4, 3], [7, 6, 5]])

startIndex = (1, 1)

goalIndex = (1, 0)

p = p.Puzzle(start, startIndex, goal, goalIndex)

p.solve()

p.print()

Output:

Start State:

[1 2 3]

[8 0 4]

[7 6 5]

Goal State :

$$\begin{bmatrix} 2 & 8 & 0 \\ 1 & 4 & 3 \\ 7 & 6 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 4 & 3 \\ 2 & 8 & 1 \\ 7 & 6 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 7 & 6 & 5 \\ 2 & 8 & 1 \\ 0 & 4 & 3 \end{bmatrix}$$

Solution :

action: up

$$\begin{bmatrix} 1 & 0 & 3 \\ 8 & 2 & 4 \\ 7 & 6 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 8 & 2 & 4 \\ 1 & 0 & 3 \\ 7 & 6 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 7 & 6 & 5 \\ 8 & 2 & 4 \\ 1 & 0 & 3 \end{bmatrix}$$

action: left

$$\begin{bmatrix} 0 & 1 & 3 \\ 8 & 2 & 4 \\ 7 & 6 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 8 & 2 & 4 \\ 0 & 1 & 3 \\ 7 & 6 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 7 & 6 & 5 \\ 8 & 2 & 4 \\ 0 & 1 & 3 \end{bmatrix}$$

action: down

$$\begin{bmatrix} 8 & 1 & 3 \\ 0 & 2 & 4 \\ 7 & 6 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 2 & 4 \\ 8 & 1 & 3 \\ 7 & 6 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 7 & 6 & 5 \\ 0 & 2 & 4 \\ 8 & 1 & 3 \end{bmatrix}$$

action: right

$$\begin{bmatrix} 8 & 1 & 3 \\ 2 & 0 & 4 \\ 7 & 6 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 0 & 4 \\ 8 & 1 & 3 \\ 7 & 6 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 7 & 6 & 5 \\ 2 & 0 & 4 \\ 8 & 1 & 3 \end{bmatrix}$$

action: right

$$\begin{bmatrix} 8 & 1 & 3 \\ 2 & 4 & 0 \\ 7 & 6 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 4 & 0 \\ 8 & 1 & 3 \\ 7 & 6 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 7 & 6 & 5 \\ 2 & 4 & 0 \\ 8 & 1 & 3 \end{bmatrix}$$

action: up

$$\begin{bmatrix} 8 & 1 & 0 \\ 2 & 4 & 3 \\ 7 & 6 & 5 \end{bmatrix}$$

action: left

$$\begin{bmatrix} 8 & 0 & 1 \\ 2 & 4 & 3 \\ 7 & 6 & 5 \end{bmatrix}$$

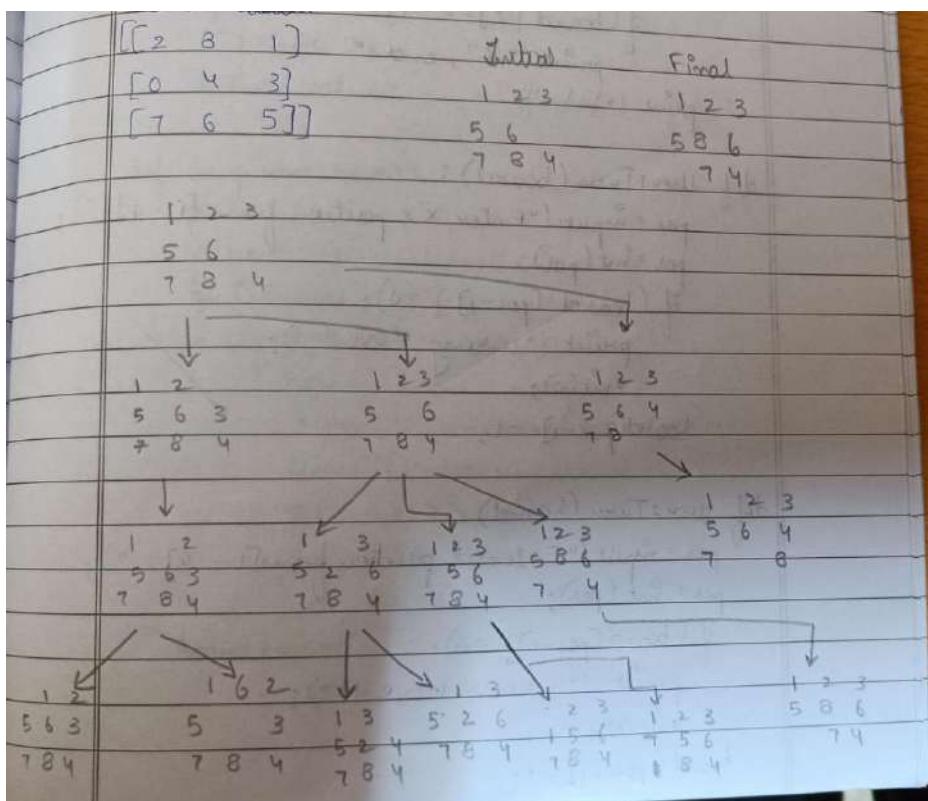
action: left

$$\begin{bmatrix} 0 & 8 & 1 \\ 2 & 4 & 3 \\ 7 & 6 & 5 \end{bmatrix}$$

action: down

$$\begin{bmatrix} 2 & 8 & 1 \\ 0 & 4 & 3 \\ 7 & 6 & 5 \end{bmatrix}$$

Initial	Final
$\begin{bmatrix} 2 & 8 & 1 \\ 0 & 4 & 3 \\ 7 & 6 & 5 \end{bmatrix}$	$\begin{bmatrix} 1 & 2 & 3 \\ 5 & 6 & \\ 7 & 8 & 4 \end{bmatrix}$
$\begin{bmatrix} 1 & 2 & 3 \\ 5 & 6 & \\ 7 & 8 & 4 \end{bmatrix}$	$\begin{bmatrix} 1 & 2 & 3 \\ 5 & 6 & 4 \\ 7 & 4 \end{bmatrix}$



2.3 Experiment - 3

2.3.1 Question:

Explore the working of Tic-tac-toe using Min Max strategy.

2.3.2 Code:

```
def ConstBoard(board):
    print("Current State Of Board : \n\n");
    for i in range (0,9):
        if((i>0) and (i%3)==0):
            print("\n");
        if(board[i]==0):
            print("- ",end=" ");
        if (board[i]==1):
            print("O ",end=" ");
        if(board[i]==-1):
            print("X ",end=" ");
    print("\n\n");
```

#This function takes the user move as input and make the required changes on the board.

```
def User1Turn(board):
    pos=input("Enter X's position from [1...9]: ");
    pos=int(pos);
    if(board[pos-1]!=0):
        print("Wrong Move!!!\"");
        exit(0) ;
    board[pos-1]=-1;
```

```
def User2Turn(board):
    pos=input("Enter O's position from [1...9]: ");
    pos=int(pos);
    if(board[pos-1]!=0):
        print("Wrong Move!!!\"");
        exit(0);
    board[pos-1]=1;
```

#MinMax function.

```
def minimax(board,player):
    x=analyzeboard(board);
    if(x!=0):
        return (x*player);
    pos=-1;
    value=-2;
    for i in range(0,9):
        if(board[i]==0):
            board[i]=player;
            score=-minimax(board,(player*-1));
            if(score>value):
                value=score;
                pos=i;
            board[i]=0;
    return value;
```

```

if(score>value):
    value=score;
    pos=i;
    board[i]=0;

if(pos== -1):
    return 0;
return value;

#This function makes the computer's move using minmax algorithm.
def CompTurn(board):
    pos=-1;
    value=-2;
    for i in range(0,9):
        if(board[i]==0):
            board[i]=1;
            score=-minimax(board, -1);
            board[i]=0;
            if(score>value):
                value=score;
                pos=i;

    board[pos]=1;

```

```

#This function is used to analyze a game.
def analyzeboard(board):
    cb=[[0,1,2],[3,4,5],[6,7,8],[0,3,6],[1,4,7],[2,5,8],[0,4,8],[2,4,6]];

    for i in range(0,8):
        if(board[cb[i][0]] != 0 and
           board[cb[i][0]] == board[cb[i][1]] and
           board[cb[i][0]] == board[cb[i][2]]):
            return board[cb[i][2]];
    return 0;

```

```

#Main Function.
def main():
    choice=input("Enter 1 for single player, 2 for multiplayer: ");
    choice=int(choice);
    #The broad is considered in the form of a single dimentional array.
    #One player moves 1 and other move -1.
    board=[0,0,0,0,0,0,0,0];
    if(choice==1):
        print("Computer : O Vs. You : X");
        player= input("Enter to play 1(st) or 2(nd) :");

```

```

player = int(player);
for i in range (0,9):
    if(analyzeboard(board)!=0):
        break;
    if((i+player)%2==0):
        CompTurn(board);
    else:
        ConstBoard(board);
        User1Turn(board);
else:
    for i in range (0,9):
        if(analyzeboard(board)!=0):
            break;
        if((i)%2==0):
            ConstBoard(board);
            User1Turn(board);
        else:
            ConstBoard(board);
            User2Turn(board);

```

```

x=analyzeboard(board);
if(x==0):
    ConstBoard(board);
    print("Draw!!!")
if(x==-1):
    ConstBoard(board);
    print("X Wins!!! Y Loose !!!")
if(x==1):
    ConstBoard(board);
    print("X Loose!!! O Wins !!!")

```

main()

2.3.3 Output:

```
Enter 1 for single player, 2 for multiplayer: 1
Computer : O Vs. You : X
Enter to play 1(st) or 2(nd) :1
Current State Of Board :

- - -
- - -
- - -


Enter X's position from [1...9]: 1
Current State Of Board :

X - -
- 0 -
- - -


Enter X's position from [1...9]: 7
Current State Of Board :

X - -
0 0 -
X - -


Enter X's position from [1...9]: 6
Current State Of Board :

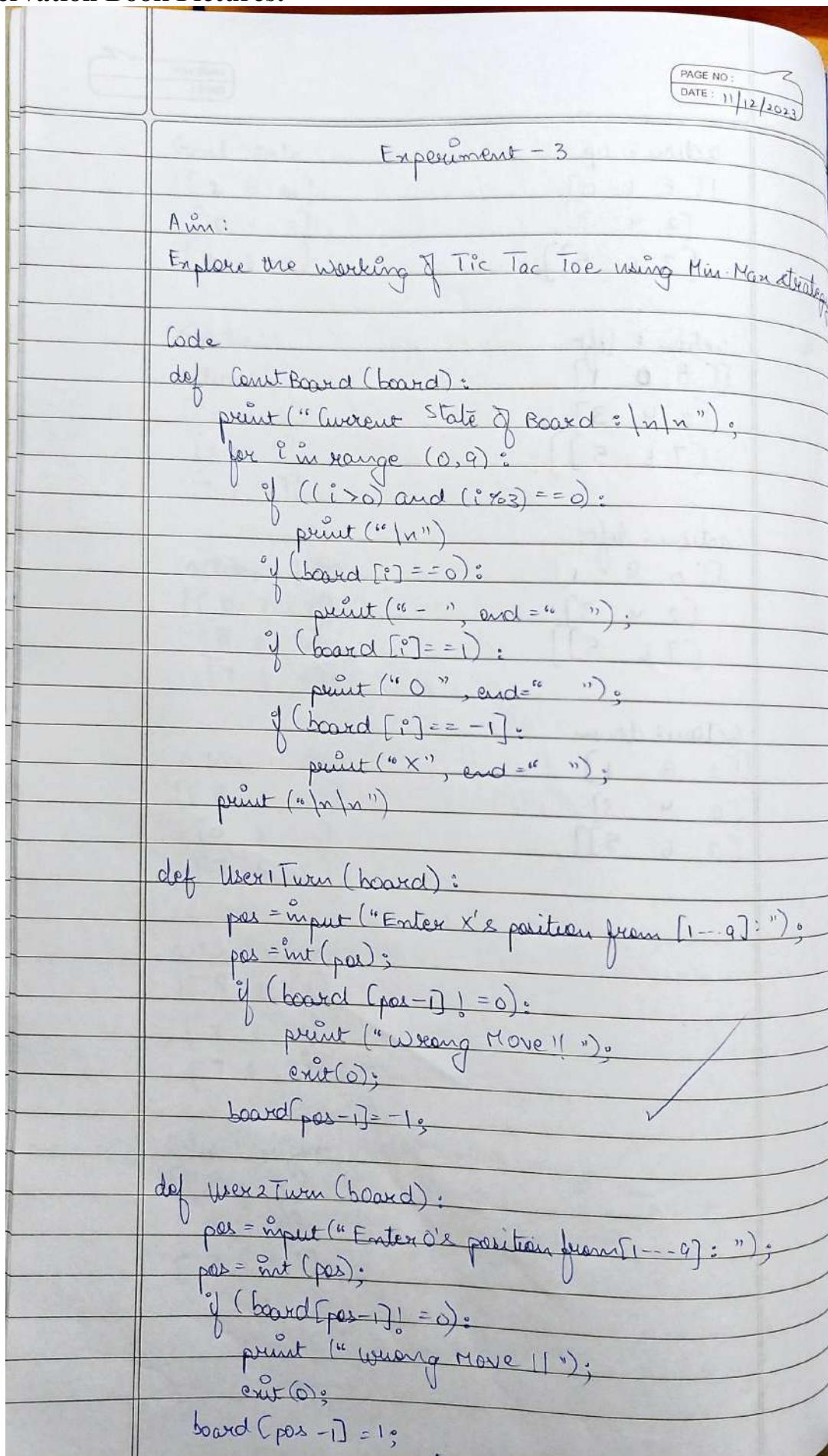
X 0 -
0 0 X
X - -


Enter X's position from [1...9]: 3
Current State Of Board :

X 0 X
0 0 X
X 0 -


X Loose!!! O Wins !!!!
```

2.3.4 Observation Book Pictures:



```

def minimax (board, player):
    x = analyzeboard (board);
    if (x != 0)
        return (x + player);
    pos = -1;
    value = -2;
    for i in range (0,9):
        if (board [i] == 0):
            board [i] = player;
            score = -minimax (board, (player * -1));
            if (score > value):
                value = score;
                pos = i;
            board [i] = 0;

    if (pos == -1)
        return 0;
    return value;

def compTurn (board):
    pos = -1;
    value = -2;
    for i in range (0,9):
        if (board [i] == 0):
            board [i] = 1;
            score = -minimax (board, -1);
            board [i] = 0;
            if (score > value):
                value = score;
                pos = i;
            board [pos] = 1;

```

```
def analyzeboard(board):
    cb = [[0, 1, 2], [3, 4, 5], [6, 7, 8], [0, 3, 6], [1, 4, 7],
          [2, 5, 8], [0, 4, 8], [2, 4, 6]]:
```

```
for i in range(0, 8):
    if (board[cb[i][0]] != 0 and
        board[cb[i][0]] == board[cb[i][1]] and
        board[cb[i][0]] == board[cb[i][2]]):
        return board[cb[i][2]]
return 0;
```

```
def main():
    choice = input("Enter 1 for single player, 2 for
multiplayer :");
```

```
choice = int(choice);
board = [0, 0, 0, 0, 0, 0, 0, 0, 0];
if (choice == 1):
    print("Computer: O Vs You: X");
    player = input("Enter to play 1st or 2nd : ");
    player = int(player);
    for i in range(0, 9):
        if (analyzeboard(board) != 0):
            break;
        if ((i + player) % 2 == 0):
            CompTurn(board);
        else:
            User1Turn(board);
```

else:

```
for i in range(0, 9):
    if (analyzeboard(board) != 0):
        break;
```

```
if ((i)%2 == 0) :  
    ConstBoard(board);  
    UserTurn(board);  
else :  
    ConstBoard(board);  
    UserTurn(board);  
  
x = analyzeboard(board);  
if (x == 0) :  
    ConstBoard(board);  
    print("Draw")  
if (x == -1) :  
    ConstBoard(board);  
    print("X wins! O loses!")  
if (x == 1) :  
    ConstBoard(board);  
    print("X loses! O wins!")  
  
main()
```

Output

Enter 1 for single player, 2 for multiplayer : 1
Computer: O vs You: X

Enter to play 1st or 2nd : 1

Current state of Board:

- - -

- - -

- - -

Enter X's position from [1-9] : 1

Current State of Board:

X	-	-
-	O	-
-	-	-

Enter X's position from [1 - 9]: 7

Current State of Board:

X	-	-
O	O	-
X	-	-

Enter X's position from [1 - 9]: 1 6

Current State of Board:

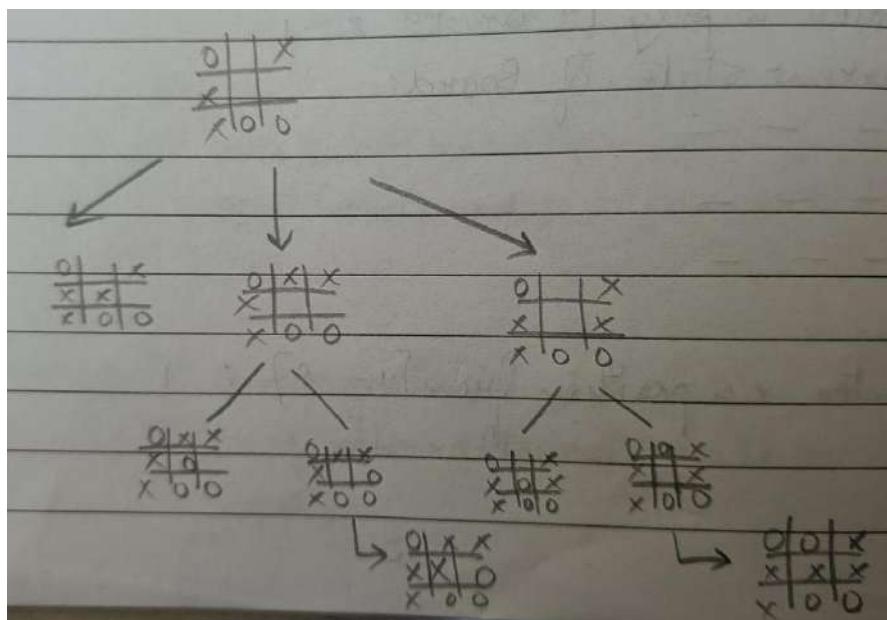
X	O	-
O	O	X
X	-	-

Enter X's position from [1 - 9]: 3

Current State of Board:

X	O	X
O	O	X
X	O	-

X loses!! O wins!!



2.4 Experiment - 4

2.4.1 Question:

Implement Iterative deepening search.

2.4.2 Code:

```
from collections import defaultdict
```

```
class Graph:  
    def __init__(self, vertices):  
        self.V = vertices  
        self.graph = defaultdict(list)  
  
    def addEdge(self, u, v):  
        self.graph[u].append(v)  
  
    def DLS(self, src, target, maxDepth, path):  
        path.append(src) # Append the current node to the path  
        if src == target:  
            return True, path  
        if maxDepth <= 0:  
            return False, path  
        for i in self.graph[src]:  
            result, path = self.DLS(i, target, maxDepth - 1, path)  
            if result:  
                return True, path  
        path.pop() # Remove the current node from the path if the target is not found at this  
        level  
        return False, path  
  
    def IDDFS(self, src, target, maxDepth):  
        for i in range(maxDepth):  
            path = [] # Initialize an empty path for each iteration  
            result, path = self.DLS(src, target, i, path)  
            if result:  
                return True, path  
        return False, []  
  
# Create a graph based on user input  
n = int(input("Enter the number of vertices: "))  
g = Graph(n)  
  
e = int(input("Enter the number of edges: "))  
for _ in range(e):  
    u, v = map(int, input("Enter edge (u v): ").split())  
    g.addEdge(u, v)
```

```

src = int(input("Enter the source node: "))
target = int(input("Enter the target node: "))
maxDepth = int(input("Enter the maximum depth: "))

# Perform IDDFS and check if the target is reachable from the source within the max depth
result, path = g.IDDFS(src, target, maxDepth)

if result:
    print(f"Target {target} is reachable from source {src} within max depth {maxDepth}.")
    print("Traversal Path:", " -> ".join(map(str, path)))
else:
    print(f"Target {target} is NOT reachable from source {src} within max depth {maxDepth}.")

```

2.4.3 Output:

```

Enter the number of vertices: 8
Enter the number of edges: 7
Enter edge (u v): 0 1
Enter edge (u v): 0 2
Enter edge (u v): 1 3
Enter edge (u v): 1 4
Enter edge (u v): 2 5
Enter edge (u v): 2 6
Enter edge (u v): 3 7
Enter the source node: 0
Enter the target node: 7
Enter the maximum depth: 4
Target 7 is reachable from source 0 within max depth 4.
Traversal Path: 0 -> 1 -> 3 -> 7

```

2.4.4 Observation Book Pictures:

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Experiment - 4

Aim :

Implement Iterative Deepening Search.

Code :

```
from collections import defaultdict
```

Class Graph :

```
def __init__(self, vertices):
```

```
    self.V = vertices
```

```
    self.graph = defaultdict(list)
```

```
def addEdge(self, u, v):
```

```
    self.graph[u].append(v)
```

```
def DLS(self, src, target, maxDepth):
```

```
    if src == target:
```

```
        return True
```

```
    if maxDepth <= 0:
```

```
        return False
```

```
    for i in self.graph[src]:
```

```
        if self.DLS(i, target, maxDepth - 1):
```

```
            return True
```

```
    return False
```

```
def IDS(self, src, target, maxDepth):
```

```
    for i in range(maxDepth):
```

```
        if self.DLS(src, target, i):
```

```
            return True
```

```
    return False
```

```
n = int(input("Enter the number of vertices:"))
```

```
g = Graph(n)
```

```
e = int(input("Enter the number of edges:"))
```

```
for _ in range(e):
```

```
    u, v = map(int, input("Enter edge(u v):").split())
    g.addEdge(u, v)
```

```
src = int(input("Enter the source node:"))
```

```
target = int(input("Enter the target node:"))
```

```
maxDepth = int(input("Enter the maximum Depth:"))
```

```
result, path = g.IDS(src, target, maxDepth)
```

```
if g.IDS(src, target, maxDepth): if result:
```

```
    print(f"Target {target} is reachable from source {src},")
```

```
    print(f"within max depth {maxDepth}.")
```

```
else:
```

```
    print(f"Target {target} is NOT reachable from source  
{src} within max depth {maxDepth}.")
```

Output:

Enter the number of vertices: 8

Enter the number of edges: 7

Enter edge(u v): 0 1

Enter edge(u v): 0 2

Enter edge(u v): 1 3

Enter edge(u v): 1 4

Enter edge(u v): 2 5

Enter edge(u v): 2 6

Enter edge(u v): 3 7

Enter the source node : 0

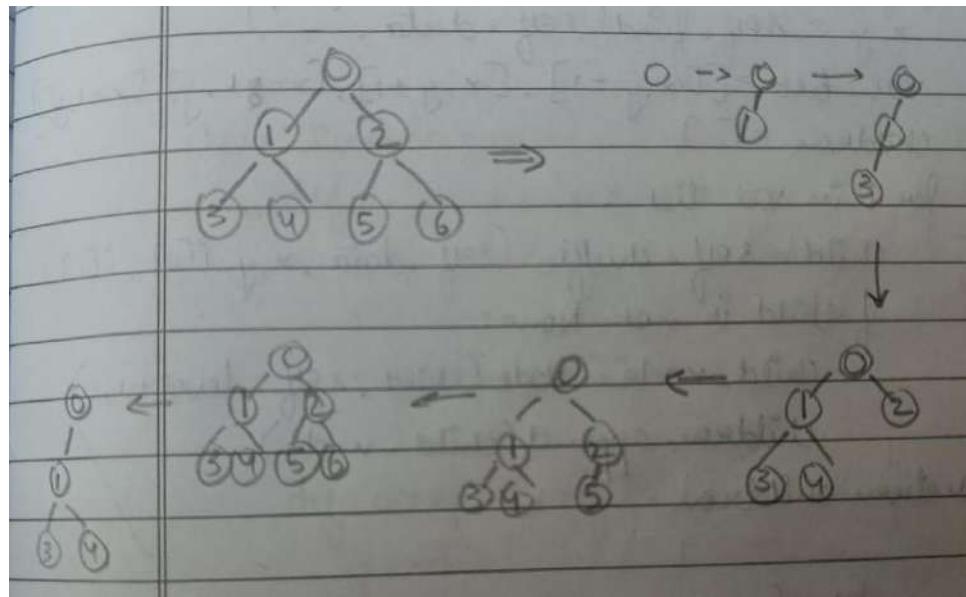
Enter the Target node : 7

Enter the maximum depth : 4

Target 7 is reachable from source 0 within max depth 4

Traversal path : 0 → 1 → 3 → 7

P/
18/12/23



2.5 Experiment - 5

2.5.1 Question:

Implement 8 puzzle using A* Algorithm.

2.5.2 Code:

```
class Node:  
    def __init__(self,data,level,fval):  
        self.data = data  
        self.level = level  
        self.fval = fval  
  
    def generate_child(self):  
        x,y = self.find(self.data,'_')  
        val_list = [[x,y-1],[x,y+1],[x-1,y],[x+1,y]]  
        children = []  
        for i in val_list:  
            child = self.shuffle(self.data,x,y,i[0],i[1])  
            if child is not None:  
                child_node = Node(child,self.level+1,0)  
                children.append(child_node)  
        return children  
  
    def shuffle(self,puz,x1,y1,x2,y2):  
        if x2 >= 0 and x2 < len(self.data) and y2 >= 0 and y2 < len(self.data):  
            temp_puz = []  
            temp_puz = self.copy(puz)  
            temp = temp_puz[x2][y2]  
            temp_puz[x2][y2] = temp_puz[x1][y1]  
            temp_puz[x1][y1] = temp  
            return temp_puz  
        else:  
            return None  
  
    def copy(self,root):  
        temp = []  
        for i in root:  
            t = []  
            for j in i:  
                t.append(j)  
            temp.append(t)  
        return temp  
  
    def find(self,puz,x):  
        for i in range(0,len(self.data)):  
            for j in range(0,len(self.data)):
```

```

if puz[i][j] == x:
    return i,j

class Puzzle:
    def __init__(self,size):
        self.n = size
        self.open = []
        self.closed = []

    def accept(self):
        puz = []
        for i in range(0,self.n):
            temp = input().split(" ")
            puz.append(temp)
        return puz

    def f(self,start,goal):
        return self.h(start.data,goal)+start.level

    def h(self,start,goal):
        temp = 0
        for i in range(0,self.n):
            for j in range(0,self.n):
                if start[i][j] != goal[i][j] and start[i][j] != '_':
                    temp += 1
        return temp

    def process(self):
        print("Enter the start state matrix \n")
        start = self.accept()
        print("Enter the goal state matrix \n")
        goal = self.accept()

        start = Node(start,0,0)
        start.fval = self.f(start,goal)
        self.open.append(start)
        print("\n\n")
        while True:
            cur = self.open[0]
            print(" ")
            print(" | ")
            print(" | ")
            print(" \\|\\ \n")
            for i in cur.data:

```

```

for j in i:
    print(j,end=" ")
print("")
if(self.h(cur.data,goal) == 0):
    break
for i in cur.generate_child():
    i.fval = self.f(i,goal)
    self.open.append(i)
self.closed.append(cur)
del self.open[0]

self.open.sort(key = lambda x:x.fval,reverse=False)

```

```

puz = Puzzle(3)
puz.process()

```

2.5.3 Output:

```

Enter the start state matrix
1 2 3
4 5 6
_ 7 8
Enter the goal state matrix
1 2 3
4 5 6
7 8 _
| |
X/Z
1 2 3
4 5 6
_ 7 8
| |
X/Z
1 2 3
4 5 6
7 _ 8
| |
X/Z
1 2 3
4 5 6
7 8 _

```

2.5.4 Observation Book Pictures:

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Experiment - 5

Aim:

S implement 8 Puzzle using A* algorithm

Code:

class Node :

```
def __init__(self, data, level, fval):
    self.data = data
    self.level = level
    self.fval = fval
```

def generate_child(self):

$x, y = self.find(self.data, '-')$

val_list = $[x-1, x+1, y-1, y+1]$

children = []

for i in val_list :

child = self.shuffle(self.data, x, y, i[0], i[1])

if child is not None:

child_node = Node(child, self.level + 1, 0)

children.append(child_node)

return children

def shuffle(self, puz, x1, y1, x2, y2):

if $x_2 = 0$ and $x_2 < \text{len}(\text{self}.data)$ and $y_2 > 0$

and $y_2 < \text{len}(\text{self}.data)$:

temp_puz = []

temp_puz = self.copy(puz)

temp = temp_puz[x2][y2]

temp_puz[x2][y2] = temp_puz[x1][y1]

temp_puz[x1][y1] = temp

return temp_puz

else:

return None

```
def copy (self, root):
    temp = []
    for i in root:
        t = []
        for j in i:
            t.append(j)
        temp.append(t)
    return temp
```

```
def find (self, puz, x):
    for i in range (0, len (self.data)):
        for j in range (0, len (self.data)):
            if puz[i][j] == x:
                return i, j
```

```
class Puzzle:
    def __init__ (self, size):
        self.n = size
        self.open = []
        self.closed = []
```

```
def accept (self):
    puz = []
    for i in range (0, self.n):
        temp = input().split(" ")
        puz.append(temp)
    return puz
```

```
def f (self, start, goal):
    return self.h (start, data, goal) + start.level
```



```

def h(self, start, goal):
    temp = 0
    for i in range(0, self.n):
        for j in range(0, self.n):
            if start[i][j] != goal[i][j] and start[i][j] != 0:
                temp += 1
    return temp

```

```

def process(self):
    print("Enter the start state matrix\n")
    start = self.accept()
    print("Enter the goal state matrix\n")
    goal = self.accept()

```

```

start = Node(start, 0, 0)
start.fval = self.f(start, goal)
self.open.append(start)
print("In\n")

```

while True:

```

cur = self.open[0]
print(" ")
print(" 1")
print(" 1")
print(" 1\n")
for i in cur.data:
    for j in i:
        print(j, end=" ")
    print(" ")

```

```

if (self.h(cur.data, goal) == 0):
    break

```

```

for i in cur.generate_child():
    i.fval = self.g(i, goal)
    self.open.append(i)

```

self.closed.append (cur)
def self.open (o)

self.open.set (key = lambda n: n.fval,
reverse = False)

puz = Puzzle (3)

puz.process ()

Output:

Enter start state matrix:

1 2 3

4 5 -

7 8 6

Enter goal state matrix:

1 2 3

4 5 6

7 8 -

1 2 3

4 5 -

7 8 6

↓

1 2 3

4 5 6

7 8 -

R/
Solved

2.6 Experiment - 6

2.6.1 Question:

Create a knowledge base using propositional logic and show that the given query entails the knowledge base or not.

2.6.2 Code:

```
from sympy import symbols, And, Not, Implies, satisfiable
```

```
def create_knowledge_base():
    # Define propositional symbols
    p = symbols('p')
    q = symbols('q')
    r = symbols('r')

    # Define knowledge base using logical statements
    knowledge_base = And(
        Implies(p, q),      # If p then q
        Implies(q, r),      # If q then r
        Not(r)              # Not r
    )

    return knowledge_base
```

```
def query_entails(knowledge_base, query):
    # Check if the knowledge base entails the query
    entailment = satisfiable(And(knowledge_base, Not(query)))

    # If there is no satisfying assignment, then the query is entailed
    return not entailment
```

```
if __name__ == "__main__":
    # Create the knowledge base
    kb = create_knowledge_base()

    # Define a query
    query = symbols('p')

    # Check if the query entails the knowledge base
    result = query_entails(kb, query)

    # Display the results
    print("Knowledge Base:", kb)
    print("Query:", query)
    print("Query entails Knowledge Base:", result)
```

2.6.3 Output:

Knowledge Base: $\neg r \wedge (\text{Implies}(p, q)) \wedge (\text{Implies}(q, r))$
Query: p
Query entails Knowledge Base: False

2.6.4 Observation Book Pictures:

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Experiment - 6

Aim:

Create a knowledge base using propositional logic and show that the given query entails the knowledge base or not.

Code:

```
from sympy import symbols, And, Not, Implies, satisfiable

def create_knowledge_base():
    p = symbols('p')
    q = symbols('q')
    r = symbols('r')
    knowledge_base = And(
        Implies(p, q),
        Implies(q, r),
        Not(r))
    return knowledge_base

def query_entails(knowledge_base, query):
    entailment = satisfiable(And(knowledge_base,
                                 Not(query)))
    return not entailment

if __name__ == "__main__":
    kb = create_knowledge_base()
    query = symbols('p')
    result = query_entails(kb, query)
    print("knowledge base:", kb)
    print("query:", query)
    print("query entails Knowledge Base:", result)
```

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Output:

Knowledge base : $\neg r \wedge (\text{Implies}(p, q)) \wedge (\text{Implies}(q, r))$
Query: p
Query entails Knowledge Base: False

2.7 Experiment - 7

2.7.1 Question:

Create a knowledge base using prepositional logic and prove the given query using resolution.

2.7.2 Code:

```
import re

def main(rules, goal):
    rules = rules.split(' ')
    steps = resolve(rules, goal)
    print('\nStep\tClause\tDerivation\t')
    print('-' * 30)
    i = 1
    for step in steps:
        print(f'{i}\t{step}\t{steps[step]}\t')
        i += 1
    def negate(term):
        return f'~{term}' if term[0] != '~' else term[1]

    def reverse(clause):
        if len(clause) > 2:
            t = split_terms(clause)
            return f'{t[1]}v{t[0]}'
        return ""

    def split_terms(rule):
        exp = '(~*[PQRS])'
        terms = re.findall(exp, rule)
        return terms

    split_terms('~PvR')
    def contradiction(goal, clause):
        contradictions = [f'{goal}v{nugate(goal)}', f'{nugate(goal)}v{goal}']
        return clause in contradictions or reverse(clause) in contradictions

    def resolve(rules, goal):
        temp = rules.copy()
        temp += [negate(goal)]
        steps = dict()
        for rule in temp:
            steps[rule] = 'Given.'
        steps[negate(goal)] = 'Negated conclusion.'
        i = 0
        while i < len(temp):
            n = len(temp)
            j = (i + 1) % n
            clauses = []
```

```

while j != i:
    terms1 = split_terms(temp[i])
    terms2 = split_terms(temp[j])
    for c in terms1:
        if negate(c) in terms2:
            t1 = [t for t in terms1 if t != c]
            t2 = [t for t in terms2 if t != negate(c)]
            gen = t1 + t2
            if len(gen) == 2:
                if gen[0] != negate(gen[1]):
                    clauses += [f'{gen[0]} v {gen[1]}']
                else:
                    if contradiction(goal,f'{gen[0]} v {gen[1]}'):
                        temp.append(f'{gen[0]} v {gen[1]}')
                        steps[""] = f"Resolved {temp[i]} and {temp[j]} to {temp[-1]}, which is in
turn null.\n
A contradiction is found when {negate(goal)} is assumed as true.
Hence, {goal} is true."
                    return steps
            elif len(gen) == 1:
                clauses += [f'{gen[0]}']
            else:
                if contradiction(goal,f'{terms1[0]} v {terms2[0]}'):
                    temp.append(f'{terms1[0]} v {terms2[0]}')
                    steps[""] = f"Resolved {temp[i]} and {temp[j]} to {temp[-1]}, which is in
turn null.\n
A contradiction is found when {negate(goal)} is assumed as true. Hence,
{goal} is true."
                return steps
        for clause in clauses:
            if clause not in temp and clause != reverse(clause) and reverse(clause) not in temp:
                temp.append(clause)
                steps[clause] = f'Resolved from {temp[i]} and {temp[j]}.'
            j = (j + 1) % n
            i += 1
    return steps
rules = 'Rv~P Rv~Q ~RvP ~RvQ' #(P^Q)<=>R : (Rv~P)v(Rv~Q)^(~RvP)^(~RvQ)
goal = 'R'
main(rules, goal)

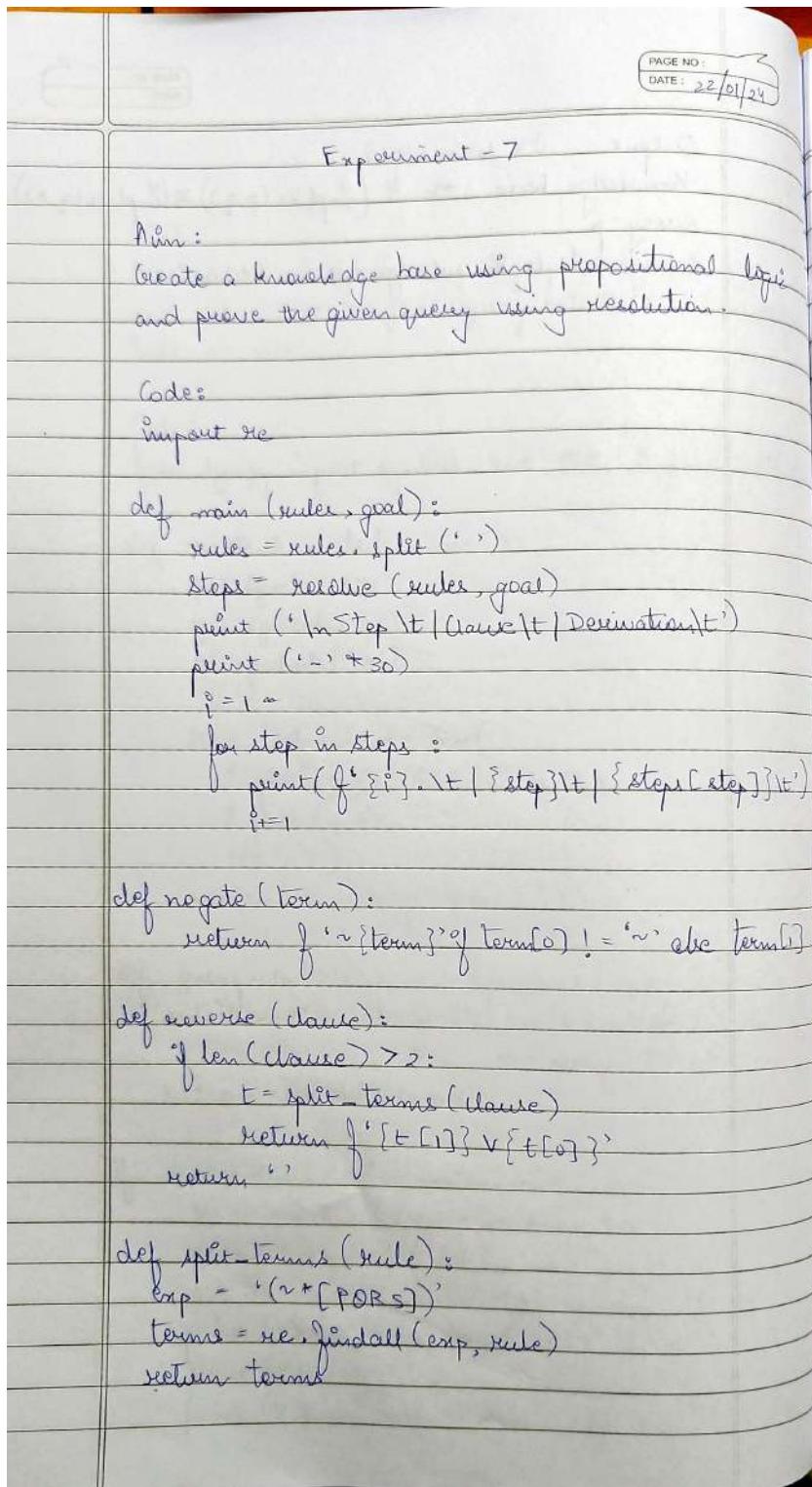
```

2.7.3 Output:

Step	Clause	Derivation
1.	Rv~P	Given.
2.	Rv~Q	Given.
3.	~RvP	Given.
4.	~RvQ	Given.
5.	~R	Negated conclusion.
6.		Resolved Rv~P and ~RvP to Rv~R, which is in turn null.

A contradiction is found when ~R is assumed as true. Hence, R is true.

2.7.4 Observation Book Pictures:



split-terms ($\neg P \vee R$)

def contradiction(goal, clause):

$$\text{contradiction} = \begin{cases} f'[\{\text{goal}\} \vee \{\text{negate(goal)}\}], \\ f'[\{\text{negate(goal)}\} \vee \{\text{goal}\}] \end{cases}$$

rules

return clause in contradictions or reverse(clause)
in contradictions

def resolve(rules, goal):

temp = rules.copy()

temp += [negate(goal)]

steps = dict()

for rule in temp:

steps[rule] = 'Given'

steps[negate(goal)] = 'Negated Conclusion'
 $i=0$

while $i < \text{len(temp)}$:

$n = \text{len(temp)}$

$j = (i+1) \% n$

clauses = []

while $j \neq i$:

term1 = split_terms(temp[i])

term2 = split_terms(temp[j])

for c in term1:

if negate(c) in term2:

$t_1 = [t \text{ for } t \text{ in term1 if } t \neq c]$

$t_2 = [t \text{ for } t \text{ in term2 if } t \neq \text{negate}(c)]$

gen = $t_1 \cup t_2$

if len(gen) == 2:

if $\text{gen}[0] \neq \text{negate}(\text{gen}[1])$:

clauses += [$f'[\{\text{gen}[0]\} \vee \{\text{gen}[1]\}]$]

else:

if contradiction(goal, f'[\{\text{gen}[0]\} \vee \{\text{gen}[1]\}]):

$\text{temp.append}(\{ \}) \cup \{\text{gen}[0]\} \vee \{\text{gen}[j]\}$
 $\text{steps}[\cdot] = f^{\text{Resolved}} \{ \text{temp}[\cdot] \}$
 and $\{ \text{temp}[j] \}$ to $\{ \text{temp}[-1] \}$,
 which is then null.
 In A contradiction is found
 when $\{ \text{negate}(\text{goal}) \}$ is
 assumed true. Hence, $\{ \text{goal} \}$
 is true."
 return steps

if len(gen) == 1:
 $\text{clauses} += [f\{\text{gen}[0]\}]$
 else:

if contradiction(goal, j, $\{ \text{terms}_1[0] \} \vee \{ \text{terms}_2[0] \}$)
 $\text{temp.append}(\{ \text{terms}_1[0] \} \vee \{ \text{terms}_2[0] \})$
 $\text{steps}[\cdot] = f^{\text{Resolved}} \{ \text{temp}[\cdot] \}$ and $\{ \text{temp}[j] \}$ to
 $\{ \text{temp}[-1] \}$, which is in turn null.
 In A contradiction is found when
 $\{ \text{negate}(\text{goal}) \}$ is assumed as true
 hence, $\{ \text{goal} \}$ is true."

return steps

for clause in clauses:

if clause not in temp and clause != reverse(clause)
 and reverse(clause) not in temp:

$\text{temp.append}(\text{clause})$

$\text{steps}[\text{clause}] = f^{\text{Resolved}} \{ \text{temp}[\cdot] \}$ and
 $\{ \text{temp}[j] \},$

$$i \leftarrow (j+1) \% n$$

return steps

rules = ' $R \vee \sim P$ $R \vee \sim Q$ $\sim R \vee P \sim R \vee Q$ $\sim R \vee Q'$ ' #

goal = ' R '

main (rules, goal)

Output

Step	Clause	Derivation
1.	$R \vee \sim P$	Given
2.	$R \vee \sim Q$	Given
3.	$\sim R \vee P$	Given
4.	$\sim R \vee Q$	Given
5.	$\sim R$	Negated Conclusion
6.		Resolved $R \vee \sim P$ and $\sim R \vee P$ to $R \vee \sim R$, which is in turn null.

A contradiction is found when $\sim R$ is assumed as true. Hence R is true.

2.8 Experiment - 8

2.8.1 Question:

Implement unification in first order logic.

2.8.2 Code:

```
import re

def getAttributes(expression):
    expression = expression.split("(")[1:]
    expression = ".join(expression)
    expression = expression[:-1]
    expression = re.split("(?<!\\(.),(?!..\\))", expression)
    return expression

def getInitialPredicate(expression):
    return expression.split("(")[0]

def isConstant(char):
    return char.isupper() and len(char) == 1

def isVariable(char):
    return char.islower() and len(char) == 1

def replaceAttributes(exp, old, new):
    attributes = getAttributes(exp)
    for index, val in enumerate(attributes):
        if val == old:
            attributes[index] = new
    predicate = getInitialPredicate(exp)
    return predicate + "(" + ",".join(attributes) + ")"

def apply(exp, substitutions):
    for substitution in substitutions:
        new, old = substitution
        exp = replaceAttributes(exp, old, new)
    return exp

def checkOccurs(var, exp):
    if exp.find(var) == -1:
        return False
    return True

def getFirstPart(expression):
    attributes = getAttributes(expression)
    return attributes[0]

def getRemainingPart(expression):
    predicate = getInitialPredicate(expression)
```

```

attributes = getAttributes(expression)
newExpression = predicate + "(" + ",".join(attributes[1:]) + ")"
return newExpression

def unify(exp1, exp2):
    if exp1 == exp2:
        return []

    if isConstant(exp1) and isConstant(exp2):
        if exp1 != exp2:
            return False

    if isConstant(exp1):
        return [(exp1, exp2)]

    if isConstant(exp2):
        return [(exp2, exp1)]

    if isVariable(exp1):
        if checkOccurs(exp1, exp2):
            return False
        else:
            return [(exp2, exp1)]

    if isVariable(exp2):
        if checkOccurs(exp2, exp1):
            return False
        else:
            return [(exp1, exp2)]

    if getInitialPredicate(exp1) != getInitialPredicate(exp2):
        print("Predicates do not match. Cannot be unified")
        return False

    attributeCount1 = len(getAttributes(exp1))
    attributeCount2 = len(getAttributes(exp2))
    if attributeCount1 != attributeCount2:
        return False

    head1 = getFirstPart(exp1)
    head2 = getFirstPart(exp2)
    initialSubstitution = unify(head1, head2)
    if not initialSubstitution:
        return False
    if attributeCount1 == 1:
        return initialSubstitution

```

```

tail1 = getRemainingPart(exp1)
tail2 = getRemainingPart(exp2)

if initialSubstitution != []:
    tail1 = apply(tail1, initialSubstitution)
    tail2 = apply(tail2, initialSubstitution)

remainingSubstitution = unify(tail1, tail2)
if not remainingSubstitution:
    return False

initialSubstitution.extend(remainingSubstitution)
return initialSubstitution

exp1 = "knows(X)"
exp2 = "knows(Richard)"
substitutions = unify(exp1, exp2)
print("Substitutions:")
print(substitutions)

```

2.8.3 Output:

```

Substitutions:
[('X', 'Richard')]

```

2.8.4 Observation Book Pictures:

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Experiment - 3

Aim:

Implement unification in first order logic.

Code:

import re

def getAttributes(expression):

 expression = expression.split("(")[1:]

 expression = " ".join(expression)

 expression = expression[:-1]

 expression = re.split("(?<=[!])\\(|,(?!\\))", expression)

 return expression.

def getInitialPredicate(expression):

 return expression.split("(")[0]

def isConstant(char):

 return char.isupper() and len(char) == 1

def isVariable(char):

 return char.islower() and len(char) == 1

def replaceAttributes(exp, old, new):

 attributes = getAttributes(exp)

 for index, val in enumerate(attributes):

 if val == old:

 attributes[index] = new

 predicate = getInitialPredicate(exp)

 return predicate + "(" + " ".join(attributes) + ")"

def apply(exp, substitutions):
 for substitution in substitutions:
 new, old = substitution
 exp = replaceAttributes(exp, old, new)
 return exp

def checkOccurs(var, exp):
 if exp.find(var) == -1:
 return False
 return True.

def getFirstPart(expression):
 attributes = getAttributes(expression)
 return attributes[0]

def getRemainingPart(expression):
 predicate = getInitialPredicate(expression)
 newExpression = predicate + " (" + ", ".join(attributes[1:])
 + ")"
 return newExpression

def unify(exp1, exp2):
 if exp1 == exp2:
 return []

if isConstant(exp1) and isConstant(exp2):
 if exp1 != exp2:
 return False

if isConstant(exp1):
 return [(exp1, exp2)]



if isConstant(exp_1):
 return [exp_2 , exp_1])

if isVariable(exp_1):
 if checkOccurs(exp_1 , exp_2):
 return False

else:

 return [(exp_2 , exp_1)]

if isVariable(exp_2):
 if checkOccurs(exp_2 , exp_1):
 return False
 else:
 return [(exp_1 , exp_2)]

if getInitialPredicate(exp_1) != getInitialPredicate(exp_2):
 print("Predicates do not match. Cannot be unified")

attributeCount1 = len(getAttributes(exp_1))
attributeCount2 = len(getAttributes(exp_2))
if attributeCount1 != attributeCount2:
 return False

head1 = getFirstPart(exp_1)
head2 = getFirstPart(exp_2)
initialSubstitution = unify(head1, head2)
if not initialSubstitution:
 return False
if attributeCount1 == 1:
 return initialSubstitution

tail₁ = getRemainingPart(exp₁)

tail₂ = getRemainingPart(exp₂)

if initialSubstitution != [] :

tail₁ = apply(tail₁, initialSubstitution)

tail₂ = apply(tail₂, initialSubstitution)

remainingSubstitution = unify(tail₁, tail₂)

if not remainingSubstitution :

return False

initialSubstitution = extend(remainingSubstitution)

return initialSubstitution

exp₁ = "knows(x)"

exp₂ = "knows(Richard)"

substitutions = unify(exp₁, exp₂)

print("Substitutions :")

print(substitutions)

Output:

Substitutions :

[('x', 'Richard')]

2.9 Experiment - 9

2.9.1 Question:

Convert a given first order logic statement into Conjunctive Normal Form (CNF).

2.9.2 Code:

```
def getAttributes(string):
    expr = '\([^\)]+\)'
    matches = re.findall(expr, string)
    return [m for m in str(matches) if m.isalpha()]

def getPredicates(string):
    expr = '[a-zA-Z~]+\\([A-Za-z,]+\\)'
    return re.findall(expr, string)

def DeMorgan(sentence):
    string = ".join(list(sentence).copy())
    string = string.replace('~~', '')
    flag = '[' in string
    string = string.replace('~[', '')
    string = string.strip(']')
    for predicate in getPredicates(string):
        string = string.replace(predicate, f'~{predicate}')
    s = list(string)
    for i, c in enumerate(string):
        if c == '|':
            s[i] = '&'
        elif c == '&':
            s[i] = '|'
    string = ".join(s)
    string = string.replace('~~', '')
    return f'{string}' if flag else string

def Skolemization(sentence):
    SKOLEM_CONSTANTS = [f'{chr(c)}' for c in range(ord('A'), ord('Z')+1)]
    statement = ".join(list(sentence).copy())
    matches = re.findall('[ \\exists ].', statement)
    for match in matches[:-1]:
        statement = statement.replace(match, "")
    statements = re.findall('[[^]]+\\]', statement)
    for s in statements:
        statement = statement.replace(s, s[1:-1])
    for predicate in getPredicates(statement):
        attributes = getAttributes(predicate)
        if ".join(attributes).islower()":
            statement = statement.replace(match[1], SKOLEM_CONSTANTS.pop(0))
```

```

else:
    aL = [a for a in attributes if a.islower()]
    aU = [a for a in attributes if not a.islower()][0]
    statement = statement.replace(aU, f'{SKOLEM_CONSTANTS.pop(0)}({aL[0]} if
len(aL) else match[1]})')
return statement

import re

def fol_to_cnf(fol):

    statement = fol.replace("<=>", "_")
    while '_' in statement:
        i = statement.index('_')
        new_statement = '[' + statement[:i] + '=>' + statement[i+1:] + ']&[' + statement[i+1:] +
'=>' + statement[:i] + ']'
        statement = new_statement
    statement = statement.replace("=>", "-")
    expr = '\[(\^]\+)\]''
    statements = re.findall(expr, statement)
    for i, s in enumerate(statements):
        if '[' in s and ']' not in s:
            statements[i] += ']'
    for s in statements:
        statement = statement.replace(s, fol_to_cnf(s))
    while '-' in statement:
        i = statement.index('-')
        br = statement.index('[') if '[' in statement else 0
        new_statement = '~' + statement[br:i] + ']' + statement[i+1:]
        statement = statement[:br] + new_statement if br > 0 else new_statement
    while '¬∀' in statement:
        i = statement.index('¬∀')
        statement = list(statement)
        statement[i], statement[i+1], statement[i+2] = '∃', statement[i+2], '¬'
        statement = ''.join(statement)
    while '¬∃' in statement:
        i = statement.index('¬∃')
        s = list(statement)
        s[i], s[i+1], s[i+2] = '∀', s[i+2], '¬'
        statement = ''.join(s)
    statement = statement.replace('¬[ ∀', '[¬∀')
    statement = statement.replace('¬[ ∃', '[¬∃')
    expr = '¬[ ∀ | ∃ ].)'
    statements = re.findall(expr, statement)
    for s in statements:

```

```

statement = statement.replace(s, fol_to_cnf(s))
expr = '^\[[^\]]+\]''
statements = re.findall(expr, statement)
for s in statements:
    statement = statement.replace(s, DeMorgan(s))
return statement
print(Skolemization(fol_to_cnf("animal(y)<=>loves(x,y)")))
print(Skolemization(fol_to_cnf("∀ x[ ∀ y[animal(y)=>loves(x,y)]]=>[ ∃ z[loves(z,x)]]")))
print(fol_to_cnf("[american(x)&weapon(y)&sells(x,y,z)&hostile(z)]=>criminal(x)"))

```

2.9.3 Output:

```

[~animal(y)|loves(x,y)]&[~loves(x,y)|animal(y)]
[animal(G(x))&~loves(x,G(x))]|[loves(F(x),x)]
[~american(x)|~weapon(y)|~sells(x,y,z)|~hostile(z)]|criminal(x)

```

2.9.4 Observation Book Pictures:

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Experiment - 9

Aim:
Convert a given first order logic statement into
Conjunctive Normal form (CNF).

Code:

```

import re

```

```

def getAttributes(string):
    expr = '[^+])'
    matches = re.findall(expr, string)
    return [m for m in str(matches) if m.isalpha()]

```

```

def getPredicates(string):
    expr = '[a-zA-Z~]+)([A-Za-z.]+)'
    return re.findall(expr, string)

```

```

def DMorgan(sentence):
    string = ''.join(list(sentence).copy())
    string = string.replace('~~', '')
    flag = '[' in string
    string = string.replace('~[', ''))
    string = string.strip(']')
    for predicate in getPredicates(string):
        string = string.replace(predicate, f'~{predicate}')
    s = list(string)
    for i, c in enumerate(string):
        if c == '|':
            s[i] = '&'
        elif c == '&':
            s[i] = '|'
    string = ''.join(s)

```

string = string.replace ('~~', '')

string = string.replace ('~~', '')

return f'[{string}]' if flag else string

def Skolemization(sentence):

SKOLEM_CONSTANTS = [f'{var(c)}' for c in
range(ord('A'), ord('Z') + 1)]

statement = ''.join(list(sentence).copy())

matches = re.findall('([VZ].)', statement)

for match in matches[:-1]:

statements = statement.replace(match, '')

statements = re.findall('([VZ][^]+)',
statement)

for s in statements:

statement = statement.replace(s, s[:-1])

for predicate in getPredicates(statement):

attributes = getAttributes(predicate)

if ''.join(attributes).islower():

statement = statement.replace(match[1],
SKOLEM_CONSTANTS.pop(0))

else

aL = [a for a in attributes if a.islower()]

aU = [a for a in attributes if not a.islower()][0]

statement = statement.replace(aU, f'{SKOLEM_CONSTANTS.pop(0)}{aL[0]} if len(aL) else
match[1]}')

return statement

def fol_to_cnf(fol):

statement = fol.replace("=>", "-")

while '-' in statement:

i = statement.index('-')



$\text{new_statement} = ' [' + \text{statement}[i:i] + ' \Rightarrow ' + \text{statement}[i+1:i] + '] \neq [' + \text{statement}[i+1:i] + ' \Rightarrow ' + \text{statement}[i:i] + '] '$

$\text{Statement} = \text{new_statement}$

$\text{statement} = \text{statement.replace}(' \Rightarrow ', ' - ')$

$\text{expr} = ' 1 [([\sim]) + 1] '$

$\text{statements} = \text{re.findall(expr, statement)}$

for i , s in enumerate(statements):

if '[' in s and ']' not in s :

$\text{statements}[i] += '] '$

for s in statements:

$\text{statements} = \text{statement.replace}(s, \text{fol_to_inf}(s))$

while '-' in statement:

$i = \text{statement.index}('-')$

$br = \text{statement.index}(['])$ if '[' in statement else 0

$\text{new_statement} = ' \sim ' + \text{statement}[br:i] + ' 1 ' + \text{statement}[i+1:]$

$\text{statement} = \text{statement}[:br] + \text{new_statement} + \text{statement}[br:]$
else new statement.

while ' $\sim A$ ' in statement:

$i = \text{statement.index}(\sim v)$

$\text{statement} = \text{list(statement)}$

$\text{statement}[i], \text{statement}[i+1], \text{statement}[i+2] = ' \exists ', \text{statement}[i+2], \sim$

$\text{statement} = ': \text{join(statement)}$

while ' $\sim \exists$ ' in statement:

$i = \text{statement.index}(\sim \exists)$

$s = \text{list(statement)}$

$s[i], s[i+1], s[i+2] = ' \forall ', [i+2], \sim,$

$\text{statement} = ': \text{join(s)}$

statement = statement.replace ('~(A)', '[~A]')

statement = statement.replace ('~(E)', '[~E]')

expr = '(~(A|E).)'

statements = rec.findall(expr, statement)

for s in statements :

statement = statement.replace (s, fol_to_cnf(s))

expr = '~~[[~]]+1]'

statements = rec.findall(expr, statement)

for s in statements :

statement = statement.replace (s, DeMorgan(s))

return statement

print(Skolemization(fol_to_cnf("animal(y) \leftrightarrow loves(x,y))))

print(Skolemization(fol_to_cnf("A(x)[y[animal(y) \rightarrow loves(x,y)]]) \Rightarrow
 $[\exists z[\text{loves}(z,x)]]$)))

print(fol_to_cnf("American(x) \wedge weapon(y) \wedge sells(x,y,z) \wedge
hostile(z) \Rightarrow criminal(x)"))

Output:

[~animal(y) | loves(x,y))] \wedge [~loves(x,y) | animal(y)]

[animal(F(x)) \rightarrow ~loves(x, F(x))] \mid [loves(F(x)), x]

[american(x) | ~weapon(y) | ~sells(x,y,z) | ~hostile(z)] \mid criminal(x)

2.10 Experiment - 10

2.10.1 Question:

Create a knowledge base consisting of first order logic statements and prove the given query using forward reasoning.

2.10.2 Code:

```
import re

def isVariable(x):
    return len(x) == 1 and x.islower() and x.isalpha()

def getAttributes(string):
    expr = '\([^\)]+\)'
    matches = re.findall(expr, string)
    return matches

def getPredicates(string):
    expr = '([a-zA-Z~]+)([^&|]+\\)'
    return re.findall(expr, string)

class Fact:
    def __init__(self, expression):
        self.expression = expression
        predicate, params = self.splitExpression(expression)
        self.predicate = predicate
        self.params = params
        self.result = any(self.getConstants())

    def splitExpression(self, expression):
        predicate = getPredicates(expression)[0]
        params = getAttributes(expression)[0].strip(')').split(',')
        return [predicate, params]

    def getResult(self):
        return self.result

    def getConstants(self):
        return [None if isVariable(c) else c for c in self.params]

    def getVariables(self):
        return [v if isVariable(v) else None for v in self.params]

    def substitute(self, constants):
        c = constants.copy()
        f = f'{self.predicate}({",".join([constants.pop(0) if isVariable(p) else p for p in self.params])})'
        return Fact(f)
```

```

class Implication:
    def __init__(self, expression):
        self.expression = expression
        l = expression.split('=>')
        self.lhs = [Fact(f) for f in l[0].split('&')]
        self.rhs = Fact(l[1])

    def evaluate(self, facts):
        constants = {}
        new_lhs = []
        for fact in facts:
            for val in self.lhs:
                if val.predicate == fact.predicate:
                    for i, v in enumerate(val.getVariables()):
                        if v:
                            constants[v] = fact.getConstants()[i]
                    new_lhs.append(fact)
        predicate, attributes = getPredicates(self.rhs.expression)[0],
        str(getAttributes(self.rhs.expression)[0])
        for key in constants:
            if constants[key]:
                attributes = attributes.replace(key, constants[key])
        expr = f'{predicate} {attributes}'
        return Fact(expr) if len(new_lhs) and all([f.getResult() for f in new_lhs]) else None

```

```

class KB:
    def __init__(self):
        self.facts = set()
        self.implications = set()

    def tell(self, e):
        if '=>' in e:
            self.implications.add(Implication(e))
        else:
            self.facts.add(Fact(e))
        for i in self.implications:
            res = i.evaluate(self.facts)
            if res:
                self.facts.add(res)

    def query(self, e):
        facts = set([f.expression for f in self.facts])
        i = 1
        print(f'Querying {e}:')
        for f in facts:

```

```

if Fact(f).predicate == Fact(e).predicate:
    print(f'\t{i}. {f}')
    i += 1

def display(self):
    print("All facts: ")
    for i, f in enumerate(set([f.expression for f in self.facts])):
        print(f'\t{i+1}. {f}')

kb = KB()
kb.tell('missile(x)=>weapon(x)')
kb.tell('missile(M1)')
kb.tell('enemy(x,America)=>hostile(x)')
kb.tell('american(West)')
kb.tell('enemy(Nono,America)')
kb.tell('owns(Nono,M1)')
kb.tell('missile(x)&owns(Nono,x)=>sells(West,x,Nono)')
kb.tell('american(x)&weapon(y)&sells(x,y,z)&hostile(z)=>criminal(x)')
kb.query('criminal(x)')
kb.display()

```

2.10.3 Output:

```

Querying criminal(x):
    1. criminal(West)
All facts:
    1. criminal(West)
    2. hostile(Nono)
    3. weapon(M1)
    4. missile(M1)
    5. sells(West,M1,Nono)
    6. enemy(Nono,America)
    7. owns(Nono,M1)
    8. american(West)

```

2.10.4 Observation Book Pictures:

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Experiment - 10

Aim:
(Create a knowledge base consisting of first order logic statements and prove the given query using forward reasoning.)

Code:

```
import re
```

def isVariable(x):
 return len(x) == 1 and x.islower() and x.isalpha()

def getAttributes(string):
 expr = '([^\s]+|\s+)'
 matches = re.findall(expr, string)
 return matches

def getPredicate(string):
 expr = '([a-zA-Z]+|[^\s]+\s+[a-zA-Z]+\s+)'
 return re.findall(expr, string)

class Fact:

```
def __init__(self, expression):  
    self.expression = expression.  
    predicate, params = self.splitExpression(expression)  
    self.predicate = predicate  
    self.params = params  
    self.result = any(self.getConstants())
```

def splitExpression(self, expression):
 predicate = getPredicate(expression)[0]
 params = getAttributes(expression)[0].strip(')').split(',')
 return [predicate, params]

def getResult(self):
 return self.result

def getConstants(self):
 return [None if isVariable(c) else c for c in self.params]

def getVariables(self):
 return [v if isVariable(v) else None for v in self.params]

def substitute(self, constants):
 c = Constants.copy()
 f = f"{{self.predicate}}({{}})".join(constants.pop(0) if
 isVariable(p) else p for p in self.params))}"
 return Fact(f)

Class Implication:

def __init__(self, expression):
 self.expression = expression
 l = expression.split('=>')
 self.lhs = [Fact(f) for f in l[0].split('&')]
 self.rhs = Fact(l[1])

def evaluate(self, facts):

constants = {}

new_lhs = []

for fact in facts:

for val in self.lhs:

if val.predicate == fact.predicate:

for i, v in enumerate(val.getVariables()):

if v:

constants[v] = fact.getConstants()[i]

new_lhs.append(fact)

predicate, attributes = getPredicates (self), expression
str(getAttributes(self)) + " " + predicate

for key in constants:
if constants[key]:

 attributes = attributes.replace(key, constants[key])
expr = f'{predicate} {{ attributes }}'
return Fact(expr) if len(new_rhs) == 1 else all([f'getattribute(f, i)' for f in new_rhs]) else None

class KB:

def __init__(self):

 self.facts = set()

 self.implications = set()

def tell(self, e):

 if '=>' in e:

 self.implications.add(Implication(e))

 else:

 self.facts.add(Fact(e))

 for i in self.implications:

 res = i.evaluate(self.facts)

 if res:

 self.facts.add(res)

def query(self, e):

 facts = set([f.expression for f in self.facts])

 print(f'querying {e}:')

 for f in facts:

 if Fact(f).predicate == Fact(e).predicate:

 print(f' {f} {e} {f.predicate}')

def display(self):

print("All facts: ")

for i, f in enumerate (list (f-expression for f in self.facts)): :

print(f' {i+1}. {f}')

kb = KB()

kb.tell = ('missile(x) \Rightarrow weapon(x)')

kb.tell = ('missile(M)')

kb.tell = ('enemy(x, American) \Rightarrow hostile(x)')

kb.tell = ('american(West)')

kb.tell = ('enemy(Nono, America)')

kb.tell = ('owns(Nono, M)')

kb.tell = ('missile(x) \wedge owns(Nono, x) \Rightarrow sells(West, x, Nono)')

kb.tell = ('american(x) \wedge weapon(y) \wedge sells(x, y, z) \wedge hostile(z)
 \Rightarrow criminal(x)')

kb.query('criminal(x)')

kb.display()

Output:

Querying criminal(x):

Criminal(West)

All facts:

1. sells(West, M1, Nono)

2. criminal(West)

3. weapon(M)

4. american(West)

5. missile(M)

6. owns(Nono, M1)

7. hostile(Nono)

8. enemy(Nono, America)

3. Certificates of Python:

3.1 Kaggle:



3.2 Infosys Springboard:



Issued on: Monday, November 27, 2023
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